Lake volume and potential hazards of moraine-dammed glacial

lakes in temperatemaritime glaciation regions:—A case study of

Bienong Co

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Abstract. The existence of glacial lakes in the Southeastern Tibetan Plateau (SETP) is a potential hazard to downstream regions, as the outburst of some lakes has the potential to result in disastrous glacial lake outburst flood (GLOF) events of high-magnitude. In the present study, we conducted a comprehensive investigation for Bienong Co, an end moraine-dammed glacial lake in SETP. First, the lake basin morphology was simulated and the lake volume was estimated, obtaining showing that the maximum lake depth is ~181 m and the lake volume of is ~102.3×10⁶ m³. Then, we assumed that the ice avalanche (Scenarios A1, A2, and A3) and the lateral moraine landslide (Scenarios B1, B2, and B3 and C1, C2, and C3) induced GLOFs in the process chain of Bienong Co. The volume of nine trigger scenarios of trigger was calculated using the RAMMS model, and the displacement wave generation and propagation in the lake, overtopping flow and erosion on the moraine dam, and subsequent downstream flooding were simulated by the BASEMENT model. The results show demonstrate that the ice avalanche scenarios produce the largest amount of material into the lake, resulting in displacement wave amplitudes of up to 25.2 m (Scenario A3) near the moraine dam. Smaller volumes of landslides entering the lake only result in smaller displacement waves in the lake, such as that Scenario C1 has a wave amplitude below 1 m near the moraine dam. Scenarios A1, A2, and A3 result in the released water from the lake of 24.1×10^6 m³, 25.3×10^6 m³, and 26.4×10^6 m³, and the peak discharges at the moraine dam of 4,996 m³/s, 7,817 m³/s, and 13,078 m³/s, respectively. These high discharges cause scour erosion of the moraine dams, resulting in breaches widths of 295.0 m, 339.4 m, and 368.5 m, and breach depths of 19.0 m, 19.1 m, and 19.3 m, respectively. However, in landslide scenarios, only the overtopping flow generated by Scenarios B3 and C3 caused moderate erosion of the moraine dam, with breach depths of 6.5 m and 7.9 m, and breach widths of 153 m and 169 m, respectively. GLOFs generated by Scenario A1, A2, and A3 can all flow through 18 settlements downstream, and will threaten more than half of the settlements. Both Scenarios B3 and C3 produced floods that flow through eight downstream settlements within 20 hours and had a relatively small impact on them. Comparisons show that Bienong Co is the relative deepest glacial lake known on the Tibetan Plateau, and this study could provide a-new insight of about the moraine-dammed glacial lakes in the SETP and a valuable reference for GLOFs disaster prevention to for the local governments.

1 Introduction

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Due to global warming, the accelerated retreat and thinning of glaciers has occurred in most regions compared to the last century (Zemp et al., 2019), resulting in a rapid increase in the number, area, and volume of glacial lakes worldwide (Shugar et al., 2020; Wang et al., 2020). Glacier meltwater can be confined and stored in certain depressions dammed by moraine, ice, or bedrock (Vilímek et al., 2013). Once the dam is damaged, the water can be suddenly and catastrophically released to form Glacial glacial Lake-lake Outburst outburst Floods (GLOFs), which may cause severe social and geomorphic impacts

several dozens of kilometers and more downstream (Lliboutry, 1977; Richardson and Reynolds, 2000; Osti and Egashira, 2009;

Carrivick and Tweed, 2016; Cook et al., 2018; Harrison et al., 2018; Zheng et al., 2021). Moraine-dammed glacial lakes are of particular attention-concern owing-due to their large volume (Fujita et al., 2013; Veh et al., 2020), weak dam composition, and exposure to various triggers, such as the-ice and/or rock avalanches, and heavy precipitation, and intense glacier melting (Emmer and Cochachin, 2013; Nie et al., 2018), which are the most common sources of GLOFs (Watanbe and Rothacher, 1996; Westoby et al., 2014). The Himalayas and the Southeastern Tibetan Plateau (SETP) are regions of frequently occurrence of GLOFs caused by moraine-dammed glacial lakes (Wang, 2016). Study-Research shows that the Himalayas, especially the southern region, is are likely to experience more GLOFs at-in the coming decades (Veh et al., 2020).

The SETP is a broad mountainous area covering the central and eastern Nyaingêntanglha Ranges, eastern Himalayas and western Hengduan Mountains, and has thehas most highly complicated terrains (Ke et al., 2014). Controlling Controlled by the warm and humid Indian monsoons, a plentya large number of temperate maritime glaciers have developed here (Yang et al., 2008), featured as the adequate recharge, strong ablation, low snowline distribution, high temperature, fast movement, and strong geological, as well as geomorphological, effect (Li et al., 1986; Qin et al., 2007; Liu et al., 2014), which have been observed with the most markedly negative mass balances during the past decades (Kääb et al., 2012; Neckel et al., 2014; Kääb et al., 2015; Brun et al., 2017; Dehecq et al., 2019). Therefore, the combination of active glacial processes and heavy rainfall during the monsoon season makes the region prone to glacier-related natural hazards (Wang et al., 2012b). Studies of glacial lakes in the SETP have mainly focused on regional-scale assessment of glacial lake changes (Wang et al., 2011a; Song et al., 2016; Wang et al., 2017; Zhang et al., 2020; Zhang et al., 2021), identification of potentially dangerous glacial lakes (Wang et al., 2011; Liu et al., 2019; Duan et al., 2020; Qi et al., 2020), site-specific analysis of formation mechanisms, development trends, risk evolution and management measures of GLOFs (Cui et al., 2003; Cheng et al., 2008, 2009; Sun et al., 2014; Liu et al., 2021; Wang et al., 2021), and exploration of geological features of a single glacial lake (Yuan et al., 2012; Liu et al., 2015; Huang et al., 2016). Fewer studies have applied hydrodynamic models to simulate GLOFs in the SETP. Wang et al. (2011b) evaluated the applicability of ASTER GDEM (the Global Digital Elevation Model) and SRTM DEM in the simulation of GLOF processes based on the HEC RAS hydrodynamic model (Brunner, 2002). Zheng et al. (2021) analyzed and reconstructed a GLOF process chain of Jinwu Co using the published empirical relationships and the GIS-based r.avaflow simulation tool (Mergili et al., 2017; Pudasaini and Mergili, 2019; Mergili and Pudasaini, 2020).

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As a key factor related to the peak discharge and outburst volume of a GLOF event (Evans, 1987; Huggel et al., 2002), lake storage capacity is difficult to directly obtain by means of satellite remote sensing approach. Currently, owing due to the easy availability of area information from remote sensing images, the volume of glacial lakes is generally estimated using the developed empirical formulas to connect glacial lake area and volume based on bathymetric data for a small number of glacial lakes (O'Connor et al., 2001; Huggel et al., 2002; Yao et al., 2014). However, the estimated volume may be inaccurate because of the unique geographical conditions of different glacial lakes (Cook and Quincey, 2015). The Although the SETP region is an area with a high incidence of GLOFs (Sun et al., 2014; Zheng et al., 2021), however, there were have been few publicly available bathymetric data of glacial lakes and related research works. Previous bathymetric works in the Tibetan Plateau were carried out mainly for those glacial lakes located in the Himalayas (LIGG/WECS/NEA, 1988; Geological survey Survey of India, 1995; Yamada, 1998; Mool et al., 2001; Sakai, 2003; Yamada, 2004; ICIMOD, 2011; Sakai, 2012; Yao et al., 2012; Wang et al., 2015; Haritashya et al., 2018; Sharma et al., 2018; Li et al., 2021). This is unfavorable to fully understand the morphology and optimal disaster prevention strategies of glacial lakes in the SETP region. In recent years, the uUnmanned Surface surface Vessel (USVs) have developed rapidly (Liu et al., 2016), which and have been widely used in certain scenarios, such as bathymetric map creation, transportation, environmental monitoring, and moraine surveys (Larrazabal and Peñas, 2016; Yan et al., 2010; Specht et al., 2019a), owing to the favorable security on personnel safety and the high flexibility in complex environments. Glacial lakes are mostly located at high altitudes and in harsh environments (Zhang et al., 2020), and USVs makes the measurement of the underwater topography of glacial lakes safer, more convenient, and more accurate (Li et al., 2021).

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In this study, we aim to complete an investigation of the potential GLOF hazard of an end moraine-dammed glacial lake, Bienong Co ("Co" means "lake" in Tibetan) in the SETP based on field bathymetric data and remote sensing data using a multi-model combination method. First, the lake basin morphology of Bienong Co is modelled. Then, multiple components of the GLOF process chain, including initial mass movement from the mother glacier and lateral moraine slope, displacement wave generation and propagation in the lake, overtopping flow and erosion on the moraine dam, and subsequent downstream flooding were simulated. This study will help assist the local government to understand the potential hazards of Bienong Co and serve as a reference for other scholars studying glacial lakes and GLOFs in the SETP region.

90 2 Study area

Bienong Co is located in the upper area of the Yi'ong Zangbo ("Zangbo" means "river" in Tibetan) watershed (30°05' -31°03'N, 92°52' - 95°19'E) in the SETP (Fig. 1a). As a one-level tributary of the Parlung Zangbo and a two-level tributary of the Yarlung Zangbo (i.e., the Brahmaputra River), the Yi'ong Zangbo drains an area covering 13,533 km². The terrain is high in the west and low in the east with high mountains and valleys. The climate is warm and humid, featuring the a mean annual precipitation of 958 mm and a mean annual temperature of 8.8 °C (Ke et al., 2013, 2014). There were was 1,907.76 km² glacier coverage, and 105 moraine-dammed glacial lakes with a total area of 16.87 km²₃-in 2016 (Duan et al., 2020). Seven glacial lakes in the watershed, including Bienong Co, were considered to have high GLOFs potential (Duan et al., 2020), of which, the Jinwu Co collapsed on June 26, 2020 (Zheng et al., 2021). As of 2021, there have been three recorded large GLOF events in the basin, all of which caused very significant damage to the infrastructures in the downstream region (Sun et al., 2014; Yao et al., 2014; Zheng et al., 2021) (Fig. 1b). Bienong Co is an end moraine-dammed lake constrained by the snout of the mother glacier (Mulang Glacier) on the south and a massive unconsolidated terminal moraine dam on the northwest (Fig. 1c). The elevation of the water surface in 2021 was 4745 m covering an area of 1.15 ± 0.05 km² that has experienced less significant changes. The Mulang Glacier had an area of $8.29 \pm 0.22 \text{ km}^2$ and a mean surface slope of ~18.28°, which has also remained a largely unchanged area over the last 45 years. However, the glacier ablation zone experienced a thinning process of 6.5 m/a. The flow of Bienong Co converges into Xiong Qu ("Qu" means "river" in Tibetan), which is one of the two main tributaries of the upper Yi'ong Zangbo (Fig. 1b). The flow channel from the Bienong Co to the confluence of Xiong Qu and Song Qu (another main tributary of the upper Yi'ong Zangbo) stretches ~53 km, with the a river longitudinal drop ratio of 14.48%. There are 18 settlements and 13 bridges densely distributed along the flow channel, as well as a large amount of agricultural land. In addition, the Jiazhong Highway extends closely along the river (Fig. 1d).

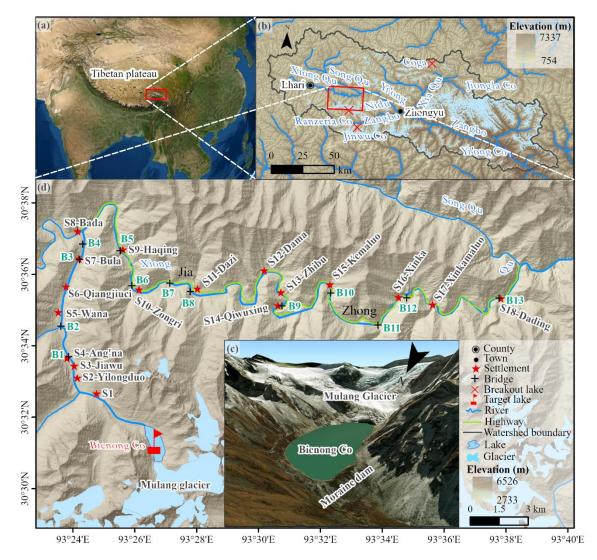


Figure 1. The one of the study area. (a) The location of the Yi'ong Zangbo watershed, (b) the location of Bienong Co, (c) the a close view of Bienong Co, and (d) the distribution of settlements, as well as bridges, within ~53 km downstream of Bienong Co. Background The background of Fig. 1a and c is the a MapWorld image, based on which, settlements, bridges, and the Jiazhong Highway along the flow channel were identified. Background The background of Fig. 1b and d is the Advanced Land Observing Satellite ALOS) mission Phased Array type L-band Synthetic Aperture Radar (PALSAR) Digital Elevation Model (DEM).

The area of Bienong Co has remained basically stable in the past 40 years, but its area of 1.15 ± 0.05 km² in 2021 was almost twice the size of the two nearby outburst moraine-dammed glacial lakes, one is of which is Jinwu Co (Zheng et al., 2021) and the other is Ranzeria Co, which were located just 24 km and 9 km southeast of Bienong Co (Sun et al., 2014), respectively. The moraine dam of Bienong Co has an average height of 72 m, enclosing a lake volume of 65.2×10⁶ m³, accounting for 64% of the total (Fig. 2e). The Overall, the greater is the volume of water retained in the lake, the greater is the volume of water available for potential flooding (Westoby et al., 2014), and the greater is the hazard caused by GLOFs. GLOFs are extremely highly complex phenomena, each of them which constitutes a distinctly unique event with the characteristics determined by the triggering mechanism, lake hypsometry, the geometry, composition, and structural integrity of the moraine dam, as well as the topography and geology of the flood path (Westoby et al., 2014). Studies of historically GLOFs reveal that the most common cause of glacial lakes' failure in the Himalayas is mass movement (snow, ice, and/or rock) entering lakes (Richardson and Reynolds, 2000; Wang et al., 2012a; Emmer and Cochachin, 2013; Worni et al., 2014), and subsequently overtopping and eroding of the moraine dam (Risio et al., 2011). Bienong Co is directly connected to the Mulang Glacier, whose ablation zone that is defined as the mother glacier tongue in this study, and has an average slope of 20° with well-

developed ice crevasses (Fig. 2a and b). Lv et al.; (1999) proposed that a slope of mother glacier tongue greater than 8° is conducive to the occurrence of ice avalanche. In the context of global warming, glacial meltwater can lubricate the glacier itself, increasing the likelihood of overhanging ice sliding into the lake (Wang et al., 2015). Therefore, ice disintegration from the Mulang Glacier could be a potential trigger for GLOFs of Bienong Co. In addition, the GLOF of Jinwu Co was caused by an initial moraine landslide with a slope range of 30° - 45° on the left side (Zheng et al., 2021). Bolch et al. (2011) and Rounce et al. (2016) both deemed reported that non-glacierized areas around a lake with a slope > 30° are potential rock fall, landslide, or other solid mass movement regions. There are multiple locations with lateral moraines around Bienong Co that fit into this slope range (Fig. 2c, d, and e). Thus Therefore, lateral moraine landslides could also be a potential trigger for Bienong Co's GLOF.

Dam characteristics, such as dam geometry (freeboard, width_to-height ratio, distal face slope), dam material properties, and ice-cored moraine conditions, govern the stability of the dam (Huggel et al., 2004; Prakash and Wang et al., 2011a; Nagarajan, 2017). Freeboard refers to the vertical distance between the lake level and the lowest point on the dam crest, which reflects the minimum requisite wave amplitude needed for the occurrence of the overtopping, and a higher freeboard is not conducive to the occurrence of overtopping (Emmer and Vilímek, 2014). A natural outlet with a width of ~50 m is in the right of the dam (facing downstream) (Fig. 2e and f), indicating that the freeboard of Bienong Co is 0 m, which signals the high potential for overtopping of the lake. The moraine dam is ~520 m wide and the height is variable with an average height of ~72 m_a and the width-to-height ratio of is 7.2 (Fig. 2e). According to the thresholds favoring GLOFs of dam widths smaller than 60 m proposed by Lv et al. (1999) and -width-to-height ratios smaller than 0.2 proposed by Huggel et al. (2004), the moraine dam of Bienong Co is stable. However, the freeboard of 0 m and the distal facing slope of 35° are the conditions that are conducive to GLOFs based on favorable the favoring thresholds of smaller than 25 m (Mergili et al., 2011) and larger than 20° (Lv et al., 1999). The moraine dam of Bienong Co is covered with vegetation, the surface layer is a larger particle size of the stone, and below the smaller particle size, the material is loose and poorly cemented, which is susceptible to destruction by water forces (Fig. 2e). The existence of ice core inside of the moraine dam is unknown, but there is no ice core in Jinwu Co's breached dam. The dam crest elevation of Bienong Co is 320 m higher than that of Jinwu Co. Additionally, McKillop and Clague (2007) argued that moraines with rounded surfaces and minor superimposed ridges are considered ice-cored, whereas narrow, sharp-crested moraines with angular cross-sections are interpreted as ice-free, and the dam of Bienong Co clearly fits the latter category. In summaryaggregate, we consider that the potential threats to Bienong Co are mainly ice avalanches from the mother glacier and lateral moraine landslides.

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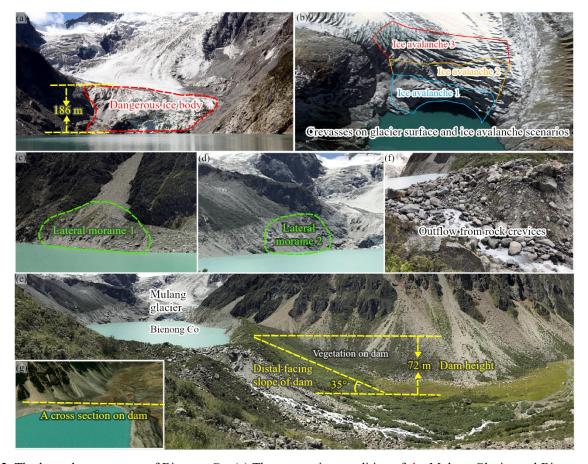


Figure 2. The hazards assessment of Bienong Co. (a) The connection condition of the Mulang Glacier and Bienong Co, (b) the crevasses on the glacier surface and the assumed ice avalanche scenarios of the Mulang Glacier, (c) and (d) the assumed lateral moraine location, (e) and (f) the moraine dam of Bienong Co, and (g) a cross—section on of the moraine dam for statistical purposes. Fig. 2-(b) and (g) is are based on the MapWorld image, and the other pictures photographs were taken by Xiaojun Yao and Qi Wang on August 27, 2020.

3 Methodology

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3.1 Bathymetry and modeling

Lake bathymetric information is one of the most important inputs in the dynamic modeling of GLOFs, which and can accurately reflect the topography of the lake basin below the water surface and be used to calculate the potential flood volume released in different breach scenarios (Westoby et al., 2014). In this study, the depth data were obtained by a USV (APACHE 3) system, which consists of four main parts; i.e., the data acquisition module; the data transmission module; the positioning and navigation control module; and the power module (Li et al., 2021) (Fig. 3a and b). The USV system has a draft of 10 cm, which is smaller than the inflatable kayak used in previous studies investigations (Haritashya et al., 2018; Sattar et al., 2019, 2021). The D230 Single-Frequency Depth Sounder mounted on the USV is designed the to measure a range of 0.15 - 300 m with the a depth resolution of 1 cm and the a bathymetry error of ± 1 cm+0.1%×h (water depth). The sounder can operate at 200 kHz and a water temperature range of -30°C - 60°C, °C. Mmeanwhile, a real-time kinematic system enables a precise positioning for the bathymetric position with the a horizontal error of ± 8 mm, the a vertical error of ± 15 mm, and the a directional error of 0.2° on the 1 m baseline. Field measurements were carried out on August 27, 2020. We designed four longitudinal routes and 13 transverse routes prior to the survey, along which the USV_based measurement was conducted (Fig. 3c). The maximum speed of the USV can reach 8 m/s, and our survey was conducted with at a speed of 2 m/s for a total route of 22.58 km in the Bienong Co. Due to absence of any obstructions on the lake, such as ice or small islands, the high

performance of the USV and the real-time monitoring, the survey was accurately completed along the designed route. A total of 16,020 valid sounding points, essentially basically covering the entire glacial lake, were measured, which well fulfilled the data density requirement to model the lake basin topography (Fig. 3c).

The bathymetric map was created within ArcGIS Pro software using the natural neighbor interpolation algorithm (Thompson et al., 2016; Haritashya et al., 2018; Watson et al., 2018). In addition, Surfer software was used employed to simulate the 3D morphology of the Bienong Co's lake basin. Lake capacity can be understood as the volume of water storage below a certain water level, which is the volume between a certain spatial curved surface and a certain horizontal surface (Shi et al., 1991). In this study, the volume of Bienong Co was obtained by multiplying the depth data and map resolution (5 m) as Eq. (1) follows:

$$V = \sum_{i=1}^{n} H_i \cdot \lambda \tag{1}$$

where V is the volume (m³) of Bienong Co; H_i is the depth (m) at the i-th pixel; n is the number of the pixels in the lake area; and λ is the pixels resolution (m²) of the bathymetric map.

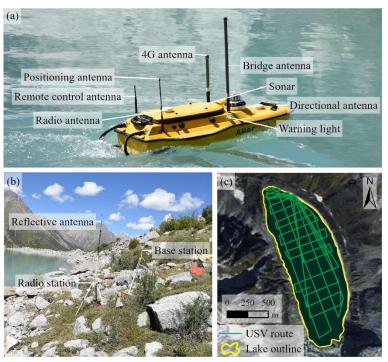


Figure 3. The bathymetry of Bienong Co. (a) the <u>The</u> USV sampling equipment in water <u>__</u> and (b) on land; (c) the sampling path of USV on Bienong Co covering the base map of <u>the</u> MapWorld image. <u>Photos-Photographs were</u> taken by Xiaojun Yao on August 27, 2020.

3.2 Potential GLOF modeling

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Emmer and Vilímek (2014) and Haeberli et al. (2001) suggested that the assessment of glacial lake hazards should be conducted carried out based on a systematic and scientific analysis of lake types, moraine dam characteristics, outburst mechanisms, downstream processes in the river valley, and possible process cascades. The methodology used in this study refers to the GLOFs process chain proposed by Worni et al. (2014), which has been employed utilized by Somos-Valenzuela et al. (2016) and Lala et al. (2018) to study Imja Tsho in Nepal and Palcacocha and Huaraz lakes in Peru, respectively. And in In this study, we aim to depict potential GLOFs induced by ice avalanches originate originating from the Mulang Glacier (Fig. 2a and b) and landslides from the lateral moraine (Fig. 2c and d), and assess the potential inundation in the downstream region. The wave resulted resultant from material entering Bienong Co might overtop the moraine dam and initiate an erosive breaching process, releasing considerable amounts of water and debris into the downstream flow channel (Somos-Valenzuela et al., 2016).

Three models were used to simulated the GLOFs process chain,—: the RAMMS model was used for simulation of potential mass movement (Christen et al., 2010),—); the BASEMENT model was used to simulate the displacement wave in the lake,—i and the Heller-Hager model was used as a calibration for BASEMENT's results,—. The and BASEMENT model was also adopted to simulate the dynamic breaching process of the moraine dam, the propagation of the flood wave, and the inundation in downstream. In the next sections, simulation methods for ice avalanches and landslides, displacement waves in lakes, overtopping flow and erosion on the moraine dam, and downstream inundation were are described.

3.2.1 Triggers determination and simulation

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Ice avalanches are the most common GLOFs trigger in the Tibet in China (Yao et al., 204; Liu et al., 2019). Mass movements into lakes generate impulse waves that may produce overtopping flow scouring and eroding erosion of moraine dams, or disrupt the hydrostatic pressure-bearing capacity of moraine dams. Based on a survey of the environment surrounding Bienong Co, ice avalanches from the Mulang Glacier and two locations of lateral moraine landslides were selected as potential triggers for GLOFs. Wang et al., (2012) defined the volume of dangerous glaciers as the volume from the location of the abrupt changing slope to the glacier termini or the volume of the glacier snout where ice cracks are well developed. We adopted the latter, i.e., the crevasse-developed ice body of the Mulang Glacier shown in the MapWorld image with a surface area of 0.19 km² was selected as the potentially ice avalanche source of Bienong Co (Fig. 2a). For the convenience of subsequent description, we name it Scenario A. The elevation difference between the top of the dangerous ice body and the lake surface was measured to be about-approximately 155 - 208 m based on ALOS PALSAR DEM. We divided the dangerous ice body into three parts according to elevation range to simulate subsequence processes from ice avalanches of different magnitudes (ice avalanche 1, 2, and 3 in Fig. 2b,). Scenario A1 was defined as a low-magnitude trigger, and the ice body at an elevation below 4,844 m yields a release area of 0.05 km² with the maximum and average elevation differences of 99 m and 75.8 m from the lake surface, respectively. Scenario A2 was defined as a moderate-magnitude trigger, and the ice body at an elevation below 4,889 m yields a release area of 0.11 km² with the maximum and average elevation differences of 144 m and 102.7 m from the lake surface, respectively. Scenario A3 was defined as an extreme-magnitude trigger, and the total ice body of crevasse with an area of 0.19 km² was set as a release area, with the average elevation difference between glacier surface and lake surface of 131 m. In the above three cases, we assumed that the release depths of ice avalanches are the average elevation differences from the glacier surface to the lake surface, i.e., the glacier is supported by flat bedrock located at the height of the lake water table.

Lateral moraine landslides as a GLOFs trigger is are not common on the Tibetan Plateau, but the GLOF of Jinwu Co in 2020 was caused by a lateral moraine landslide (Liu et al., 2021; Zheng et al., 2021), therefore it and thus was taken as a trigger of the potential GLOF for Bienong Co. Two areas of lateral moraine within the slope range of 30° - 45° were selected as potential landslide sites, one of which is located on the left bank (in this study, the left and right sides are defined in a downstream-oriented manner) of Bienong Co, near the moraine dam with an area of 0.015 km², and we named it Scenario B (Fig. 2c). Another The second area is located on the right bank, near the mother glacier with an area of 0.024 km², and we named it Scenario C (Fig. 2d). Two The two sites are at different distances from the moraine dam, and we set three different release depths of 2 m (Scenario B1 and C1), 5 m (Scenario B2 and C2), and 10 m (Scenario B3 and C3) for each release area as low-, moderate-, and extreme-magnitude trigger, respectively. Therefore, a total of two different types, three different locations, and nine different magnitudes of materials were designed to enter the lake as potential triggers for GLOFs in this study. The above design fully considers the impact of triggers on Bienong Co under different magnitudes, and the results are used as the input for the subsequent disaster chain simulation.

In this study, ice avalanches and lateral moraine landslides of Bienong Co were modeled using the Avalanche module of the Rapid Mass Movement Simulation RAMMS model (Barteltet al., 2013), which has been successfully used for simulating triggers of GLOFs (Somos-Valenzuela et al., 2016; Lala et al., 2018; and Sattar et al., 2021). RAMMS adopts the Voellmy-

Salm finite volume method to solve the depth-averaged equations governing mass flow in two dimensions (Christen et al., 2010). Based on the basic inputs of DEM, the initial release area and depth, the calculation domain, and the friction parameters μ (the velocity-independent dry Coulomb) and ξ (velocity-dependent turbulent friction terms), the outputs of runout distances, flow height, and flow velocity can be calculated. And In addition, the time series of material entering the glacial lake can serve as the input condition for subsequent simulations. For this study case, the initial release area was determined by combining the MapWorld image of with athe spatial resolution of 0.5 m (https://www.tianditu.gov.cn/) and ALOS PALSAR DEM with a spatial resolution of 12.5 m (https://asf.alaska.edu/data-sets/derived-data-sets/alos-palsar-rtc/alos-palsar-radiometric-terrain-correction/). Values of μ =0.12, ξ =1,000 m s⁻², and ρ =1,000 kg m⁻³ for ice avalanche and ρ =2,000 kg m⁻³ for landslide were used, which agree with values used in previous GLOF-producing avalanche models (Schneider et al., 2014; Somos-Valenzuela et al., 2016).

3.2.2 Hydrodynamic wave simulation

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Processes following mass movement entering the lake, such as the generation and propagation of displacement waves, the overtopping flow and erosion on the moraine dam, and the inundation of downstream inundation, were modeled using the BASEMENT model v2.8.2 (Vetsch et al., 2017), developed by the Laboratory of Hydraulics, Glaciology and Hydrology (VAW), ETH Zurich. BASEMENT is both a hydrodynamic model and a sediment transport model, making it well suited to model much of the GLOF process chain (Worni et al., 2014). It solves the 2D shallow water equation (SWE) in combination with sediment transport equations, primarily the Shields parameters and the Meyer-Peter and Müller (MPM) equations (Shields, 1936; Vetsch et al., 2017). The simulation of hydrodynamic waves in the lake is performed using the 2D modeling of BASEMENT based on unstructured grids. The BASEmesh plugin for QGIS (QGIS Development Team, 2016) developed by BASEMENT greatly facilitates the generation of mesh. The lake bathymetry data were produced entered into DEM with a spatial resolution of 5 m using ArcGIS Pro software for reflecting to reflect the lake basin topography. The triangular irregular network (TIN) within the lake area was set to a maximum area of 500 m² to simulate the generation and propagation of hydrodynamic waves in the lake effectively and accurately. The input boundary conditions are time series of ice avalanches and landslides generated by the RAMMS model. In each time period, RAMMS calculates the total amount of sediment, and the inflow rate can be determined by calculating the difference of sediment entering the lake at the two time points. Pure rock landslides have been studied-investigated with densities ranging from 1,950 kg m⁻³ to 2,200 kg m⁻³ (Wang et al., 2017), and most ice-dominated avalanches have densities of about approximately 1000 kg m⁻³. In this study, the ice avalanche density was set as 1,000 kg m⁻³-, and the landslide density is-was set to as 2,000 kg m⁻³. Since BASEMENT only accepts water as an inflow, this difference due to density is considered by expanding the landslide material entry rate by a factor of two (namelyi.e., 1,000 kg m⁻³ of water is equivalent to 1,000 kg m⁻³ of ice avalanche volume, and only 500 kg m⁻³ of landslide material), which is the usual approach used in the simulation process (Byers et al., 2018 and 2020).

It was shown that the 2D SWE used by the BASEMENT model inherently leads to excessive wave attenuation. The Heller-Hager model (Heller et al., 2009) is a combination of analytical and empirical equations used to simulate impulse wave generation, propagation, and run-up from the movement of material entering a lake. Although the approach relies on simplifying measurements about lake geometry, it has been used to successfully simulate multiple real events and performs well in characterizing impulse waves within lakes, making it a simple, but useful, calibration measure for more complex hydrodynamic models (Somos-Valenzuela et al., 2016). BASEMENT simulated waves are usually considered more accurate when they are of the same order of magnitude as Heller-Hager waves; however, when they are not, the mass entry rate is varied by adjusting the inflow hydrograph and boundary width to match the amplitude of the Heller-Hager empirical model near the dam of the initial wave trajectory (Lala et al., 2018). The Heller-Hager model simulates waves in two cases: (a) with longitudinal impacting slide and confined transverse wave propagation; and (b) with the slide impacting across the reservoir and completely free radial wave propagation. In present study, ice avalanches belong to case (a), and landslides belongs to

case (b). Compared to case (a), the impulse wave (its amplitude and energy) in case (b) decreases more rapidly because it propagates over a larger area, and is accompanied by wave refraction and reflection.

3.2.3 Moraine dam erosion simulation

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The aA bnormally high lake outflow is sufficient to destroy the surface protection layer of the outlet streambed and trigger vertical dam erosion. After the initial cut, more lake water was able to flow out, followed by an increase in sediment transport rate and a gradual widening of the rift. In this study, the hydro-morphodynamic simulations of potential erosion-driven breach failures of Bienong Co was were carried out by the BASEMENT model, which uses the Meyer-Peter and Müller (MPM) equation to characterize sediment transport, and estimates suspended and nudged mass fluxes by calculating the shear stress in the flow through the modified Shields parameter (Vetsch et al., 2017). The overtopping flow leading to erosion of the moraine dam is generated by the wave amplitude of the BASEMENT model calibrated by the Heller-Hager model. In the previous step, we adjusted the wave amplitude near the moraine dam in the BASEMENT model to be close to (difference within 1 m) that calculated by the Heller-Hager model by modifying the width of the upstream boundary. ALOS PALSAR DEM is the base data for the mesh generation of the moraine dam with the maximum TIN area of 200 m². We set a crosssection along the crest of the moraine dam (Fig. 2g), where the moraine dam deformation, i.e., erosion, and the overtopping, as well as outflow discharges, were analyzed. The BASEMENT model provides both single-grain (MPM) and multi-grain (MPM-multi) algorithms to simulate material transport. The MPM-Multi-multi model simulates hiding and armoring processes that may lead to unrealistically low levels of erosion (Vetsch et al., 2017). The MPM model ignores these processes, however, it which can lead to an overestimation of erosion. In this study, we applied the MPM-multi model to simulate the bed-load transport of the moraine dam, which are is composed of materials with different grain sizes. The specific grain size distribution was not measured, #-but was instead taken from an inventory of glacial lakes in the Indian Himalayas (Worni et al., 2013) that had performed well in recreating previous GLOFs in Nepal (Byers et al., 2020). Despite uncertainty in the actual grain size distribution, a similar GLOF modeling study in the Barun Valley (Byers et_al., 2018) found little difference in simulated moraine erosion between the grain size distributions listed in Worni et al. (2013). The moraine dam of Bienong Co consists of a large grain cover with a thickness of about approximately 0.5 m at the top and fine grain underneath, which is clearly visible on the side walls of the channel scoured by water (Fig. 2e). We set up two soil layers in the BASEMENT model to represent the above situation. The largest particle size ($d_{50} = 180 \text{ mm}$) in the upper layer with a depth of 0.5 m, while and the grain size distribution of the lower layer that has with a depth of 71.5 m (considering the mean height of moraine dam of 72 m), is are consistent with Worni et al. (2013). Finally, a correction factor of 2.0 was used in the model to increase the rate of bed load transport. Values between 0.5 (low transport) and 1.7 (high transport) are generally realistic (Wong and Parker, 2006). whereas, while a value of 2.0 provides high sediment transport conditions (Somos-Valenzuela et al., 2016) to compensate for the lower erosion of the MPM-multi model.

3.2.4 Downstream impact analysis

The flow channel from Bienong Co to the convergence with Song Qu stretches ~53 km (Fig. 1d), along which 18 settlements, 13 bridges, and the Jiazhong Highway are distributed. In this study, the BASEMENT model was used to simulate Hydrodynamic the hydrodynamic behavior of potential GLOFs along the flow channel, and the hazard of floods was assessed by analyzing the inundation area, flow velocity, and flood arrival time at these settlements. The 2D model for an unsteady hydraulic simulation requires input of terrain data and boundary conditions. The terrain data was were represented by a 2D mesh covering the entire flow area, which was obtained from ALOS PALSAR DEM. The mesh was also generated by the BASEmesh plugin of QGIS software, and the individual cell area for the main flow channel and other regions were set to 500 m² and 5,000 m², respectively, considering the accuracy requirements of the simulation and the computational efficiency of the model. Friction of the river channel to a given flow is was determined by the Manning's roughness coefficient (Coon,

1998), which is dependent on the land use and land cover of the modeling river channel in the study area. In this study, the GLC10 LULC product (http://data.ess.tsinghua.edu.cn/fromglc10_2017v01.html) with a spatial resolution of 10 m was used to obtain the value of Manning's N in the flow channel. The upstream boundary is the outflow hydrograph from the moraine dam simulated by the BASEMENT model. And the downstream boundary is the water level-discharge relationship of the cross-section in the downstream boundary of the simulation area, it and was estimated by the critical depth method (Byers et al., 2018).

4 Results

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4.1 Morphology and lake volume estimation of Bienong Co

The basin morphology of Bienong Co was modeled based on the TIN grid created by the field depth data (Fig. 3). Apparently, this lake has a relatively flat basin bottom, and both deep-both flanks are deep (Fig. 4). Similar to most glacial lakes (Yao et al., 2012; Zhou et al., 2020), the slope of the lake shores near the glacier is steeper than that near the moraine dam. The water depth profile from the moraine dam to the mother glacier shows that the depth of the lake reaches a maximum of ~181 m at about approximately 1,000 m from the moraine dam, corresponding to the a slope of 11.3°. The depth keeps remains stable at a distance of 1,000 m to 1,500 m from the moraine dam, and the distance from the Mulang Glacier to the deepest point of the lake is 600 m with the a slope of 16.5°. A depth profile facing the moraine dam from the left bank to the right bank shows that the left side is steeper than the right side. The glacial lake reaches its deepest point at 200 m from the left shore with the a slope of 43.4°, then maintains remains flat to 430 m, and the distance between the bottom and right shore is 273 m with the a slope of 32°. The volume of Bienong Co, calculated using the surface elevation and the lake bed derived from the TIN grid, was about approximately 102.3×10⁶ m³ in 2020, which is a generally accurate estimate of the magnitude of this moraine-dammed lake.

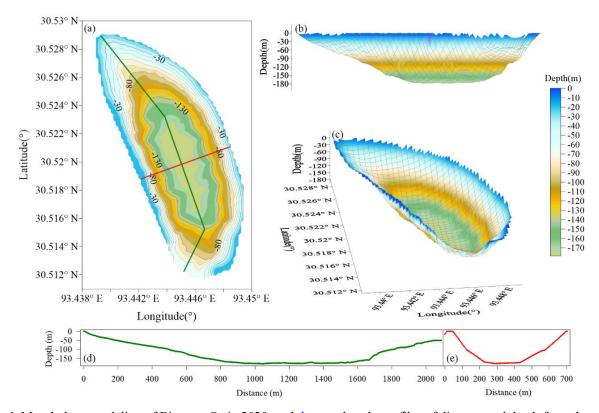


Figure 4. Morphology modeling of Bienong Co in 2020, and the equal-scale profiles of distance and depth from the moraine dam to the Mulang Glacier (green line) and from the left shore to right shore (red line).

4.2 Potential GLOFs modeling

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4.2.1 Ice avalanches and lateral moraine landslides

As calculated by RAMMS, the volume of ice avalanches entering Bienong Co for Scenarios A1, A2, and A3 are 3.8 × 10⁶ m³, 4.9 × 10⁶ m³, and 5.8 × 10⁶ m³ (, respectively (Fig. 5a). Most of the materials enter the lake within about approximately 120 s. Based on the area of ~1.15 km² in 2021, the above three scenarios could result in a rise of about approximately 3.3 m, 4.2 m, and 5.1 m in the lake surface, respectively. Material volumes entering the lake by both landslides are much smaller than that those of the ice avalanches (Fig. 5b and c). Scenarios B1, B2, and B3 and C1, C2, and C3 dump 0.03 × 10⁶ m³, 0.09 × 10⁶ m³, and 0.17 × 10⁶ m³, and 0.06 × 10⁶ m³, 0.15 × 10⁶ m³, and 0.30 × 10⁶ m³ of material into the lake, respectively. The time for materials entering the lake is less than in Scenario A, with Scenarios B1, B2, and B3/2/3 b being completed in about approximately 10 s, and Scenarios C1, C2/2, and C3/3 in about approximately 15 s.

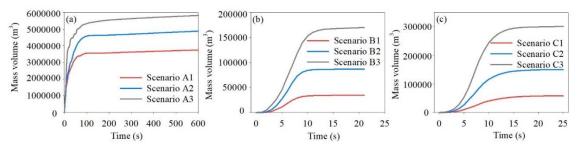


Figure 5. Volume of material entering Bienong Co for different (a) ice avalanches scenarios and (b) and (c) landslide scenarios.

The impact area caused by material entering the lake differs for different scenarios. The impact zones caused by Scenarios A1, A2, and A3 are 0.27 km², 0.31 km²-, and 0.38 km², respectively, with horizontal distances of 549 m, 629 m, and 752 m from the upper boundary, respectively (Fig. 6). In contrast, each of these three scenarios for Scenarios B and C result in a relatively small impact zone, with Scenario C3 being the largest of at 0.14 km² and Scenario B1 being the smallest of at 0.04 km². Scenarios A1, A2, and A3 produce maximum flow heights of 39.5 m, 46.2 m, and 53.5 m, and average flow heights of 12.2 m, 14.6 m, and 12.3 m in the impact area, respectively. The maximum flow height range for Scenarios B1/2/3, B2, and B3 is 6.8 - 14.6 m, and the average flow height range is 1.8 - 3.5 m. The maximum and average flow height ranges for Scenarios C1/2/3C1, C2, and C3 are 5.7 - 29.2 m and 2.0 - 4.7 m, respectively (Fig. 6). The maximum flow velocities for Scenarios A1, A2, and A3 are 34.9 m/s, 43.1 m/s, and 51.4 m/s, with the average flow velocities of 11.1 m/s, 12.3 m/s, and 16.8 m/s, respectively. The maximum and average flow velocities for Scenarios B1, B2, and B3 and C1, C2, and C3 are in the range of 21.3 - 33.6 m/s and 8.5 - 14.2 m/s, respectively (Fig. 6).

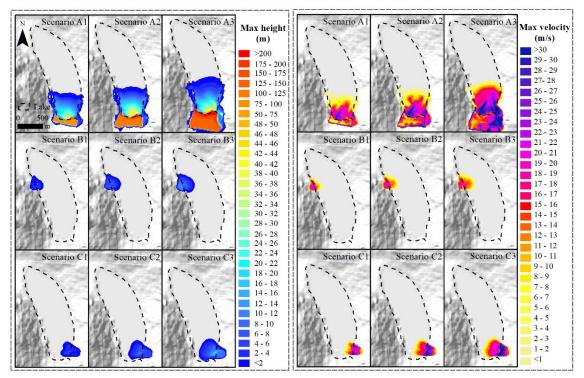


Figure 6. Maximum flow height (left) and maximum flow velocity (right) for different ice avalanches and landslides scenarios.

4.2.2 Generation and propagation of displacement waves

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By counting material volumes of ice avalanches and landslides entering Bienong Co at different time periods based on the RAMMS model, we derived the time series of the material_entering rate, as shown in Fig. 7. Compared to Scenarios A2 and A3, Scenario A1 has the highest peak flow rate of 439,952.57 m³/s, but it decreases rapidly after reaching the peak within two seconds2 s of the ice avalanche, i.e., the ice avalanche occurs in a moment. Scenarios A2 and A3 show_exhibit obvious fluctuations in the process of ice avalanches into the lake, with sub-peaks in both scenarios that are comparable to the first peak, after which the flow rates still have possess strong fluctuations. The peak and sub-peak flow rate of Scenario A2 and A3 are 263,922 m³/s and 238,086 m³/s and 386,359 m³/s and 373,449 m³/s, respectively, both occurring at the 2nd and 8th seconds of the ice avalanche, respectively. This is because the ice avalanches of Scenarios A2 and A3 are further away from the lake than Scenario A1, and total volumes of ice avalanches are larger than Scenario A1, so and thus they theyentry into the lake undergo a more complex process when they enter the lake. The process of landslide material entering the lake is simpler in Scenarios B and C. The peak flows increase sequentially from Scenarios B1 and fC1, B2 and fC2, to B3 and fC3, with peak values of 50,849 m³/s and 92,529 m³/s for Scenarios B3 and C3, respectively. The peak flows for the six scenarios of Scenarios B and C occur in the range of 6th 8th seconds6 - 8 s (Fig. 7).

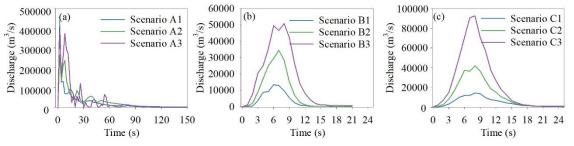


Figure 7. Time series of material entry into the lake for different ice avalanches and landslide scenarios.

The time-volume relationships of materials entering a lake have important effects on the generation and propagation of

displacement waves in the lake. Ice avalanches scenarios (A1, A2, and A3) have a much greater impact on Bienong Co than the two landslide scenarios (B1, B2, B3, C1, C2, and C3) because the assumed release volume of ice avalanches is much greater than that of landslides. The wave height near the moraine dam is the result of the BASEEMENT model calibrated by the Heller-Hager model. By adjusting the inflow boundary's width, we made the BASEMENT model produce wave amplitudes near the dam with a difference smaller than 1 m of those calculated by the Heller-Hager model, which is important for subsequent simulations, although the maximum wave amplitude in the lake is exaggerated.

In Scenario A, displacement waves propagate straight from the glacier to the moraine dam, and arrive at the vicinity of the moraine dam at about approximately 70 s. Scenarios A1, A2, and A3 produce the highest wave amplitudes in the lake of 35.2 m, 39.0 m, and 66.4 m, respectively, and the wave amplitudes near the moraine dam of 17.1 m (72 s), 20.2 m (74 s), and 25.2 m (72 s), respectively (Fig-.8). Compared with Scenario A, the wave amplitudes of Scenarios B and C are much markedly lower. In Scenario B, a landslide occurs at the left shore of Bienong Co near the moraine dam (Fig. 2c). Displacement waves first propagate to the opposite shore along the in a perpendicular direction to the inflow boundary, and then they propagate to the moraine dam with the expansion. The maximum wave amplitudes in Bienong Co of Scenarios B1, B2, and B3 are 6.5 m, 14.1 m, and 18.0 m, respectively, and the wave amplitudes near the moraine dam are 1.2 m, 3.0 m, and 5.3 m, respectively (Fig. 8). The landslide in Scenario C occurs on the right bank of Bienong Co near the glacier, in the same manner as that in as Scenario B, is that in which waves propagate to the opposite bank first after materials entering the lake, with the maximum wave amplitudes of 4.8 m, 9.6 m, and 24.7 m for Scenarios C1, C2, and C3. Unlike Scenario B, displacement waves in Scenario C cross the entire lake, reaching the moraine dam with wave amplitudes of 0.6 m, 2.2 m, and 4.9 m near the moraine dam, respectively (Fig. 8). Therefore, although the landslide volume of Scenario C is larger than that of Scenario B, wave amplitudes near the moraine dam are smaller than those of Scenario B.

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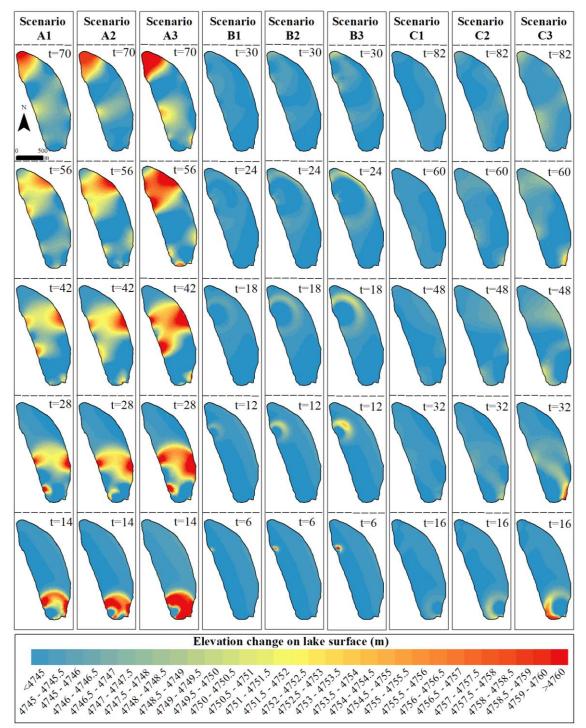


Figure 8. Propagation of displacement waves in the lake for different ice avalanches and landslide scenarioss.

4.2.3 Overtopping flow and erosion on the moraine dam

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Since the freeboard of the moraine dam is 0 m, the occurrence of overtopping flow is inevitable in all scenarios, but there are differences in magnitude. In Scenarios A1, A2, and A3, peak discharges at breaches of the moraine dam are 4,996 m³/s, 7,817 m³/s, and 13,078 m³/s, corresponding to a total released volume of 24.1×10⁶ m³, 25.3×10⁶ m³-, and 26.4×10⁶ m, respectively (Fig. 9). Discharges at the moraine dam stabilize after ice avalanches entering Bienong Co about at approximately 18,000 s, 10,800 s, and 7,200 s, respectively. Therefore, the erosion of the moraine dam and the total volume of water lost in the lake were counted based on the above time points. The moraine dam is eroded by huge enormous discharge output in Scenarios A1, A2, and A3, forming breaches. Due to the similar volume of released water, the depth of the breach is slightly different for Scenarios A1, A2, and A3, they—which are 19.0 m, 19.1 m, and 19.3 m, respectively (Fig. 10). While-Moreover, the peak

discharge is much quite different for the three scenarios, resulting in different breach widths of 295.0 m, 339.4 m, and 368.5 m, respectively. Scenarios B1, B2, and B3 and C1, C2, and C3 resulted in overtopping flows of 0.6×10^6 m³, 1×10^6 m³ a, and 2.6×10^6 m³, as well as and 0.1×10^6 m³, 0.9×10^6 m³, and 0.1×10^6 m³, respectively, in which, only Scenarios B3 and C3 cause erosion of the moraine dam and form a breach. Discharges at the breach become stable since beginning at 18,000 s following landslide material entry into the lake in Scenarios B3 and C3, with breach depths of 0.5 m and 0.5 m, respectively and breach widths are 0.5 m and 0.5 m and

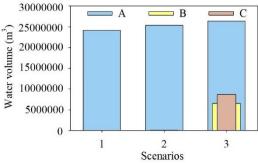


Figure 9. Discharge of water bodies in glacial lakes under different scenarios.

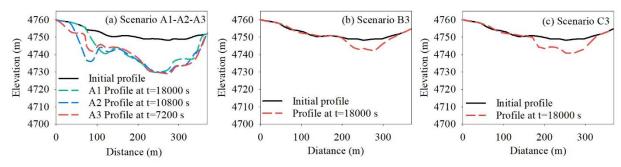


Figure 10. Erosion of the moraine dams under different conditions at the eross-cross-section in Fig. 2g.

4.2.4 GLOFs impact in the downstream region

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The hydraulic behavior of GLOFs in the flow channel that from the immediately downstream of the moraine dam to the convergence with Song Qu with a distance of ~53 km was simulated using the BASEMENT model. Due to the lack of reliable data on small baseflows in the flow channel, they were neglected in the simulation. Considering the propagation of floods in different scenarios, we assessed the propagation of GLOF in the downstream channel within 20 hours from ice avalanche and landslide materials entry into the lake. Peak discharges at the breach outlet of Scenarios A1, A2, and A3 all occur about approximately 600 s after the ice avalanche material enters the lake, and they are 4,996 m³/s, 7,817 m³/s, and 13,078 m³/s, respectively, based on which, floods all pass through 18 settlements in the downstream river in 20 hours, with the inundation areas of 7.6 km², 8.0 km², and 8.5 km², as well as average water depths of 8.4 m, 9.1 m, and 10.0 m, respectively (Fig. 11). The Scenarios B1 and C1 only have a small amount of overtopping flow from the lake (peak discharges of 106 m³/s (after 40 s) and 12 m³/s (after 50 s)), and fail to generate runoff downstream of the dam. Scenarios B2 and C2 produce very limited overtopping flow with peak discharges of 177 m³/s (after 240 s) and 186 m³/s (after 480 s), respectively, and outflows remain only within approximately 1 km downstream of the dam. Peak discharges at the breach outlet of Scenarios B3 and C3 are 504 m³/s (after 240 s) and 733 m³/s (after 480 s), yielding inundation areas of 1.7 km² and 2.2 km² with average water depths of 1.9 m and 2.4 m in the downstream region, respectively. Both GLOFs pass through the first eight settlements, but the flood of Scenario C3 flows farther (Fig. 11). Among the nine scenarios we assumed that we considered, only Scenarios of A1, A2, A3, B3, and C3 caused GLOFs propagation in the downstream region with a far distance, in which Scenario A3 had the largest flood magnitude, and Scenario B3 had the smallest <u>flood</u> magnitude.

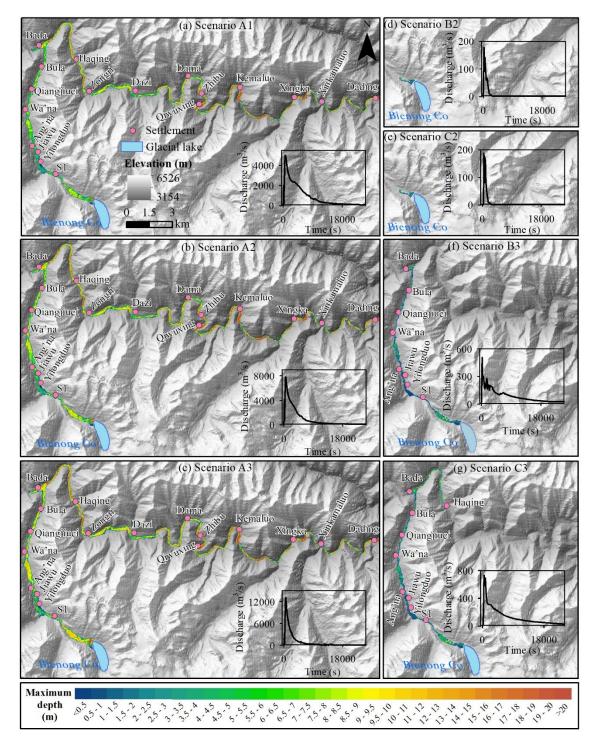


Figure 11. Propagation of flood water downstream and the time series of discharge at the breach outlet (inset) for different scenarios.

GLOFs of different magnitudes pose different potential hazards to each settlement along the flow channel. Scenario A3 produces the most severe threat of GLOF to the downstream region. Six settlements, including Ang'na, Wa'na, Haqing, Kemaluo, Xinka, and Dading, will be completely submerged by flooding. Kemaluo village, located 37.9 km downstream of Bienong Co, will experience the relatively largest maximum flow depth of 19.8 m, and the village of Ang'na, having a distance of 6.0 km from Bienong Co, will experience the relatively smallest maximum flow depth of 6.1 m. Wa'na village is the most affected of all of the villages by GLOF due to the most flooded houses. Eight settlements of Scenario S1, Qiangjiuci, Bula, Bada, Dama, Zhibu, Qiwuxing, Xingka, and Xinkamaluo, will be partially flooded. The maximum flow depth of 11.0 m in Bada village is the largest, and that of 7.2 m in both Dama and Zhibu villages is the smallest. Four settlements, Yilongduo, Jiawu, Zongri, and Dazi are spared from floods, in which, Yilongduo may be slightly affected, while Dazi is the safest village

owing due to its far distance from the river. Flooding in Scenario A2 has a relatively small impact on downstream villages compared to that of Scenario A3, showing the reduced extent of inundation and flow depth. Ang'na and Haqing villages have reduced flood ranges. However, villages Wa'na, Kemaluo, Xinka, and Dading will still be completely flooded, but the maximum flow depth is reduced from 16.5 m, 19.8 m, 12.5 m, and 17.5 m, to 13.6 m, 19.3 m, 12.0 m, and 16.6 m, respectively. For the nine villages that are partially affected by Scenario A3, they are still affected by flooding of Scenario A2, except for Dama village, but the impact of flooding has a weakenis diminished. Scenario A1 differs from Scenario A3 in that Dama and Xingkamaluo villages have been able to bewere spared from flooding, while other villages have experienced significant reductions in flood extent and inundation depth. The floods of Scenarios B3 and C3 have significantly less impact in the downstream than the above three scenarios. Only Wa'na, Qiangjiuci, and Bula villages will be partially affected, with the maximum flow depth of 3.1 m, 1.9 m, and 2.0 m in Scenarios B3 and 4.0 m, 2.4 m, and 2.7 m in Scenarios C3, respectively (Fig. 12). The total areas of houses, courtyards, and farmlands (around settlement) affected by Scenarios A1, A2, A3, B3, and C3 were estimated to be 23,984 m2, 32,076 m2, 41,038 m2, 3,820 m2, and 3,918 m2, respectively. In Scenarios A1, A2, A3, all 13 bridges and road with a length of approximately 35 km are within the flood zones, and in Scenarios B3 and C3, there are four bridges as well as road with a length of approximately 3.6 km and 6.7 km within the flood zones. Here we only assess the potential impact of floods on these man-made structures, but the concrete magnitude of the impact is beyond the scope of this study.

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The peak discharge and velocity of GLOFs at in these villages undergo experience a gradually decreasing process, while the arrival time of peak discharges is prolonged, favoring the evacuation of residents in the downstream area. Peak discharges in Scenario S1, Yilongduo, Jiawu, and Ang'na villages, are similar for each scenario, ~4,000 m³/s of Scenario A1, ~6,000 m³/s of Scenario A2, and ~10,000 m³/s of Scenario A3. Wa'na, Qiangjiuci, and Bula villages have the similar peak discharges, which are ~3,800 m³/s, ~5,000 m³/s, and ~8,000 m³/s for Scenarios A1, A2, and A3, respectively. Since Beginning with Bula village, peak discharges of each scenario decrease significantly towards the downstream. Taking Scenario A3 as an example, at Bula village, peak discharge is 7,512 m³/s, to at Haqing village, it becomes smaller than 6,000 m³/s, to at Dama village, it drops below 4,000 m³/s, to at Qiwuxing village it drops below 3,000 m³/s, and at Xinka village it decreases to below 1,000 m³/s (Fig. 13). The flood flow velocity varies dramatically, with Scenarios A1, A2, and A3 corresponding to maximum velocities of 8.9 m/s, 12.2 m/s, and 14.9 m/s, respectively, at in village Scenario S1. To At Dading village, the maximum flow velocity of GLOFs is about approximately 2 m/s.

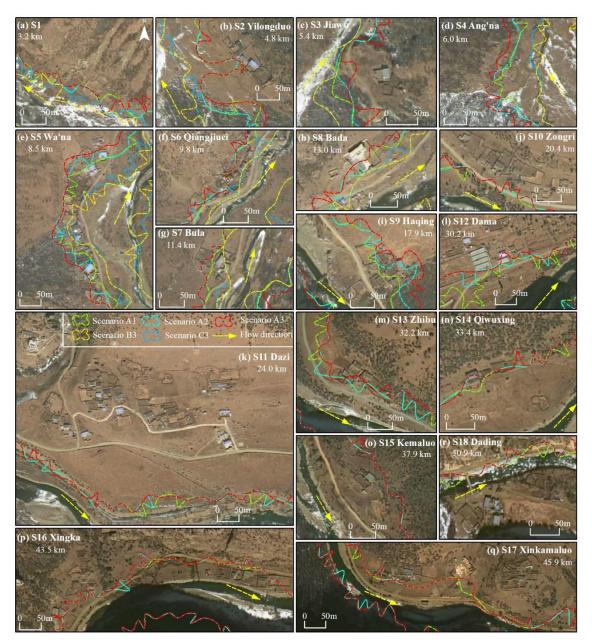


Figure 12. The potential threat of GLOFs to settlements and roads in the downstream under different ice avalanches and landslide scenarios (the background is a MapWorld image).

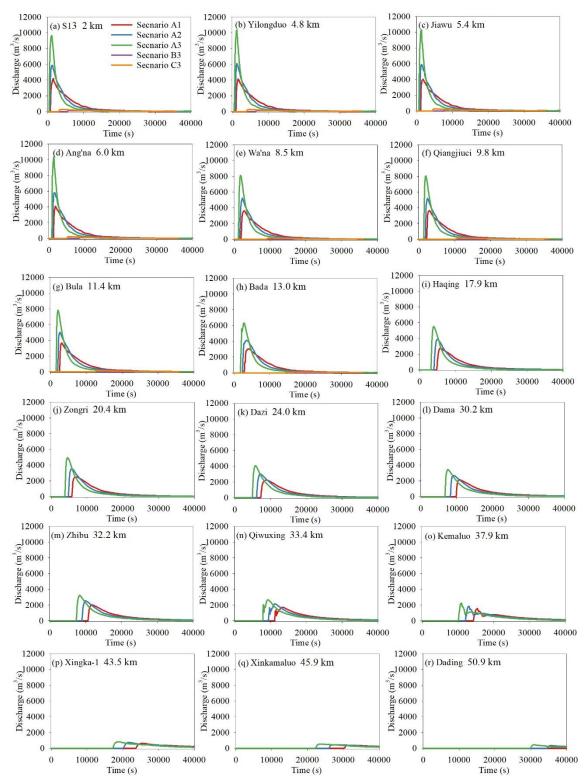


Figure 13. Time series of discharge at different settlements along the flow channel (locations in Fig. 1) of different scenarios.

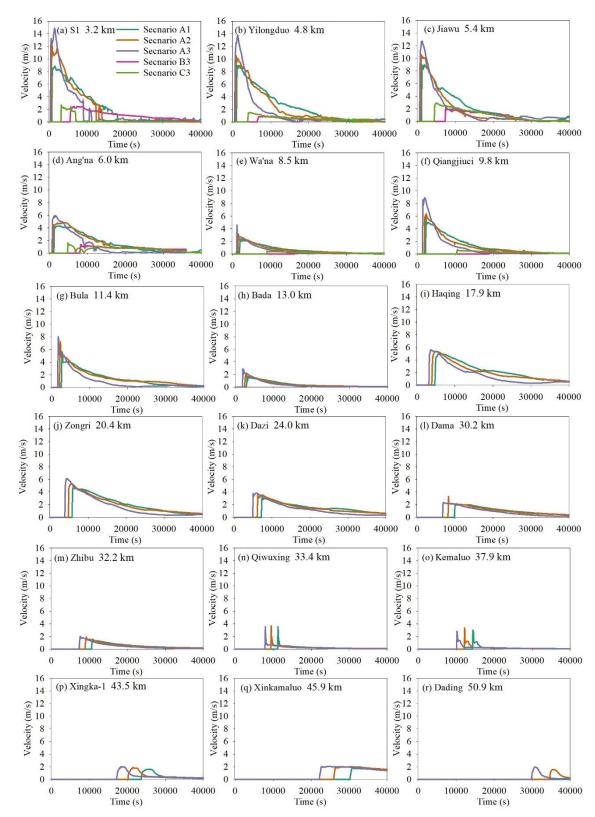


Figure 14. Time series of velocity at different settlements along the flow channel (locations in Fig.1) of different scenarios.

5 Discussion

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5.1 Lake volume of Bienong Co

Based on the accurate bathymetric results of the USV, we obtained found that the maximum and depth average of Bienong Co were 181 m and 85.4 m, respectively, with the lake volume of 102.3 × 10⁶ m³ in August 2020. Considering the rarity of bathymetric data, but the frequent occurrence of GLOFs, in the region, we try attempted to explore obtain more information about glacial lakes in the region by using bathymetry and lake volume of Bienong Co. First, relationships with significant correlations for area-volume, area-depth, and depth-volume of Bienong Co were established (Fig. 15), and it is hoped that this the valuable information is pinned on the hope that could provide a valuable data reference for future studies of Bienong Co and other glacial lakes in the region. Then, we compared the depth and lake volume information of Bienong Co with other glacial lakes that have been measured. At present, there are few glacial lakes with measured bathymetry on the Tibetan Plateau, and they are mainly concentrated in the Himalayas of Nepal and the Poiqu basin-Basin of Tibet, China. Longbasaba is an end moraine-dammed glacial lake located at the northern slope of the Himalayas, which has had an area of 1.22 ± 0.02 km² in 2009, with average and maximum depths of 48 ± 2 m and 102 ± 2 m, respectively, having and a volume of 64×10^6 m³ (Yao et al., 2012). Although the area of Longbasaba is about approximately 6% larger than that of Bienong Co, the lake volume is only 60% of that of Bienong Co. This is an example This example shows that showing that a glacial lake in the temperate maritime glaciation zone is significantly larger in volume than a similarly_sized glacial lake in the continental glaciation zone. However, due to the lack of measured bathymetric data of glacial lakes in the continental glaciation zone, no more comparisons can be made. We compared the depth and lake volume of Bienong Co with other glacial lakes in the temperatemaritime glaciation zone. Comparison between and can be achieved. The area of Lugge glacial lake in Butan was about approximately 1.17 km² in 2004, which is slightly larger than that of Bienong Co, but its average depth and maximum depth were 49.8 m and 126 m. respectively, with a lake volume of 58×106 m³ (Yamada, 2004), which was smaller than the corresponding value of Bienong Co. At the time of bathymetry, both South Lhonak lake in India and Imja glacial lake in Nepal had an area of about approximately 1.3 km², which is about approximately 13% larger than that of Bienong Co, but both lakes have 64% and 76% of Bienong Co's Co's volume, respectively (Sharma et al., 2018; Haritashya et al., 2018). Areas of Raphsthren glacial lake in Buhtan and Tsho Rolpa glacial lake in Nepal were 1.4 km² and 1.5 km² when bathymetries were carried out, which are 22% and 30% larger than that of Bienong Co, but their lake volume are-is 65% and 84% of that of Bienong Co, respectively (Geological survey-Survey of India, 1995; ICIMOD, 2011). The area of Lower Barun glacial lake in Nepal was 1.8 km², which is 57% larger than that of Bienong Co, but the lake volume was 112×10⁶ m³, which is only 9% larger than that of Bienong Co (Haritashya et al., 2018), showing that Bienong Co is relatively deeper and has a larger storage.

Additionally, due to the scarcity of glacial lake bathymetry data and its-their importance for GLOF hazards, scholars have proposed relationships to estimate volumes of glacial lakes through area, width, and length (O'Connor et al., 2001; Huggel et al., 2002; Sakai, 2012; Wang et al., 2012a; Yao er al., 2012, Cook and Quincey, 2015; Qi et al., 2022). We estimate the lake volume of Bienong Co using published equations based on glacial lakes on the Tibetan Plateau, and the results show that the eight published volume-area/width-length relationships all underestimate the volume of Bienong Co to varying degrees. It can be inferred that Bienong Co is the relative deepest glacial lake among these on the Tibetan Plateau that currently have been measured. Whether this is unique to Bienong Co or a common feature of glacial lakes in the region is not yet known, as few glacial lakes in this region has-have field bathymetry. Future bathymetry is necessary for more typical glacial lakes in the region.

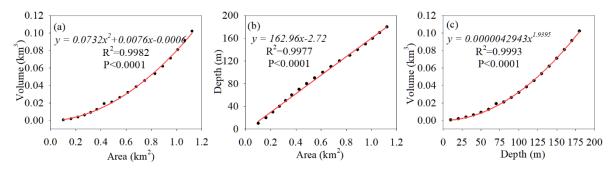


Figure 15. Fitting relationship of (a) area and volume, (b) area and depth, and (c) depth and volume of Bienong Co.

Table 1. Calculated volumes of Bienong Co based on published volume-area relationships for glacial lakes in the Tibetan Plateau.

No	Source		Relationships	Calculated	Error (%)
				Volume volume	
1	Qi et al. <u>(</u> -2022 <u>)</u>	(1)	$V{=}0.04066A^{1.184}\text{-}0.003207w_{mx}/l_{mx}$	$46.9 \times 10^6 \mathrm{m}^3$	-54%
2		(2)	$V=0.0126A^2+0.0056A+0.0132$	$36.3 \times 10^6 \text{ m}^3$	-65%
3	Wang et al. (,		$V=0.0354A^{1.3724}$	$42.9\times10^6~m^3$	-58%
	2012)				
4	Sakai <u>(</u> ,-2012 <u>)</u>		$V=0.04324A^{1.5307}$	$53.6 \times 10^6 \text{m}^3$	-48%
5	Yao et al. (,-2012)		$V=0.0493A^{0.9304}$	$56.1 \times 10^6 \text{m}^3$	-45%
6	Fujita et al. (-,		$V = 0.055A^{1.25}$	$65.5 \times 10^6 \text{ m}^3$	-36%
	2013)				
7	Khanal et al. (,		$V = 0.0578A^{1.5}$	$71.3 \times 10^6 \text{m}^3$	-30%
	2015)				
8	Zhou et al. (,-2020)		$V=0.0717 w_{mx}^2 l_{mx}$	$70.3\times10^6~m^3$	-31%

Note: Error = ($\frac{\text{Volume-volume}}{\text{volume}}$ of empirical formulas – $\frac{\text{athymetrically-bathymetrically-derived volume}}{\text{bathymetrically-derived volume}} / <math>\frac{\text{Bathymetrically-derived volume}}{\text{bathymetrically-derived volume}}$

5.2 Limitations and uncertainties future research

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Triggers is are the beginning of the simulated GLOFs process chain in this study, and we only consider ice avalanche and landslide scenarios, instead of other factors, such as increased glacial meltwater and heavy precipitation. The magnitude, location, and probability of ice avalanches and landslides are constitute the largest sources of uncertainty in this study. Ice avalanches is are the trigger for over 70% of GLOFs on the Tibetan Plateau, but there is no reliable reference of the for the magnitude, including the release area and depth, of previous ice avalanche events. Ice avalanches in this study come from the mother glacier tongue, where the slope is relatively steep and the fissures are well-developed. We simulated three different-magnitude ice avalanches, and each scenario assumes that the ice body breaks off in the vertical direction until to it reaches the lake surface, which is unrealistic and may overestimate the volume of the ice avalanche. The RAMMS model can estimate the possible release volume based on the input DEM data and the release area, as well as the release depth, which are 5×10^6 m³, 13.1×10^6 m³-, and 41.3×10^6 m³ for Scenarios A1, A2, and A3, respectively. However, simulations show that about approximately 76%, 37%, and 14% of the estimated release volume enter the lake in Scenarios A1, A2, and A3, respectively. The simulation duration is set to 600 s to ensure the integrity of the ice avalanche process, and most of the ice avalanche entering the lake and the estimated release volume is mainly influenced determined by the slope between the ice body and the entering the lake and the estimated release volume is mainly influenced determined by the slope between the ice body and the

lake and the distance from the lake. The gentler slope and far distance from the lake of the ice body in Scenarios A2 and A3 result in fewer ice avalanches entering the glacial lake, and affect the process of ice avalanche material entering the lake, e.g., Scenarios A2 and A3 have stronger fluctuations in the ice avalanche process than Scenario A1. In addition, we also consider landslides as a trigger given the failure of Jinwu Co in 2020. Two release areas were selected by referring to the slope and location of Jinwu Co's landslide. H, however, the release depth has no quantified reference data and we assumed three release depths of 2 m, 5 m, and 10 m for each release area to simulate the consequences resulting from as many scenarios as possible.

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A reliable simulation of potential future disaster events using scientific methods can assist people understand the possible risks and raise prevention awareness. However, the accurate ice avalanche or landslide prediction is generally difficult due to limited geological information and details of triggering mechanisms such as extreme rainfall event. In this study, the RAMMS model was used to estimate the consequences of potential ice avalanche and landslide events, in which DEM resolution as well as the dry-Coulomb type friction μ, and the viscous-turbulent friction ξ all have influences on the modelling results (Bezak et al., 2019). The accuracy and resolution of DEM data is crucial for all model calculations and it should stand in a reasonable relation to the avalanche size (Schneider et al., 2010). The DEM accuracy issue in glacial environments is mainly due to topographic changes between the DEM acquisition time and the avalanche event and the DEM resolution is concerned with the accurate reflection of the process of an ice avalanche event. The ALOS PALSAR DEM product used in this study was released globally in October 2014, the volumes of future ice avalanches will almost certainly be smaller than the volumes formulated in this study due to glacier melting caused by climate warming, whereas the landslide volumes should not change much. The resolution of the ALOS PALSAR DEM is 12.5 m, which can generally reflect the intensity and pathway of the ice avalanche and landslide events simulated in this study. However, it is undeniable that the accuracy of the DEM can greatly affect the topography and the avalanche and landslide pathways, and the DEM with lower resolution can lead to an overestimation of sediment area and an underestimation of sediment thickness (Cesca and D'Agostino, 2008). Mikoš and Bezak (2021) suggested that the ice avalanche or landslide magnitude slightly decreases and increases with increasing friction parameters μ and ξ, while the correlation is not strong. Schneider et al. (2014) found that higher μ and ξ combinations lead to higher peak velocities, faster stopping mechanisms, and hence shorter process durations. The value of μ and ξ covered wide ranges in the past applications (Mikoš and Bezak, 2021), and they were usually calibrated by actual events. In this study, they were adopted as 0.12 and 1,000 m s-2 which were used in the avalanche into Lake 513 (Schneider et al., 2014).

The BASEMENT model was applied to simulate the subsequent chains of GLOF process following ice avalanches and landslides. Much of the work in impulse wave generation, propagation and run-up have been focused on empirical models that replicate wave characteristics based on laboratory observations (Heller and Hager, 2010). Numerical simulations have been limited to simplified 2D SWE simulations (Ghozlani et al., 2013), however, the 2D SWE is not adequate to simulate waves generated by avalanches because of the large energy dissipation due to significant vertical accelerations (Lala et al., 2018). Therefore, empirical models are often used to calibrate the numerical simulations, namely the Heller-Hager model was used to calibrate the simulation of the BASEMENT model, which has been adopted in past studies (Byers et al., 2018; Lala et al., 2018). Nevertheless, the numerous parameters required by the Heller-Hager model are only the simple quantifications about the geometry of the lake, and potential uncertainties still exist. Also worth mentioning is the limitation that lake hydrodynamic model can only accept inflow in the form of water volume but not the material itself, such as moraine material, ice, snow, and the combination (Kafle et al., 2016). Generally, simulations are calibrated by controlling the height and depth of the release area and converting the density between the material and water to influence the flow height and flow velocity in the model as avalanches enter a lake. However, the energy dissipated in the form of water does not same as the true avalanche mixture, and the model can't present the mixing of the avalanche fluid with a lake (Somos-Valenzuela et al., 2016). Furthermore, the maximum area of TIN representing a lake also has influence on the wave amplitude, smaller areas lead to finer values, which have little influence on the absolute value of the wave amplitude, but the calculation time will increase significantly. In terms of the simulation of the moraine dam's erosions, the grain size distribution of the moraine dam of Bienong Co is an important parameter, but it is not obtained in this study. The simulations were performed by referencing an inventory of glacial lakes in the Indian Himalayas (Worni et al., 2013), which have been validated to be generally reliable, but errors in Bienong Co are inevitable.

The ALOS PALSAR DEM with a spatial resolution of 12.5 m has been widely used in studies of cryospheric changes and disasters. In this study, it was pre-processed to fill sinks, but there is still the phenomenon of flood water accumulating in deep puddles, especially in the relatively narrow valley. We manually smoothed several large bumps according to the elevation of the upstream and downstream. However, there are still some smaller bumps that converge the flow to a section of the flow channel, mainly in the downstream area. Therefore, the flooding situation in Qiwuxing, Kemaluo, Xingka and Dading villages might be overestimated, especially in the first two villages because they are relatively far away from the river, while the latter two villages are still very likely to be threatened by flooding due to their close distance to the river. For more accurate simulation of in-channel floods, the resolution of the ALOS PALSAR DEM is clearly insufficient. Therefore, more precise topographic information, such as DEM data generated using panchromatic stereo images with resolutions better than 0.8 m obtained by the Gaofen-7 satellite and UAV-derived DEM products with low-cost are prospective. The frictional resistance is derived from the GLC10 LULC data of the downstream channel of Bienong Co, which basically fits the reality and has litter error of the simulations. GLOF flow processes can be very complex (Zhou et al., 2019), and flows can transform from clear water flow, to hyperconcentrated flow, to a debris flow, and these rheological transformations can occur in both space and time as the flow evolves (Worni et al., 2014). In this study, we do not consider the effects of sediment on flow rheology, and the erosion and deposition of sediment along the flow path.

Emmer et al. (2022) divided the research evolution of simulations of GLOF1 process chains into three stages, and this study belongs to the second stage, i.e., applying tailored physically based simulation tools for each component of the process chain and coupling them at the process boundaries. The third stage is the two-phase (Pudasaini, 2012) and three-phase (Pudasaini and Mergili, 2019) mass flow models and related simulation tools (Mergili et al., 2017; Mergili and Pudasaini, 2021) and the integrated simulations of the entire GLOF process chain in one single simulation step. The main advantage of the methods in the second stage is the simplicity and operability, with the convenient GUI interface of software in different links. Models for different links have been matured and widely applied in the corresponding fields with reliable performance and accessibility of the required parameters. However, the third stage is undoubtedly the focus of future research, with a more detailed, in-depth, and improved study of the whole GLOF flooding process and reduced uncertainty in the coupling between different models. This will certainly involve more detailed parameters, increasing the difficulty of the simulation.

Secondly, the grain size distribution of the moraine dam of Bienong Co was not obtained in this study, and the simulation was performed by referencing an inventory of glacial lakes in the Indian Himalayas. Although the data used have been validated to be generally reliably reliably general, the grain size distribution of the moraine dam of Bienong Co itself would be more useful for an accurate simulation of the moraine dam's erosion.

Finally, DEM data are the most important basic data affecting the downstream propagation of GLOFs in this study. ALOS PALSAR DEM data with a spatial resolution of 12.5 m have been widely used in studies related to cryospheric changes and disasters. In this study, the DEM was pre-processed to fill sinks, but there was still the phenomenon of flood water being piled up in some accumulating in deep puddles during the simulation, i.e., there were errors in the DEM data, especially in the relatively narrow valley. We have manually smoothed several large bumps according to the elevation of the upstream and downstream. However, there are still some smaller bumps that converge the flow to a section of the flow channel, mainly in the downstream area. Therefore, the flooding situation in Qiwuxing, Kemaluo, Xingka, and Dading villages might be overestimated, especially in the first two villages because they are relatively far away from the river, while the latter two villages are still very likely to be threatened by flooding due to a their close distance to the river. More accurate flood hazard simulations in the future could relay on yield more precise topographic information, such as DEM data generated using panchromatic stereo images with resolutions better than 0.8 m carried obtained by the Gaofen 7 satellite.

6 Conclusion

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As a moraine-dammed glacial lake located in the a temperate maritime glaciation region, Bienong Co has been highly regarded by local governments due to its larger area and high potential of for GLOF hazards. Based on bathymetric data, remote sensing images and DEM data, combined with the multiple models of RAMMS, BASEMENT, and Heller-Hager, we completed a comprehensive investigation of the potential GLOF process chain of Bienong Co, including the initial mass movement from the mother glacier and the lateral moraine slope, displacement wave generation and propagation in the lake, overtopping flow and erosion on the moraine dam, and subsequent downstream flooding. The following main conclusions were drawnmain results were obtained:

- (1) According to the field bathymetric data, the lake basin morphology of Bienong Co features a relatively flat basin bottom and the steep flanks, with the slope near the glacier (16.5°) is being steeper than that near the moraine dam (11.3°). The water storage of Bienong Co was ~102.3 × 10⁶ m³ in August 2020, with the a maximum depth was of ~181 m. The huge enormous water storage combined with the fissure-developed mother glacier tongue, steep lateral moraine slope, steep distal facing slope of the moraine dam, and low freeboard make it of possess high GLOF potential.
- that of the six scenarios of landslides (B1, B2, and B3 and C1, C2, and C3). Volumes of ice avalanches entering the lake in Scenarios A1, A2, and A3 are 3.8 × 10⁶ m³, 4.9 × 10⁶ m³, and 5.8 × 10⁶ m³, respectively. Among the six landslide scenarios, Scenario B1 releases a minimum volume of 0.03 × 10⁶ m³ and Scenario C3 releases a maximum volume of 0.30×10⁶ m³. As a result, the impact zone, maximum flow height, and maximum flow velocity in the lake also present show that Scenarios A1, A2, and A3 are significantly larger than the other six scenarios, where in which Scenario B1 is the smallest and Scenario A3 is the largest. Wave amplitudes near the moraine dam in Scenarios A1, A2, and A3 are 17.1 m, 20.2 m, and 25.2 m, respectively. The overtopping flow of all three scenarios causes erosion of the dam, with little difference in breach depth (19.0 m, 19.1 m, and 19.3 m), but large difference in breach width (295.0 m, 339.4 m, and 368.5 m). The volumes of water lost in the lake of the three scenarios are 24.1 × 10⁶ m³, 25.3 × 10⁶ m³, and 26.4 × 10⁶ m³, and the flood peak flows are 4,996 m³/s, 7,817 m³/s, and 13,078 m³/s, respectively. Among the other six scenarios, only Scenarios B3 and C3 with larger magnitudes formed breaches on the moraine dam, with breaches of 6.5 m and 7.9 m in depth and 153 m and 169 m in width, respectively.
- (3) Floods all pass through 18 settlements in the downstream river in 20 hours, with the inundation areas of 7.6 km², 8.0 km²-, and 8.5 km²-, as well as average water depths of 8.4 m, 9.1 m, and 10.0 m, respectively. The GLOFs threatened more than half of the villages in the downstream region. Scenarios B1/ and B2 and C1/ and C2 produce very limited overtopping flow that cannot pose a threat to the downstream region. Both Scenarios B3 and C3 produced floods that flow through eight downstream settlements within 20 hours and had a relatively small impact on them.
- (4) Bienong Co is the relative deepest glacial lake among these those on the Tibetan Plateau that currently have currently been measured and is very markedly different from glacial lakes on the south slope of the Himalayas. In addition, it Furthermore, it is also important to use high-precision topographic data for disaster simulation of GLOF lakes.
- Code and data availability. The Landsat MSS/TM/OLI image are available from the United States Geological Survey (https://earthexplorer.usgs.gov/). The AST14DEM dataset and ALOS PALSAR DEM used in this study can be obtained from the National Aeronautics and Space Administration (NASA) EARTHDATA website (https://earthdata.nasa.gov/). The MapWorld image is provided by the National Platform for Common Geospatial Information Services (https://www.tianditu.gov.cn/). The GLC10 LULC product is available from http://data.ess.tsinghua.edu.cn/fromglc10 2017v01.html.

Author contributions. HD contributed the conceptualization, methodology, software, formal analysis, visualization, and writing of the original draft; XY contributed the conceptualization, supervision, funding acquisition, investigation of the glacial lake, as well as review and editing of the manuscript; YZ, HJ, and QW contributed the investigation of the glacial lake; ZD, BW, and QW contributed the model progress; JH contributed the setting up of the experimental equipment and obtaining data.

Competing interests. The authors declare that they have no conflicts of interest.

Financial support. This research has been supported by the National Key Research Program of China (grant_no. 2019YFE0127700), the National Natural Science Foundation of China (grant nos. 41861013 and 42071089), "Innovation Star" of the Outstanding Graduate Student Program in Gansu Province (grant_no. 2021-CXZX-215), Northwest Normal University's 2020 Graduate Research Grant Program (grant_no. 2020KYZZ001012), and the Outstanding Ph.D. Student Program in Gansu Province (grant_no. 22JR5RA139).

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