

A simple model of mélange buttressing for calving glaciers

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Abstract. Both ice sheets on Greenland and Antarctica are discharging ice into the ocean. In many regions along the coast of the ice sheets, the icebergs calve into a bay. If the addition of icebergs through calving is faster than their transport out of the embayment, the icebergs will be frozen into a mélange with surrounding sea ice in winter. In this case, the buttressing effect of the ice mélange can be considerably stronger than any buttressing by mere sea ice would be. This in turn stabilizes the glacier terminus and leads to a reduction in calving rates. Here we propose a simple model of ice mélange buttressing which leads to an upper bound on calving rates and can be used in numerical and analytical modeling.

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1 Introduction

Ice sheets gain mass by snowfall and freezing of sea water and lose mass through calving of icebergs and melting at the surface and the bed. Currently the ice sheets on Antarctica and Greenland have a net mass loss and contribute increasingly to sea level rise (Rignot et al., 2014; Shepherd et al., 2018b; WCRP Global Sea Level Budget Group, 2018; Eric Rignot, 2019; Mouginot et al., 2019). The ice sheet's future mass loss is important for sea level projections (Church et al., 2013; Ritz et al., 2015; Golledge et al., 2015; DeConto and Pollard, 2016; Mengel et al., 2016; Kopp et al., 2017; Slangen et al., 2017; Golledge et al., 2019; Levermann et al., 2020).

For the Greenland ice sheet, calving accounted for two-thirds of the ice loss between 2000 and 2005, while the rest was lost due to enhanced surface melting (Rignot and Kanagaratnam, 2006). Because surface melt increased faster than glacier speed, calving was responsible for a third of the mass loss of the Greenland ice sheet between 2009 and 2012 (Enderlin et al., 2014). In the future, enhanced warming (Franco et al., 2013) and the melt elevation feedback (Weertman, 1961; Levermann and Winkelmann, 2016) will further increase surface melt but also intensify the flow of ice into the ocean. Calving accounts for roughly half the ice loss of the Antarctic ice shelves, the rest is lost by basal melt (Depoorter et al., 2013).

It is clear that calving plays an important role in past and present ice loss and is therefore very likely to play an important role for future ice loss. However, by just calving off icebergs into the ocean and considering them eliminated from the stress field

of the ice-sheet-ice-shelf system, most studies neglect the buttressing effect of a possible ice mélange, which can form within the embayment into which the glacier is calving. This study provides a simple parametrization that accounts for the buttressing effect of ice mélange on calving on a large spatial scale and that can be used for continental scale ice sheet modeling. Such simulations are typically run on resolutions of several kilometres and over decadal to millennial timescales.

5 Any mélange parameterization needs to be combined with a large-scale calving parameterizations of which there are some. Benn et al. (2007) proposed a crevasse-depth calving-criterion assuming that once a surface crevasse has reached the water level, an iceberg calves off. This does not give a calving rate but rather the position of the calving front with the assumption that ice in front calved off. It has been implemented in a flow-line model by Nick et al. (2010). Levermann et al. (2012) proposed a strain rate dependent calving rate for ice shelves. Morlighem et al. (2016) proposed a calving rate parametrization based on
10 von Mises stress and glacier flow velocity. Mercenier et al. (2018) derived a calving rate for a grounded glacier based on tensile failure.

In addition to calving caused by crevasses, another calving mechanism called cliff calving has first been proposed by Bassis and Walker (2011), who found that ice cliffs with a freeboard (ice thickness minus water depth) larger than 100 m are inherently unstable due to shear failure. Cliff calving was implemented as an almost step-like calving rate by Pollard et al. (2015);
15 DeConto and Pollard (2016), while Bassis et al. (2017) implemented cliff calving as a criterion for the calving front position. Finally, Schlemm and Levermann (2019) derived a cliff calving rate dependent on glacier freeboard and water depth by analyzing stresses close to the glacier terminus and using a Coulomb failure criterion.

Mélange buttressing is likely to have a stabilizing effect on possible ice sheet instabilities. First, the so-called Marine Ice
20 Sheet Instability (MISI) (Mercer, 1978; Schoof, 2007; Favier et al., 2014) can unfold if the grounding line is situated on a reverse-sloping bed. Secondly, if the ice shelves buttressing the grounding line have disintegrated due to calving or melting and large ice cliffs become exposed, runaway cliff calving might lead to the Marine Ice Cliff Instability (MICI) (Pollard et al., 2015). DeConto and Pollard (2016) carried out past and future simulations of the Antarctic ice sheet with cliff calving implemented as a step function with a discussed but rather ad-hoc upper limit of 5 km/a as well as an additional hydrofracturing process that at-
25 tacks the ice shelves. Edwards et al. (2019) did further analysis and compared the simulations of mid-Pliocene ice retreat (about 3 million years ago), where sea level was 5 – 20 m higher than present day, to observations. Given the uncertainty in many ice sheet parameters, uncertainties in air and ocean temperature forcing as well as uncertainty in determining Pliocene sea-level, agreement between simulations and observations could be achieved even without MICI. Calving rates larger than 5 km/a were not considered, but it is clear that using one of the recently derived calving parametrizations with calving rates up to at least
30 65 km/a (see fig. 1) would result in too much and too fast ice retreat. An upper limit on the calving rates appears to be necessary.

So far, the calving rate cutoff has been an ad-hoc assumption. However, this upper limit should correspond to some physical process that is responsible for limiting calving rates. We propose that ice mélange, a mix of icebergs and sea ice that is found in many glacial embayments, gives rise to a negative feedback on calving rates.

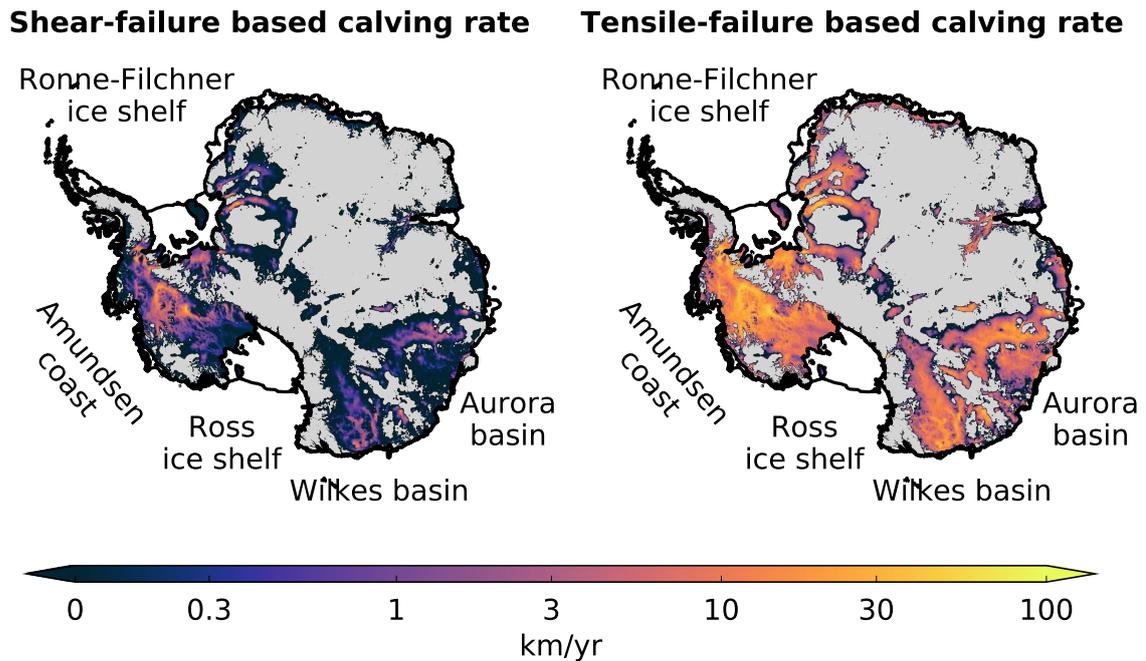


Figure 1. Potential shear-failure based calving rates (eq. 14) and tensile-failure based calving rates (eq. 13) in the grounded, marine regions of the Antarctic ice sheet. Floating ice is shown in white and grounded ice above sea level in grey. In the marine regions, ice is assumed to be at floatation thickness, which gives a minimal estimate of the potential calving rates. Estimates for shear calving rates go up to 65 km/a and estimates for tensile calving rates go up to 75 km/a. If the grounding line retreat is faster than the speed with which the glacier terminus thins to floatation, calving rates could be even larger. Imposing an upper bound on the calving rates is necessary to prevent unrealistic, runaway ice loss.

Observations in Store glacier and Jakobshavn glacier in Greenland have shown that in the winter, when sea ice is thick, ice mélangé prevents calving (Walter et al., 2012; Xie et al., 2019). This has also been reproduced in modelling studies of grounded marine glaciers (Krug et al., 2015; Todd et al., 2018, 2019): Backstresses from the mélangé reduce the stresses in the glacier terminus thereby limiting crevasse propagation and reducing calving rates or preventing calving completely. There's a large uncertainty in the value of mélangé backstresses, values given in the literature range between 0.02 – 3 MPa (Walter et al., 2012; Krug et al., 2015; Todd et al., 2018). Mélangé backstress increases with L/W , the ratio of mélangé length to the width of confining channel (Burton et al., 2018; Amundson and Burton, 2018). The presence of pinning points where the mélangé grounds can also increase the backpressure. Seasonality of basal and surface melting and resulting thinning of the ice mélangé is another important parameter for mélangé backstress.

In addition to the reduced stresses caused by the backstress of the mélangé, the presence of mélangé prevents a full-thickness ice berg from rotating away from the terminus, even more so if the glacier is thicker than floatation thickness (Amundson et al., 2010). Tensile-failure based calving (Mercenier et al., 2018) is likely to produce full thickness icebergs and may be hindered

significantly by mélange. Shear-failure based calving (Schlemm and Levermann, 2019) is more likely to produce many smaller icebergs (breakup occurs through many small, interacting fractures at the foot of the terminus) and might be less influenced by mélange.

Ice mélange is also relevant for calving from ice shelves in Antarctica: the presence of mélange stabilizes rifts in the ice shelf and can prevent tabular icebergs from separating from the iceshelf (Rignot and MacAyeal, 1998; Khazendar et al., 2009; Jeong et al., 2016).

We propose a negative feedback between calving rate and mélange thickness: A glacier terminus with high calving rates produces a lot of icebergs, which become part of the ice mélange in front of the glacier. The thicker the mélange is, the stronger it buttresses the glacier terminus leading to reduced calving rates.

In section 2, we will show that with a few simple assumptions, this negative feedback between calving rate and mélange thickness leads to an upper limit on the calving rates. Application to two calving parametrizations and possible simplifications are discussed in section 4. Section 5 applies the mélange buttressed calving rates to an idealized glacier setup.

2 Derivation of an upper limit to calving rates due to mélange buttressing

Mélange can prevent calving in two ways: First, in the winter, additional sea ice stiffens and forcifies the mélange and can thus inhibit calving for example of Greenland glaciers (Amundson et al., 2010; Todd and Christoffersen, 2014; Krug et al., 2015). Secondly, a weaker mélange can still prevent a full-thickness iceberg from rotating out (Amundson et al., 2010) and thus prevent further calving.

Ice sheet models capable of simulating the whole Greenland or Antarctic ice sheet over decadal to millennial timescales cannot resolve the stresses at individual calving glacier termini and often do not resolve seasonal variations in forcing. Therefore, we need a model of mélange buttressed calving that is dependent on the geometries of the embayment and the ice sheet averaged over the year.

To this end, we start by assuming a linear relationship between mélange thickness and the reduction of the calving rate:

$$C = \left(1 - \frac{d_{cf}}{\gamma H}\right) C^*, \quad (1)$$

where C^* is a calving rate derived for an unbuttressed glacier terminus (Morlighem et al., 2016; Mercenier et al., 2018; Schlemm and Levermann, 2019) and C is the reduced calving rate caused by mélange buttressing. H is the ice thickness at the glacier terminus and d_{cf} is the mélange thickness at the calving front. In the absence of mélange, $d_{cf} = 0$, the calving rate is not affected. As the effective mélange thickness increases, the calving rate is reduced, and when the mélange thickness equals a specific fraction γ of the ice thickness H , calving is completely suppressed. The value of γ may depend on the stiffness and compactness of the mélange and on how fractured the calving front is.

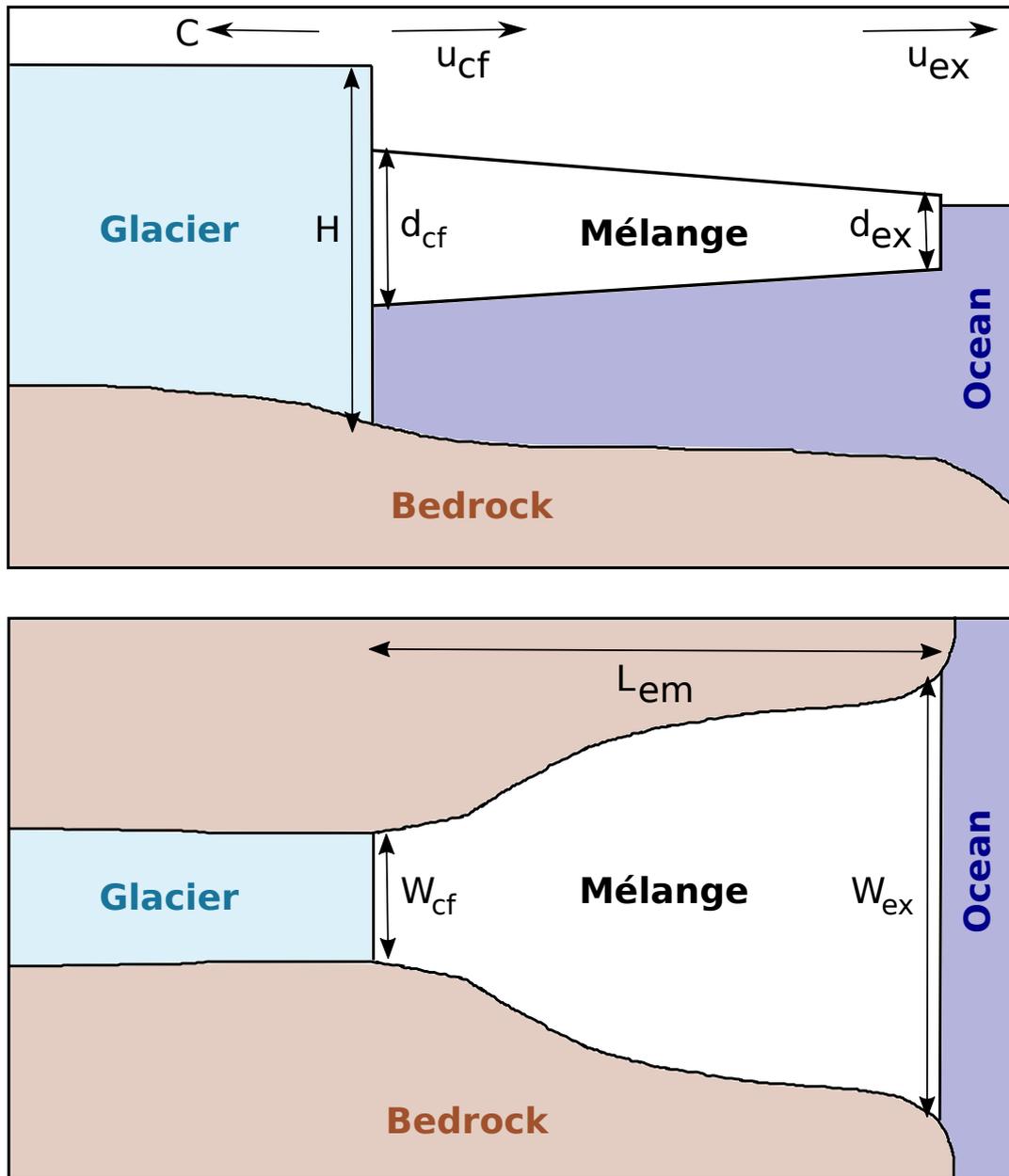


Figure 2. Geometry of the glacier terminus, ice mélange and embayment as a side view and a top view. The side view shows the ice thickness H , the calving front thickness d_{cf} and exit thickness d_{ex} of the ice mélange as well as the calving rate C and the mélange exit velocity u_{ex} . The plan view shows the embayment width at the calving front W_{cf} and the embayment exit width W_{ex} as well as the length of the embayment L_{em} .

H	ice thickness
C^*, C	unbuttressed and buttressed calving rates
γ	fraction of the ice thickness
d_{cf}	mélange thickness at the calving front
d_{ex}	mélange thickness at the embayment exit
\bar{d}	average mélange thickness
V	mélange volume
W_{cf}	embayment width at the calving front
W_{ex}	embayment width at the embayment exit
\bar{W}	average embayment width
L_{em}	embayment length
A_{em}	embayment area
u_{cf}	ice flow velocity at the calving front
u_{ex}	mélange exit velocity
m	mélange melt rate
β	mélange thinning gradient
μ_0	mélange internal friction
d_m	mélange thickness lost due to melting
a	inverse of C_{max}
C_{max}	upper limit on calving rates

Table 1. Overview over the variables used in sec. 2. The embayment and mélange geometry is illustrated in fig. 2

In order to estimate the effective mélange thickness d at the calving front, we assume a glacier terminating in an embayment already filled with ice mélange. Furthermore, we assume that the mélange properties are constant over the entire embayment and that the mélange thickness thins linearly along the flow direction (fig. 2).

The embayment area is given by A_{em} , its width at the calving front by W_{cf} and its width at the exit by W_{ex} . At the calving front, the glacier terminus has thickness H and is assumed to remain at a fixed position so that the calving rate C is equal to the ice flow u_{cf} . The mélange thickness at the calving front is given by d_{cf} . As the mélange thins on its way to the embayment exit, it has an exit thickness d_{ex} and an exit velocity u_{ex} at which mélange and icebergs are transported away by ocean currents. We consider a mélange volume $V = A_{em}\bar{d}$, where \bar{d} is the average mélange thickness. The overall rate of change of the mélange volume is given by:

$$10 \quad \frac{dV}{dt} = W_{cf}HC - W_{ex}d_{ex}u_{ex} - mA_{em} \quad (2)$$

where the first term corresponds to mélange production at the calving front, the second term corresponds to mélange exiting into the ocean and the third term corresponds to mélange loss through melting (assuming constant melt rate m throughout the embayment). Assuming a steady state of mélange production and loss resulting in a constant mélange geometry ($dV/dt = 0$),

we can solve eq. 2 for d_{ex} :

$$d_{ex} = \frac{W_{cf}HC - mA_{em}}{W_{ex}u_{ex}} \quad (3)$$

This equation only has a physical solution if $mA_{em} < W_{cf}HC$, which implies that melting is small enough that mélange actually reaches the embayment exit. Assuming a viscoplastic rheology of ice mélange, Amundson and Burton (2018) found that
 5 mélange thickness thinning along the embayment length is given by an implicit exponential function. A linear approximation gives

$$d_{cf} = \beta d_{ex}, \quad \beta = b_0 + b_1 \mu_0 L_{em} / \bar{W} \quad (4)$$

where μ_0 is the internal friction of the mélange, b_0 and b_1 are constants slightly larger than 1 and \bar{W} is the average embayment width (for more details see appendix A). Then the mélange thickness at the calving front is given as

$$10 \quad d_{cf} = aCH - d_m, \quad \text{with} \quad a = \frac{W_{cf}}{W_{ex}} \frac{\beta}{u_{ex}}, \quad d_m = \beta \frac{mA_{em}}{W_{ex}u_{ex}} \quad (5)$$

d_m is the mélange thickness lost to melting, a has the units of an inverse calving rate and will be related to the upper bound on calving rates in eq. 7. Inserting d_{cf} from eq. 5 into d in eq. 1, we get

$$C = \left(1 + \frac{d_m}{\gamma H}\right) \frac{C^*}{1 + \tilde{a}C^*}, \quad \text{with} \quad \tilde{a} = a\gamma^{-1} \quad (6)$$

Neglecting melting for simplicity we get

$$15 \quad C = \frac{C^*}{1 + \tilde{a}C^*} = \frac{C^*}{1 + C^*/C_{max}} \quad (7)$$

This function is linear, $C \approx C^*$, for small unbuttressed calving rates ($C^* \ll C_{max} = \tilde{a}^{-1}$) and the buttressed calving rate C saturates at an upper limit $C_{max} = \tilde{a}^{-1}$ for large unbuttressed calving rates ($C^* \gg C_{max} = \tilde{a}^{-1}$). This means that the parameter \tilde{a} can be considered as the inverse maximum calving rate, $C_{max} = \tilde{a}^{-1}$, which is dependent on the embayment geometry, mélange flow properties and the embayment exit velocity. Including melt of the mélange leads to higher calving rates, because
 20 melting thins the mélange and weakens the buttressing it provides to the calving front.

Rather than imposing an upper bound on the calving rates as an ad hoc cut-off as done by DeConto and Pollard (2016); Edwards et al. (2019), mélange buttressing gives a natural upper bound on the calving rate which is reached smoothly. The value of the upper bound can be different for each glacier, depending on the embayment geometry, and may change seasonally
 25 in accord with mélange properties.

According to eq. 5 and eq. 7, the upper limit on calving rates is a function of embayment geometry and mélange properties,

$$C_{max} = \frac{W_{ex}}{W_{cf}} \left(b_0 + b_1 \mu_0 \frac{L_{em}}{\bar{W}} \right)^{-1} \gamma u_{ex} \quad (8)$$

Since C_{max} is proportional to W_{ex}/W_{cf} , embayments that become narrower at some distance from the calving front experience stronger mélangé buttressing and consequently have smaller upper limits than embayments that are widening towards the ocean. Also the longer the embayment is compared to the average embayment width (L_{em}/\bar{W}), the smaller the upper limit is, even though friction between the mélangé and the embayment walls has not been taken explicitly into account. Previous studies

5 have already shown this for the mélangé backstress (Burton et al., 2018; Amundson and Burton, 2018). Fast ocean currents or strong wind forcing at the embayment exit may lead to fast export of mélangé (fast exiting velocities u_{ex}) and hence reduced mélangé buttressing. The stronger the internal friction of the mélangé (μ_0), the larger the buttressing effect.

3 Beyond a steady-state solution

10 The mélangé buttressing model derived in section 2 assumes mélangé to be in a steady state with a fixed mélangé geometry. This implies a fixed calving front position. This assumption is not fulfilled if glacier retreat is considered. Therefore it is worthwhile to go beyond the steady-state solution.

If the mélangé geometry changes in time, the change in the mélangé volume can be expressed as:

$$\frac{dV}{dt} = \frac{d}{dt} \int_0^{L(t)} dx W(x) d(x, t) \quad (9)$$

15 where $L(t)$ is the distance between the the embayment exit and the calving front, $W(x)$ the width of the embayment at a distance x from the embayment exit, $d(x, t)$ is the mélangé thickness and the embayment exit is fixed at $x = 0$. This expression is equal to the sum of mélangé production and loss terms given in eq. 2. By applying the Leibniz integral rule to the volume integral of eq. 9 as well as rewriting the mélangé production and loss terms as functions of time and calving front position, eq. 2 becomes

$$20 \quad W_L H C - W_0 d_0 u_{ex} - m \int_0^L dx W(x) = W_L \beta d_0 \cdot \frac{d}{dt} L + \left(\int_0^L dx W(x) \right) \cdot \frac{d}{dt} (\beta d_0) \quad (10)$$

with $L = L(t)$, $H = H(L(t))$, $C = C(t)$, $d_0 = d(0, t)$, $W_0 = W(0)$, $W_L = W(L(t))$ and $\beta = \beta(L(t))$. The first three terms on the left hand side are the mélangé production through calving, the mélangé loss at the embayment exit and the mélangé melting, respectively, and the right hand side is the rewritten volume integral. This differential equation for $d(0, t)$ can be solved if the embayment geometry $W(x)$ as well as ice thickness at the calving front $H(L(t))$ are known, the calving rate $C(t)$ is given by

$$25 \quad C(t) = \left(1 - \frac{\beta(L(t))d(0, t)}{\gamma H(L(t))} \right) C^* \quad (11)$$

and the change rate of the embayment length, $L(t)$, is given by

$$\frac{d}{dt} L(t) = C(t) - u_{cf}(t) \quad (12)$$

where the ice flow velocity at the calving front, $u_{cf}(t)$, depends on the bed topography and the ice dynamics.

We will now consider an idealized setup with constant ice thickness, $H(x) = H$, as well as constant embayment width, $W(x) = W$, while neglecting ice flow by setting $u_{cf} = 0$. Eqs. 10 - 12 are solved numerically for the parameter values $H = 1000$ m, $W = 10$ km, $\mu = 0.3$, $\gamma = 0.2$, $C^* = 3$ km/a, $u_{ex} = 100$ km/a, $b_0 = 1.11$, $b_1 = 1.21$, and the initial conditions $L(0) = 10$ km and $d(0) = 10$ m. We consider a scenario without *mélange* melting, $m = 0$, and a scenario with *mélange* melting, where the melt rate is set to $m = 10$ m/a.

The solutions for *mélange* length, $L(t)$, *mélange* thickness at the embayment exit, $d(0, t)$, *mélange* thickness at the calving front, $d(L(t), t)$, and the resulting buttressed calving rate, $C(t)$ are shown in fig. 3. In the scenario without melting, *mélange* length and thickness at the calving front increase, while *mélange* thickness at the embayment exit and buttressed calving rate decrease. If melting of *mélange* is considered, the *mélange* thickness at the calving front increases initially, and then decreases until the embayment is *mélange*-free, since the volume of *mélange* melted increases with *mélange* area.

A comparison between these solutions, where the *mélange* geometry is free to evolve, and the corresponding steady-state solution for *mélange* thickness at the calving front and the calving front, obtained by plugging the *mélange* length, $L(t)$, into eq. 5 and 6, respectively, shows good agreement (see bottom panels of fig. 3). The initial conditions chosen do not correspond to a steady-state solution, but the *mélange* equilibrates quickly, with the free evolution solution reaching the steady state solution in less than six months of simulation time, and follows it closely in the remaining time considered. This justifies the adaptive approach discussed in section 5.2.

4 Application to stress-based calving parametrizations

Bassis and Walker (2011) showed that ice cliffs with a glacier freeboards (ice thickness minus water depth) exceeding ≈ 100 m are inherently unstable due to shear failure. However, smaller ice cliffs calve off icebergs as well. Mercenier et al. (2018) derived a tensile-failure based calving parametrization for calving fronts with freeboards below this stability limit, while Schlemm and Levermann (2019) derived a shear-failure based calving parametrization for calving fronts with freeboards exceeding the stability limit.

4.1 Tensile-failure based calving

A calving relation based on tensile failure was derived by Mercenier et al. (2018) who used the Hayhurst stress as failure criterion to determine the position of a large crevasse that would separate an iceberg from the glacier terminus and calculated the timescale of failure using damage propagation. The resulting tensile calving rate is given by

$$C_t^* = B \cdot (1 - w^{2.8}) \cdot ((0.4 - 0.45(w - 0.065)^2) \cdot \rho_i g H - \sigma_{th})^r \cdot H \quad (13)$$

with effective damage rate $B = 65 \text{ MPa}^{-r} \text{ a}^{-1}$, stress threshold for damage creation $\sigma_{th} = 0.17 \text{ MPa}$, constant exponent $r = 0.43$, ice density $\rho_i = 1020 \text{ kgm}^{-3}$, gravitational constant $g = 9.81 \text{ ms}^{-2}$ and the relative water depth, $w = D/H$. This calving

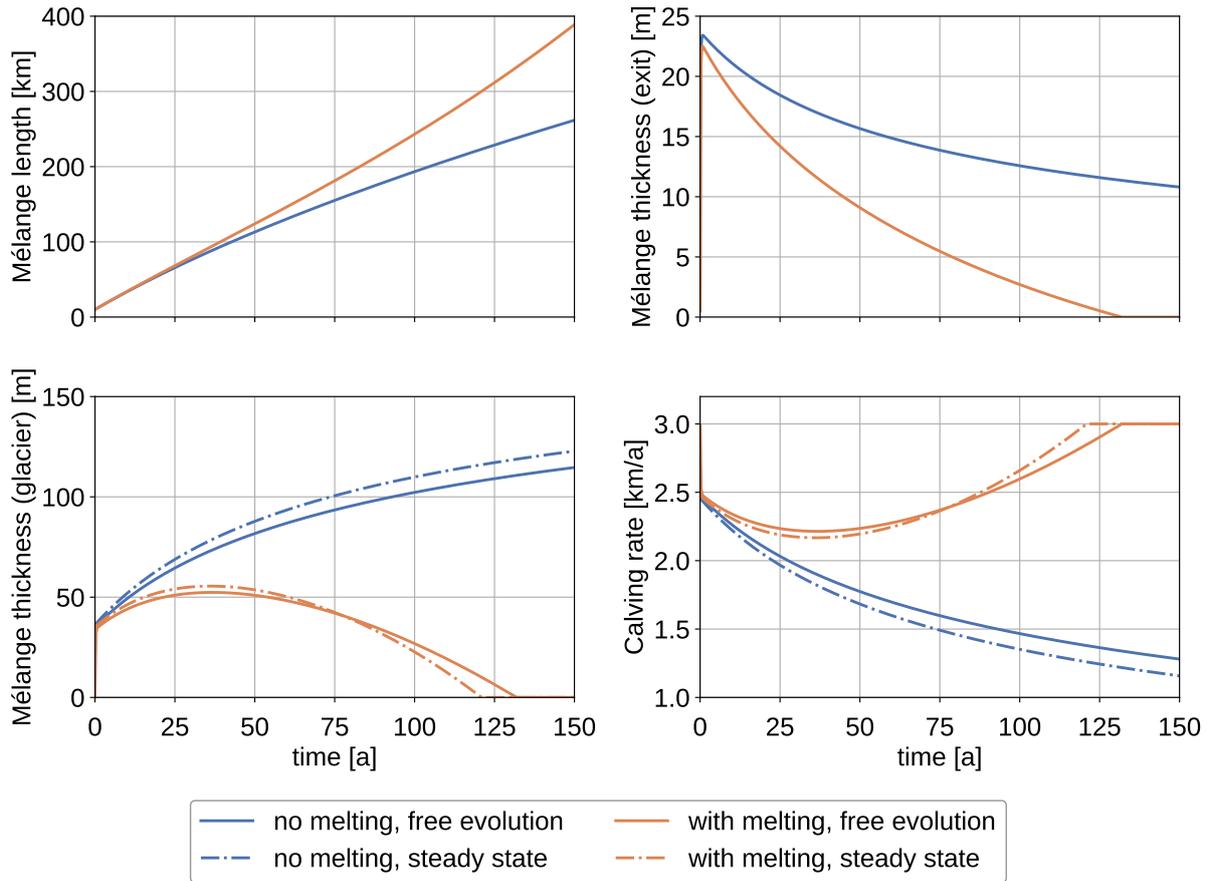


Figure 3. Top row panels show the numerical solutions of mélangé length, $L(t)$, and mélangé thickness at the embayment exit, $d(0, t)$, given by eqs. 10 - 12.. Two scenarios are considered: without melting (blue line) and with melting (orange). The bottom panels show the mélangé thickness at the calving front, $d(L(t), t)$, and the resulting buttressed calving rate, $C(t)$. The solution with free evolution of the mélangé geometry (continuous line) is contrasted with the steady-state solution obtained by plugging the mélangé length, $L(t)$, into eq. 5 and 6, respectively, (dashed line).

relation was derived for glacier fronts with a glacier freeboard smaller than the stability limit.

4.2 Shear-failure based calving

An alternative calving relation based on shear failure of an ice cliff was derived in Schlemm and Levermann (2019), where shear failure was assumed in the lower part of an ice cliff with a freeboard larger than the stability limit. The resulting shear

calving rate is given by:

$$C_s^* = C_0 \cdot \left(\frac{F - F_c}{F_s} \right)^s \quad (14)$$

$$F_s = \left(114.3(w - 0.3556)^4 + 20.94 \right) \text{ m} \quad (15)$$

$$F_c = (75.58 - 49.18w) \text{ m} \quad (16)$$

$$s = 0.1722 \cdot \exp(2.210w) + 1.757 \quad (17)$$

with relative water depth $w \equiv D/H < 0.9$ and glacier freeboard $F \equiv H - D = H \cdot (1 - w)$. F_c is the critical freeboard above which calving occurs, F_s is a scaling parameter and s a nonlinear exponent. The scaling parameter C_0 is given as $C_0 = 90 \text{ ma}^{-1}$, but this value is badly constrained and therefore C_0 can be considered a free parameter which parametrizes the uncertainty in the time to failure. This calving law assumes that there is no calving for freeboards smaller than the critical freeboard $F < F_c$.

Plugging the calving relation, eq. 14, into the mélange buttressed calving rate given by eq. 7 and expanding, it can be shown that the value of the upper bound C_{max} has a greater influence on the resulting calving rates than the scaling parameter C_0 : Let's call the dimensionless freeboard-dependent part of the cliff calving relation

$$\tilde{C}_s = \left(\frac{F - F_c}{F_s} \right)^s, \quad (18)$$

then the buttressed calving rate is

$$C_s = \frac{\tilde{C}_s}{\frac{1}{C_0} + \frac{\tilde{C}_s}{C_{max}}} \quad (19)$$

Then if $1 \ll \tilde{C}$

$$C_s = C_{max} - \frac{C_{max}^2}{\tilde{C}C_0} \quad (20)$$

For small \tilde{C} the choice of scaling parameter C_0 influences the final calving rate C , but for large \tilde{C} , the upper bound C_{max} determines the resulting calving rate. Since the scaling parameter C_0 is difficult to constrain and has little influence on the mélange buttressed calving rate, it makes sense to use a fixed value, e.g. $C_0 = 90 \text{ ma}^{-1}$, and treat only the upper bound C_{max} as a free parameter (which is dependent on the embayment geometry and mélange properties).

4.3 Comparison of the calving parametrizations

A comparison of the two stress-based calving rates can be divided into four parts (see fig. 4a):

1. According to the calving parametrizations considered here (eq. 13 and eq. 14), glacier fronts with very small freeboards ($< \approx 20 \text{ m}$) do not calve.

2. For glacier freeboards below the stability limit of ≈ 100 m, there is only tensile calving with calving rates up to ≈ 10 km/a and no shear calving.
3. Above the stability limit, shear calving rates increase slowly at first but speed up exponentially and equal the tensile calving rates at freeboards between 200 – 300 m and calving rates between 15 – 60 km/a. There is a spread in these values because both calving rates depend on the water depth as well as the freeboard.
4. For even larger freeboards, shear calving rates have a larger spread than tensile calving rates and much larger values for cliffs at floatation.

A comparison of the buttressed calving rates can be classified in the same way (see fig. 4b-d) where the only difference is that large calving rates converge to a value just below the upper limit C_{max} and hence the difference between tensile and shear calving rates for large freeboards is smaller.

Summarizing, there are two different calving parametrizations, based on tensile and shear failure and derived for glacier freeboards below and above the stability limit, respectively. It might seem obvious that one should simply use each calving law in the range for which it was derived. However, that would lead to a large discontinuity in the resulting calving rate because the tensile calving rate is much larger at the stability limit than the shear calving rate. Another possibility is to use each parametrization in the range for which it gives the larger calving rate. Since it is likely that in nature large ice cliffs fail due to a combination of failure modes, it also seems reasonable to use a combination of tensile and shear calving rates.

In the context of the Marine Ice Cliff Instability (MICI) hypothesis, one would expect a sudden and large increase in calving rates for ice cliffs higher than the stability limit. Despite a nonlinear increase of calving rates in the unbuttressed case, neither of the two stress-based calving parametrizations (Mercenier et al., 2018; Schlemm and Levermann, 2019) nor a combination of them shows discontinuous behaviour at the stability limit.

4.4 Simplified calving relations

There are uncertainties in both calving laws because a dominating failure mode is assumed (shear and tensile failure, respectively), while in reality failure modes are likely to interact. Also, in the calving laws ice is assumed to be previously undamaged, whereas a glacier is usually heavily crevassed and therefore weakened near the terminus. In addition, shear calving has a large uncertainty with respect to the time to failure which leads to uncertainty in the scaling parameter C_0 . These uncertainties together with the observation that the upper limit C_{max} seems to have a stronger influence on resulting calving rates than the choice of calving law provide a good reason to consider simplifying these calving laws.

The important distinction between shear and tensile calving is that shear calving has a much larger critical freeboard: for small freeboards ($F < 100$ m), we have tensile calving but no shear calving. Since the mélange buttressed calving rate is linear in the calving rates for small calving rates, this distinction remains in the buttressed calving rates (see fig. 4). However, for larger

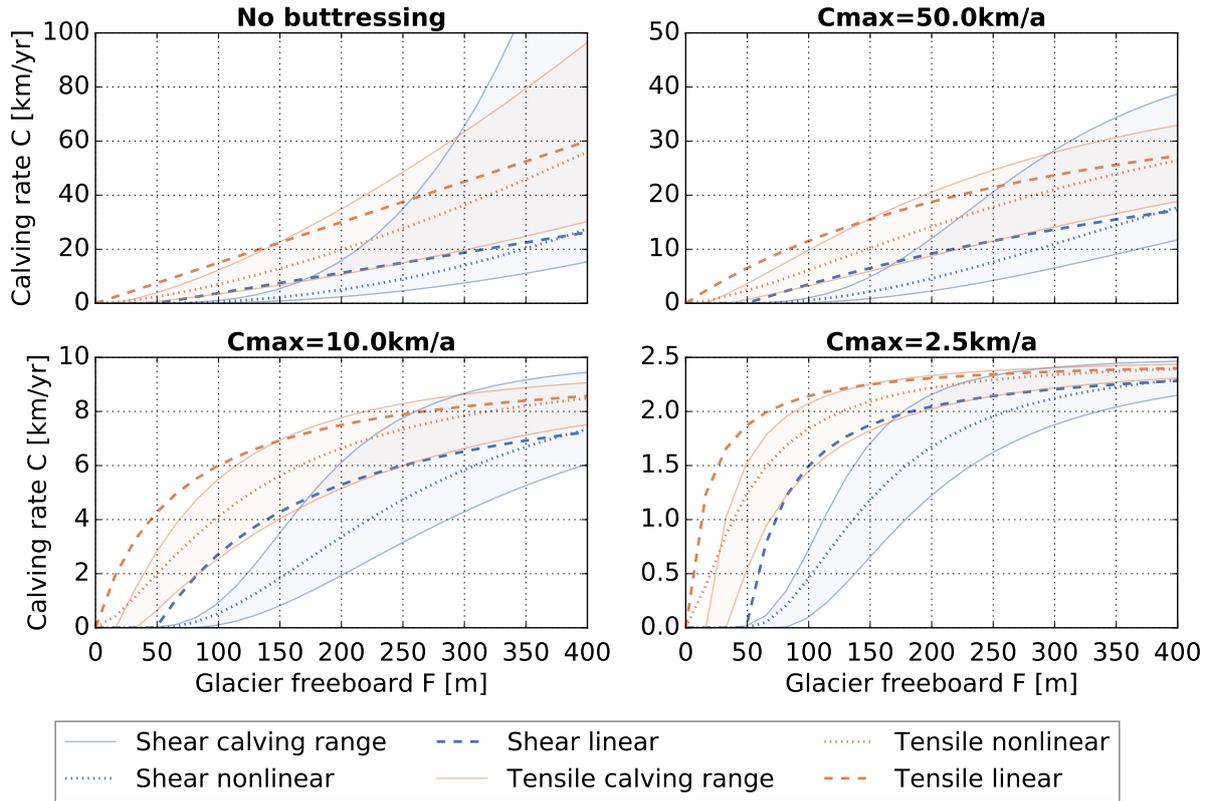


Figure 4. Calving rates as a function of glacier freeboard (ice thickness - water depth) in the unbuttressed case and for a range of upper bounds C_{max} . Shear calving and tensile calving rates depend also on the water depth: Two lines are shown for each configuration, the lower line for a dry cliff ($w = 0.0$) and the upper line for a cliff at floatation ($w = 0.8$). This spans the range of possible calving rates for a given freeboard. Also shown are the nonlinear (dotted line) and linear (dashed lines) approximations to these calving laws. In the tensile case, calving commences with freeboard $F=0$, while shear calving only happens for freeboards larger $F_c \approx 50$ m.

freeboards the calving rates approach the upper limit no matter which calving law was chosen. This distinction should be conserved in the simplified calving relations.

The dependence of the calving rate on water depth is important in the unbuttressed case (see fig. 4a): there's a large range between calving rates for the same freeboard and different relative water depths – that's because larger relative water depth implies a larger overall depth. For the same glacier freeboard, this means a larger ice thickness and therefore larger stresses in the ice column, implying a larger calving rate. But in the *mélange* buttressed case, large calving rates are more strongly buttressed than small calving rates. Thus the large range of possible calving rates for a given glacier freeboard is transformed into a much smaller range, so that water depth becomes less important. (see fig. 4b-d)

Therefore we consider simplifications of the calving relations where we average over the water depth and further simplify. This

is done mostly for illustrative purposes.

Take the shear calving relation:

$$C_s^* = C_0 \cdot \left(\frac{F - F_c}{F_s} \right)^s \quad (21)$$

- 5 where $C_0 = 90 \text{ m/a}$, $s(w) \in [1.93, 3.00]$, $F_c(w) \in [30.9, 75.0] \text{ m}$ and $F_s(w) \in [21.0, 31.1] \text{ m}$. In choosing round values within these intervals, we can simplify the relation.

$$C_{s,nonlin}^* = 90 \text{ m/a} \cdot \left(\frac{F - 50 \text{ m}}{20 \text{ m}} \right)^2 \quad (22)$$

- Because the exponent s is on the smaller end of the possible values we chose a smaller value for F_s to get an approximation that lies well within the range of the full cliff calving relation, though it lies at the lower end (see fig. 4). An even simpler linear
10 approximation

$$C_{s,lin}^* = 75 \text{ a}^{-1} \cdot (F - 50 \text{ m}) \quad (23)$$

overestimates the calving rates for small freeboards ($F < 200 \text{ m}$) and underestimates for large freeboards ($F > 600 \text{ m}$).

The tensile calving relation can be written as

$$15 C_t^* = a(w) (b(w)F - \sigma_{th})^{0.43} \cdot F \approx c \cdot F^{1.5} \quad (24)$$

and can be fitted with a power function

$$C_{t,nonlin}^* = 7 \text{ m}^{-0.5} \text{ a}^{-1} \cdot F^{1.5} \quad (25)$$

or a linear function

$$C_{t,lin}^* = 150 \text{ a}^{-1} \cdot F \quad (26)$$

- 20 Here we neglect the small offset in freeboard that tensile calving has. This gives us two kinds of simplified calving relations to compare: one that begins calving immediately and one that only calves off cliffs larger than a certain critical freeboard. For both we have a linear approximation that overestimates small calving rates, and a nonlinear approximation that lies well within the original spread of calving rates (see fig. 4).

5 Mélange buttressed calving in an idealized glacier setup

- 25 We consider a MISMIP+-like glacier setup (Cornford et al., 2020), that is symmetric about $x = 0$ and has periodic boundary conditions on the fjord walls. The glacial valley has an average bedrock depth of 200m and a width of 40 km and experiences

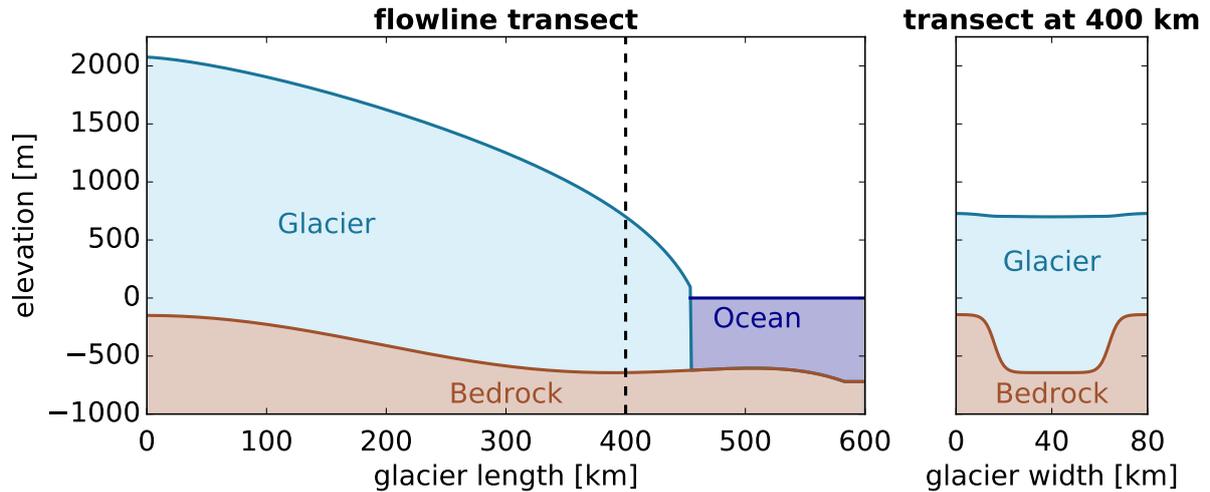


Figure 5. Setup of the idealized glacier experiments. Only one half of the setup is shown, the glacier is connected to an identical copy at the left to ensure periodic boundary conditions at the ice divide.

a constant accumulation of 1.5 m/a (see fig. 5). The setup has rocky fjord walls and where the bedrock wall is below sea level, there is grounded ice resting on it. This grounded ice does not retreat during the calving experiments and forms the embayment. Ice flow is concentrated in the middle of the channel where the bedrock is significantly deeper. Since there is no ice reservoir at the top of the glacier, this setup can also be considered as a model for a mountain glacier.

- 5 The experiments were done with the Parallel Ice Sheet Model (PISM) (Bueler and Brown, 2009; Winkelmann et al., 2011) which uses the shallow ice approximation (Hutter, 1983) and the shallow shelf approximation (Weis et al., 1999). We use Glen’s flow law in the isothermal case and a pseudoplastic basal friction law (the PISM authors, 2018).

A spin-up simulation was run until it reached a steady state configuration with an attached ice shelf. During the experiment phase of the simulation all floating ice is removed at each timestep. When the ice shelf is removed, the marine ice sheet instability (MISI) kicks in because of the slightly retrograde bed topography and the glacier retreats. Calving accelerates this retreat. Experiments were made with no calving (MISI only), mélange buttressed shear calving and its nonlinear and linear approximation as well as mélange buttressed tensile calving and its two approximations. The initial upper bound was varied $C_{max} = [2.5, 20.0, 50.0, 500.0]$ km/a where the last upper bound was chosen to be large enough that the calving rates nearly match the unbuttressed calving rates.

15 5.1 Constant upper bound on calving rates

In this experiment, the upper bound was kept constant even though the glacier retreated and embayment length increased. The buttressing eq. 7 was derived assuming a steady-state mélange geometry which implies a fixed calving front. Therefore applying it to a situation where a glacier retreats as done in the simulations described here is illustrative rather than predictive.

Fig. 6 shows the simulated glacier retreat. Even without calving in the MISI only experiment, there is a significant retreat after removing the ice shelves because of the buttressing loss and slightly retrograde bed of the glacier. The glacier retreats from a front position at 440km to 200km in the first 100 years, after which the retreat decelerates and the glacier stabilizes at a length of about 130km. Adding calving leads to additional retreat: the higher the upper bound on the calving rates, the faster the retreat.

Shear calving causes less additional retreat than tensile calving because it has small calving rates for freeboards below 150m. Since the channel is rather shallow the freeboards are generally small. Only the linear approximation of shear calving has a significant ice retreat because even though it starts only with a freeboard of 50m, it grows much faster than the actual shear calving or the nonlinear approximation. But it also reaches a stable glacier position when the ice thickness is smaller than the critical freeboard condition.

The assumption of tensile calving causes the glacier to retreat much faster. The linear approximation, which has higher calving rates for small freeboards, leads to a faster retreat. For the nonlinear approximation the glacier is close to floatation for most of its retreat which corresponds to the upper half of the tensile calving range. This approximation gives smaller calving rates and hence slower retreat. None of the tensile calving relations allow the glacier to stabilize. That is to say the minimum freeboard below which an ice front is stable for shear calving is ultimately the stabilizing factor in these simulations.

Fig. 7 shows that the effect of *mélange* buttressing becomes relevant for small values of the export of ice out of the embayment, i.e. for small values of C_{max} . In this limit of strong buttressing, i.e. where the parameterization of equation 7 is relevant, the glacier retreat becomes almost independent of the specific calving parameterization.

5.2 An adaptive upper limit on calving rates

Assuming that *mélange* equilibration is faster than glacier retreat, the upper bound C_{max} can be calculated as a function of *mélange* length L_{em} . This is further justified by the discussion in section 3.

Here we assume that the position of the embayment exit remains fixed, so that the *mélange* length grows with the same rate with which the glacier retreats. We assume an initial upper bound $C_{max0} = [2.5, 20.0, 50.0, 500.0]$ km/a at $t = 0$, and update C_{max} each simulation year. We perform the same experiments as described above.

This adaptive approach leads to much smaller calving rates and slows down the glacier retreat significantly (compare fig. 8 to fig. 6). In the case with $C_{max0} = 10$ km/a and $C_{max0} = 2.5$ km/a, the adaptive approach prevents the complete loss of ice. Due to the increase in embayment length, the upper bound in calving rate is reduced to down to 30% of its original value (see fig. 9).

6 Conclusions

We considered *mélange* buttressing of calving glaciers as a complement to previously derived calving relations. The approach here is to provide an equation that uses simple and transparent assumptions to yield a non-trivial relation.

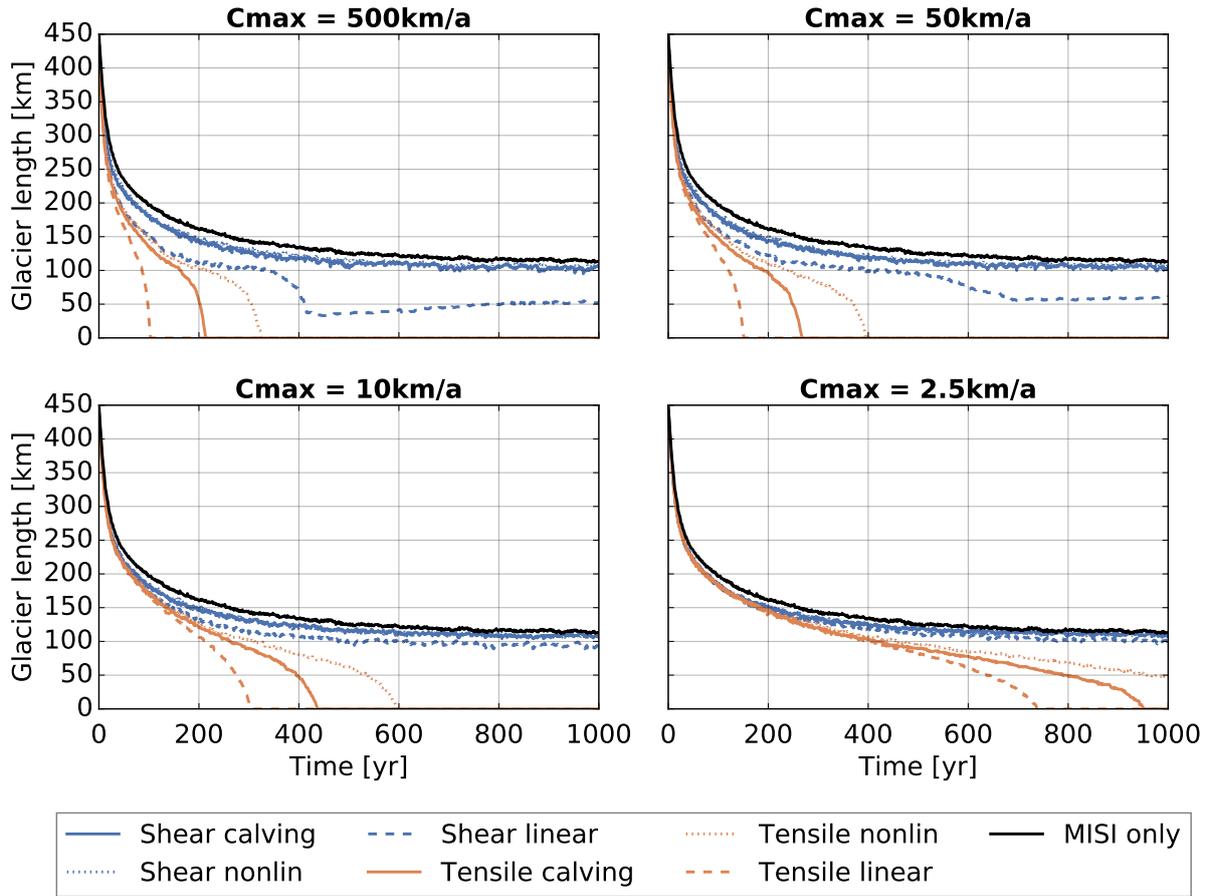


Figure 6. Glacier length timeseries. Upper left panel shows runs with an upper limit of $C_{max} = 500 \text{ km/a}$ which is essentially equivalent to the unbuttressed calving rates. Then we have decreasing upper limits and consequently the glacier retreat slows down.

The buttressing is described in form of a reduced calving rate which is a functional of the maximum calving rate as it is derived for the ice front without mélange buttressing. First, we assumed that calving rates decrease linearly with the mélange thickness. Secondly, we assume a steady state between mélange production through calving and mélange loss through melting and exit from the embayment. This implies a fixed calving front position. Using these two assumptions, we derived a mélange buttressed calving rate, eq. 7, that is linear for small calving rates and converges to an upper limit C_{max} , which depends on the embayment geometry, mélange flow properties and the embayment exit velocity.

We also went beyond the steady-state solution of mélange buttressing and considered an evolving mélange geometry. We found that mélange equilibration is faster than glacier retreat, which justifies the use of an adaptive approach in which the upper limit C_{max} is dependent on the mélange geometry.

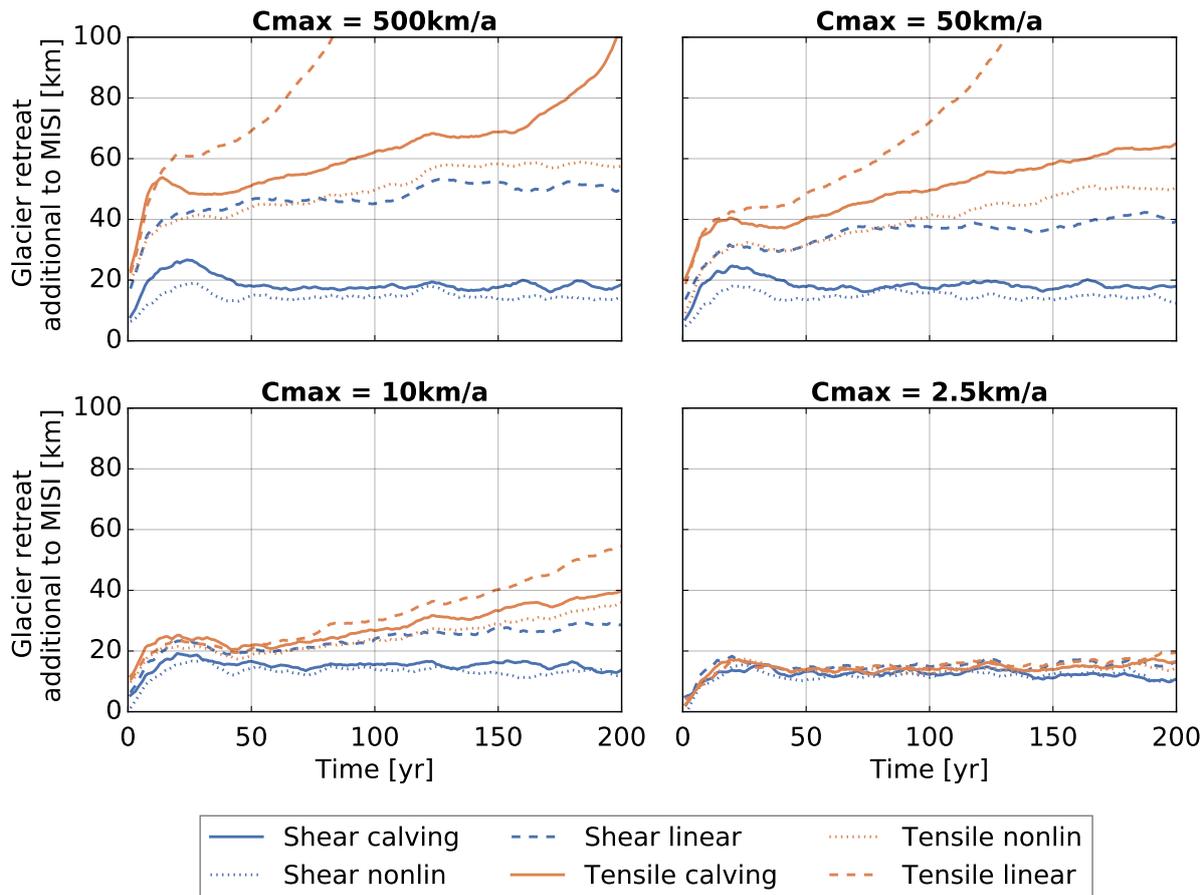


Figure 7. Timeseries of glacier retreat additional to the MISI retreat, i.e. retreat caused by calving.

This framework can be applied to any calving parametrization that gives a calving rate rather than the position of the calving front. We investigated its application to a tensile-failure based calving rate and to a shear-failure based calving rate. For small calving rates, the differences between the parametrizations persist in the buttressed case. However, large calving rates converge to the upper limit and the choice of calving parametrization becomes less important. This suggest that it is possible to simplify the calving parametrizations further, but we show that the simplifications differ for small calving rates and those differences persist.

We illustrated this with a simulation of an idealized glacier. Choice of calving parametrization and choice of upper limit determine the retreat velocity. Following the adaptive approach, glacier retreat leads to a larger embayment and hence larger mélange buttressing and smaller calving rates.

10

Embayment geometry plays an important role in determining how susceptible glaciers facing similar ocean conditions are to rapid ice retreat: Pine Island Glacier and Thwaites Glacier in West Antarctica face similar ocean conditions in the Amundsen

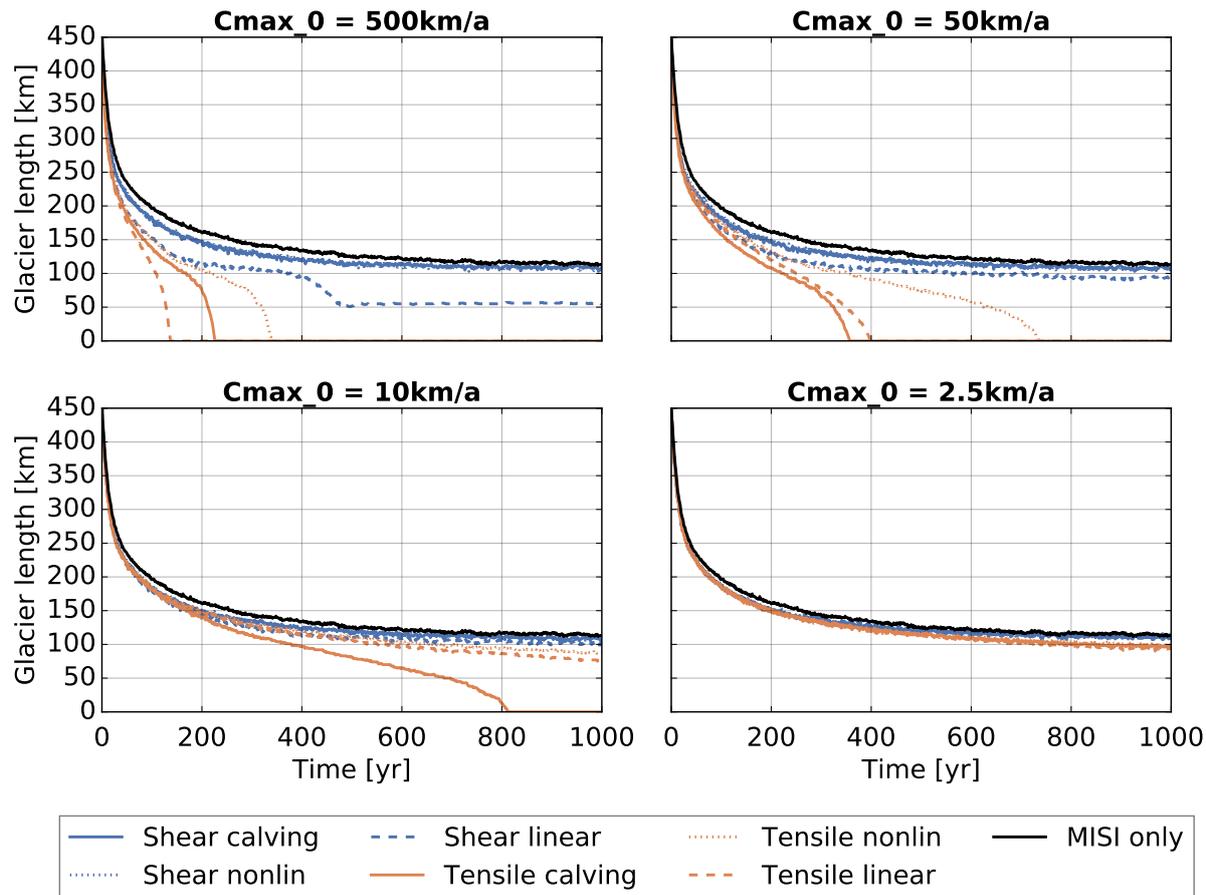


Figure 8. Glacier length timeseries with an adaptive calving limit.

Sea, where the warming ocean (Shepherd et al., 2004, 2018a) leads to the retreat and rifting of their buttressing ice shelves (Jeong et al., 2016; Milillo et al., 2019), and might be susceptible to both MISI and MICI. Pine Island terminates in an embayment about 45 km wide, currently filled by an ice shelf of roughly 60 km length. The upper part of the glacier lies in a straight narrow valley with a width of about 35 km (distances measured on topography and ice thickness maps provided by Fretwell et al. (2013)). If Pine Island glacier lost its current shelf, it would have a long and narrow embayment holding the ice mélangé and would therefore experience strong mélangé buttressing. In contrast, Thwaites glacier is more than 70 km wide and its ice shelf spreads into the open ocean. It has currently no embayment all and once it retreats, it lies in a wide basin that can provide little mélangé buttressing. Hence, Thwaites glacier has a much larger potential for large calving rates and runaway ice retreat (MICI) than Pine Island glacier.

10 Ocean temperatures off the coast of Antarctica are mostly sub-zero with $0.5 - 0.6^\circ\text{C}$ warming expected until 2200, while the ocean temperatures off the coast of Greenland are sub-zero in the north but up to 4°C in the south with an expected $1.7 - 2.0^\circ\text{C}$ warming until 2200 (Yin et al., 2011). This leads to increased mélangé melting in Greenland compared to Antarctica and there-

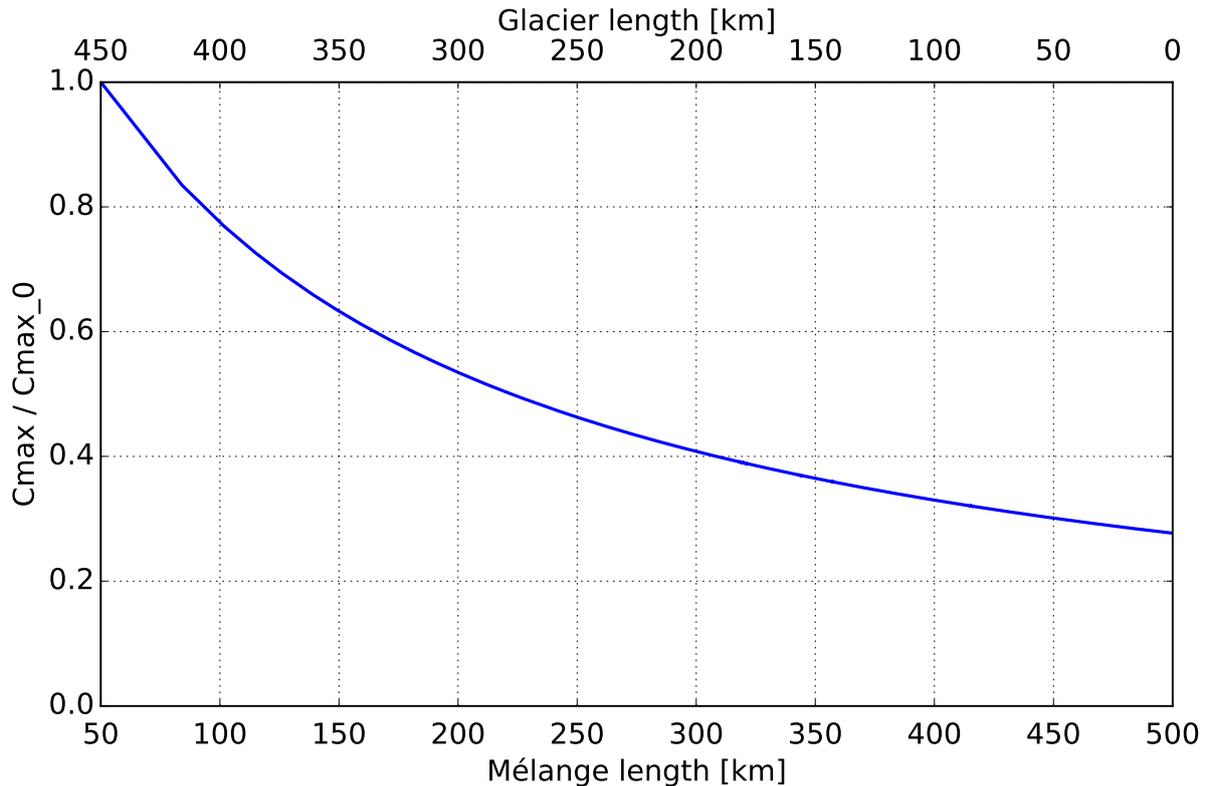


Figure 9. Reduction of the upper limit on calving rates as a function of mélange length and glacier length.

fore higher upper limits on calving rates in Greenland glaciers that have geometries comparable to Antarctic glaciers.

Future ocean warming and intrusion of warm ocean water under the ice mélange increases melting rates and the upper limit on calving rates. This could be another mechanism by which ocean warming increases calving rates.

- 5 The concept of cliff calving and a cliff calving instability is not without criticism. According to Clerc et al. (2019), the lower part of the glacier terminus where shear failure is assumed to occur (Bassis and Walker, 2011; Schlemm and Levermann, 2019) is actually in a regime of thermal softening with a much higher critical stress and thus remains stable for large ice thicknesses. Tensile failure may occur in the shallow upper part of the cliff and initiate failure in the lower part of the cliff (Parizek et al., 2019). The critical subaerial cliff height at which failure occurs depends on the timescale of the ice shelf collapse: for collapse
- 10 times larger than 1 day, the critical cliff height lies between (170 – 700 m) (Clerc et al., 2019).

The mélange buttressing model proposed here does not depend on the specific calving mechanism and it is not comprehensive especially since it is not derived from first principles but from a macroscopic perspective. The advantage of the equation proposed here is the very limited number of parameters.

Appendix A: Mélange thickness gradient

In sec. 2, the mélange thickness was assumed to thin linearly along the embayment length with $d_{cf} = bL_{em}d_{ex}$. Amundson and Burton (2018) give an implicit exponential relation for the mélange thickness:

$$d_{cf} = d_{ex} \exp\left(\mu_0 \frac{L_{em}}{W} + \frac{d_{cf} - d_{ex}}{2d_{cf}}\right) \quad (\text{A1})$$

- 5 where μ_0 is the coefficient of internal friction of the mélange and ranges from about 0.1 to larger than 1. The embayment width, W , is assumed to be constant along the embayment in Amundson and Burton (2018), here we can replace it with the average embayment width. In a linear approximation, eq. A1 becomes

$$d_{cf} = d_{ex} \left(1 + \mu_0 \frac{L_{em}}{W} + \frac{d_{cf} - d_{ex}}{2d_{cf}}\right) \quad (\text{A2})$$

This equation has one physical solution for d_{cf} :

$$10 \quad d_{cf} = d_{ex} \cdot \frac{1}{4} \left(3 + 2\mu_0 \frac{L_{em}}{W} + \sqrt{1 + 12\mu_0 \frac{L_{em}}{W} + 4 \left(\mu_0 \frac{L_{em}}{W}\right)^2}\right) \approx \beta d_{ex} \quad (\text{A3})$$

- The parameter β can be linearized to take the form given in eq. 4, where the parameters b_0 and b_1 are determined by the way of obtaining the linear approximation: Completing the square under the squareroot gives the asymptotic upper limit with $b_0 = 1.5$, $b_1 = 1.0$. Taylor expansion can be used to get a more accurate approximation around a specific value of $\mu_0 L/W$: expansion around $\mu_0 L/W = 0.5$ gives $b_0 = 1.11$, $b_1 = 1.21$ while expansion around $\mu_0 L/W = 1.0$ gives $b_0 = 1.17$, $b_1 = 1.11$. The
- 15 choice of linearisation parameters b_0 and b_1 should depend on the expected range of values for $\mu_0 L/W$. Fig A1 shows that each of the linear approximations given in the text overestimates β slightly but that it is possible to achieve a small error ($< 5\%$) over a rather large range of values for L/W .

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- 20 *Competing interests.* No competing interests

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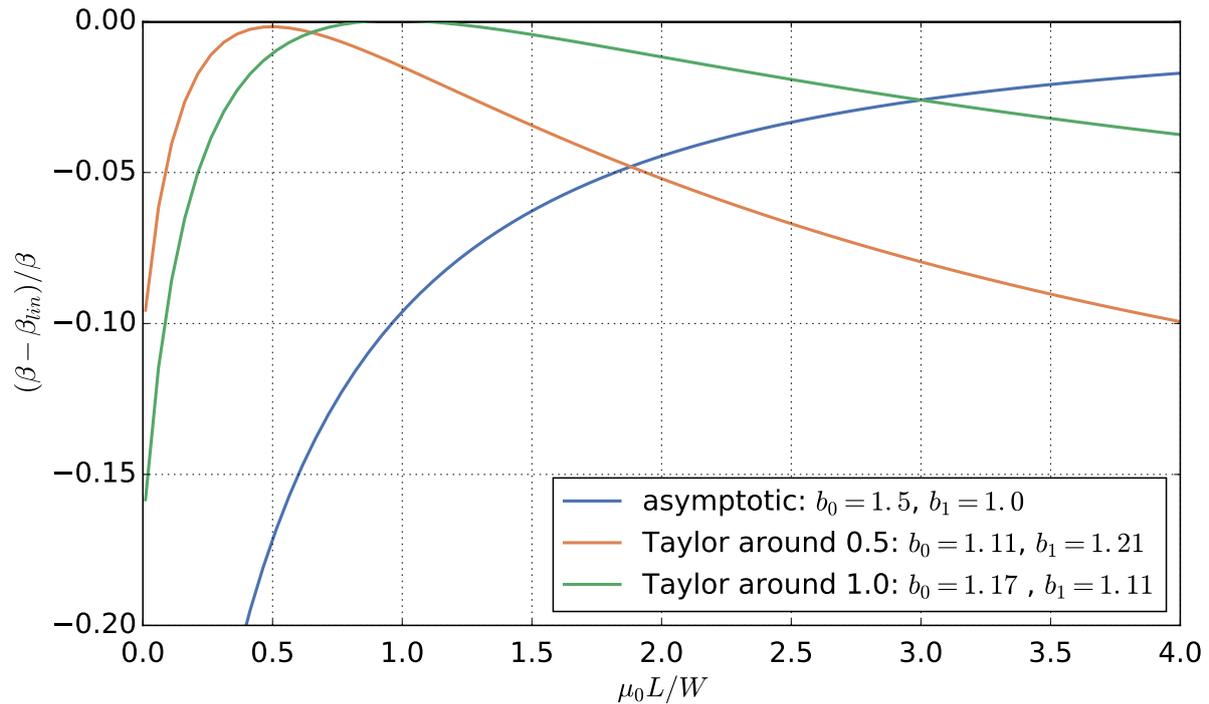


Figure A1. The relative difference between β given by eq. A3 and different linear approximations of β .

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