

1 **Brief communication: Evaluation of the snow cover detection in the**

2 **Copernicus High Resolution Snow & Ice Monitoring Service**

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10 **Abstract:** The High Resolution Snow & Ice Monitoring Service was launched in 2020 to provide near real time, pan-European
11 snow and ice information at 20 m resolution from Sentinel-2 observations. Here we present an evaluation of the snow detection
12 using a database of snow depth observations from 1764 stations across Europe over the hydrological year 2016-2017. We find a
13 good agreement between both datasets with an accuracy ([proportion of correct classifications](#)) of 94% and kappa of 0.81. More
14 accurate (+6% kappa) retrievals are obtained by excluding low quality pixels at the cost of a reduced coverage (-13% data).

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15 **1 Introduction**

16 The snow cover area, defined as the spatial extent of the snow cover on the land surface (Fierz et al., 2009), is a key variable in
17 many hydrology, climatology and ecology studies. Earth observation satellites have been used to routinely map the snow cover
18 area at continental scale since the late 1960s (Matson and Wiesnet, 1981). Such observations are increasingly used for
19 meteorological, climate, hydrological, ecosystem and natural hazards applications. The Committee on Earth Observation Satellites
20 has listed nineteen operational remote sensing products which provide information on the spatial extent of the snow cover either
21 as binary (snow/no-snow) or fractional (snow covered fraction of the pixel area) representation. However, most of them have a
22 spatial resolution of 500 m and above, and therefore do not meet a range of user needs both for science and operational applications
23 (Malnes et al., 2015). Previous studies suggest that the spatial scale of variability of snow depth is less than 100 m (e.g. Trujillo et
24 al., 2007; Mendoza et al., 2020). In snow dominated catchments, a fine description of snow cover properties distribution is
25 important to compute snow melt (Freudiger et al., 2017). High resolution snow cover maps reflect the spatial heterogeneity of the
26 snow cover properties and therefore can be assimilated to improve snow water equivalent estimation (Margulis et al., 2016; Baba
27 et al., 2018). High resolution snow cover maps are also critical to understand plant species distribution in alpine and arctic
28 ecosystems (Dedieu et al., 2016; Niittynen and Luoto, 2018). In the disaster management sector, high spatial and temporal
29 resolution snow products down to 50 m resolution were requested by road and avalanches authorities (Malnes et al., 2015). High
30 resolution snow cover maps can also be useful for outdoor activities.

31 On behalf of the European Commission, the European Environment Agency has commissioned the development and real-time
32 production of the Copernicus High Resolution Snow & Ice products (HRSI), including a snow cover component to address these
33 needs. In particular, this service provides a canopy-adjusted Fractional Snow Cover (FSC) at 20 m resolution along with a cloud
34 and cloud shadow mask and quality flags. The products are derived from Sentinel-2 observations, resulting in a revisit time less or
35 equal to five days. The products are distributed with a maximal latency of 3 hours after the availability of the level 1C product in
36 the Sentinel-2 mission ground segment, which means that they are generally available on the same day as the sensing time. The

39 products are computed using MAJA (atmospheric correction and cloud detection) and LIS (snow detection and snow fraction
40 calculation) software (Hagolle et al., 2015; Gascoin et al., 2019). The performance of the snow detection with this processing
41 pipeline was previously evaluated over the French Alps and Pyrenees using snow depth records at 120 stations from the Météo-
42 France database (Gascoin et al., 2019). The accuracy (proportion of correct classifications) was 94 % ($\kappa = 0.83$), with a higher false
43 negative rate than the false positive rate. However, this evaluation was spatially limited to 10 Sentinel-2 tiles in France (a tile is
44 110 km by 110 km), whereas the HRSI products cover 1054 Sentinel-2 tiles over 39 countries in Europe. Any operational snow
45 cover detection algorithm applied to optical multispectral imagery is challenged by spectral similarities between clouds and the
46 snow cover (Stillinger et al., 2019), forest cover obstruction (Xin et al., 2012) and lack of solar irradiance during the winter
47 particularly in mountain regions (due to shading from the surrounding slopes) and high latitude regions (due to low sun elevation).
48 These factors vary significantly across Europe and could have been misrepresented by the former evaluation. In the aim of
49 providing a more robust assessment of the snow product reliability to users of the service, we report here on a much more extensive
50 evaluation using 1764 stations from 36 countries, covering a wider range of climate and topographic conditions. This evaluation
51 was made possible thanks to a massive processing of the Sentinel-2 archive using MAJA and LIS to generate the HRSI collection
52 (about 600'000 products, i.e. 500 Terabytes of input data).

53 **2 Data and Methods**

54 **2.1 In situ data**

55 The evaluation database was prepared by merging two datasets of in situ snow depth (height of snow, HS) measurements. First,
56 we extracted daily snow depth measurements of 1094 SYNOP data (WMO automatic weather station) covering 36 countries. Then,
57 we selected daily data from a recent compilation of snow depth measurements in the Alps (Matiu et al., 2021). The latter dataset
58 consisted of 670 stations located in France, Italy and Germany. The evaluation period spans a hydrological year from 1 Sep 2017
59 to 31 Aug 2018. This period was chosen to take advantage of the 5-days revisit periodicity reached by the Sentinel-2 mission in
60 Sep 2017 and because the Alps dataset is smaller after 2018. All values were rounded to the nearest centimeter. We combined all
61 these data sources into a single dataset totaling 26933 data points of daily snow depth measurements distributed across 36 countries
62 in Europe (Fig.1). A data point was classified as snow covered if HS was strictly greater than a threshold HS_0 . We tested the
63 sensitivity to this threshold by calculating the confusion matrix between the FSC products and the reference dataset for 1 cm
64 increments of HS_0 from 0 to 10 cm (Klein and Barnett, 2003; Gascoin et al., 2015, 2019).

65 **2.2 Snow product**

66 We used the on-ground fractional snow cover (FSCOG) layer but the analysis would be identical with the top-of-canopy layer
67 (FSCTOC) as the canopy adjustment does not change the snow classification (HR-S&I consortium, 2020a). Pixels with value of
68 205 (cloud or cloud shadow) and 255 (no data) were set to "no data". A pixel was classified as snow if $0 < FSC \leq 100$ and no-snow
69 if $FSC = 0$. We matched each point of the reference dataset with the nearest pixel of an overlapping FSC product that was acquired
70 on the same day, resulting in a maximal distance of $10\sqrt{2}$ m between the pixel center and the station. If there were more than one
71 matching FSC product on the same day, we selected one whose nearest pixel was neither cloud nor no data. We also assessed the
72 impact of the quality layer on the performance. The QCFLAGS (quality control flags) layer provides bit-encoded quality flags to
73 identify lower quality retrievals e.g. due to low sun elevation, thin cloud cover, surface water (HR-S&I consortium, 2020b). Hence
74 we performed the same analysis as above by excluding all pixels with at least a non-zero quality flag, i.e. $QCFLAGS > 0$.

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76 **2.3 Stratification data**

77 We stratified the analysis using four external variables: tree cover density, land cover type, elevation and country of measurement.
78 The tree cover density (TCD) was obtained from Copernicus Land Monitoring Service. It was derived using Sentinel-2 data too
79 and is available at 20 m resolution with pixel values ranging from 0 to 100%. We used the 2015 product and partitioned the data
80 into 10 segments of equal TCD range. The land cover was obtained from the Copernicus Global Land Service version 3 (Buchhorn
81 et al., 2020). We used the 2018 discrete classification map where a pixel's label is the majority label from the fractional cover map.
82 The classes were regrouped into the following labels: closed or open forest, herbaceous vegetation or wetland, urban, water bodies,
83 snow and ice, shrubs, moss and lichen, bare and sparse vegetation, cropland, and open sea. The elevation was extracted from the
84 Copernicus global 30 m digital elevation model. We used it to partition our data into 11 segments. We excluded from the analysis
85 all pixels that were non-valid in at least one of the external datasets, so that the population sizes are equal for each stratification
86 variable.

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87 **2.4 Metrics**

88 The comparison between in situ/satellite matchups was performed by computing a confusion matrix and the derived false positive
89 (FP), false negative (FN), true positive (TP), true negative (TN), recall or fraction of successfully identified positives
90 (TP/(TP+FN)), precision (TP/(TP+FP)), accuracy ((TP+TN)/(TP+FP+FN+TN)), and kappa coefficient (κ).

91 **3 Results**

92 Figure 2 shows the evaluation of the snow/no-snow detection with in-situ data, and in particular the variation of the kappa
93 coefficient with the HS_0 threshold and corresponding confusion matrices. It indicates a good overall agreement between both
94 datasets with an accuracy of 94% and $\kappa = 0.80$ at $HS_0 = 0$. The kappa coefficient increases to 0.84 if low quality retrievals are
95 excluded. The optimal HS_0 is equal to 1 cm in both cases and used for the analysis with the stratification data. The false negative
96 rate is higher than the false positive rate (precision is 93% but recall is 78%). The exclusion of low quality data reduces the total
97 amount of available data points by 13% and increases the recall (82%) more than the precision (94%), meaning that more false
98 negative errors are avoided. Figure 3 shows that the best performances ($\kappa > 0.8$) are at locations of "urban", "cropland", "open
99 forest", "herbaceous vegetation" or "bare/sparse" land cover types. A lower performance ($\kappa \approx 0.6$) is evident for the "closed forest"
100 and "water body" class. The "shrubs" class has a very low performance ($\kappa \approx 0.1$) but there are only 13 snow values in the in situ
101 data. The analysis by TCD bins shows that performances tend to decrease as the forest cover increases, in agreement with the lower
102 accuracy for the "closed forest" land cover type. The snow detection is robust across elevations between 400 m and 2800 m with
103 kappa values above 0.7, but a higher proportion of false negative between 100 m and 400 m is observed; it is likely related to the
104 presence of dense forest at low elevation in nordic regions. The performances are also shown for the countries with at least 100
105 data points. Countries with more than 1000 data points (France, Germany, Italy and Turkey) have kappa scores above 0.75 except
106 Turkey. Finland and Norway, two high latitude countries and with more than 200 data points each, also have kappa scores equal
107 or above 0.75. Stratifying the results of all countries by month (supplementary Figure S1) indicates that the number of false
108 negatives is highest in December while the accuracy increases every month from January to April.

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112 **4 Discussion**

113 The results are in line with the previous evaluation with an accuracy of 94% and a kappa of 0.8 and an optimal snow depth threshold
114 of 1 cm close to the previously reported 2 cm (Gascoïn et al., 2019). This value is very low, ten times lower than the one that can
115 be obtained with MODIS data (Klein and Barnett, 2003; Gascoïn et al., 2015). This suggests that Sentinel-2 is much more sensitive
116 to thin snow cover due to its higher spatial resolution which reduces the prevalence of mixed pixels. We also find that the proportion
117 of FN is larger than the proportion of FP, indicating that the HRSI snow products are more likely to omit a snow pixel than to
118 falsely classify a pixel as snow covered at the stations locations. This study demonstrates that this effect can be partly attributed to
119 the adverse effect of the forest canopy on snow detection as the number of false negatives is higher in the closed forest land cover
120 type. However, the results also show that this tendency for underdetection is present across nearly all subcategories, suggesting
121 that this limitation is not only due to land cover. The lower performance in winter indicates that it may be a consequence of the
122 low signal-to-noise ratio in Sentinel-2 radiances during the periods of low solar elevation angle. The lower proportion of FP than
123 FN in this study also suggests that the occurrence of false snow detection in large clouds that was visually identified in the previous
124 evaluation (Gascoïn et al., 2019) is actually not be the main issue to focus on in order to improve the product accuracy.

125 **5 Conclusion**

126 This brief communication reports on the performance of the HRSI snow classification based on a year of in situ snow depth data.
127 Although the in situ dataset is unbalanced with about four times more no-snow values than snow values, it is sufficiently large to
128 have thousands of observations in the two categories. It is also well distributed across Europe, as we obtained hundreds of
129 observations in many subcategories (country, land cover, elevation, and tree cover density). This dataset therefore allows drawing
130 more robust conclusions than previously on the performance of the MAJA-LIS algorithm to detect the snow cover. We conclude
131 that Sentinel-2-derived HRSI snow products are sufficiently reliable to study snow cover variations across the variety of European
132 landscapes from the northernmost Arctic regions to the southern semiarid mountains, excluding the densest forest regions.
133 Although the evaluation dataset spans only one year of data, its large geographical scale compensates for its short duration. Further
134 progress would result from a wider public availability of in situ snow cover data in the future over extended periods, including
135 additional sources of data (e.g. citizen science observations, webcam-based snow cover observations, higher resolution satellite
136 observations, etc.).

137 **Data availability**

138 The FSC products are available from the Copernicus Land website (<https://land.copernicus.eu/pan-european/biophysical-parameters/high-resolution-snow-and-ice-monitoring>). The TCD product is also available from Copernicus Land
139 (<https://land.copernicus.eu/pan-european/high-resolution-layers/forests/tree-cover-density>). The SYNOP data are available upon
140 request to the authors. The Alps data providers are Météo France, Deutscher Wetterdienst, Agenzia regionale per la protezione
141 dell'ambiente (ARPA) Friuli Venezia Giulia - Osservatorio Meteorologico Regionale e Gestione Rischi Naturali, ARPA
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144 **Author contribution**

145 CRediT contributor roles taxonomy. Conceptualization: SG, Data curation: ZBD, MD, Formal analysis: ZBD, Funding acquisition:
146 SG, OH, GS, MA, MD, SM, Investigation: ZBD, SG, Methodology: SG, Project administration: MA, FM, Resources: AD,

147 Software: RJ, GS, OH, ZBD, SG, AD, Supervision: SG, Validation: ZBD, Visualization: ZBD, Writing – original draft preparation:
148 ZBD, SG, Writing – review & editing: ZBD, SG, SM, MD, FM, OH.

149 **Competing interests**

150 The authors declare that they have no conflict of interest.

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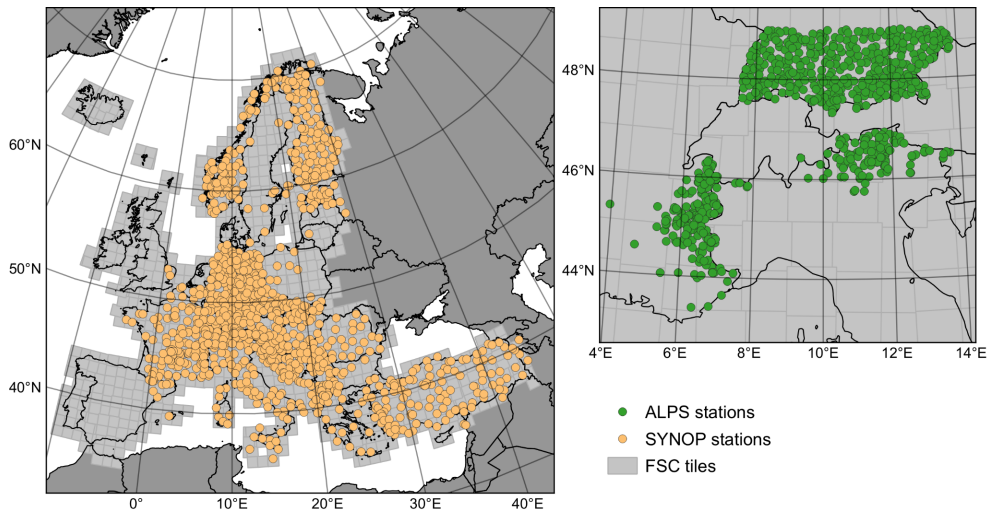
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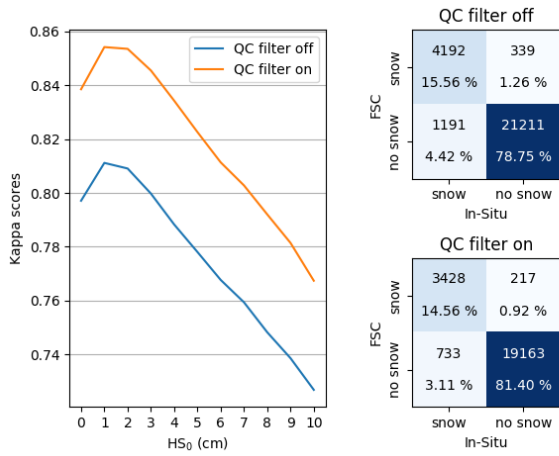
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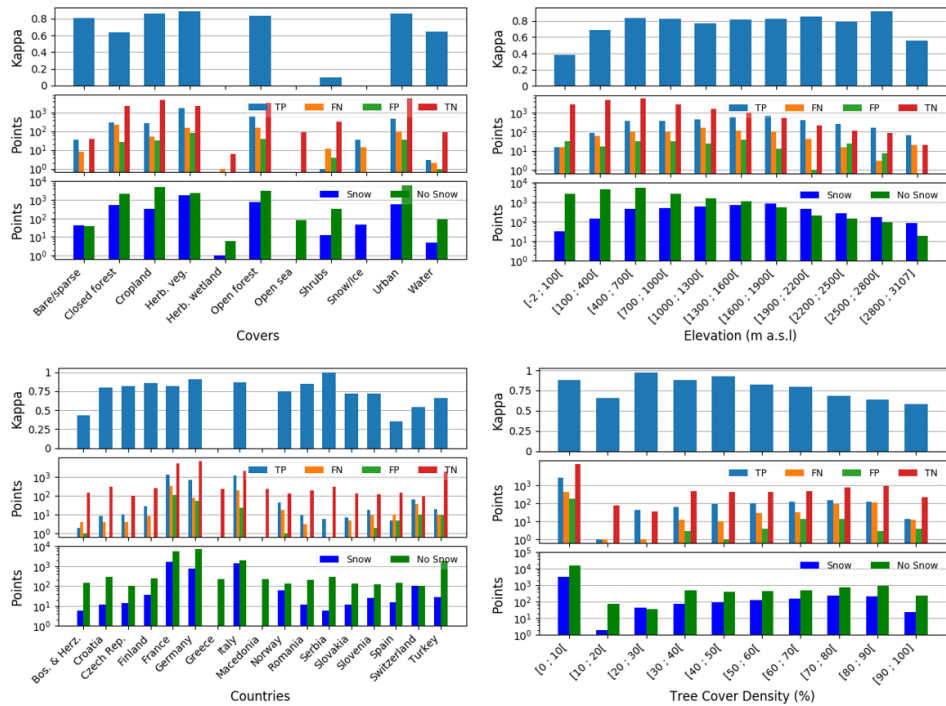
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211 **Figure 1.** Map of the study area and location of the in situ measurements. Each FSC (fractional snow cover) tile covers an area of 5490
 212 by 5490 pixels of 20 m resolution.
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215 **Figure 2.** Evaluation of the snow/no-snow detection with in situ data. Variation of the kappa coefficient with the HS_0 threshold and
 216 confusion matrices with and without data flagged as low quality (using $HS_0 = 1$ cm). QC filter on/off indicate whether the retrievals were
 217 filtered using the corresponding QCFLAGS layer or not.



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Figure 3: Results of the evaluation by strata of land cover, elevation, countries and Tree Cover Density. Each subplot shows three histograms for each stratification variable. The histograms represent, from top to bottom respectively, the kappa, the amount of TP (true positive), FN (false negative), FP (false positive) and TN (true negative) on a logarithmic scale and the amount of in situ snow (TP + FN) and no-snow (FP + TN) on a logarithmic scale for each strata. A kappa score of zero happens when there are zero snow observations or zero no-snow observations for either the HRSI FSC or the reference dataset. For example, we get a kappa of zero in Greece despite the results being all true negatives.