# Geodetic point surface mass balances: A new approach to determine point surface mass balances on glaciers from remote sensing measurements

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#### 17 Abstract

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19 Mass balance observations are very useful to assess climate change in different regions of the world. As opposed to glacier-wide mass balances, which are influenced by the dynamic response of each glacier, 20 point mass-balances provide a direct climatic signal that depends on surface accumulation and ablation 21 22 only. Unfortunately, major efforts are required to conduct in situ measurements on glaciers. Here, we 23 propose a new approach that determines point surface mass balances from remote sensing observations. 24 We call this balance the geodetic point surface mass balance. From observations and modelling performed on Argentière and Mer de Glace glaciers over the last decade, we show that the vertical ice 25 flow velocity changes are small in areas of low bedrock slope. Therefore, assuming constant vertical 26 27 velocities in time for such areas and provided that the vertical velocities have been measured for at least 28 one year in the past, our method can be used to reconstruct annual point surface mass balances from surface elevations and horizontal velocities alone. We demonstrate that the annual point surface mass 29 30 balances can be reconstructed with an accuracy of about 0.3 m w.e. a<sup>-1</sup> using the vertical velocities observed over the previous years and data from Unmanned Aerial Vehicle images. Given the recent 31 32 improvements of satellite sensors, it should be possible to apply this method to high spatial resolution 33 satellite images as well. 34

### 1. Introduction

36 Glacier surface mass balance observations are widely used to assess climate change in various climatic 37 38 regimes because of their sensitivity to climate variables [e.g. Zemp et al., 2019; Marzeion et al., 2014; Kaser et al., 2006; Gardner et al., 2013; Huss and Hock, 2018; IPCC, 2019]. In situ surface mass balance 39 40 measurements have been conducted on only a few of the 200,000 mountain glaciers worldwide [WGMS, 2017; Zemp et al., 2015]. In the European Alps, about a dozen annual surface mass balance time series 41 42 from *in situ* measurements extending over more than 50 years are available [WGMS, 2017]. Recently, 43 considerable efforts have been made to assess ice volume changes at the mountain-range scale over long 44 time periods using geodetic measurements obtained from remote sensing techniques [e.g. Paul and 45 Haeberli, 2008; Abermann et al., 2011; Gardelle et al., 2012; Gardner et al., 2013; Berthier et al., 2014; 46 Brun et al., 2017]. These geodetic methods determine glacier-wide volume changes, or glacier-wide 47 mass balances, by differencing repeated determinations of glacier surface elevations obtained from 48 airborne and spaceborne surveys, usually over multiyear to decadal periods [e.g. Vincent, 2002; Bauder et al., 2007; Soruco et al., 2009; Berthier et al., 2014; Dussaillant et al., 2019]. These methods are 49 effective to estimate the overall glacier mass change and quantify the related hydrological impacts or 50 51 sea level contribution [e.g. Hock et al., 2005; Kaser et al., 2010; Huss, 2011; Immerzeel et al., 2013; 52 Zemp et al., 2019]. However, the meaningfulness of a climatic interpretation of these results is 53 questionable. Indeed, glacier-wide mass balances are not solely driven by changes in climate but also 54 by changes in glacier geometry controlled by the dynamic response of each glacier [Vincent, 2002; Fischer et al., 2010; Abermann et al., 2011; Huss et al., 2012; Vincent et al., 2017]. Consequently, they 55 do not provide a direct climatic signal. On the other hand, point surface mass balances provide a direct 56 climatic signal which depends only on local ablation and accumulation (Huss and Bauder, 2009; Thibert 57 58 et al., 2013; Vincent et al., 2004, 2017, 2018b). Ablation is related directly to the surface energy balance. Accumulation is related to precipitation but is also strongly influenced by valley topography. Indeed, 59 glaciers are generally surrounded by very steep non-glacial slopes which capture precipitation over a 60 larger area than that of the glacier itself. In this way, high accumulation values are due to downhill 61 transportation and strong winds actions [Vincent, 2002]. Statistical modelling enables us to extract a 62 climatic signal from a heterogeneous in-situ observations of point mass balance networks independently 63 of effects related to ice flow dynamics and glacier area changes (Vincent et al., 2018b). However, these 64 previous studies showed that it is crucial to perform observations of point annual surface mass balance 65 66 at the same locations every year. Unfortunately, the only way to presently obtain point mass balance 67 data is to make *in situ* measurements. In particular, the net annual ablation in the ablation zone is usually obtained from ablation stakes. These point surface mass balance measurements require huge efforts 68 69 involving field campaigns and the collection of data from stake measurements scattered over the glacier. This explains why so few in situ measurements are performed, especially on glaciers located in remote 70 areas with very difficult access (e.g., Azam et al., 2018; Wagnon et al., 2013; Hoezle et al., 2017). 71

The objective of this paper is to propose an approach to determine point surface mass balances from measurements obtained by remote sensing techniques. In this way, we aim at determining point surface mass balances in ablation areas without setting up ablation stakes each year. We will develop this method using a comprehensive dataset of *in situ* measurements and analysis of ice motion, elevation changes and point surface mass balance data in the ablation area of Argentière Glacier (French Alps). We will then validate our method in other areas of the ablation zone of this glacier and of the Mer de Glace glacier.

#### 2. Study area

82 The Argentière Glacier is located in the Mont-Blanc range, French Alps (45°55' N, 6°57'E). Its surface 83 area was about 10.9 km<sup>2</sup> in 2018 (Fig. 1). The glacier extends from an altitude of about 3,400 m a.s.l. at 84 the upper bergschrund down to 1,600 m a.s.l. at the snout. The length of this glacier is about 10 km. It faces north-west, except for a large part of the accumulation area (south-west facing tributaries). The 85 annual surface mass balance ranges roughly from 2 meters of water equivalent per year (m w.e. a<sup>-1</sup>) in 86 the accumulation area to about -10 m w.e. a<sup>-1</sup> close to the snout. This glacier is free of rock debris except 87 88 for the lowermost part of the tongue, below the ice fall located between 2,000 and 2,300 m a.s.l. In the detailed studied region at 2350 m, the ice is generally free of debris. The debris cover can be 5 to 10 cm 89 90 thick in some locations. The field observations of the Argentière Glacier (i.e. mass-balance, thickness 91 variations, ice-flow velocities and length fluctuations over 50 years) come from the French glacier monitoring program called GLACIOCLIM (Les GLACIers, un Observatoire du CLIMat; 92 https://glacioclim.osug.fr/). For the present study, additional detailed observations were carried out in 93 the framework of the SAUSSURE program (Sliding of glAciers and sUbglacial water pressure 94 (https://saussure.osug.fr). The main part of our study focuses on a small area of Argentière Glacier (~0.2 95 km<sup>2</sup>) located between 2,320 and 2,400 m a.s.l. in the ablation zone (Fig. 1 and 2). In this area, the glacier 96 is ~600 m wide, the horizontal ice flow velocity is ~55 m  $a^{-1}$  (Vincent and others, 2009) and the 97 maximum ice thickness is 250 m (Rabatel et al., 2018). Experiments conducted in boreholes (Hantz and 98 Lliboutry, 1983) indicate that the bed is composed of hard rock with no thick and deforming sediment 99 100 layer.

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#### 3. Data

In the selected area, point annual surface mass balances and ice flow velocities were monitored with a high positioning accuracy at the end of each ablation season between 2016 and 2019 from 19 ablation stakes (Fig. 2). Our study also used surface mass balance and ice flow velocity observations from a small part of the ablation zone of the Mer de Glace glacier, at the location named "Tacul glacier" (Fig.1). 108 The ablation stakes are 10 meters long and made of five 2-m long sticks tied together with metallic 109 chains. We performed the observations of point annual surface mass balance at the same locations every year. Errors in ablation measurements mainly come from the mechanical play of the jointed sticks. The 110 uncertainties of the annual surface mass balance measurements performed in this ablation zone have 111 been assessed at 0.14 m w.e. a<sup>-1</sup> (Thibert et al., 2008). Topographic measurements were performed to 112 obtain the 3D coordinates of the ablation stakes. For this purpose, we used a Leica 1200 Differential 113 Global Positioning System (GNSS) receiver, running with dual frequencies. Occupation times were 114 typically one minute with 1-second sampling and the number of visible satellites (GPS and GLONASS) 115 was greater than 7. The distance between fixed and mobile receivers was less than 1 km. The DGPS 116 positions have an intrinsic accuracy of  $\pm 0.01$  m. However, given the size of the holes drilled to insert 117 the stakes, we estimate that the stake positions have an uncertainty of  $\pm 0.05$  m. 118

119 Both velocity components are required. The vertical velocity is the vertical component of the surface 120 velocity obtained from measuring altitude differences of the bottom tip of stakes. For this purpose, the emergence measurement is required to obtain the buried length of the stake. Thus, the purpose of 121 emergence observations is two-fold. They enable (i) to calculate the surface mass balance from two field 122 123 campaigns and, (ii) to obtain the altitude of the bottom tip of the stake using the altitude of the surface. In practice, the DGPS measurements are performed simultaneously with the emergence measurements 124 in order to obtain the exact position of the bottom tip of the stake buried in ice. In this way, it is possible 125 to monitor ice velocity along the three coordinate directions. Depending on the tilt of the ablation stakes, 126 127 the size of the drilling hole and the mechanical play of the jointed stakes, we assume that the annual 128 horizontal and vertical velocities are known with an uncertainty of  $\pm 0.10$  m a<sup>-1</sup>.

129 Aerial photographs of the glacier surface were taken on 5 September 2018 and 13 September 2019 using the senseFly eBee+ Unmanned Aerial Vehicle (UAV). A total of 720 photos in 2018 and 673 photos in 130 131 2019 were collected with the onboard senseFly S.O.D.A. camera (20 Mpx RGB sensor with a 28 mm focal length from an average altitude of 140 m above the glacier surface). Prior to the survey flights, we 132 collected GNSS measurements of ground control points (GCPs) that consist in rectangular pieces of red 133 fabric (100x60 cm) with white painted circles (40 cm diameter) on the glacier (10 in 2018, 20 in 2019) 134 and ten 40 cm diameter white circles painted on rocks on the sides of the glacier. The original horizontal 135 136 resolutions of the ortho-photo mosaics and digital elevation models (DEMs) are 10 cm and 1.00 m, respectively. The photos from the survey were processed using the Structure for Motion (SfM) algorithm 137 that is implemented in the Agisoft Metashape Professional version 1.5.2 software package (Agisoft, 138

139 2019). The SfM stereo technique was then used to generate a dense point cloud of the glacier surface. This dense point cloud was used to construct the DEMs using the GCPs surveyed during the field 140

141 campaigns. A detailed description of the processing steps can be found in Kraaijenbrink et al. (2016) or 142 Brun et al. (2016). The horizontal resolutions of the ortho-photo mosaics and digital elevation models (DEMs) are 10 cm and 1.0 m, respectively. 143

144 To calculate horizontal ice flow velocities over the studied area, we used the UAV ortho-photo mosaics with COSI-Corr (Co-registration of Optically Sensed Images and Correlation), a software tool 145 developed for image correlation (Leprince et al., 2007; Ayoub et al., 2009). Due to the velocities of the 146

Argentière glacier in this region ( $\sim$ 55 m a<sup>-1</sup>), we resampled the UAV ortho-photo at 1.0 m resolution 147

because the correlation was too noisy even with very large window sizes (i.e. 512 pixels). The surface 148

velocities were computed using an initial window size of 256 pixels, a final window size of 64 pixels 149 and a step of 4 pixels. The output velocity field was filtered using signal-to-noise ratios (SNR) provided 150

by COSI-Corr. Using an SNR threshold greater than 0.9 provides a good compromise between output 151

details, noise and computing time. A detailed description of the correct choice of the window size for 152 correlation can be found in Kraaijenbrink et al. (2016). 153

154 To establish the possible errors on the correlation process, horizontal displacements on stable off-glacier 155 areas were evaluated over 25 random points and provided a maximum horizontal error of ~0.55 m.

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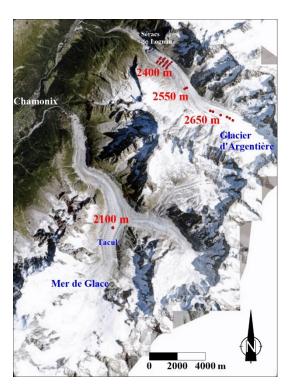


Figure 1: Map of Argentière and Mer de Glace glaciers. The red dots on Argentière glacier are the ablation stakes used in this study for annual surface mass balance and ice flow velocity measurements in 3 regions of the glacier (at approximately 2,400; 2,550 and 2,700 m a.s.l.). Aerial photo from the French National Geographical Institute, 2015 (https://www.geoportail.gouv.fr/).

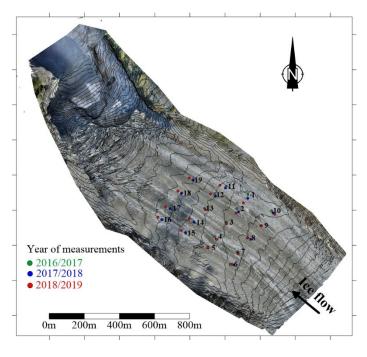


Figure 2: Map of the studied area in the ablation zone of Argentière glacier. The contour lines of surface
topography correspond to the surface in 2018. The green, blue and red dots are the positions of the
ablation stakes used for surface mass balance and ice flow velocity measurements when they were set
up in 2016, 2017 and 2018, respectively. Aerial photo from Unmanned Aerial Vehicle survey (5
September 2018).

#### 4. Method

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We will now introduce the mathematical framework used further on.

#### 4.1 Emergence velocities

The emergence velocity is the upward or downward flow of ice relative to the glacier surface. This flow 179 180 compensates the surface mass balance exactly if the glacier is under steady state conditions. The surface elevation change equation (Cuffey and Paterson, 2010, p. 332) expresses the surface mass balance as a 181 182 function of surface velocity and surface gradient:

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$$b_s = \partial S / \partial t - (w_s - u_s \partial S / \partial x - v_s \partial S / \partial y)$$
 (1)  
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with  $b_s$  the surface mass balance expressed in meters of ice, firn or snow (m a<sup>-1</sup>), S the surface elevation 186 (m),  $u_s$ ,  $v_s$ ,  $w_s$  the components of ice flow velocity at the surface (m a<sup>-1</sup>),  $\partial S / \partial x$  the surface gradient in the 187 188 x direction and  $\partial S / \partial y$  in the y direction.

189 The term  $w_s - u_s \partial S / \partial x - v_s \partial S / \partial y$  is called the emergence velocity. If the horizontal x-axis is taken in the flow direction,  $v_s = 0$ , and the emergence velocity is written as: 190

(2)

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$$v_e = w_s - u_s \partial S / \partial x$$

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Note that, under steady state conditions,  $\partial S/\partial t = 0$  and  $b_s = -v_e$ . The emergence velocities can be 193 calculated for each ablation stake from horizontal and vertical velocities and the slope of the surface 194  $\partial S/\partial x$ . In this way we assume that the downslope direction is the flow direction. The slope of the surface 195 can be obtained from GNSS field measurements and calculated over a distance similar to that travelled 196 197 by the stake over one year. In the ablation zone, the emergence velocities are positive, which corresponds to an upward flow of ice relative to the glacier surface. Note also that the vertical velocity can be positive 198 or negative on any region of the glacier. The emergence velocity is a classical way to relate the surface 199 200 mass balance to the thickness changes (Eq. 1). Unfortunately, as shown later in our study (Section 6.1), even if the horizontal and vertical velocities are accurately measured, the large uncertainties related to 201 202 the slope and thickness changes prevent us from calculating the point surface mass balance from the emergence velocities. 203

At the scale of the year, according to Equation 1 and Figure 3, and considering that the x-axis is taken 204 205 along the flow line direction (*i.e.*,  $v_s = 0$ ), the annual surface mass balance B<sub>s</sub> between the years t and 206 t+1 is obtained from:

$$\mathbf{B}_{s} = \Delta \mathbf{h}_{1} + \mathbf{U}_{s} \tan \alpha_{t+1} - \mathbf{W}_{s} = \Delta \mathbf{h}_{2} + \mathbf{U}_{s} \tan \alpha_{t} - \mathbf{W}_{s}$$
(3)

where  $u_s \partial S / \partial x$  is replaced by  $U_s \tan \alpha_t$  or  $U_s$ .  $\tan \alpha_{t+1}$  and  $U_s$  is the annual surface horizontal velocity and 210  $\tan \alpha_t$  and  $\tan \alpha_{t+1}$  are the slopes for the years t and t+1 respectively.  $W_s$  is the annual vertical velocity. 211

 $\partial S/\partial t$  is replaced by  $\Delta h_1$  and  $\Delta h_2$ , which are the annual thickness changes observed at the ends of the 212 annual ice flow vector.

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- Figure 3 illustrates the components of Equation 3. 214
- Note that the slope of the surface may change from year t to year t+1 and the expression depends on the 215
- 216 selected slope and thickness changes  $\Delta h_1$  or  $\Delta h_2$  (Fig. 3). Obviously, the results are the same.
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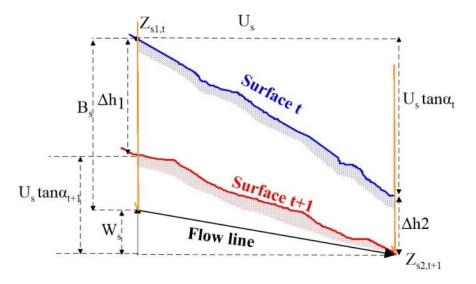


Figure 3: Diagram illustrating horizontal, vertical and emergence velocities (m a<sup>-1</sup>) observed from an 220 ablation stake (orange).  $U_s$  (m  $a^{-1}$ ) and  $W_s$  (m  $a^{-1}$ ) are the components of horizontal and vertical 221 velocities,  $\alpha_t$  and  $\alpha_{t+1}$  the slopes for the years t and t+1 respectively,  $Z_{s1,t}$  and  $Z_{s2,t+1}$  the elevations of the

222 surface at each end of the ice flow vector and  $\Delta h_1$  and  $\Delta h_2$  the elevation changes (m) at each end of the 223

ice flow vector. 224

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#### 226 4.2 Calculation of the "geodetic point surface mass balance"

(4)

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228 Let us reconsider the emergence velocity formulation in order to express the point surface mass balance 229 as a function of vertical velocity and altitude changes at the ends of the annual displacement vector.

According to Equation 3 and given that  $\Delta h_1 + U_s \tan \alpha_{t+1} = \Delta h_2 + U_s \tan \alpha_t = Z_{s2,t+1} - Z_{s1,t}$  (Fig. 3), we 230 231 can write:

232  $B_s = Z_{s2,t+1} - Z_{s1,t} - W_s$ 233

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This expression has a great advantage in that it does not depend on the surface slope that can change 235 from one year to the next. It is also independent of thickness changes that can change from one site to 236

another. 237

The term geodetic point surface mass balance refers to the value of  $B_s$  obtained from Equation 4. Once 238 239 the vertical velocity is known, B<sub>s</sub> can be obtained from topographical surface measurements alone. Note that even if the horizontal velocity is not included in Equation 4, it is needed to estimate the positions at 240 241 which  $Z_{s2,t+1}$  and  $Z_{s1,t}$  should be measured.

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5. Results

#### 5.1 Annual horizontal and vertical velocities over the three years

248 Annual horizontal and vertical velocities were measured from a network of 19 ablation stakes over three years between 2016 and 2019 (Fig. 2). The stakes were replaced each year and were always set up at the 249 250 same locations, using a handheld GPS device, allowing a relevant comparison, except for stakes 1 and 11 which were located in areas with large crevasses, preventing the possibility of drilling stakes at the 251 252 chosen location. In addition, for the year 2018/2019, stake 12 was accidentally replaced at a distance of more than 30 meters from the initial position due to both a lack of rigour and the uncertainty in the 253 254 handheld GPS measurement. This difference in locations led to a difference in the horizontal velocity of 3 m a<sup>-1</sup> in a region with a strong horizontal gradient (left edge of the area in Figure 4). However, it 255 256 does not change the pattern of horizontal velocities or horizontal velocity changes with time. This is not

- the case for vertical velocities as described in the next paragraph. In the area of this network, the annual
- horizontal velocities range from 35 to 60 m a<sup>-1</sup>. The annual ice flow velocities have been interpolated
- from kriging over the entire coloured areas shown in Figure 4. In this way, we can accurately compare
- the ice flow velocities over three years, 2016/2017, 2017/2018 and 2018/2019, at the locations of each
- stake (Fig. 5a). Strong deceleration in horizontal ice flow velocities can be observed over these three
- years. On the average, ice flow velocity decreased by 2.4 and 1.8 m a<sup>-1</sup> over the two periods 2016/2017 2017/2018 and 2017/2018-2018/2019, which corresponds to an average decrease of about 4.8 and 3.6%
- per year, respectively. Note that the regression lines shown in Figure 5a are almost parallel, which means
   that the change in velocities is homogeneous in space.
- The vertical velocities were obtained from the altitude changes of the bottom tip of the stakes from one 266 year to the next (Fig. 3). In the studied area, the vertical velocities can be positive or negative and range 267 from -4 to 4 m  $a^{-1}$  (Fig. 4). The vertical velocities have been interpolated over the entire coloured areas 268 269 shown in Figure 4 using kriging. The patterns of vertical velocities are very similar for the year 2016/2017 and 2017/2018. We note some differences with the 2018/2019 pattern. As mentioned 270 previously, stakes 1, 11 and 12 set up in 2018/2019 are located at distances of more than 30 meters from 271 272 the initial positions. In addition, stakes 17, 18, 19 were replaced in 2018 at distances ranging between 273 25 and 30 meters from the initial positions. These six stakes are shown with small dots in Figure 5b. If we exclude the velocity values of 2018/2019 for these stakes, we can conclude that the measured vertical 274
- velocities are very similar over this 3-year period. The differences do not exceed  $0.5 \text{ m s}^{-1}$ . The average
- of the differences is  $0.01 \text{ m a}^{-1}$  and the standard deviation is  $0.29 \text{ m a}^{-1}$ . These differences barely exceed the measurement uncertainty. Note also that the vertical velocity changes could be affected by the
- 277 the measurement uncertainty. Note also that the vertical velocity changes could be alle278 horizontal motion changes or vertical strain rate changes as discussed in Section 6.
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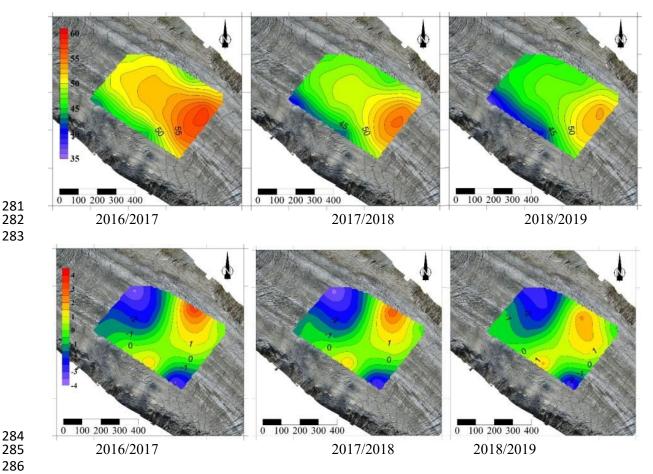


Figure 4: Horizontal (top panel) and vertical (bottom) ice flow velocities (m a<sup>-1</sup>) measured over three years from the ablation stakes. Note the different colour scales. Distances in m.



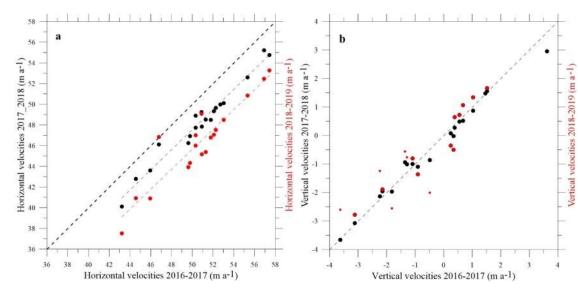


Figure 5: Comparison of horizontal ice flow velocities (a) and vertical velocities (b) between the years 2016/2017, 2017/2018 and 2018/2019. The black dots correspond to the comparison between the 2016/2017 and 2017/2018 periods. The red dots correspond to the comparison between the 2016/2017 and 2018/2019 periods. The thick dashed line corresponds to the bisector and the thin dashed lines to the regression lines. The small dots in the figure on the right correspond to the stakes that were set up in 2018 at distances of more than 25 m from the initial positions.

- 5.2 Emergence velocities

The emergence velocities have been calculated from Equation 2 for each stake and reported in Figure 6. The slope was determined from the Digital Elevation Model using UAV measurements. We compared the emergence velocities obtained each year at each stake location (Fig. 7). Unlike the vertical velocities, the differences between emergence velocities calculated over the 3 years reveal a standard deviation of 

0.8 m w.e. a<sup>-1</sup>. The value of emergence velocities is affected by large uncertainties related to the slope. Combined with the measured thickness changes, the emergence velocity should make it possible to estimate the surface mass balance. However, our study shows that the uncertainties in the emergence velocity prevent us from calculating the point surface mass balance accurately. Indeed, the dispersion of 0.8 m w.e. a<sup>-1</sup> is large compared to the spatial variability of about 1 m w.e. a<sup>-1</sup> for point surface mass balance in the ablation zone of alpine glaciers (Vincent et al., 2018b).

- For this reason, to calculate the surface mass balance, we suggest using the "geodetic point surface mass balance" described earlier rather than the emergence velocity.

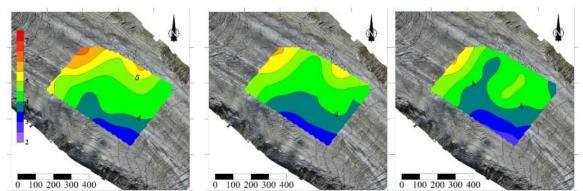


Figure 6: Emergence velocities between the years 2016/2017, 2017/2018 and 2018/2019 (m  $a^{-1}$ )

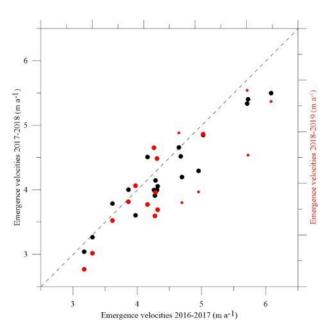


Figure 7: Comparison of emergence velocities between the years 2016-2017, 2017-2018 and 2018-2019. The black dots correspond to the comparison between the 2016-2017 and 2017-2018 periods. The red dots correspond to the comparison between the 2016-2017 and 2018-2019 periods. The red small dots correspond to the stakes that were set up in 2018 at distances of more than 25 m from the initial positions

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#### 5.3 "Geodetic point surface mass balances" using *in situ* GNSS measurements

330 The geodetic point surface mass balance is calculated according to Equation 4. We first tested the method in the studied region of Argentière glacier at 2,400 m a.s.l. using the *in situ* GNSS measurements. 331 For this purpose, we used the altitudes of the surface at the stake locations for the years 2017 and 2018 332 333 and the vertical velocities observed in 2016-2017. The resulting point surface mass balances for the hydrological year 2017-2018 are compared with the observed surface mass balance and plotted in Figure 334 8a. Note that the surface mass balances are in m of ice per year. The comparison shows very good 335 agreement. The maximum difference is 0.39 m of ice per year and the standard deviation is 0.20 m of 336 337 ice or 0.18 m w.e. per year. In addition, we calculated the surface mass balances of 2018-2019 from the 338 vertical velocities observed in 2016-2017 and 2017-2018 (Fig. 8b). In this case, the comparison with the 339 observed surface mass balances shows large discrepancies. However, a more detailed analysis reveals that the calculated and observed surface mass balances are very similar if the vertical velocities observed 340 341 in 2016-2017 and 2017-2018 were measured exactly at the same location of the stakes measured in 2018-2019. In Figure 8b, the large dots show the calculated and observed surface mass balances for the 342 343 stakes located within a distance no greater than 15 m. From this comparison, the differences are less than 0.5 m a<sup>-1</sup> of ice and the standard deviation is 0.17 m of ice or 0.15 m w.e. a<sup>-1</sup>. 344

345 From this analysis, we conclude that the geodetic point surface mass balance can be obtained with an accuracy of about 0.2 m w.e. a<sup>-1</sup> using the vertical velocities observed over the previous years. It requires 346 347 measurement of the horizontal ice flow velocity and the altitudes of the ends of the velocity vector 348 exactly at the same location, within a radius of less than 15 m compared to that of vertical velocity 349 determination. In practice, the vertical velocities should be observed accurately between two years t and 350 t+1 from stakes and GNSS measurements. Then, for the following or previous years, the point surface 351 mass balance can be obtained from surface measurements only (without drillings and setting new stakes) using the horizontal velocity and the altitudes of the surface measured at each end of the horizontal 352 vector. In the next section, we examine how such measurements obtained from remote sensing data can 353 354 also be used effectively to determine the point surface mass balance.

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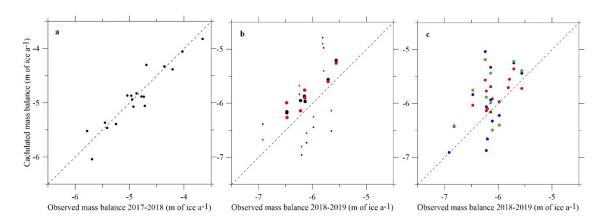


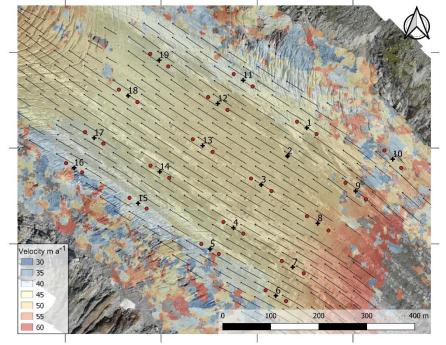
Figure 8: Observed and calculated point surface mass balances at 2,350 m a.s.l. at Argentière glacier. 359 The point surface mass balances have been calculated: a) for the year 2017-2018 using the vertical 360 velocities measured in 2016-2017 and elevations from GNSS measurements; b) for the year 2018-2019 361 using the vertical velocities measured in 2016-2017 (black dots) and 2017-2018 (red dots), and 362 elevations from GNSS measurements; c) for the year 2018-2019 using elevations from remote sensing 363 data (UAV data) and the vertical velocities measured in 2018-2019 (red dots), 2017-2018 (blue dots) 364 365 and 2016-2017 (green dots). The large dots shown in Figure 8b correspond to the stakes which were set up within a radius of less than 15 m. 366

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#### 5.4 "Geodetic point surface mass balances" using remote sensing measurements

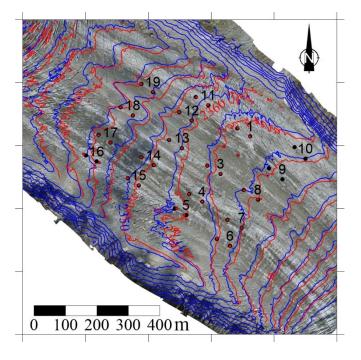
Here, we used the same method described in the previous section. However, the *in situ* GNSS measurements used to determine the altitudes and horizontal velocities are replaced by remote sensing measurements. For this purpose, we used the horizontal velocities (Figure 9) and the DEMs (Figure 10) obtained from UAV surveys in 2018 and 2019. The vertical velocities are those observed in 2018-2019, 2017-2018 and 2016-2017. The horizontal velocities have been neglected for stakes 9 and 10 given the poor quality of the correlation and the opening and/or closing of crevasses in the ice (close to the stake 10) that caused a drastic change between the photos, which subsequently affected the image correlation

- 379 (Fig. 9).
- 380 Some details on the procedure are given below for the sake of clarity. The horizontal velocities retrieved
- 381 from the UAV surveys were determined at positions where vertical velocities were measured. In this
- way, the coordinates XY of each vector end have been calculated (green dots on Fig. 9). Then we used the DEMs from 2018 and 2019 (Fig. 10) to determine the elevations of these points  $Z_{s1, 2018}$  and  $Z_{s2, 2019}$ (see Eq. 4 and Figure 3). The comparison between the *in situ* horizontal velocities and the velocities obtained from the UAV surveys reveals a standard deviation of 0.7 m a<sup>-1</sup>.
- The reconstructed point surface mass balances are compared with the observed surface mass balances in Figure 8c. For this reconstruction, we used the vertical velocities observed in 2018-2019 (red dots), 2017-2018 (blue dots) and 2016-2017 (green dots). For the reconstructions using the vertical velocities of 2016-2017 and 2017-2018, we excluded data of sites 1, 11, 12, 17, 18 and 19 for which the stakes were measured at distances of more than 30 m from those of 2018-2019.
- 391 The differences between the observations and the reconstructed surface mass balances using the 2018-
- 392 2019 vertical velocities are less than 0.45 m of ice per year and the standard deviation is 0.24 m of ice
- 393 or 0.22 m w.e. a<sup>-1</sup>. The differences between the observations and the reconstructed surface mass balances
- using the 2016-2017 and 2017-2018 vertical velocities show standard deviations of 0.42 and 0.40 m
- 395 w.e.  $a^{-1}$ . respectively.
- From these results, we conclude that the point surface mass balances can be obtained with an accuracy
- of about 0.3 m w.e. a<sup>-1</sup> using remote sensing measurements, assuming that the vertical velocities have
- been observed accurately over the previous years.



399

Figure 9: Horizontal velocities obtained from feature tracking (Cosi-Corr) using UAV images. The
black crosses show the locations where the vertical velocities were observed. The red dots correspond
to the ends of horizontal vectors for 2018-2019, determined from UAV images.



404 405

Figure 10: DEMs obtained from the UAV survey in 2018 (blue contour lines) and 2019 (red contour lines). The black dots correspond to the positions of the stakes in 2018 and 2019 observed from GNSS measurements. The red dots correspond to the ends of the horizontal velocity vectors obtained from UAV images.

#### 5.5 Validation of the method: geodetic surface mass balances obtained in other regions

In order to establish that the results are neither accidental nor site-dependent, we tested the method on other areas of Argentière glacier and on another glacier, which is the Mer de Glace, located approximately 10 km away (Fig. 1) and for which vertical velocities were available. Here, we used GNSS *in situ* measurements given that accurate elevations observations from remote sensing data are not available.

First, we selected two ablation stakes in a sector of Argentière glacier located at 2,530 m a.s.l. These 419 420 stakes were replaced within a radius of  $\pm$  35 m each year between 2001 and 2018 (Fig. 1). Note that these measurements were not intended for vertical velocity determination but rather for point surface 421 mass balance measurements. This explains why the stakes were not set up at exactly the same locations 422 423 over the whole period. Note also that the region is not debris-covered and consequently the surface roughness is lower compared to the studied area at 2,350 m. Using Equation 4 and the method described 424 425 in the previous section, we calculated the point surface mass balances at these two stakes over the period 2001-2018. For this purpose, we used the average vertical velocities calculated over this period. In 426 addition, the altitudes of each stake for each year of this period have been observed. These two stakes 427 428 (named stake 2 and stake 3) are located about 120 m apart. The average calculated vertical velocities are -0.24 m a<sup>-1</sup> ( $\pm$  0.44 m a<sup>-1</sup>) and -0.79 m a<sup>-1</sup> ( $\pm$  0.33 m a<sup>-1</sup>) respectively, and did not show strong temporal 429 changes (Fig. 11b). Note that the horizontal velocity decreased from 75 to 50 m a<sup>-1</sup> in this region between 430 431 2002 and 2018 (Fig. 11a). The geodetic point surface mass balances are compared to the observations 432 (Fig. 12a). The standard deviations of the calculated and observed surface mass balance differences are similar to those of the vertical velocities (0.44 and 0.33 m a<sup>-1</sup>, i.e. 0.4 and 0.3 m w.e. a<sup>-1</sup>). 433

Second, we tested the method in another sector of Argentière glacier, close to the equilibrium line, which is located close to 2,800 m a.s.l. For this purpose, we selected 6 stakes (stakes 7, 8, 9, 10, 11, 12) which were measured along a longitudinal section between 2,650 and 2,750 m a.s.l. (Fig. 1) over the period 2005-2018. In this region, the horizontal ice flow velocity is about 50 m a<sup>-1</sup> (Fig. 11a). Here again, the network of stakes was mainly designed for point surface mass balance measurements. Thus, given that the stakes were set 10-m deep in the ice and the surface mass balance ranges between -4 and 0 m w.e. 440  $a^{-1}$  depending on the year, the ablation stakes were not replaced each year. As the ablation stakes move 441 with the ice flow, we selected only the measurements that were performed at the same locations. Indeed, 442 after the first year following installation, the location of each stake was far from its initial position and 443 we cannot assume that the vertical velocity was similar. Consequently, 5 years are available to calculate 444 the vertical velocities and to make the comparison between calculated and observed point surface mass 445 balances (Fig. 12b). The standard deviations of calculated and observed point surface mass balance 446 differences are 0.22 m of ice  $a^{-1}$ , *i.e.* 0.20 m w.e.  $a^{-1}$ .

Finally, we tested the method on another glacier, Mer de Glace (Fig. 1). On this glacier, we selected

one stake at 2100 m a.s.l that was measured over 15 years between 2003 and 2018 (Vincent et al., 2018a). This ablation stake was set up each year at the same location, within a radius of about 30 meters.

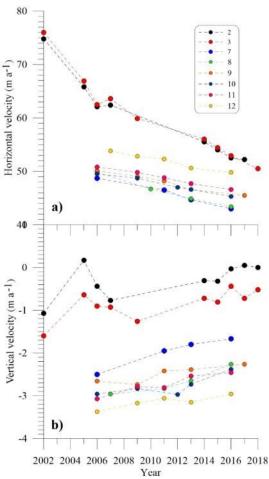
445 Using the method described in the previous sections, we calculated the point surface mass balances at

451 this stake over the period 2003-2018. The average calculated vertical velocity is  $-1.10 \text{ m a}^{-1}$ . Note that

452 the horizontal velocity decreased from 80 to 50 m  $a^{-1}$  and the thickness by 55 m in this region between

453 2003 and 2018. The results are plotted in Figure 12c. The standard deviation of the calculated and 454 observed point surface mass balance differences is  $0.40 \text{ m w.e. a}^{-1}$ .

454 455



456 Year
457 Figure 11: Horizontal (a) and vertical (b) velocities observed at the different stakes at 2,550 m a.s.l. (Stakes 2 and 3) and 2,700 m a.s.l. (stakes 7, 8, 9, 10, 11 and 12).

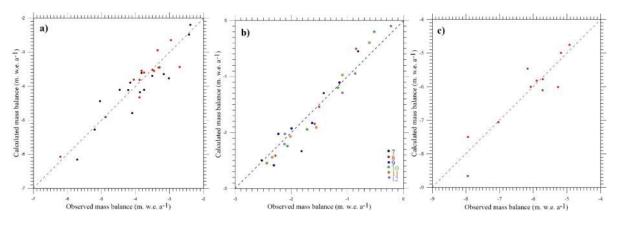


Figure 12: Observed and calculated point surface mass balances from: a) two ablation stakes located at 2,550 m
a.s.l. at Argentière glacier measured between 2002 and 2018, b) six stakes located at around 2,700 m a.s.l. at
Argentière glacier measured between 2006 and 2017 and c) one stake located at 2,100 m a.s.l. on Mer de Glace
glacier measured between 2003 and 2018.

#### 466 6. Discussions

467

#### 6.1 Point surface mass balance obtained from emergence velocities vs. vertical velocities

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470 A classical approach to relate the point surface mass balance to thickness change is to use the emergence 471 velocity (Cuffey and Paterson, 2010; Kaab and Funk, 1999). From this approach, the point surface mass 472 balance is obtained from the sum of the emergence velocity and the thickness change (Eq. 1). However, 473 the value of the mass balance reconstructed from the emergence velocity depends strongly on the 474 selected surface slope and on thickness change, which both vary considerably with space and time. The 475 value of the slope depends on the choice of the selected distance for the slope calculation and on the 476 roughness of the surface.

In addition, the slope can change significantly from one year to the next. The emergence velocity is
therefore not well-defined given that it depends strongly on the spatial and temporal changes of surface
roughness, preventing an accurate determination of point surface mass balance as shown in our study.

- In contrast, in our analysis, we find that the changes in vertical velocity are insignificant over the 3 years 481 482 of observations at 2350 m. From the other long series of observations, one can also that they are small over decadal time scales. Thus, we propose to reformulate the emergence velocity formulation (Eq. 1) 483 in order to express the point surface mass balance as a function of vertical velocity and altitude changes 484 at the ends of the annual displacement vector (Eq. 4). In this way, provided that the vertical velocity has 485 486 been assessed from *in situ* measurements over previous years, the point surface mass balance can be determined from remote sensing measurements alone, outside the period of field measurements, with 487 488 no need of prescribing surface slope nor elevation changes as required when using emergence velocities, 489 but which introduce significant uncertainties. Our results from the detailed studied area at Argentière 490 glacier (2,350 m a.s.l.), for which the observations were designed to accurately determine the vertical velocity, demonstrate that the surface mass balance can be obtained from this method with an accuracy 491 of about 0.2 m w.e. a<sup>-1</sup> from *in situ* GNSS measurements and about 0.3 m w.e. a<sup>-1</sup> using elevations and 492 horizontal velocities obtained from very high resolution remote sensing data acquired from UAV 493 494 surveys.
- 494 495 496

#### 6.2 Spatial and temporal variability of the vertical velocities

497 498 499

#### 6.2.1 Analysis from observations

500 Our dataset shows that vertical velocities strongly vary in space over the glacier surface. Our detailed 501 observations from the network used between 2016 and 2018 at the Argentière Glacier (2350 m) showed 502 that the vertical velocity change can exceed 0.3 m  $a^{-1}$  if the stakes are located at distances of more than 503 25 or 30 meters (section 5.1). We showed that the surface mass balance can be reconstructed with an

accuracy of about 0.2 m w.e. a<sup>-1</sup> using the vertical velocities observed within a radius of less than 15 m. 504 505 Records from the whole network suggest that the vertical velocity spatial gradient can exceed 1.5 m a 1/100 m in this region. As a consequence, a horizontal deviation of 10 m could lead to a vertical velocity 506 change exceeding the measurement uncertainty  $(0.15 \text{ m a}^{-1})$ . To better assess the vertical velocity spatial 507 508 gradient over length scales of 20 to 100 m, the vertical velocities have been calculated from 10 stakes set up in 2018/2019 on a longitudinal profile located between stakes 3 and 13 (Fig. 2). Note that the 509 510 distances between these stakes is small and enable to assess the vertical velocity variations at small 511 scales. According to measurements shown in Figure S1, the spatial gradient can reach up to  $0.02 \text{ a}^{-1}$ , which is slightly more important than what we found previously  $(0.015 a^{-1})$ . We can conclude that 512 reconstructing surface mass balance from remote sensing requires measurements of the horizontal ice 513 flow velocity and the altitudes of the ends of the velocity vector exactly at the same locations, i.e. within 514 515 a radius of less than 15 m compared to that of vertical velocity determination.

516 The analysis of temporal changes also deserves particular attention. The 3 years of detailed observations performed at 2350 m at Argentière Glacier does not reveal temporal changes exceeding the measurement 517 uncertainties, as shown in Figure 5b. Note that the longer series of observations available to study the 518 519 temporal changes over decadal time scales were not designed to measure the vertical velocities. However, from the longer series of observations performed at Argentière glacier at 2550 m and 2700 m 520 a.s.l. (Fig. 11b), we assessed a general temporal trend of about 0.07 m a<sup>-2</sup>. We can conclude that the past 521 period over which the vertical velocities are determined should not exceed 4 years in order to not exceed 522 an uncertainty of 0.3 m w.e. a<sup>-1</sup> on the reconstructed surface mass balance. This conclusion could be 523 different with stronger temporal change in vertical velocities. Further observations and analysis are 524 525 needed to better estimate the temporal changes.

#### 526 527 528

#### 6.2.1 Analysis from numerical modelling

529 To analyse the spatial and temporal variabilities of the vertical velocities over the entire glacier, we performed 3D full-Stokes ice-flow simulations for two different glacier geometries using a surface DEM 530 measured in 1998 and 2015 and reconstructed bedrock topography (Rabatel et al., 2018). The calculation 531 532 is solved using the Elmer/Ice model (Gagliardini et al., 2013). The linear basal friction parameter is 533 inferred from surface velocity and topography measurements made in 2003 (Berthier et al., 2005) using the adjoint-based inverse method (Gillet-Chaulet et al., 2012). For each given glacier geometry, we 534 compute the corresponding flow solution and assume constant friction over time. Therefore, changes in 535 velocity are only induced by changes in the glacier geometry between 1998 and 2015. We used an 536 537 unstructured mesh with a 100 m horizontal resolution, refined down to 10 m in the stake network 538 monitoring area at 2,400 m a.s.l.

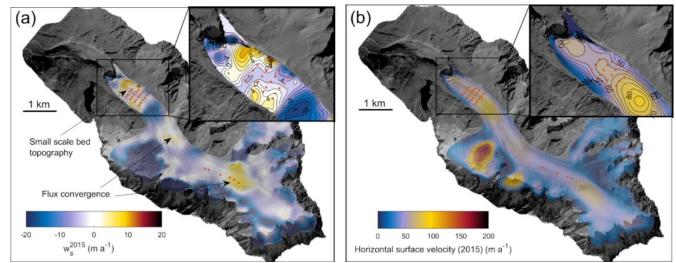
By integrating the mass conservation equation for an incompressible fluid along the vertical axis we canwrite:

541

 $w_s = w_b - \int_{z_b}^{z_s} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} dz \qquad (5)$ 

542

where  $w_b$  is the vertical velocity at the bed,  $z_s$  is the surface elevation and  $z_b$  the bed elevation. Vertical 543 velocity at the surface can therefore be viewed as a sum of a component coming from sliding along the 544 545 bedrock and a component coming from convergence/divergence of the ice flow integrated over the glacier thickness. For example, local depression in the bedrock topography creates negative vertical 546 547 velocity  $w_b$  at the glacier base but also flow convergence that creates positive vertical velocity resulting in a smoothing of surface vertical velocity  $w_s$  by the ice deformation. Figure 13a shows the modelled 548 vertical surface velocity in 2015. At the scale of the glacier, vertical surface velocities are spatially 549 550 heterogeneous due to a combination of bedrock slope and the ice flux divergence/convergence (Fig. 13a). In the model, the basal vertical velocity  $w_b$  produced by ice flow along the bedrock can lead to 551 552 small scale variability of the basal vertical velocity that can be visible at the surface when sliding velocity is significant, as modelled around 2,400 m a.s.l. in the studied stake network (Fig. 13a). Bedrock 553 554 topography is therefore likely the origin of the observed pattern at 2,400 m a.s.l. (Fig. 4). The pattern 555 differences between the observations and the modelling results are likely due to bedrock elevation errors. Although the pattern of horizontal velocities is well reproduced (Fig. 13b), it seems difficult to properly 556 557 reconstruct the vertical velocities.



559

562

Figure 13 – Vertical (a) and horizontal (b) surface velocities modelled at Argentière glacier in 2015.
Red dots show the locations of the ablation stakes set up at 2,400 m and 2,650 m a.s.l.

563 Our numerical experiments were used to analyse the temporal changes in vertical velocities. We found 564 that the response of the vertical velocities at the glacier surface to changes in glacier thickness over time is sensitive to the bedrock slope (averaged over a distance greater than the ice thickness). Consequently, 565 566 a decreasing vertical velocity magnitude should be associated with decreasing horizontal velocities 567 where bed slopes are significant (Fig. 14). However, the magnitude of small scale (length-scale inferior to glacier thickness) spatial variations of vertical velocity due to bedrock topography seems to be little 568 569 affected by the large change in horizontal velocities (Fig. 14 and 15). We show that reduced amplitude of  $w_b$  due to decreasing sliding speed is compensated by the reduced amplitude of the ice flux 570 convergence/divergence produced by bedrock anomalies (red arrows in Fig. 15). Bedrock depressions 571 and bumps of sizes comparable to glacier thickness produce respectively convergence and divergence 572 573 in the ice flow, creating vertical velocities of opposite sign compared to the velocities created by sliding 574 at the glacier base. These two components of the surface vertical velocity decrease in magnitude in 575 response to thickness changes, resulting in a limited change in the sum of the two components and therefore in surface vertical velocities. This results in nearly constant vertical velocity where large scale 576 577 averaged bedrock slope is low, which explains why the observed pattern of surface vertical velocity (Fig. 4) is well conserved over time. 578

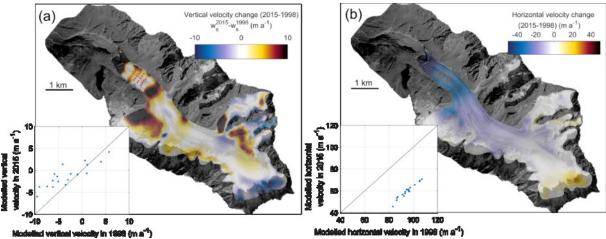


Figure 14: Modelled changes in vertical (a) and horizontal (b) surface velocities between 1998 and
2015. Insets compare modelled velocities at the stake location (orange dots) between 1998 and 2015.

583 In summary, at large scale, the magnitude of surface vertical changes over time are proportional to 584 bedrock slope and changes in horizontal velocities while at small scale, the spatial patterns tend to be 585 conserved over time due to compensation between changes in bedrock vertical velocities and ice flux 586 convergence/divergence. These findings suggest that our method is likely applicable only in areas of 587 low bedrock slope.

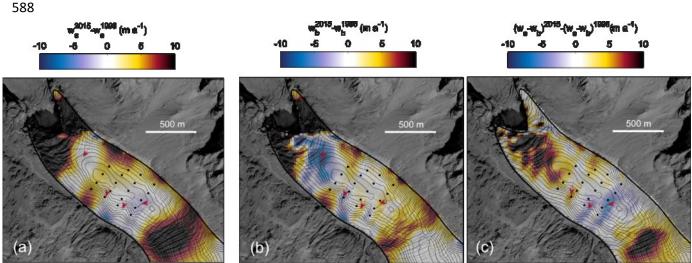


Figure 15: Modelled changes in vertical velocities at the surface (a) and at the bedrock (b) between 1998 and 2015. The righthand figure (c) shows the change in vertical velocity at the surface due to change in flow convergence/divergence. The red arrows indicate the locations where changes in basal vertical velocities are compensated by flow convergence/divergence changes, resulting in constant surface vertical velocities.

Note that, in our study, we used the annual velocities measured at the end of the ablation season (from
September to September), such that potential seasonal changes in the vertical and horizontal motion or
in basal uplift and bed separation (e.g. Sugiyama et al, 2004; Nienow et al., 2005) are not expected to
bias the geodetic annual surface mass balances obtained from the vertical velocities.

#### 6.3 Uncertainties on geodetic point surface mass balances

(6)

The uncertainty related to the point surface mass balance determination results from uncertainties on the elevation measurements and on the vertical velocity. Using Equation 4 and assuming independence of the different sources of uncertainties, the overall uncertainty related to the reconstructed point surface mass balance is obtained by applying the method of error propagation and assuming uncorrelated errors: 606

607 
$$\sigma_b^2 = 2\sigma_z^2 + \sigma_w^2$$
  
608

609 in which  $\sigma_b$ ,  $\sigma_z$ ,  $\sigma_w$  are the uncertainties relative to the point surface mass balance, elevation and vertical 610 velocity, respectively.

The uncertainty in elevation depends both on the method of XY positioning, the surface slope or roughness and the method of altitude determination. Depending on the surface roughness, we can assess
the elevations with an accuracy ranging from 0.1 to 0.3 m from UAV measurements as shown in this

614 study.

600

601

The uncertainty in vertical velocity is  $\pm 0.1$  m a<sup>-1</sup>, as mentioned in the Data section. However, additional 615 uncertainty could come from the method of elevation observations for the bottom of the stakes. Indeed, 616 617 the GNSS measurements are commonly related to the surface of the ice at the location of the stakes and 618 not to the summit of the stakes. Consequently, the altitude of the bottom of each stake results from the difference between the altitude of the surface and the buried height of the ablation stake. Indeed, this 619 620 determination is accurate only if the measurement of emergence has been performed exactly from the point on which the GNSS measurement was made. Unfortunately, in most cases, one operator held the 621 622 stick of the GPS antenna at the ice surface close to the ablation stake and another operator measured the 623 emergence of the stake, but not exactly from the surface altitude that corresponds to the bottom tip of 624 the GPS antenna. Except for the measurements performed at 2,350 m a.s.l between 2016 and 2019, 625 which were designed for this purpose, this gives an additional uncertainty of  $\pm$  0.1 m for the altitude of 626 the bottom of the stake, *i.e.*  $\pm$ 0.14 m a<sup>-1</sup> for the calculated vertical velocity.

627 The overall uncertainty in the geodetic point surface mass balance obtained from remote sensing data is 628 therefore estimated to range between  $\pm 0.20$  and  $\pm 0.60$  m a<sup>-1</sup> using accurate DEMs from UAV 629 photogrammetry depending on the surface roughness and the method used for vertical velocity 630 determination.

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634

#### 633 7 Conclusions

635 The classical way to determine the point surface mass balance in the ablation zone of a glacier is to set 636 up ablation stakes and dig pits or conduct drillings in the accumulation zone. Here, we showed that, in the ablation zone, the point surface mass balances can be reconstructed from surface altitudes and 637 638 horizontal velocities only, provided that the vertical velocities have been measured for at least one year in the past. Our method first requires accurate measurement of the vertical velocities between two years 639 640 t and t+1 from stakes and GNSS measurements. Then, for the following or previous years, the point surface mass balances can be obtained easily from surface measurements only, using the horizontal 641 642 velocity and the surface elevation at each end of the horizontal displacement vector (Eq. 4). These measurements can be obtained from remote sensing provided that the ice flow velocity and altitude 643 644 determinations are sufficiently accurate.

645 Our method assumes that the annual vertical velocities are almost constant with time. We have used a 646 numerical modelling study to show that this approximation holds in areas of low bedrock slope (averaged averaged over a distance greater than the ice thickness). This is supported by our detailed 647 648 observations performed on Argentière Glacier at 2,400 m a.s.l. and designed for this purpose. Comparison between the reconstructed point surface mass balances and the observed values shows close 649 agreement. Further tests performed on datasets acquired in other regions of the Argentière and Mer de 650 651 Glace glaciers show standard deviations of  $\pm 0.2$  to  $\pm 0.4$  m w.e. a<sup>-1</sup> between reconstructed and observed point surface mass balances, despite the fact that these measurements were not designed for this purpose. 652 For these tests, we used the averaged vertical velocities obtained over the last decade. 653

From our results, we conclude that the point surface mass balances can be obtained with an accuracy of 654 about 0.3 m w.e. a<sup>-1</sup> using remote sensing measurements and assuming that the vertical velocities have 655 656 been observed accurately over the previous years within a radius of less than 15 m. We also conclude, from our datasets that the past period over which the vertical velocities are determined should not exceed 657 4 years in order to not exceed an uncertainty of 0.3 m w.e. a<sup>-1</sup> on the reconstructed surface mass balance, 658 although further observations and analysis are needed to better estimate these spatial and temporal 659 changes. Note that, for comparison, the measurement uncertainty related to the *in situ* measurements of 660 point surface mass balance is 0.14 m w.e. a<sup>-1</sup> in the ablation zone (Thibert et al., 2008). 661

Given the recent improvements in satellite sensors, it is conceivable to apply our method using high spatial resolution satellite images like Pléiades or WorldView (0.5 m resolution). For these point surface mass balance reconstructions, note that, given the strong spatial variability of vertical velocity, it is crucial to determine the altitudes of the surface at each end of the horizontal displacement vector at the exact sites on which the vertical velocities are known. We conclude that our method could be useful to determine numerous point surface mass balances and reduce the amount of effort required to conduct field measurements, especially in remote areas.

669 Previous studies have shown that the point surface mass balance signal reveals a climatic signal that is 670 unbiased by the dynamic glacier response, unlike the commonly used glacier-wide mass balance 671 (Rasmussen, 2004; Huss et al., 2009; Eckert et al., 2011; Thibert et al., 2018; Vincent et al., 2017). In 672 the glaciological community, there is growing awareness that point surface mass balance measurements 673 are important basic data to be shared for mass balance and climate change analyses. In this respect, the 674 World Glacier Monitoring Service has started collecting such data on a systematic basis as a complement 675 to glacier-wide surface mass balances [WGMS, 2015]. Our method should open up new prospects to

obtain more numerous point surface mass balances in the future while reducing the amount of time and

677 energy required for *in situ* measurements.

678 Another line of research, not explored in the present study, could also be examined. The method 679 proposed in the present study requires the vertical velocity to reconstruct the annual point surface mass balance. However, if we derive Equation 4 and assume that vertical velocity is constant with time, we 680 681 can determine the surface mass balance changes, instead of the absolute surface mass balances, with the 682 elevation determinations only. Assuming that satellite sensors provide sufficient accuracy in elevation and horizontal velocity, this method could be very helpful to reconstruct changes in surface mass balance 683 in remote areas for which in situ measurements are very difficult. In this way, point surface mass balance 684 685 changes on numerous unobserved glaciers could be considered with remote sensing observations only.

This would make it possible to obtain climatic signals all over the world, unbiased by dynamic glacierresponse.

688

**Data availability:** The surface mass balance, ice flow velocities and DEM data can be accessed upon
 request by contacting Christian Vincent (christian.vincent@univ-grenoble-alpes.fr).

691

692 Author contributions: DC, OL, DS, BJ, LA, UN, AW, LP, OG, VP, ET, FB and CV performed the 693 topographic measurements (photogrammetry, lidar, GNSS). OL, DC, AG, FG, OG, FB and CV 694 performed the numerical calculations and the analysis. AG performed the numerical modelling 695 calculations. CV supervised the study and wrote the paper. All co-authors contributed to discussion of 696 the results.

- 697
- 698 **Competing interests**: the authors declare that they have no conflict of interest.
- 699

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#### 897 Supplementary Material

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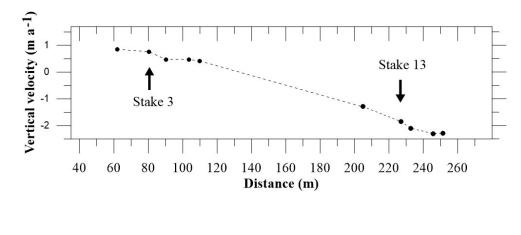


Figure S1: Vertical velocities obtained from 10 stakes measured in 2018/2019 on a longitudinal profile

located between the stakes 3 and 13 (see Figure 2 for the locations of the stakes 3 and 13).