

Brief communication: Evaluation of the snow cover detection in the Copernicus High Resolution Snow & Ice Monitoring Service

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Abstract: The High Resolution Snow & Ice Monitoring Service was launched in 2020 to provide near real time, pan-European snow and ice information at 20 m resolution from Sentinel-2 observations. Here we present an evaluation of the snow detection using a database of snow depth observations from 1764 stations across Europe over the hydrological year 2016-2017. We find a good agreement between both datasets with an accuracy (proportion of correct classifications) of 94% and kappa of 0.81. More accurate (+6% kappa) retrievals are obtained by excluding low quality pixels at the cost of a reduced coverage (-13% data).

1 Introduction

The snow cover area, defined as the spatial extent of the snow cover on the land surface (Fierz et al., 2009), is a key variable in many hydrology, climatology and ecology studies. Earth observation satellites have been used to routinely map the snow cover area at continental scale since the late 1960s (Matson and Wiesnet, 1981). Such observations are increasingly used for meteorological, climate, hydrological, ecosystem and natural hazards applications. The Committee on Earth Observation Satellites has listed nineteen operational remote sensing products which provide information on the spatial extent of the snow cover either as binary (snow/no-snow) or fractional (snow covered fraction of the pixel area) representation. However, most of them have a spatial resolution of 500 m and above, and therefore do not meet a range of user needs both for science and operational applications (Malnes et al., 2015). Previous studies suggest that the spatial scale of variability of snow depth is less than 100 m (e.g. Trujillo et al., 2007; Mendoza et al., 2020). In snow dominated catchments, a fine description of snow cover properties distribution is important to compute snow melt (Freudiger et al., 2017). High resolution snow cover maps reflect the spatial heterogeneity of the snow cover properties and therefore can be assimilated to improve snow water equivalent estimation (Margulis et al., 2016; Baba et al., 2018). High resolution snow cover maps are also critical to understand plant species distribution in alpine and arctic ecosystems (Dedieu et al., 2016; Niittynen and Luoto, 2018). In the disaster management sector, high spatial and temporal resolution snow products down to 50 m resolution were requested by road and avalanches authorities (Malnes et al., 2015). High resolution snow cover maps can also be useful for outdoor activities.

On behalf of the European Commission, the European Environment Agency has commissioned the development and real-time production of the Copernicus High Resolution Snow & Ice products (HRSI), including a snow cover component to address these needs. In particular, this service provides a canopy-adjusted Fractional Snow Cover (FSC) at 20 m resolution along with a cloud and cloud shadow mask and quality flags. The products are derived from Sentinel-2 observations, resulting in a revisit time less or equal to five days. The products are distributed with a maximal latency of 3 hours after the availability of the level 1C product in the Sentinel-2 mission ground segment, which means that they are generally available on the same day as the sensing time. The

37 products are computed using MAJA (atmospheric correction and cloud detection) and LIS (snow detection and snow fraction
38 calculation) software (Hagolle et al., 2015; Gascoin et al., 2019). The performance of the snow detection with this processing
39 pipeline was previously evaluated over the French Alps and Pyrenees using snow depth records at 120 stations from the Météo-
40 France database (Gascoin et al., 2019). The accuracy (proportion of correct classifications) was 94 % ($\kappa = 0.83$), with a higher false
41 negative rate than the false positive rate. However, this evaluation was spatially limited to 10 Sentinel-2 tiles in France (a tile is
42 110 km by 110 km), whereas the HRSI products cover 1054 Sentinel-2 tiles over 39 countries in Europe. Any operational snow
43 cover detection algorithm applied to optical multispectral imagery is challenged by spectral similarities between clouds and the
44 snow cover (Stillinger et al., 2019), forest cover obstruction (Xin et al., 2012) and lack of solar irradiance during the winter
45 particularly in mountain regions (due to shading from the surrounding slopes) and high latitude regions (due to low sun elevation).
46 These factors vary significantly across Europe and could have been misrepresented by the former evaluation. In the aim of
47 providing a more robust assessment of the snow product reliability to users of the service, we report here on a much more extensive
48 evaluation using 1764 stations from 36 countries, covering a wider range of climate and topographic conditions. This evaluation
49 was made possible thanks to a massive processing of the Sentinel-2 archive using MAJA and LIS to generate the HRSI collection
50 (about 600'000 products, i.e. 500 Terabytes of input data).

51 **2 Data and Methods**

52 **2.1 In situ data**

53 The evaluation database was prepared by merging two datasets of in situ snow depth (height of snow, HS) measurements. First,
54 we extracted daily snow depth measurements of 1094 SYNOP data (WMO automatic weather station) covering 36 countries. Then,
55 we selected daily data from a recent compilation of snow depth measurements in the Alps (Matiu et al., 2021). The latter dataset
56 consisted of 670 stations located in France, Italy and Germany. The evaluation period spans a hydrological year from 1 Sep 2017
57 to 31 Aug 2018. This period was chosen to take advantage of the 5-days revisit periodicity reached by the Sentinel-2 mission in
58 Sep 2017 and because the Alps dataset is smaller after 2018. All values were rounded to the nearest centimeter. We combined all
59 these data sources into a single dataset totaling 26933 data points of daily snow depth measurements distributed across 36 countries
60 in Europe (Fig.1). A data point was classified as snow covered if HS was strictly greater than a threshold HS_0 . We tested the
61 sensitivity to this threshold by calculating the confusion matrix between the FSC products and the reference dataset for 1 cm
62 increments of HS_0 from 0 to 10 cm (Klein and Barnett, 2003; Gascoin et al., 2015, 2019).

63 **2.2 Snow product**

64 We used the on-ground fractional snow cover (FSCOG) layer but the analysis would be identical with the top-of-canopy layer
65 (FSCTOC) as the canopy adjustment does not change the snow classification (HR-S&I consortium, 2020a). Pixels with value of
66 205 (cloud or cloud shadow) and 255 (no data) were set to "no data". A pixel was classified as snow if $0 < FSC \leq 100$ and no-snow
67 if $FSC = 0$. We matched each point of the reference dataset with the nearest pixel of an overlapping FSC product that was acquired
68 on the same day, resulting in a maximal distance of $10\sqrt{2}$ m between the pixel center and the station. If there were more than one
69 matching FSC product on the same day, we selected one whose nearest pixel was neither cloud nor no data. We also assessed the
70 impact of the quality layer on the performance. The QCFLAGS (quality control flags) layer provides bit-encoded quality flags to
71 identify lower quality retrievals e.g. due to low sun elevation, thin cloud cover, surface water (HR-S&I consortium, 2020b). Hence
72 we performed the same analysis as above by excluding all pixels with at least a non-zero quality flag, i.e. $QCFLAGS > 0$.

73 2.3 Stratification data

74 We stratified the analysis using four external variables: tree cover density, land cover type, elevation and country of measurement.
75 The tree cover density (TCD) was obtained from Copernicus Land Monitoring Service. It was derived using Sentinel-2 data too
76 and is available at 20 m resolution with pixel values ranging from 0 to 100%. We used the 2015 product and partitioned the data
77 into 10 segments of equal TCD range. The land cover was obtained from the Copernicus Global Land Service version 3 (Buchhorn
78 et al., 2020). We used the 2018 discrete classification map where a pixel's label is the majority label from the fractional cover map.
79 The classes were regrouped into the following labels: closed or open forest, herbaceous vegetation or wetland, urban, water bodies,
80 snow and ice, shrubs, moss and lichen, bare and sparse vegetation, cropland, and open sea. The elevation was extracted from the
81 Copernicus global 30 m digital elevation model. We used it to partition our data into 11 segments. We excluded from the analysis
82 all pixels that were non-valid in at least one of the external datasets, so that the population sizes are equal for each stratification
83 variable.

84 2.4 Metrics

85 The comparison between in situ/satellite matchups was performed by computing a confusion matrix and the derived false positive
86 (FP), false negative (FN), true positive (TP), true negative (TN), recall or fraction of successfully identified positives
87 ($TP/(TP+FN)$), precision ($TP/(TP+FP)$), accuracy ($(TP+TN)/(TP+FP+FN+TN)$), and kappa coefficient (κ).

88 3 Results

89 Figure 2 shows the evaluation of the snow/no-snow detection with in-situ data, and in particular the variation of the kappa
90 coefficient with the HS_0 threshold and corresponding confusion matrices. It indicates a good overall agreement between both
91 datasets with an accuracy of 94% and $\kappa = 0.80$ at $HS_0 = 0$. The kappa coefficient increases to 0.84 if low quality retrievals are
92 excluded. The optimal HS_0 is equal to 1 cm in both cases and used for the analysis with the stratification data. The false negative
93 rate is higher than the false positive rate (precision is 93% but recall is 78%). The exclusion of low quality data reduces the total
94 amount of available data points by 13% and increases the recall (82%) more than the precision (94%), meaning that more false
95 negative errors are avoided. Figure 3 shows that the best performances ($\kappa > 0.8$) are at locations of “urban”, “cropland”, “open
96 forest”, “herbaceous vegetation” or “bare/sparse” land cover types. A lower performance ($\kappa \approx 0.6$) is evident for the “closed forest”
97 and “water body” class. The “shrubs” class has a very low performance ($\kappa \approx 0.1$) but there are only 13 snow values in the in situ
98 data. The analysis by TCD bins shows that performances tend to decrease as the forest cover increases, in agreement with the lower
99 accuracy for the “closed forest” land cover type. The snow detection is robust across elevations between 400 m and 2800 m with
100 kappa values above 0.7, but a higher proportion of false negative between 100 m and 400 m is observed; it is likely related to the
101 presence of dense forest at low elevation in nordic regions. The performances are also shown for the countries with at least 100
102 data points. Countries with more than 1000 data points (France, Germany, Italy and Turkey) have kappa scores above 0.75 except
103 Turkey. Finland and Norway, two high latitude countries and with more than 200 data points each, also have kappa scores equal
104 or above 0.75. Stratifying the results of all countries by month (supplementary Figure S1) indicates that the number of false
105 negatives is highest in December while the accuracy increases every month from January to April.

106 **4 Discussion**

107 The results are in line with the previous evaluation with an accuracy of 94% and a kappa of 0.8 and an optimal snow depth threshold
108 of 1 cm close to the previously reported 2 cm (Gascoin et al., 2019). This value is very low, ten times lower than the one that can
109 be obtained with MODIS data (Klein and Barnett, 2003; Gascoin et al., 2015). This suggests that Sentinel-2 is much more sensitive
110 to thin snow cover due to its higher spatial resolution which reduces the prevalence of mixed pixels. We also find that the proportion
111 of FN is larger than the proportion of FP, indicating that the HRSI snow products are more likely to omit a snow pixel than to
112 falsely classify a pixel as snow covered at the stations locations. This study demonstrates that this effect can be partly attributed to
113 the adverse effect of the forest canopy on snow detection as the number of false negatives is higher in the closed forest land cover
114 type. However, the results also show that this tendency for underdetection is present across nearly all subcategories, suggesting
115 that this limitation is not only due to land cover. The lower performance in winter indicates that it may be a consequence of the
116 low signal-to-noise ratio in Sentinel-2 radiances during the periods of low solar elevation angle. The lower proportion of FP than
117 FN in this study also suggests that the occurrence of false snow detection in large clouds that was visually identified in the previous
118 evaluation (Gascoin et al., 2019) is actually not be the main issue to focus on in order to improve the product accuracy.

119 **5 Conclusion**

120 This brief communication reports on the performance of the HRSI snow classification based on a year of in situ snow depth data.
121 Although the in situ dataset is unbalanced with about four times more no-snow values than snow values, it is sufficiently large to
122 have thousands of observations in the two categories. It is also well distributed across Europe, as we obtained hundreds of
123 observations in many subcategories (country, land cover, elevation, and tree cover density). This dataset therefore allows drawing
124 more robust conclusions than previously on the performance of the MAJA-LIS algorithm to detect the snow cover. We conclude
125 that Sentinel-2-derived HRSI snow products are sufficiently reliable to study snow cover variations across the variety of European
126 landscapes from the northernmost Arctic regions to the southern semiarid mountains, excluding the densest forest regions.
127 Although the evaluation dataset spans only one year of data, its large geographical scale compensates for its short duration. Further
128 progress would result from a wider public availability of in situ snow cover data in the future over extended periods, including
129 additional sources of data (e.g. citizen science observations, webcam-based snow cover observations, higher resolution satellite
130 observations, etc.).

131 **Data availability**

132 The FSC products are available from the Copernicus Land website (<https://land.copernicus.eu/pan-european/biophysical-parameters/high-resolution-snow-and-ice-monitoring>). The TCD product is also available from Copernicus Land
133 (<https://land.copernicus.eu/pan-european/high-resolution-layers/forests/tree-cover-density>). The SYNOP data are available upon
134 request to the authors. The Alps data providers are Météo France, Deutscher Wetterdienst, Agenzia regionale per la protezione
135 dell'ambiente (ARPA) Friuli Venezia Giulia - Osservatorio Meteorologico Regionale e Gestione Rischi Naturali, ARPA
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138 **Author contribution**

139 [CRedit contributor roles taxonomy](#). Conceptualization: SG, Data curation: ZBD, MD, Formal analysis: ZBD, Funding acquisition:
140 SG, OH, GS, MA, MD, SM, Investigation: ZBD, SG, Methodology: SG, Project administration: MA, FM, Resources: AD,

141 Software: RJ, GS, OH, ZBD, SG, AD, Supervision: SG, Validation: ZBD, Visualization: ZBD, Writing – original draft preparation:
142 ZBD, SG, Writing – review & editing: ZBD, SG, SM, MD, FM, OH.

143 **Competing interests**

144 The authors declare that they have no conflict of interest.

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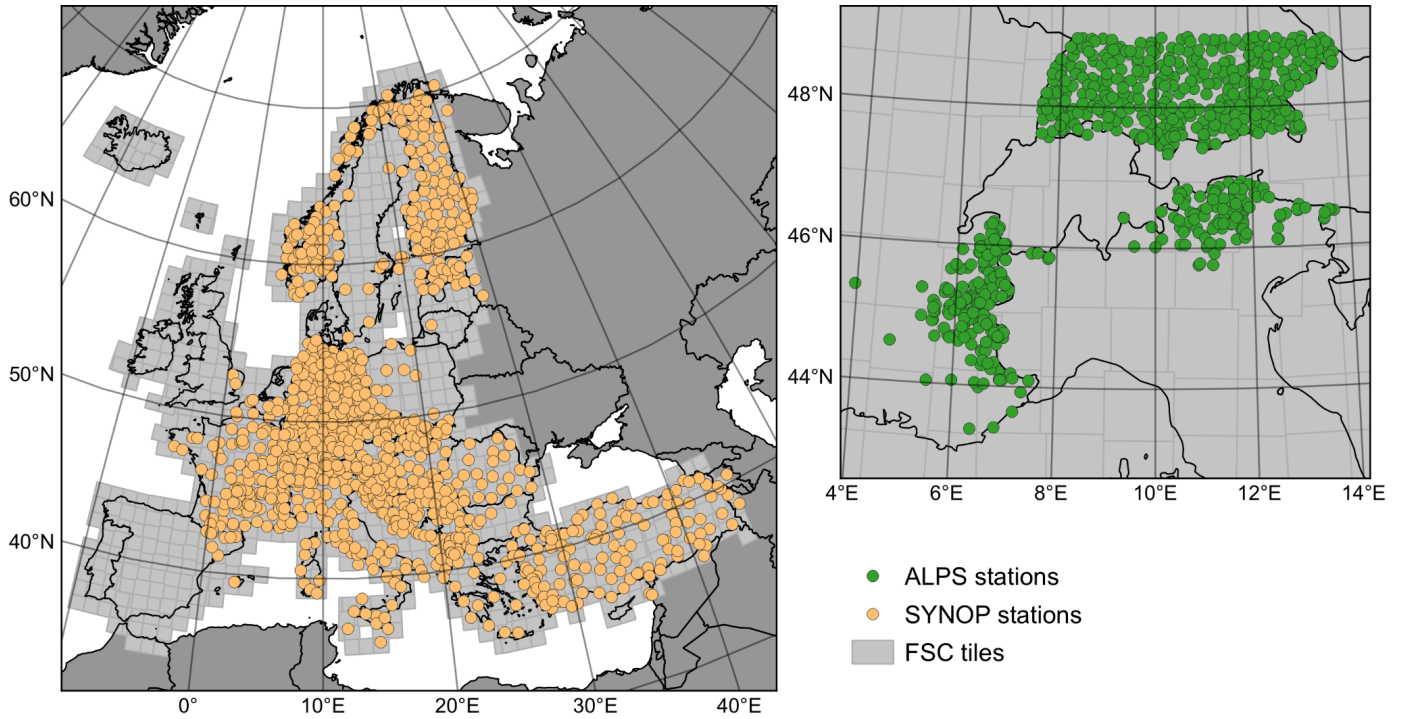
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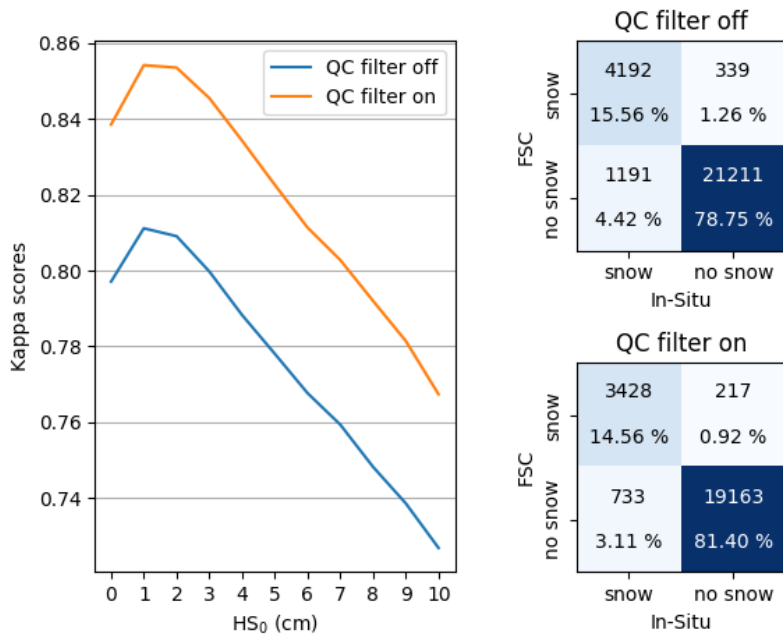
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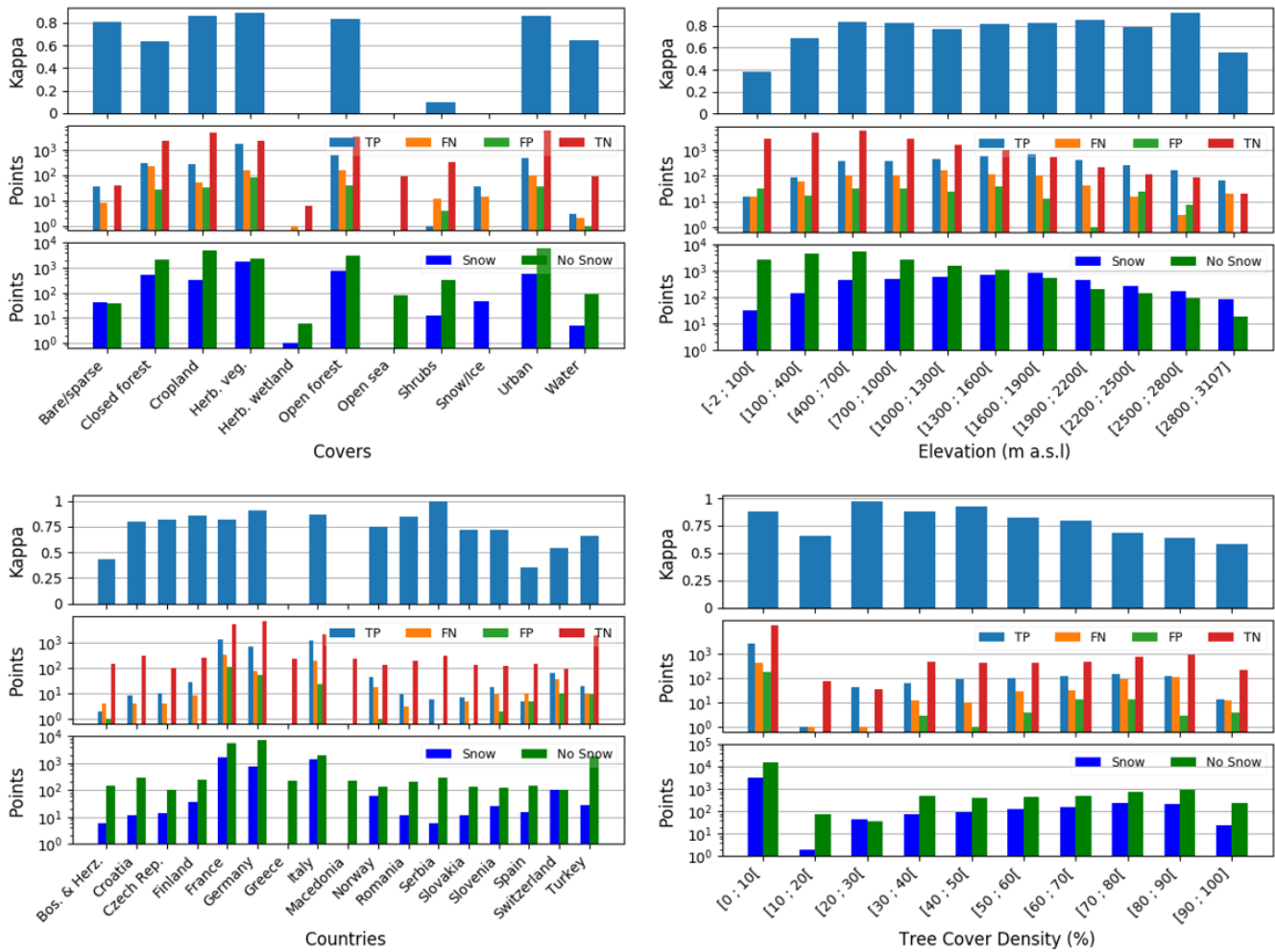
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Figure 1. Map of the study area and location of the in situ measurements. Each FSC (fractional snow cover) tile covers an area of 5490 by 5490 pixels of 20 m resolution.



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Figure 2. Evaluation of the snow/no-snow detection with in situ data. Variation of the kappa coefficient with the HS_0 threshold and confusion matrices with and without data flagged as low quality (using $HS_0 = 1$ cm). QC filter on/off indicate whether the retrievals were filtered using the corresponding QCFLAGS layer or not.



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Figure 3: Results of the evaluation by strata of land cover, elevation, countries and Tree Cover Density. Each subplot shows three histograms for each stratification variable. The histograms represent, from top to bottom respectively, the kappa, the amount of TP (true positive), FN (false negative), FP (false positive) and TN (true negative) on a logarithmic scale and the amount of in situ snow (TP + FN) and no-snow (FP + TN) on a logarithmic scale for each strata. A kappa score of zero happens when there are zero snow observations or zero no-snow observations for either the HRSI FSC or the reference dataset. For example, we get a kappa of zero in Greece despite the results being all true negatives.