

Comments from the reviewer are given in black.

Author responses are given in red, and **proposed amendments or additions to the revised manuscript in bold red.**

RC3: 'Comment on tc-2022-265', Tian Li

General Comments

In this research, Bryony Freer and co-authors mapped the short-term variations in grounding line locations at the Bungenstockrücken Ice Plain using ICESat-2 satellite laser altimetry with a new approach of calculating elevation anomalies. They observed > 15 km tidal GL migration and discovered four different modes of tidal GL migration which are useful in validating numerical model simulations of GL migration and understanding the tidal processes of the ice shelf-ocean-subglacial system. Overall, I find this study interesting, robust and provide new insights into tidal GL migrations, which is important in determining long-term GL changes. The paper is well written and the topic fits well in this journal. I have several moderate concerns detailed below and I hope the authors could address them in the revised version.

We would like to thank you for your detailed comments and express our appreciation in particular for the deep knowledge and expertise that you have brought to this review. It has greatly helped to improve the manuscript.

Major Comments

Inaccurate statements on mean-profile method:

In Section 3.2.2, the authors claim that the mean elevation profile approach cannot be used to calculate the fine-scale short-term GL migrations with ocean tides compared to the newly proposed “Lowest-Sampled Tide” (LST) approach, this is not technically correct.

First, it does not make sense to map short-term GL migrations using a mean elevation profile of all 7 repeat cycles (in the case of RGT 559 GT3L). The nature of using an average elevation profile of all repeat cycles across the study period has already determined that we can only derive one Point F - which is the most landward ice flexure location experienced by the ice shelf among all the repeat cycles. This is the reason you see the clustered Point F features in Figure 2c. But this does not mean that the mean elevation profile method itself cannot be used to derive fine-scale short-term GZ features, which can be achieved by reducing the number of cycles used in calculating the elevation anomalies using a mean elevation profile.

Second, as the authors already mentioned “only two repeat measurements are required to locate Point F using RTLA” in Line 131, if you iterate different combinations of any two ICESat2 repeat cycles, calculate the mean elevation of these two cycles and estimate Point F from elevation anomalies based on this mean elevation profile, you will get a very detailed spatial sampling of the short-term Point F locations along one ground track, similar to the results in Figure 2e. For example, using only cycles 9 and 11 along RGT559 GT3L with the mean elevation approach can produce a most seaward Point F location between -80.90 and - 80.85 latitudes.

Many thanks for these comments; we agree that the manuscript will be strengthened by clarifying a number of the points that you make here.

To address your first point, our aim in discussing the mean-profile method here is to demonstrate that the ‘traditional’ RTLA method (using a single mean reference profile calculated from all available cycles, to locate a single Point F per track) cannot directly be used to study tidal migration of Point F - as you have pointed out. Indeed, this ‘traditional’ approach could be modified by reducing the number of cycles used to calculate the reference profile (as suggested in lines 241-242), although wherever >2 cycles are used to calculate a mean reference profile in an area subject to tidal GL migration, the interpretation of the resulting elevation anomalies per cycle (and therefore the location of Point F) will always be ambiguous.

As you have suggested, if we were to reduce the number of cycles used to calculate the mean profile down to 2, it would be possible to achieve similar sampling of tidal GZ processes. In our view this is a separate approach to the ‘traditional’ method for defining the reference profile that we were comparing to in Section 3.2.2 and Figure 2 (as it involves calculating several reference profiles for each track). This addresses why it hasn’t been directly mentioned in Section 3.2.2, but following your comment we appreciate that this is unclear. **Therefore, in the revised manuscript we will mention the possibility of this alternative approach applying a mean reference profile using combinations of pairs of repeat cycles.** However, we are still confident that the LST method is a more effective approach. We discuss our reasoning for this in further detail below.

To address your second point, it is true that if we calculate along-track elevation anomalies using just 2 cycles, we should locate the same Point F position regardless of whether we use a reference profile calculated from (a) the mean of those two cycles, or (b) the elevation profile of the lower of the two sampled tides. This is illustrated in Figure R1. It is worth noting that in either case, it is only possible to locate Point F for the cycle sampled at the *higher* tide – i.e. For RGT 559, the derived Point F is attributed to the inland limit of tidal ice shelf flexure measured at Cycle 4; we cannot locate Point F for Cycle 9 in either case. Nevertheless, if we are reducing the number of cycles used to calculate elevation anomalies down to 2 anyway, we propose that it makes most sense to use the LST as the reference profile for a number of reasons:

1. It makes more sense conceptually. In using the LST as reference, we are comparing to a ‘real’ ice shelf surface profile, which gives a more realistic representation of the impact of tidal forcing between cycles on ice shelf flexure.
2. It provides a consistent reference profile, which means we can directly compare the derived Point F locations across anomaly profiles of all available cycles together along the same ground track – as shown in Figure 2(e). This would not be possible if you are recalculating a different mean reference profile for each combination of cycles.
3. It gives us a larger signal in the elevation anomalies, with a stronger change in gradient at Point F. This improves the success of the method use to locate point F using peaks in the 2nd derivative of the elevation anomaly (as described in Section 3.2.3).
4. It minimises the required calculations in the processing chain, as only one reference profile has to be defined (the LST), instead of re-calculating a mean profile for each combination of cycles.

For these reasons, we are confident in our approach using the LST that has been presented in this paper.

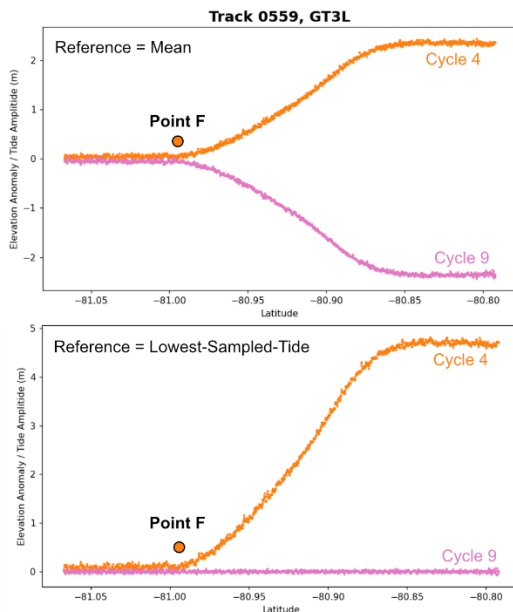


Figure R1: Comparing the derived Point F location on RGT 559 GT3L using just cycles 4 and 9 (highest and lowest sampled tides), using the mean reference profile (upper panel) vs the lowest sampled tide profile as reference (lower panel).

In fact, the mean elevation approach has several benefits over the LST approach proposed in this study:

- 1) **Denser spatial sampling:** the number of different repeat cycle combinations available for Point F calculation will be higher than LST, because the latter only compares different repeat cycles to one fixed cycle with the lowest-sampled tide.

As discussed above, regardless of the combination of repeat cycles used to calculate a mean reference profile, you will only be able to locate Point F for the cycle with the higher sampled tide. For example, there would be no added benefit (and no improvement on spatial sampling) if you were to calculate elevation anomalies along RGT 559 GT3L using mean reference profiles for cycles 4+6, 4+8, 4+9, 4+11, 4+12 and 4+13 (Figure 2), because you would still only locate the same single Point F position for cycle 4 (the highest tide).

- 2) **Higher temporal resolution:** using the neighboring two repeat cycles can provide Point F with a time resolution of 91 day, this cannot be achieved by LST.

This is true in terms of absolute temporal resolution between measurements, which is particularly relevant when looking at long-term GL position change. However, when investigating tidal GL migration patterns in a stable GZ region like Bungenstockrücken (i.e. not experiencing significant long-term advance or retreat), the temporal resolution can be understood more as the range of the overall tide cycle that has been sampled. Tidal changes are inherently sub-daily; for example, there is effectively a 6-hour time difference between the measurement of Point F at high tide vs low tide. On tidal timescales the difference between using a mean vs LST approach therefore makes no difference.

3) **Free from errors in tidal models:** the mean elevation approach doesn't need tidal model to determine a reference profile.

The LST method also does not rely on tide model input at this stage. The cycle used as the lowest sampled tide is determined using the elevation anomaly measurements alone, with the modelled tide data just used for reference here. **We will clarify this in the revised manuscript.**

Third, in contrast to the statement in **Line 227-229** "*This also overcomes the issue of the mean reference profile being skewed by inland flexure at higher tides, but with the additional advantage that it can be applied consistently across RGTs, enabling automation*", the automation of the iteration of different repeat-cycle combinations with the mean elevation approach is straightforward to implement, actually the method should be similar to the LST method shown in Figure 3.

The statement about automation refers to the specific advantage compared to using a *neutral* tide profile as reference, as opposed to the *mean* reference profile approach. **We will clarify this in the revised text.**

In addition, using only two cycles can also overcome the issues of skewed ice flexure at high tide.

As discussed above, this was only in reference to the 'traditional' method using a mean reference profile calculated from several cycles. **We will clarify this in the revised text.**

Therefore, I would like to hear the authors' opinion on this point, and would like to see a comparison between Point F locations calculated from any given two repeat cycles using the mean elevation approach and the results from their LST method.

This has now been addressed in the comments above, including Figure R1.

Tidal model accuracy:

The Neutral Tide and the LST methods proposed in this study rely on tidal model predictions from CATS2008. Previous research show that the ice at deep grounding zone at narrow ice shelf embayment may not respond adequately in phase with ocean tides (Li et al., 2023; Reeh et al., 2000), which means that tidal model cannot always provide accurate tidal amplitude predictions. If this is the case, will the proposed approach still be valid for deriving short-term Point F locations and how the inaccurate tidal model predictions will impact your Point F result? Please clarify.

As stated above, the LST method does not directly use the output from the tide model to locate Point F, so this will not impact the results in any way.

In the case of using the Neutral Tide method, the possible model inaccuracies closer to the GL would need to be taken into account in such settings, as we would want to ensure that the cycle used as a 'neutral tide' is in fact as close to a 0m neap tide. However, as discussed in the paper, the Neutral Tide method is in general not suitable for automation and application across multiple tracks and so we don't apply it in our study. **We will add a brief statement on the impact of the tide model here in Section 3.2.2 (ii).**

Specific Comments

Line 37: Please rephrase this sentence, GZ can be wider than 10 km as demonstrated by the results of >15 km migration in this study.

We will update this in the revised manuscript.

Line 45-50: This paragraph lacks mentioning previous research in studying the short-term GL migrations using satellite altimetry and DInSAR, such as:

- Brunt et al. (2011): <https://www.cambridge.org/core/journals/journal-of-glaciology/article/analysis-of-ice-plains-of-the-filchnerronne-ice-shelf-antarctica-using-icesat-laser-altimetry/80F41E7FDC8124136AF50615861D5C71>
- Milillo et al. (2017): <http://doi.wiley.com/10.1002/2017GL074320>
- Milillo et al. (2019) <https://www.science.org/doi/10.1126/sciadv.aau3433>
- Brancato et al. (2020): <https://onlinelibrary.wiley.com/doi/10.1029/2019GL086291>
- Milillo et al. (2022): <https://www.nature.com/articles/s41561-021-00877-z>

Brunt et al. (2011) and Milillo et al. (2017) are already cited, but **we will add references to the other papers, as suggested.**

Line 52-53: What are the spatial and temporal resolutions of these historical archives? What is the requirement of spatial-temporal resolution for assessing the tidal GL migration?

These are currently discussed in more detail in section 2.2. The question of temporal resolution has been addressed in the reply to your major comments, but the main requirement is that we sample the ice shelf surface elevation at a range of different tides within a period over which there has not been significant long-term GL change. This will vary across different regions depending on the rate of long-term GL change and the extent of tidal GL migration, which is not well defined in most places.

In terms of spatial resolution, this is perhaps more to do with lack of spatial coverage in historical records, including lack of coherent SAR images for DInSAR methods, missing data at high latitude GZs, and the wider track spacing (and sometimes misaligned repeat-tracks) of ICESat.

We will update this to ‘... with sufficient spatial coverage and temporal resolution’.

Line 63-65: “where short-term GL migration is likely to impact both ice dynamics through rapid variations in basal shear stress, and basal melt rate through changes in cavity geometry enhancing tidal mixing.” Here needs a reference.

We will add reference to Chen et al. (2023) and Ciraci et al. (2023) to support this statement in the revised manuscript.

Line 109-110: Dawson and Bamber (2020) also mapped Point H in addition to Point F in their study.

Thank you for this suggestion, **we will add this to the revised text.**

Line 111: Need to mention why CryoSat-2 is not suitable to detect short-term GL changes – due to its long repeat cycle (369 day) (Dawson and Bamber, 2017).

We will add this to the revised text, as suggested.

Line 116-122: Mohajerani et al. (2021) have also improved the DInSAR sampling under different tidal phases using Sentinel-1a/b SAR images across the Antarctic Ice Sheet.

We will add this to the revised text, as suggested. We will also add a reference to Chen et al. (2023) who also employ Sentinel-1 DInSAR to detect tidal GL migration (this paper has been recently published since the initial submission of our manuscript).

Line 128: Please mention that the “unrecoverable topographic biases across GZs” is caused by the large across-track slope across the GZ.

We will add this to the revised text, as suggested.

Line 128-131: *“In contrast, the Advanced Topographic Laser Altimeter System (ATLAS) that launched on board ICESat-2 in 2018 has a six-beam design with more accurate pointing, which reduces across-track deviation from the reference ground track (RGT), providing better spatial sampling of the GZ.”*

Not accurate and need clarification:

- 1) The six-beam design reduces the across-track deviation from the Reference Pair Track (RPT) inside each beam pair, not the Reference Ground Track (See https://nsidc.org/sites/default/files/icesat2_atl06_atbd_r005.pdf).
- 2) Please give a number of the ICESat-2 point control accuracy here and how it compares to ICESat. Luthcke et al. (2021) show that the performance of ICESat-2 can achieve 4.4 ± 6.0 m, this represents a very small across-track separation across repeat cycles.

To address both of these points, we will update the text in lines 128-131 to:

‘In contrast, the Advanced Topographic Laser Altimeter System (ATLAS) that launched on board ICESat-2 in 2018 has a six-beam design with more accurate pointing, which reduces across-track deviation from each reference pair track (RPT) to within 4.4 ± 6.0 m (Luthcke et al., 2021), providing better spatial sampling of the GZ.’

(Note, we will therefore redefine RGT in section 3.1, where it now appears for the first time).

Line 133: Here I suggest the authors to add some discussions on the pros and cons of Li et al. (2022b)'s results, and talk about why it is necessary to extend the data record in this study.

We will add the following text here:

‘This is a highly valuable and comprehensive dataset for the identification of long-term grounding line change, but as only a single Point F has been located per ICESat-2 ground track, it is limited in use for studying tidal GZ processes. Therefore, here we extend the Li et al. (2022c) record at

Bungenstockrücken to locate multiple Point F positions along each ground track as it migrates over the tide cycle (Fig. 1b), providing novel observations of tidal GZ behaviour.'

Line 142-144: I think there is no need to mention the switch between weak and strong beams because this study did not use this feature in GZ calculation.

We will remove this in the revised version, as suggested.

Line 149-151: see my previous comment, can also merge this sentence into Line 142-144.

We will update this in the revised version, as suggested.

Line 152: *"We obtained coincident tide amplitudes at the most seaward point of each ICESat2 ground track per cycle"*. Please provide an average distance between these ICESat-2 seaward points used in the tidal amplitude calculation and a reference (historic) grounding line. This is important because if the seaward point still locates inside the GZ, then the modelled tidal amplitude may not represent the actual ice shelf elevation change in hydrostatic equilibrium. In addition, the orientation of the ICESat-2 ground tracks are not always perpendicular with the actual grounding line, this can also introduce biases (Li et al., 2020, 2022a).

Thank you for raising this point. We were careful to ensure that all locations where modelled tides were extracted were further seaward than the known Point H, precisely to avoid this issue of the ice within the GZ not being hydrostatic equilibrium. However, as discussed above, these modelled tides were just used for reference and had no direct influence on the calculation of Point F locations. **We will therefore emphasise here that tides were calculated at locations seaward of Point H and clarify that these modelled tides were just used for reference.**

Line 157: Please clarify why the annual tidal distribution is essential in GZ calculation.

This is already addressed briefly in lines 244-248, but **we will clarify further in the revised manuscript.**

Again, as discussed above, the modelled tides are not used directly in the calculation of Point F location. Nevertheless, calculating the annual tide distribution is very important to give context for the range of tides (and therefore Point F locations) that have been sampled by ICESat-2 over the study period. This is illustrated in Figure 2(f).

As the most extreme high and low tides occur less frequently, this helps us to understand how often the region experiences tidal forcing outside the range of tides sampled by ICESat-2. For example, as illustrated in Figure 2(f), RGT 559 has not been sampled by ICESat-2 during both the lowest 3% and highest 6.4% of tides experienced in the region. This indicates that 6.4% of the time, Point F could be located further inland than the maximum inland extent we have measured in this study. In order to determine the full width of the zone of ephemeral grounding, we would have to rely on ICESat-2 overpasses coinciding almost exactly with both the highest and lowest spring tides (each only occurring fortnightly).

Line 172: “minimum segment difference exceeds 1”, I assume this is 1 meter, please add a unit.

Yes, we will amend this in the revised manuscript.

Line 192-195: Here the authors merely mention the traditional mean elevation approach in calculating elevation anomalies, then directly propose two new methods without any discussions on the disadvantages of the mean profile method. It is not clear why it is essential to develop two new approaches, why mean elevation approach fails to map short-term GL locations, and how the two new methods can further improve these research gaps. I suggest incorporating some of the information in **Line 201-235** to the beginning of **Section 3.2.2**.

This has been addressed in the response to your major comments above.

Line 201-213: As I have mentioned in the major comment, mean profile approach can provide high spatial-temporal resolution GZ calculation, please consider modify the relevant content accordingly.

This has been addressed in the response to your major comments above.

Line 229-230: The mean elevation profile approach can allow the calculation of Point F from repeat cycles both sampled at low tides, please see my major comments, and rephrase this sentence.

The major comments have been addressed above. We will rephrase this to:

‘This also overcomes the issue of the mean reference profile (calculated from multiple cycles of data) being skewed by inland flexure at higher tides, ...’

Line 500-501: “The 15 km observed tidal GL migration at Bungenstockrücken is much larger than standard model grid spacing at the GL”, what is the standard model grid size at the GL?

We will add:

“The 15 km observed tidal GL migration at Bungenstockrücken is much larger than standard model grid spacing at the GL, which is typically less than 2km, and down to 250m where mesh refinement is applied at the GL (Cornford et al., 2020)”

Line 500-503: “Similarly, the time step of an ice sheet model is generally much longer than one day; therefore, prescribing a sub-daily change in GL position is not generally possible.” Not sure why mentioning sub-daily GL change here, especially the results in this paper cannot achieve the sub-daily resolution either.

Tidal changes are inherently sub-daily; by measuring how Point F migrates at different stages of the tide cycle we are therefore effectively measuring how the GL migrates within sub-daily timescales, even when the absolute repeat time between measurements ranges from 91 days to several years. This is made possible by the fact that this is a region with long-term stability and so we can assume that the majority of the GL migration is driven by tidal ice shelf flexure. This is confirmed by

comparing the modelled ice shelf surface anomalies with the modelled tide heights (e.g. in Figure 2c-e).

We mention this here in the context of ice shelf modelling, to highlight the importance of considering the possible impact of these sub-daily tidal processes on wider ice shelf and ice sheet dynamics.

Figures 2c,d,e:

I assume the reference elevation profile of each different approach is plotted in the upper panel of subfigures c/d/e, however it is very difficult to discern them from the ICESat-2 repeat profiles. Please change the line symbols of reference elevation profile under different scenarios. Here are some suggestions:

- 1) consider only include one subfigure to show all the ICESat-2 repeat cycles with a colormap.
- 2) then add a different subfigure, plot three different reference elevation profiles in distinct colors or symbols and add all ICESat-2 repeat cycles in light grey color with low transparency as a background - this is to make sure that the reference elevation profiles can stand out from ICESat-2 profiles and the readers can clearly distinguish these three different reference profiles.

Thank you very much for these useful suggestions. We have experimented with a few different amendments to Figure 2 to improve the readability of the elevation profile panels. We propose the most effective solution is to include a smaller range of elevation values close to the ice shelf surface, which better highlights the surface profiles of each repeat cycle. By reducing the opacity of these repeat profiles and increasing the line thickness of the reference profile in each scenario, this shows the difference between the three reference profiles more effectively. **A proposed amendment to panels c-e is shown in Figure R2.**

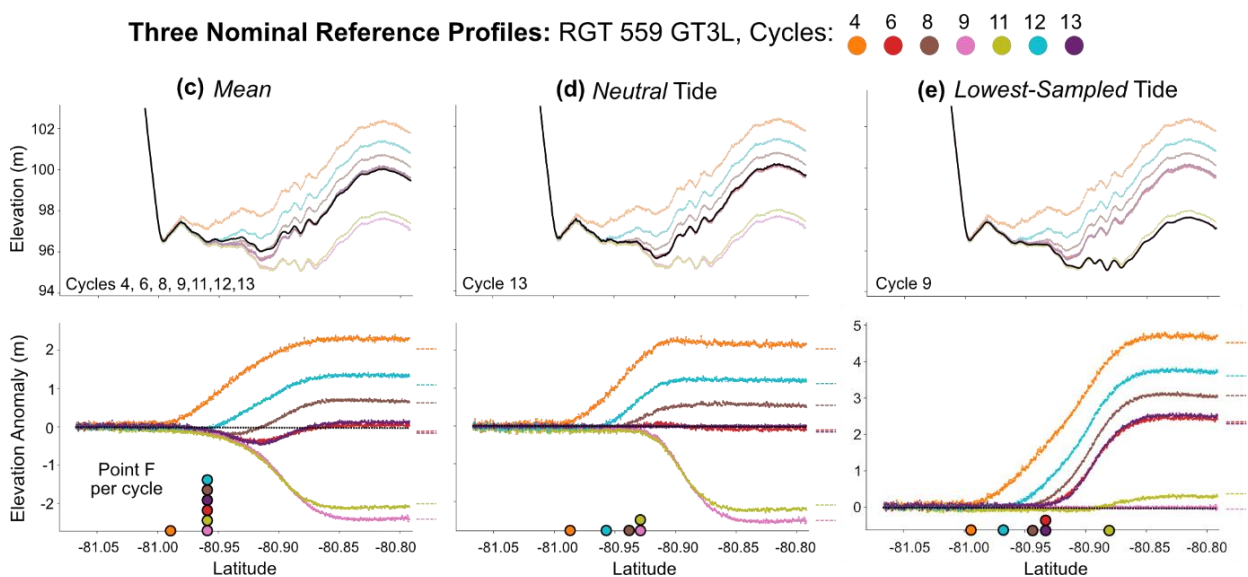


Figure R2: Proposed amendment to panels c-e in Figure 2 to improve the readability of the reference elevation profiles.

Figure 6: Both panels f and l are RGT 1223 1R, why do the Point F locations along the same ground track behave so differently? Is this a labelling error in the figure?

Yes, this is a labelling error – many thanks for spotting. **Panel (l) will be updated in the revised version to RGT 1138 1R.**

Additional References for the Revised Manuscript

Brancato, V., Rignot, E., Milillo, P., Morlighem, M., Mouginot, J., An, L., Scheuchl, B., Jeong, S., Rizzoli, P., Bueso Bello, J. L., and Prats-Iraola, P.: Grounding Line Retreat of Denman Glacier, East Antarctica, Measured With COSMO-SkyMed Radar Interferometry Data, *Geophys. Res. Lett.*, 47, <https://doi.org/10.1029/2019GL086291>, 2020.

Chen, H., Rignot, E., Scheuchl, B., and Ehrenfeucht, S.: Grounding Zone of Amery Ice Shelf, Antarctica, From Differential Synthetic-Aperture Radar Interferometry, *Geophysical Research Letters*, 50, e2022GL102430, <https://doi.org/10.1029/2022GL102430>, 2023.

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Milillo, P., Rignot, E., Rizzoli, P., Scheuchl, B., Mouginot, J., Bueso-Bello, J., and Prats-Iraola, P.: Heterogeneous retreat and ice melt of Thwaites Glacier, West Antarctica, *Sci. Adv.*, 5, eaau3433, <https://doi.org/10.1126/sciadv.aau3433>, 2019.

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Mohajerani, Y., Jeong, S., Scheuchl, B., Velicogna, I., Rignot, E., and Milillo, P.: Automatic delineation of glacier grounding lines in differential interferometric synthetic-aperture radar data using deep learning, *Sci Rep*, 11, 4992, <https://doi.org/10.1038/s41598-021-84309-3>, 2021.