

Supplementary Material to

**“High-resolution simulations of interactions between
surface ocean dynamics and frazil ice”**

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Supplementary Note S1. Ocean–atmosphere fluxes

In all formulae below, temperature is expressed in degrees Celsius and salinity in PSU.

The saturation vapor pressure over sea water with surface salinity S_0 , $e_s = e_s(T, S_0)$ is computed from:

$$e_s(T, S_0) = 6.1378\beta_S(S_0) \exp\left[\frac{17.502T}{240.97 + T}\right], \quad \text{with} \quad \beta_S(S_0) = (1.0 - 5.37 \cdot 10^{-4}S_0). \quad (1)$$

The relationships between vapor pressure e , mixing ratio r , specific humidity q , and relative humidity r_{rel} are:

$$r = \frac{0.62197e}{p - e} = r_{\text{rel}}r(e_s), \quad (2)$$

$$q = \frac{r}{1 + r}, \quad (3)$$

where p denotes atmospheric pressure.

As stated in the main text, the ocean–atmosphere fluxes are computed from the following input variables: surface water temperature T_w , surface salinity S_0 , sea level pressure p_a , air temperature T_a , relative humidity r_{rel} , and wind speed U_a . The air density ρ_a and the heat of evaporation L_e are computed from:

$$\rho_a = 0.34838 \frac{p_a(1.0 + r)}{(T_a + 273.16)(1.0 + 1.60779r)}, \quad (4)$$

$$L_e = 2.5029 \cdot 10^6 - 2.40 \cdot 10^3 T_w \quad (5)$$

and the specific heat of air and water are assumed constant, respectively, $c_{p,a} = 1004.8 \text{ J}\cdot\text{kg}^{-1}\cdot\text{K}^{-1}$ and $c_{p,w} = 3985 \text{ J}\cdot\text{kg}^{-1}\cdot\text{K}^{-1}$.

The transfer coefficients for momentum, sensible and latent heat, C_d , C_h and C_e , are computed as:

$$C_d = C_{d,n}\alpha_s, \quad (6)$$

$$C_h = C_{h,n}\alpha_s, \quad (7)$$

$$C_e = C_{e,n}\alpha_s, \quad (8)$$

where $C_{d,n}$, $C_{h,n}$ and $C_{e,n}$ are transfer coefficients under neutral conditions, and α_s is a stability parameter, given by:

$$\alpha_s = \begin{cases} 0.1 + 0.03s + 0.9 \exp[4.8s] & \text{for } s \leq 0, \\ 1.0 + 0.63s^{1/2} & \text{for } s > 0 \end{cases} \quad (9)$$

with

$$s = \max\{-3.3, \frac{s_0|s_0|}{|s_0| + 0.01}\}, \quad (10)$$

$$s_0 = \frac{T_w - T_a}{U_0^2}, \quad (11)$$

$$U_0 = \max\{0.1, U_a\} \quad (12)$$

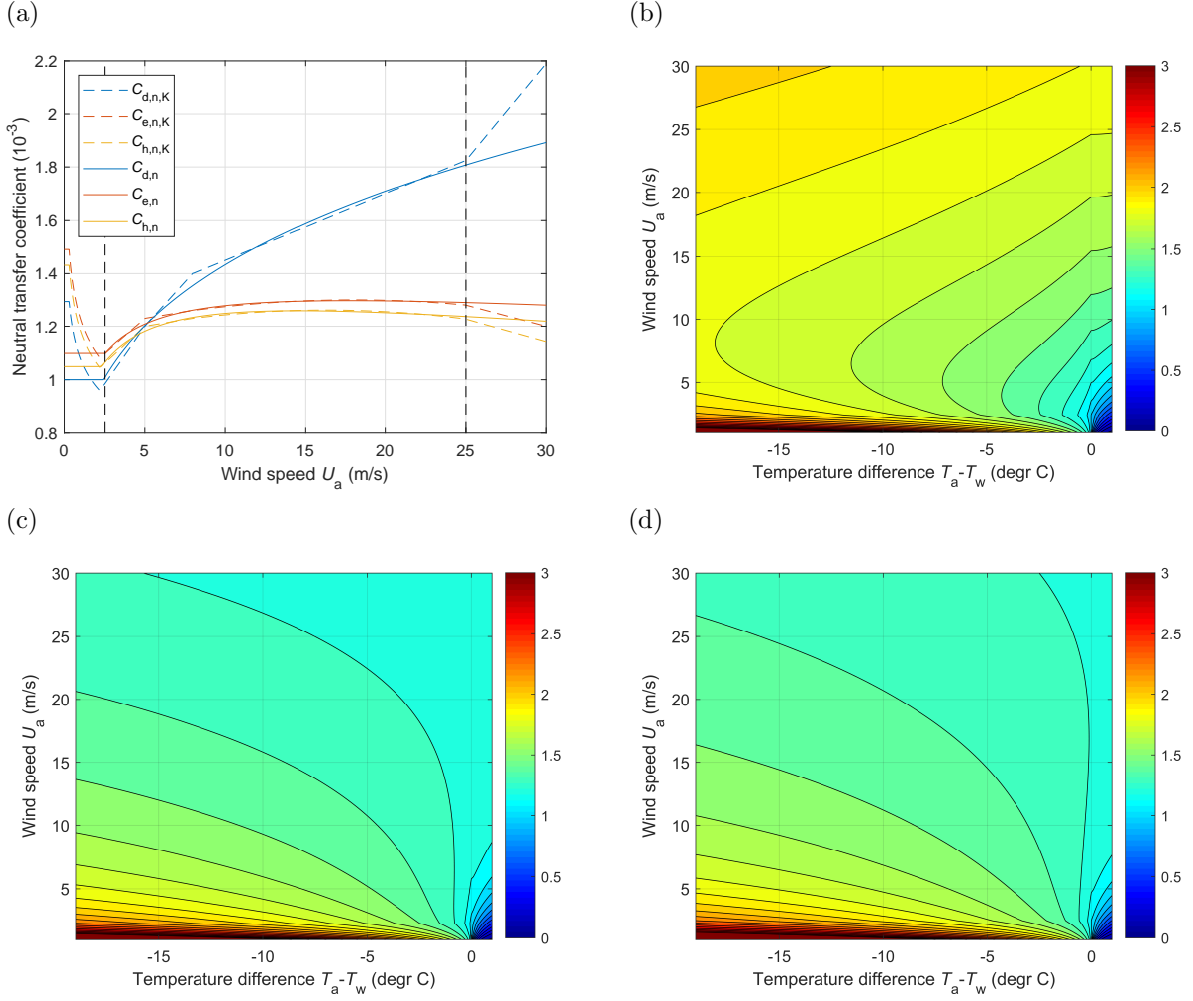
(see Appendix 3 in Kondo, 1975).

In the bulk formulae implemented in the original code of CROCO, constant values of the neutral coefficients are used, $C_{h,n} = 0.0011$ and $C_{d,n} = C_{e,n} = 0.0014$. However, under highly unstable conditions of interest in this work ($T_a \ll T_w$), formulae (6)–(12) with constant neutral coefficients lead to transfer coefficients decreasing with increasing wind speed, which is contrary to observations (for $T_a \geq T_w$ the behavior is correct). Therefore, the original formulae of Kondo (1975) are preferred. However, they are formulated for five wind speed intervals (dashed lines in Fig. 1a), which makes them unattractive computationally (several ‘if’ commands necessary in the code). Therefore, approximate formulae are used here, obtained as the following least-square fits to Kondo’s expressions:

$$10^3 C_{d,n} = \max\{a_d U_a^{b_d}, 1.0\}, \quad (13)$$

$$10^3 C_{h,n} = \max\{(a_h U_a + b_h)/(U_a^2 + c_h U_a + d_h), 1.05\}, \quad (14)$$

$$10^3 C_{e,n} = \max\{(a_e U_a + b_e)/(U_a^2 + c_e U_a + d_e), 1.1\}, \quad (15)$$



Supplementary Figure 1: Transfer coefficients for momentum, sensible and latent heat fluxes: neutral coefficients $C_{d,n}$, $C_{h,n}$, $C_{e,n}$ in function of wind speed (a) and the “total” values C_d (b), C_h (c), C_e (d) in function of air–water temperature difference and wind speed. Values in (b)–(d) are multiplied by 10^3 . In (a), dashed lines show the original formulae of Kondo (1975), and continuous lines the fitted formulae (13)–(15).

with $a_d = 0.7997$, $b_d = 0.2533$, $a_h = 297.2$, $b_h = 274.8$, $c_h = 207.0$, $d_h = 430.8$, $a_e = 474.6$, $b_e = 487.6$, $c_e = 330.4$, $d_e = 690.7$ (continuous lines in Supplementary Fig. 1a). The resulting C_d , C_h and C_e for a range of $(T_a - T_w)$ and U_a values are shown in Supplementary Fig. 1b–d.

The wind stress τ_w (in $\text{N}\cdot\text{m}^{-2}$), the two components of the turbulent heat flux, F_h and F_e (in $\text{W}\cdot\text{m}^{-2}$), and the corresponding evaporation rate H_e (in $\text{kg}\cdot\text{m}^{-2}\cdot\text{s}^{-1}$), are given by:

$$\tau_w = \rho_a C_d U_a^2, \quad (16)$$

$$F_h = -\rho_a c_{p,a} C_h U_a (T_w - T_a) \quad (17)$$

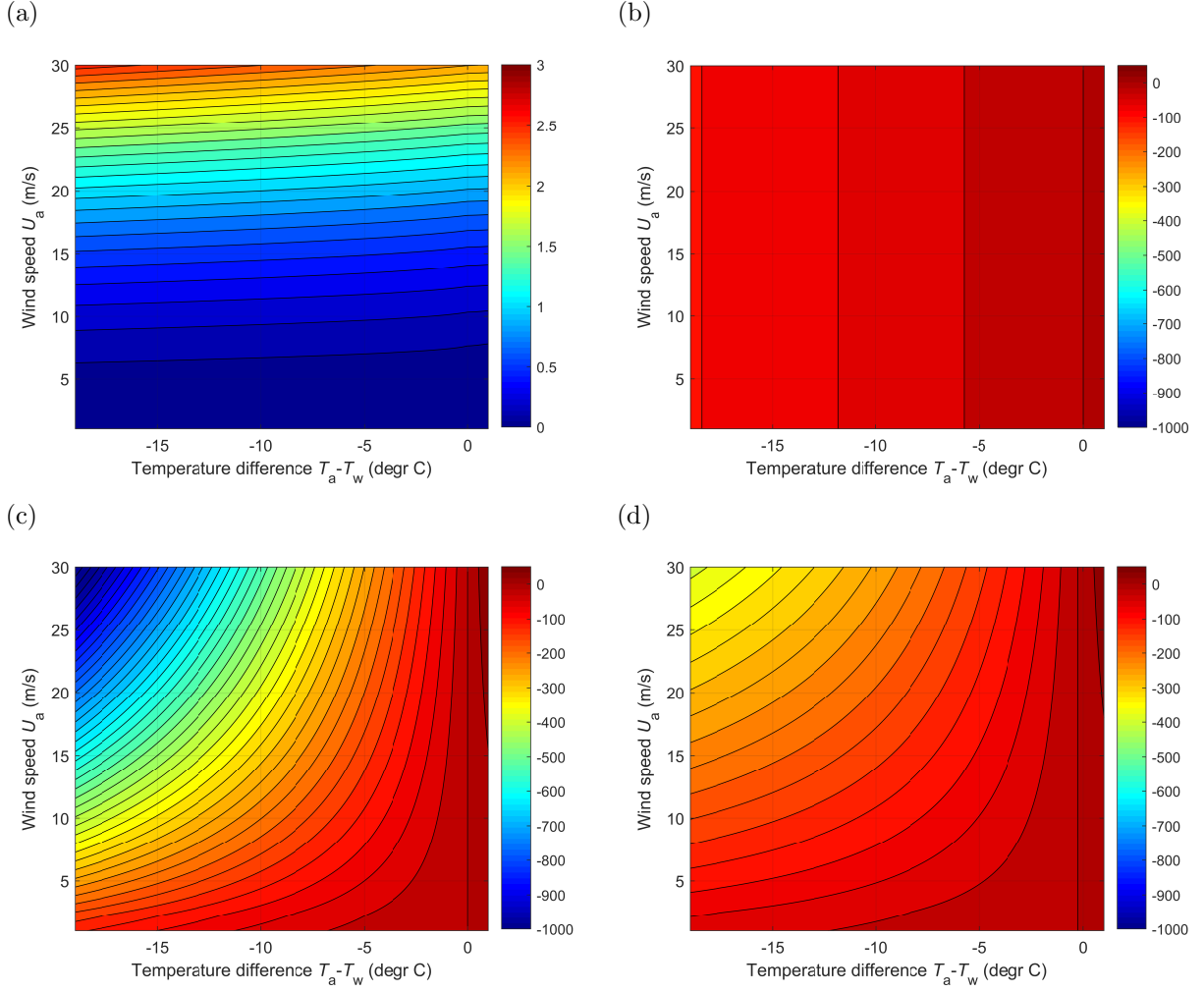
$$F_e = -\rho_a L_e C_e U_a (q_{s,w} - q_a), \quad (18)$$

$$H_e = \rho_a C_e U_a (q_{s,w} - q_a), \quad (19)$$

where q_a is the specific humidity of the air and $q_{s,w}$ is the saturation specific humidity at temperature T_w . The heat fluxes are negative when the ocean loses heat to the atmosphere. The values of τ_w , F_h and F_e for a range of $(T_a - T_w)$ and U_a values are shown in Supplementary Fig. 2a,c,d.

The net long-wave radiation at the sea surface, F_{rad} , is computed as:

$$F_{\text{rad}} = \varepsilon \sigma_{SB} [(T_a + 273.16)^4 - (T_w + 273.16)^4], \quad (20)$$



Supplementary Figure 2: Wind stress on the sea surface τ_w (a; in $\text{N}\cdot\text{m}^{-2}$) and the three components of surface heat flux (b–d; in $\text{W}\cdot\text{m}^{-2}$): F_{rad} (b), F_h (c) and F_e (d). The color scales in (b)–(d) are the same. The contour distances equal $0.1 \text{ N}\cdot\text{m}^{-2}$ in (a) and $25 \text{ W}\cdot\text{m}^{-2}$ in (b)–(d).

where $\sigma_{SB} = 5.6697 \cdot 10^{-8} \text{ W}\cdot\text{m}^{-2}\cdot\text{K}^{-4}$ is the Stefan–Boltzmann constant and $\varepsilon = 0.985$ is the emissivity (Fig. 2b).

Finally, the total net heat flux at the surface F_{net} is:

$$F_{\text{net}} = F_{\text{rad}} + F_e + F_h \quad (21)$$

(short-wave radiation is not considered in this study).

Supplementary Note S2. Estimation of relevant velocity scales

As described in the main text, the three velocity scales relevant for the OML analyzed here are:

- friction velocity u_* ,
- vertical velocity related to convective motion w_* (Deardorff's velocity scale),
- vertical velocity related to the Langmuir turbulence $w_{*,L}$.

The friction velocity u_* can be computed from τ_w , obtained with (16) as described in Supplementary Note S1:

$$u_* = (\tau_w / \rho_w)^{1/2}. \quad (22)$$

For the range of $T_a - T_w$ and U_a considered here, the resulting values of u_* are shown in Supplementary Fig. 3.

The Deardorff's velocity scale w_* is a function of the net buoyancy flux at the surface B_0 and the mixed layer depth h :

$$w_* = (B_0 h)^{1/3}, \quad (23)$$

where B_0 is the sum of the thermal buoyancy B_T and haline buoyancy B_S :

$$B_0 = B_T + B_S = \frac{g}{\rho_w} \left(\frac{\beta_T}{c_{p,w}} F_{\text{net}} + \beta_S S_0 H_e \right), \quad (24)$$

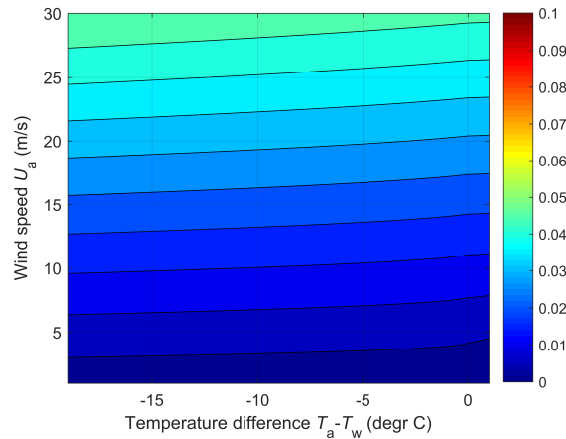
where F_{net} and H_e are computed from (21) and (19), respectively, and β_T and β_S are thermal expansion and saline contraction coefficients. Under conditions of interest, B_0 is dominated by the thermal component B_T . The resulting values of B_0 in function of $T_a - T_w$ and U_a are shown in Supplementary Fig. 4. The corresponding w_* are shown in Supplementary Fig. 5a,b for two arbitrarily selected values of h , 10 m and 100 m.

The third velocity scale, $w_{*,L}$, is given by:

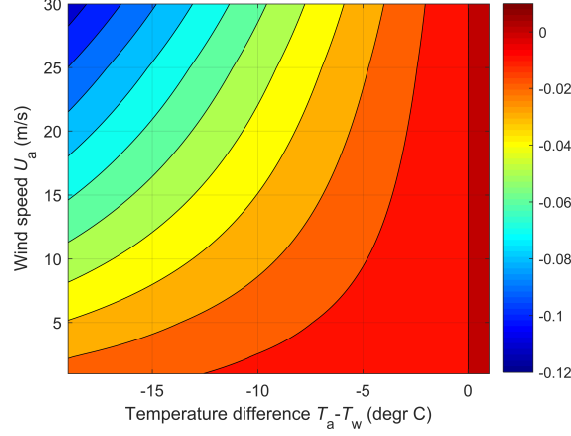
$$w_{*,L} = (u_S u_*^2)^{1/3}, \quad (25)$$

where $u_S = |\mathbf{u}_S|_{z=0}$ is the amplitude of the Stokes drift at the surface, dependent on wave amplitude a , frequency ω and wavenumber k :

$$u_S = \omega k a^2 \quad (26)$$



Supplementary Figure 3: Friction velocity u_* (in m/s). The color scale and contour interval (0.005 m/s) are the same as in Supplementary Fig. 5.



Supplementary Figure 4: Buoyancy flux B_0 (in $10^{-6} \text{ m}^2/\text{s}^3$) computed from (24) for a range of $T_a - T_w$ and U_a values.

(monochromatic waves are assumed for simplicity). For deep water waves, for which $\omega^2 = gk$:

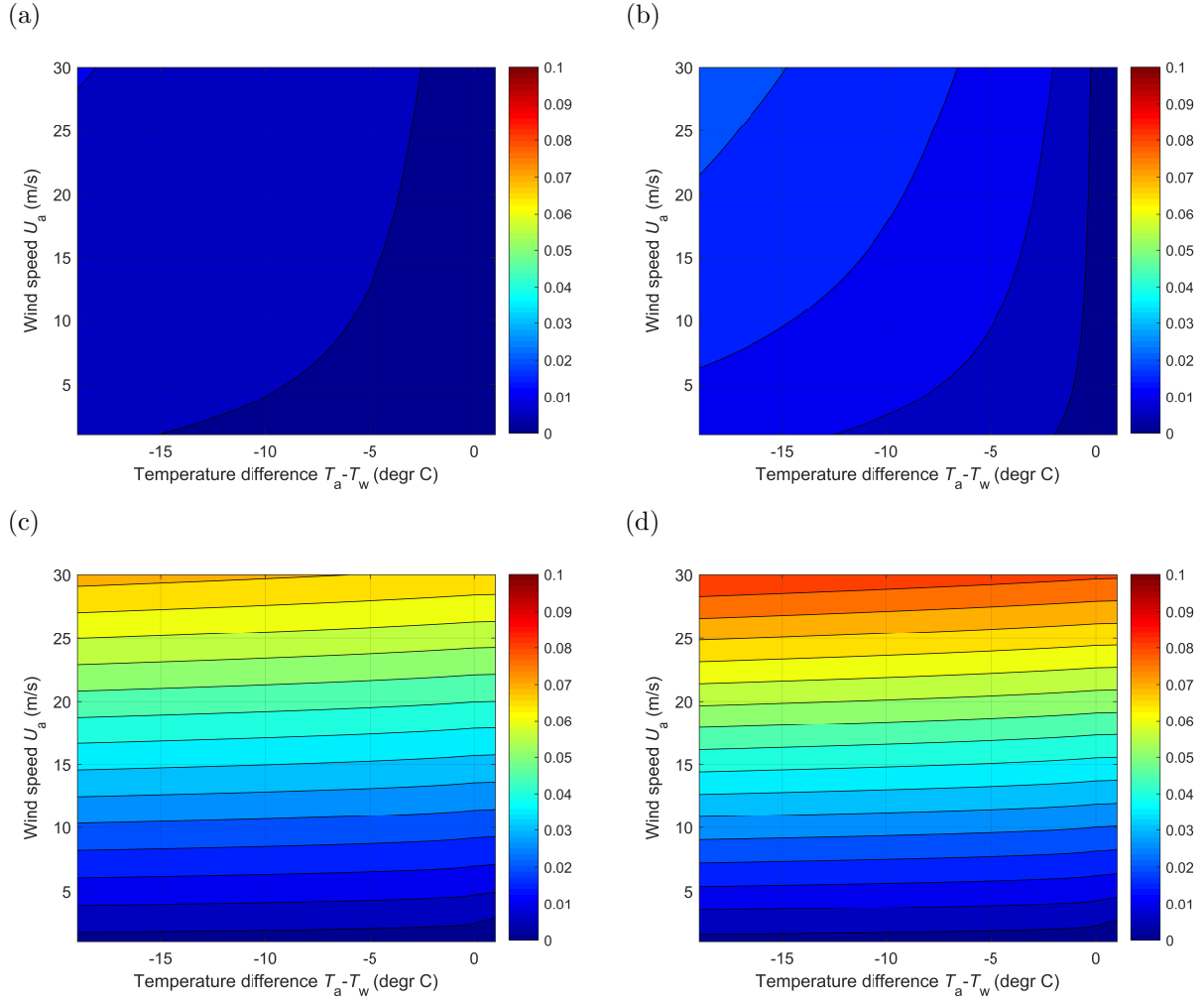
$$u_S = g^{-1} \omega^3 a^2. \quad (27)$$

Under assumptions described in the main text, i.e., for stationary, fetch-limited waves, the relevant wave parameters, i.e., significant wave height H_s and peak period T_p , can be estimated based of fetch X and wind speed U_a by means of a simple statistical model. Krylov's model is used here, as described by Massel (2013), for which:

$$H_m = 0.16 \frac{U_a^2}{g} \left[1 - \left(1 + 6 \cdot 10^{-3} \sqrt{\frac{gX}{U_a^2}} \right)^{-2} \right], \quad (28)$$

$$T_m = 19.478 \frac{U_a}{g} \left(\frac{gH_m}{U_a^2} \right)^{0.625}. \quad (29)$$

Here, H_m and T_m are the mean wave height and period. Assuming $H_s = 1.6H_m$ and $T_p = 1.25T_m$ (Holthuijsen, 2007), as well as $a = H_s/2$ and $\omega = 2\pi/T_p$, u_S and thus $w_{*,L}$ can be computed for a given combination of $(T_a - T_w)$, U_a and X . The results are shown in Supplementary Fig. 5c,d for two selected values of fetch, 100 m and 1000 km.



Supplementary Figure 5: Velocity scales w_* (a,b) and $w_{*,L}$ (c,d) in function of $T_a - T_w$ and U_a . Additional parameters: $h = 10$ m (a), $h = 100$ m (b), $X = 100$ m (c), $X = 1000$ km (d). The color scale and contour interval (0.005 m/s) are the same as in Supplementary Fig. 3.

Supplementary Note S3. Testing of the model

Turbulent Stokes–Ekman layer from McWilliams et al. (1997)

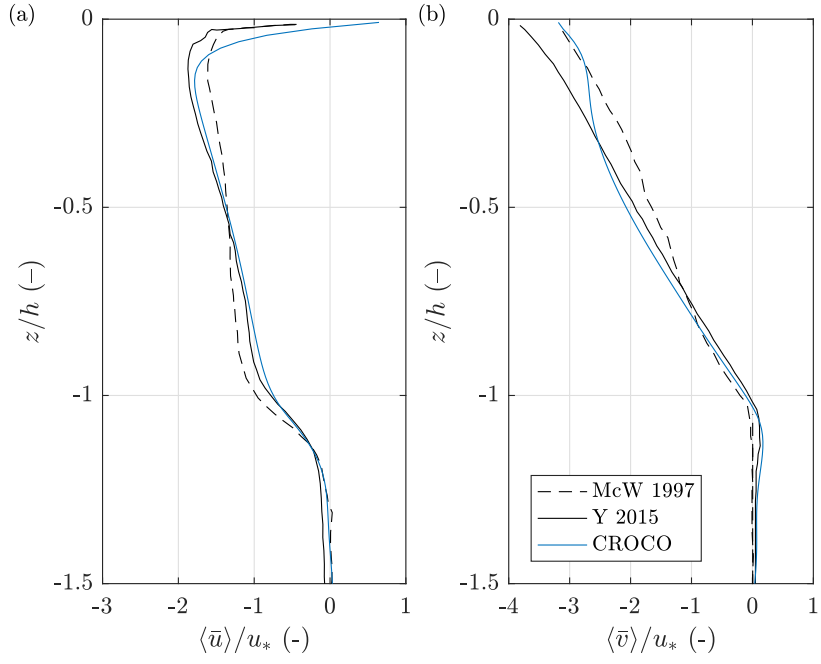
The setup of this test case is described in detail in McWilliams et al. (1997) and Yang et al. (2015). A summary of the model settings is provided in Supplementary Table 1. The prescribed wind stress corresponds to a wind speed of ~ 5 m/s. The net surface heat flux has negligible effect on the model behavior and has been used by McWilliams et al. (1997) to facilitate model spin-up. The turbulent Langmuir number resulting from the combination of model parameters in this case $La_t = 0.3$.

Apart from the parameters listed in Supplementary Table 1, all settings of the CROCO model were kept identical to those used in the main study (the turbulence model, non-hydrostatic mode, advection schemes, etc.). The model was run for 18 h, and the results from a time period corresponding to one inertial period were used to compute vertical profiles of $\langle \bar{u} \rangle / u_\star$, $\langle \bar{v} \rangle / u_\star$, $\langle u'w' \rangle / u_\star^2$, $\langle v'w' \rangle / u_\star^2$, $\langle u'u' \rangle / u_\star^2$, $\langle v'v' \rangle / u_\star^2$ and $\langle w'w' \rangle / u_\star^2$. In Supplementary Figs. 6–8 they are compared with analogous profiles obtained by McWilliams et al. (1997) and Yang et al. (2015). Additionally, in the case of $\langle w'w' \rangle / u_\star^2$, the results computed from *in situ* measurements in the open ocean by D’Asaro (2001) are shown (triangles in Supplementary Fig. 8c), analyzed earlier by Yang et al. (2015) and Li et al. (2005).

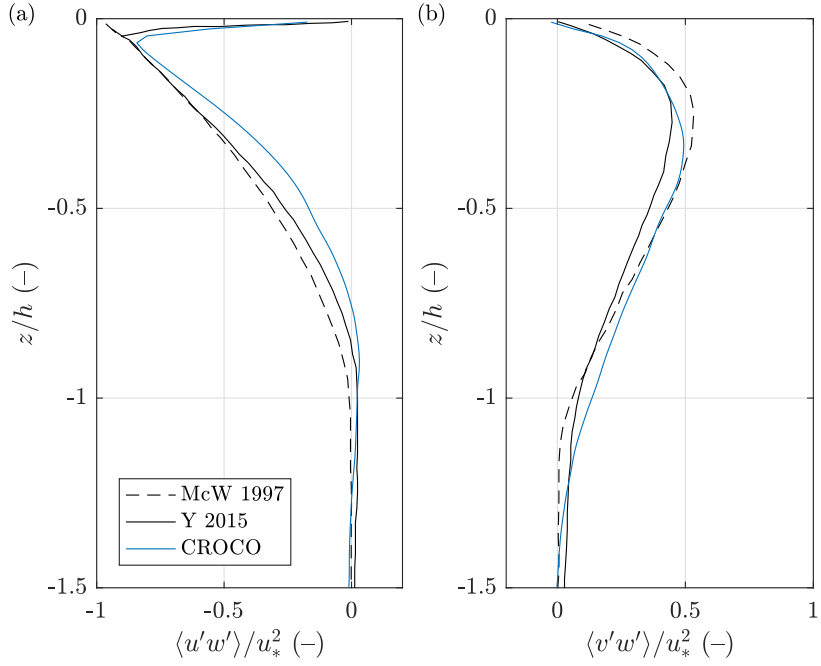
In spite of several differences between the three models considered, the vertical profiles of both the mean velocity and velocity variance are comparable. The most pronounced difference between the results of CROCO and the other two models occurs for $\langle w'w' \rangle / u_\star^2$: the maximum of $\langle w'w' \rangle / u_\star^2$ obtained with CROCO equals 1.98 and occurs at depth $z/h = -0.23$, i.e., it is smaller and located lower than the corresponding maxima in the two other studies (2.78 at $z/h = -0.14$ and 2.55 at $z/h = -0.18$). Incidentally, the observed maximum of $\langle w'w' \rangle / u_\star^2$ from D’Asaro (2001), equal to 1.93, is very close to that from CROCO, although occurs slightly closer to the surface, at $z/h = -0.18$. As pointed out in the earlier studies, the value of the turbulent Langmuir number in the study by D’Asaro (2001) is not known, but their measurements were performed in the open ocean in fully developed wind seas, in which case La_t is close to 0.3, i.e., the value used in the simulations. The values of $\langle w'w' \rangle / u_\star^2$ produced by CROCO can be thus treated as realistic, although, in comparison to other models, CROCO tends to underestimate the amplitude of $\langle w'w' \rangle / u_\star^2$ and to overestimate its depth (the latter is also true for $\langle v'w' \rangle / u_\star^2$, see Fig. 7b).

Supplementary Table 1: Setup of the CROCO model for the McWilliams et al. (1997) test case

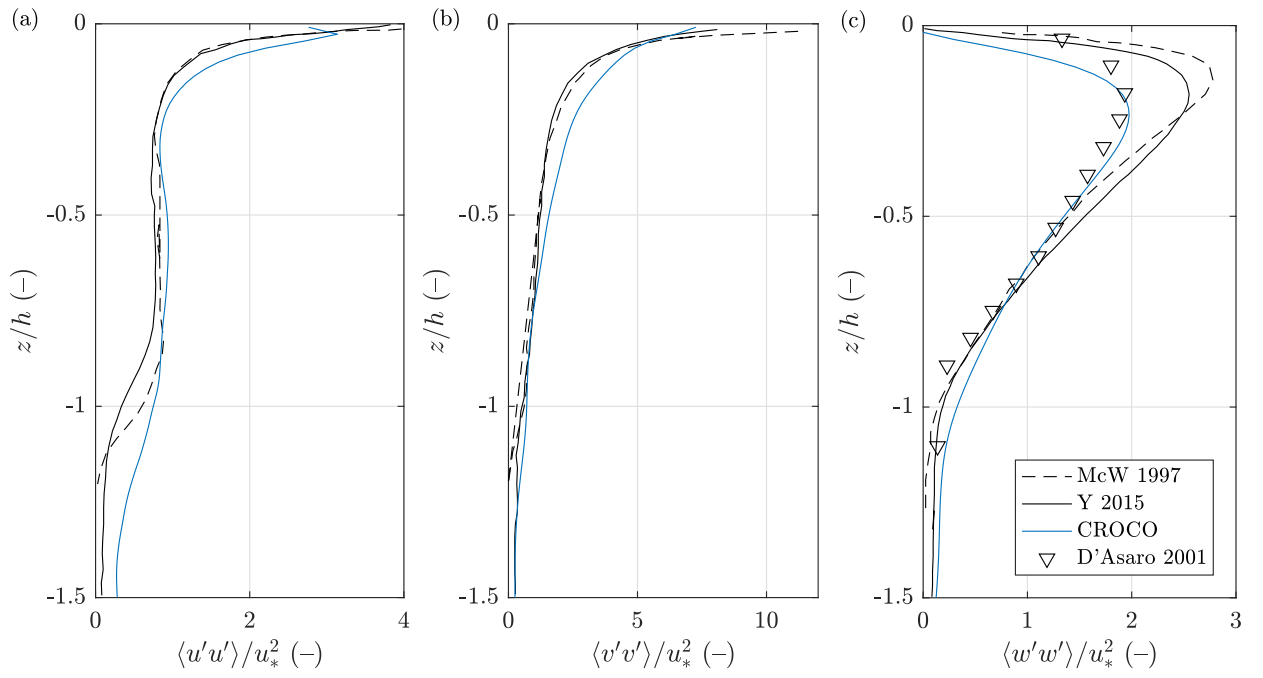
Parameter	Value
Domain size $L_x \times L_y \times L_z$	150×150×90 m
Horizontal resolution Δx	3.0 m
Vertical resolution Δz	0.6 m
Time step Δt	0.1 s
Surface wind stress in x direction $\tau_{w,x}$	0.037 N·m ⁻²
Surface wind stress in y direction $\tau_{w,y}$	0
Surface heat flux F_{net}	-5 W·m ⁻²
Coriolis parameter f	1·10 ⁻⁴ s ⁻¹
Mixed layer depth h	33 m
Water temperature profile $T_w(z)$	$T_w = 1^\circ\text{C}$ for $z \geq -h$ $T_w = [1 + 0.01(33 + z)]^\circ\text{C}$ for $z < -h$
Wave amplitude a	0.8 m
Wave period T	6.2 s
Wave direction θ relative to $\tau_{w,x}$	0°



Supplementary Figure 6: Time- and domain-averaged velocity profiles $\langle \bar{u} \rangle / u_*$ (a) and $\langle \bar{v} \rangle / u_*$ (b) obtained with CROCO (blue lines) and from the earlier studies by McWilliams et al. (1997) and Yang et al. (2015).



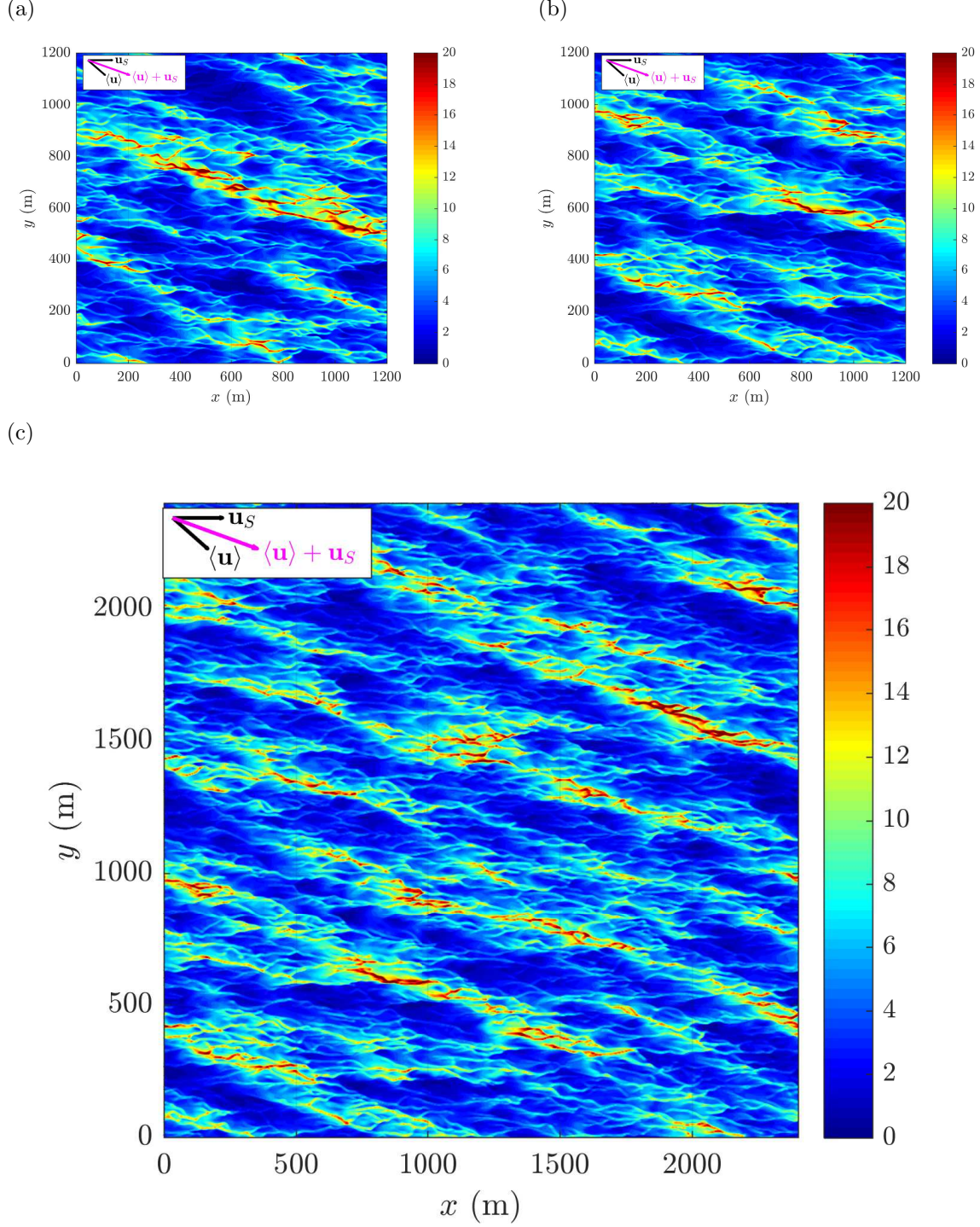
Supplementary Figure 7: As in Fig. 6, but for $\langle u'w' \rangle / u_*^2$ (a) and $\langle v'w' \rangle / u_*^2$ (b).



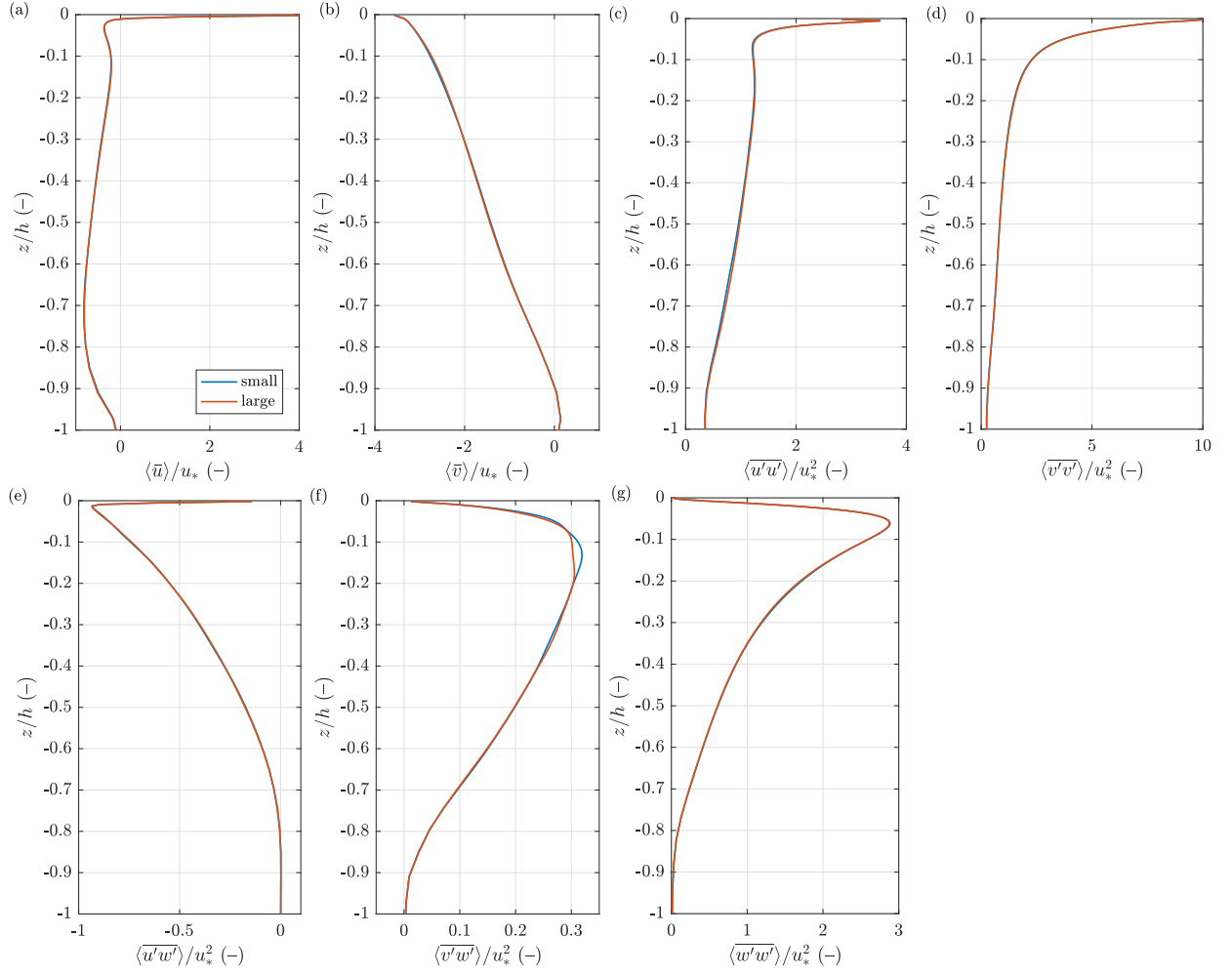
Supplementary Figure 8: As in Fig. 6, but for $\langle u'u' \rangle / u_*^2$ (a), $\langle v'v' \rangle / u_*^2$ (b) and $\langle w'w' \rangle / u_*^2$ (c). In (c), triangle symbols show $\langle w'w' \rangle / u_*^2$ obtained from measurements in the open ocean by D'Asaro (2001).

Supplementary Note S4. The influence of domain size on modelling results

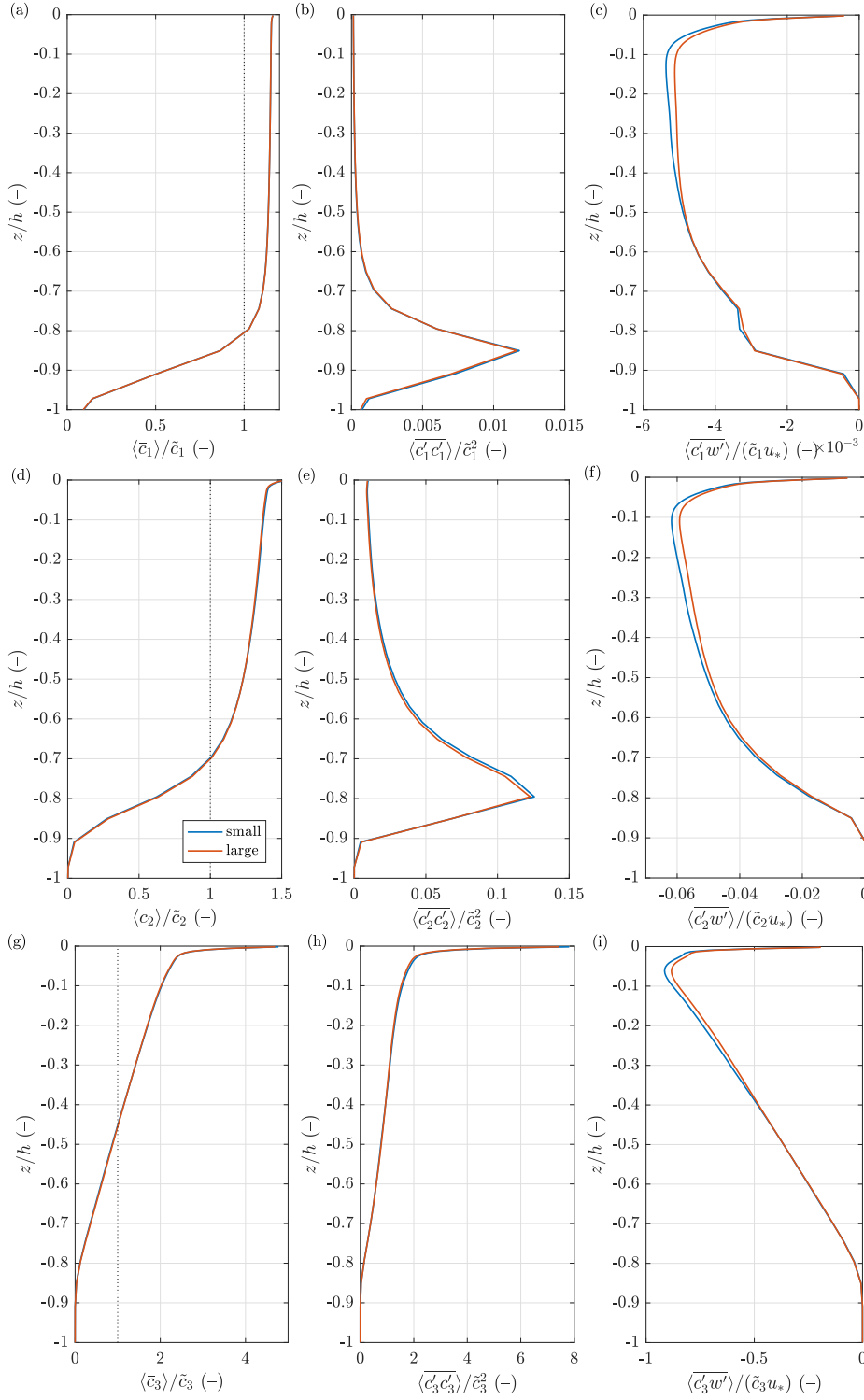
In order to test the influence of the model domain size on the modelling results, one of the forcing scenarios analyzed in the main text ($U_a = 15$ m/s and $T_a = -1.5^\circ\text{C}$) has been run on a large domain, 2400×2400 m² in size (as compared to 1200×1200 m² in the case of the ‘standard’ domain). The results are compared in Supplementary Figs. 9–11.



Supplementary Figure 9: Surface concentration of the frazil class 3 in simulations with $U_a = 15$ m/s and $T_a = -1.5^\circ\text{C}$: ‘small’ model domain, used in all simulations analyzed in the main text (a), and ‘large’ model domain with size 2400×2400 m² (c). In (b), a fragment of (c) is shown the same size as in (a).



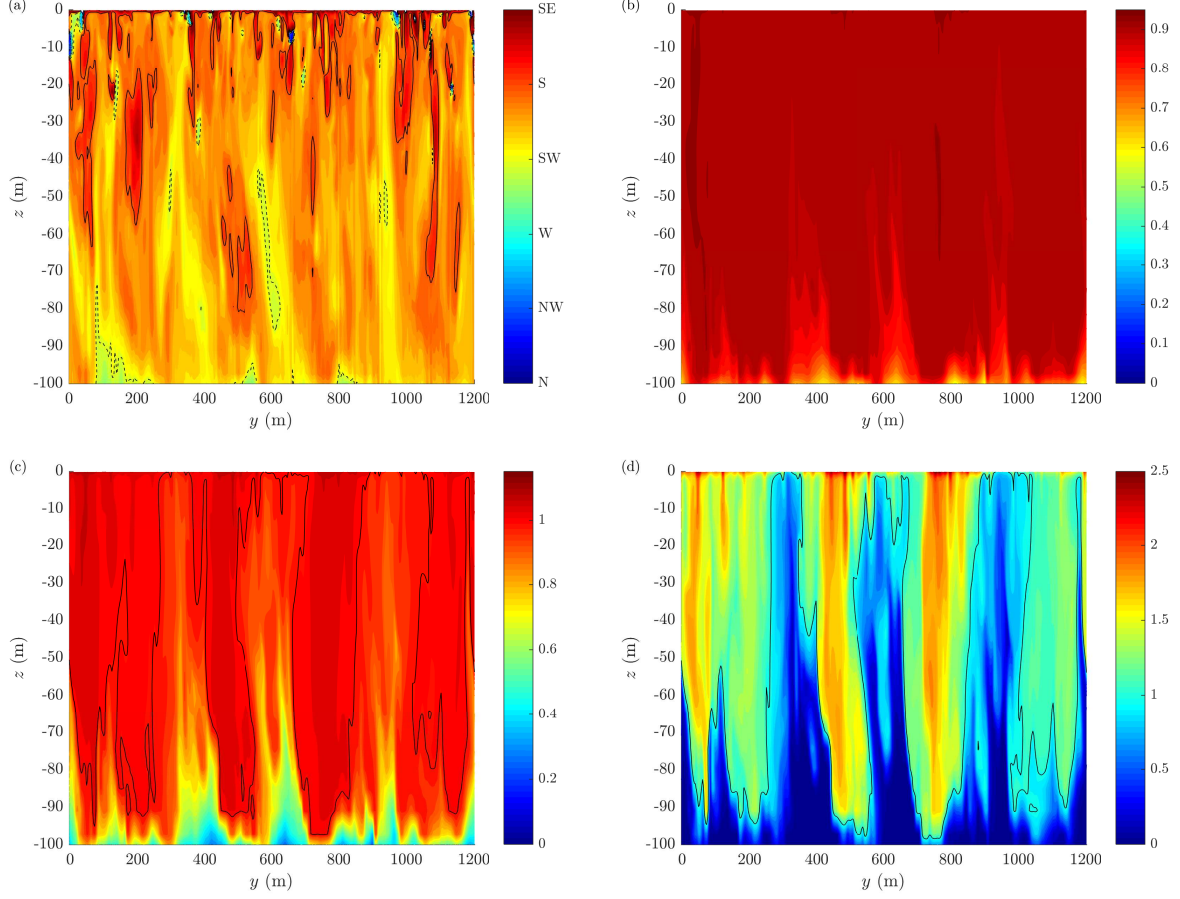
Supplementary Figure 10: Vertical profiles of the mean velocity (a,b), momentum flux (e,f) and velocity variance (c,d,g) for the small (blue) and large (red) domain. Results of simulations without frazil coupling (series \mathcal{F}_0). All values are normalized with the respective friction velocity u_* .



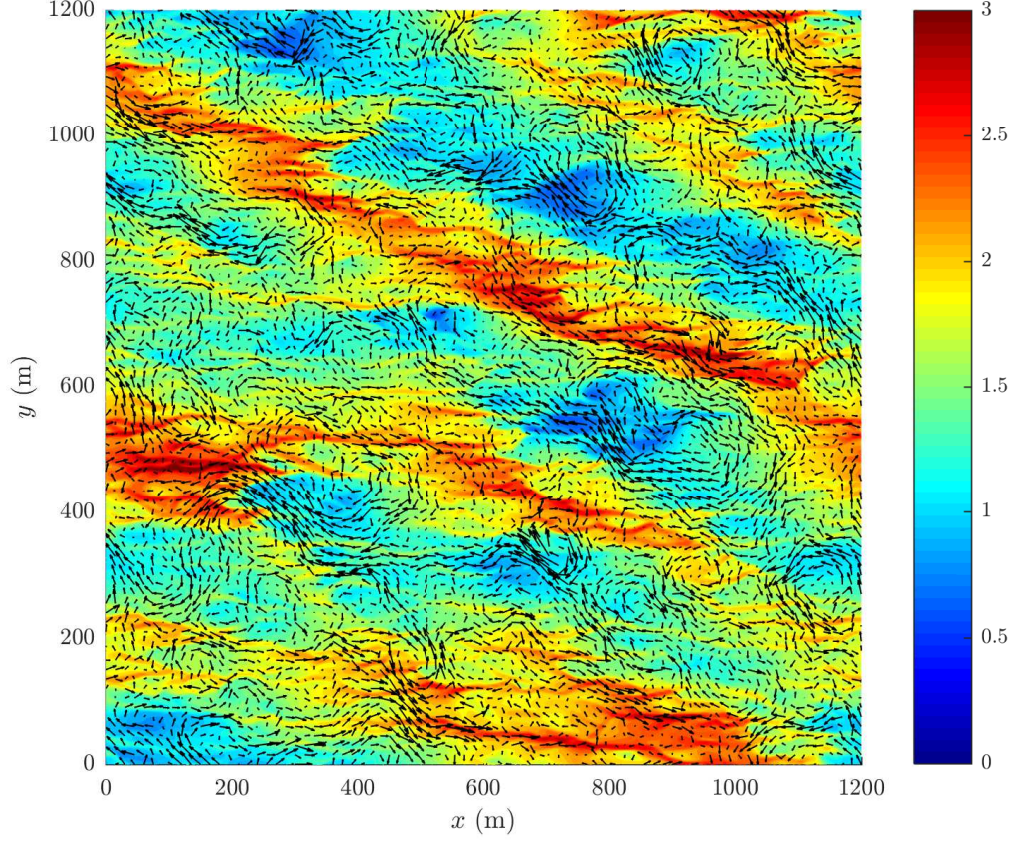
Supplementary Figure 11: Vertical profiles of the mean (a,d,g), variance (b,e,h) and vertical flux (c,f,i) of the frazil volume fraction for size classes 1–3 for the small (blue) and large (red) domain. Note different x axis ranges in the plots.

Supplementary Note S5. Selected details of simulations with $U_a = 30$ m/s, $T_a = -20^\circ\text{C}$, series \mathcal{F}_0

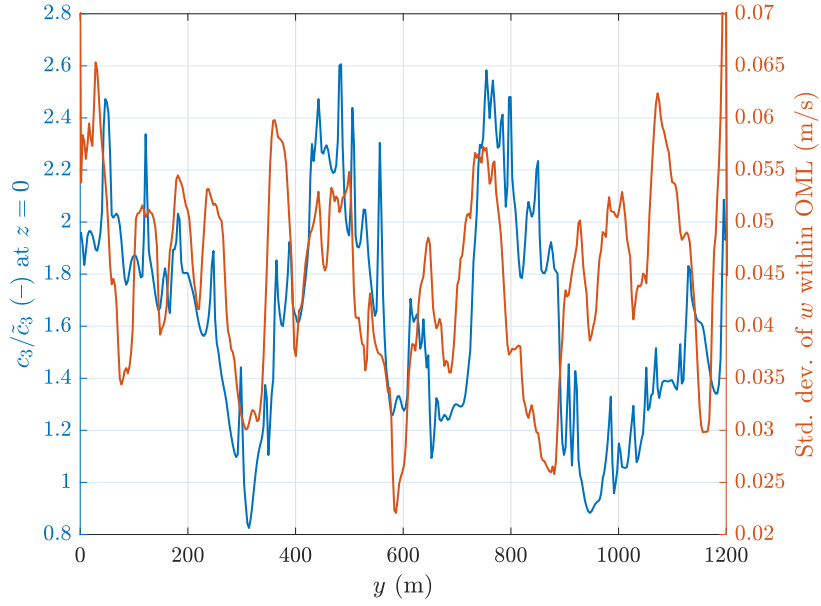
Figures in this section are analogous to those presented in Figs. 11–13 in the main text, but they present results from series \mathcal{F}_0 instead of \mathcal{F}_{all} .



Supplementary Figure 12: Direction of the horizontal flow (a) and frazil volume fraction c_i/\tilde{c}_i (b–d) along a cross-section through the model domain perpendicular to the wind/wave direction. In (a), a ‘to’-convention is used, i.e., S means current flowing *to* the south and so on. In (b)–(d), black contours show the value of 1. Results of simulations with $U_a = 30$ m/s, $T_a = -20^\circ\text{C}$, series \mathcal{F}_0 .



Supplementary Figure 13: Volume fraction of the largest frazil size class c_3/\tilde{c}_3 at the sea surface (colour) and anomalies of the vertically integrated horizontal currents (arrows) in simulations with $U_a = 30$ m/s, $T_a = -20^\circ\text{C}$, series \mathcal{F}_0 . For better visibility, only every 5th arrow in each direction has been plotted.



Supplementary Figure 14: Volume fraction of the largest frazil size class c_3/\tilde{c}_3 at the surface (left axis) and standard deviation of the vertical velocity w within the OML (right axis) in the same situation as shown in Fig. 12.

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