

Anonymous Referee #1

Thanks to devote time to the review of our manuscript. The manuscript has been revised following your comments and suggestions. In particular, we enhanced the comparison between 1.4 GHz and 19 GHz to highlight their complementary climatological information.

Interesting demonstration of SMOS (1.4 GHz) capability for melt detection compare to higher frequency (19 GHz). To my knowledge this is the first time that such a comparison has been done. Even if the observed results were expected : less sensitivity at 1.4 than at 19 GHz, the differences are well described and analysed. I suggest that the authors put more emphasis on these differences that could bring complementary climatological information compared to SSMIS.

In that sense, the Fig. 7 is very interesting (mean melting days detected at 1.4 GHz but dry at 19 GHz). What are the temporal variations of such observations over the SMOS period? Do you observe particular events, for particular years? For example, the years 2002/2003 and 2015/2016 are known to be particularly wet in the Antarctic Peninsula due to a strong ENSO events. See Zheng et al. 2019 RSE, 232 : Variations in Antarctic Peninsula snow liquid water during 1999–2017 revealed by merging radiometer, scatterometer and model estimations. This is unfortunate that the Fig. 1 stops in April 2015, because 2016 could be a good example of differences between 1.4 and 19 GHz data? See also Wiesenekker et al., 2018. A Multidecadal Analysis of Föhn Winds over Larsen C Ice Shelf from a Combination of Observations and Modeling. Atmosphere 9(5), 172. <https://doi.org/10.3390/atmos9050172> for the relationship between particular Föhn events and melting.

In order to improve the comparison between 1.4 GHz and 19 GHz, we extended the Section 4 with a more detailed view of the case, when day is detected as melting by SMOS but dry by SSMI. We mainly based this analysis on the articles that you suggest and added a focus on the Antarctic Peninsula. We focused the analysis on the period 2013–2013 2013–2016 when the variation are stronger. Fig. 1 have been extended over this period, and we added a new figure with some Peninsula maps to better highlighted the temporal variation.

Thus, we added the following text in the end of the Section 4 and putted the figure previously named 'Figure 7' in the following of this Section:

However, it also happens that some melting days are detected with the 1.4 GHz observations but not with the 19 GHz observations. This case is illustrated with the example of the Antarctic Peninsula provided by Figure 1r for the three summer seasons from 2013 to 2016. This area is known to be submitted each year to a long melting season, but an interannual variability is observed. Zheng et al. (2019) studied the Antarctic Peninsula with satellite radiometer and scatterometer as well as climate model. They found that over the period 2010–2017 the lower wet snow extend is observed in during the 2013/14 summer season, whereas the largest is observed during 2015/16. These minimum and maximum are also retrieved by SMOS and SSMI during this period.

Figure 1r (bottom) shows the number of days detected as melting at 1.4 GHz but dry at 19 GHz. In 2013/14, 2.6 days on average are only detected as melting by SMOS over a surface of 35,625 km²

(57 pixels). In 2015/16, 12.3 days on average are only detected as melting by SMOS over a surface of 83,125 km² (133 pixels), which is 57% and 24% larger than in 2013/14 and 2014/15, respectively. As 2015/16 is known to be submitted to an intensive melting event in Antarctic Peninsula due to a strong El-Nino event (Nicolas et al., 2017), this could suggest that 1.4 GHz provide another information than 19 GHz in the case of intense melting events. In this way, Wiesenekker et al. (2018) showed that a stronger than normal foehn wind, which is a hot, dry wind on the downwind side of a mountain range, happens over the Peninsula in 2015/16. This generates an increasing in melt near the foot of the Antarctic Peninsula mountains. This area matches the pixels where 1.4~GHz observations detected more than 20 days not detected by 19 GHz (Figure 1r). Moreover, Datta et al. (2019) also found that high melt occurrence induced by foehn wind are observed in 2015/16, and they highlighted that the foehn wind increases the meltwater percolation up 2-m depth along the mountains. This suggests that SMOS observations could provide information about a part of snowpack in depth, which is not reaches by SSM/I observations.

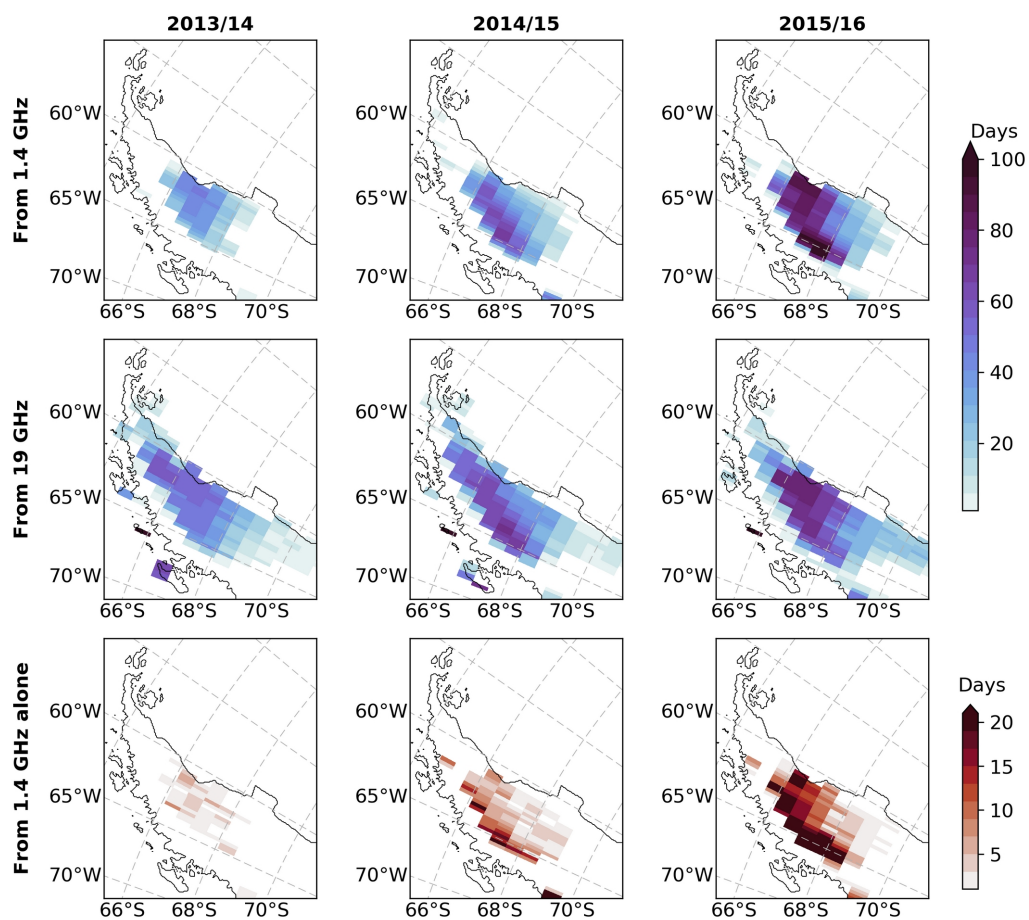


Figure 1r: Annual melting duration (days) over the Antarctic Peninsula detected with observations (top) at 1.4 GHz and (middle) at 19 GHz from 2013/14 to 2015/16. (bottom) Number of days detected as melting at 1.4 GHz but dry at 19 GHz.

Figure 7 (now 6) maps for the whole continent the mean number of melting days detected at 1.4 GHz without concurrent detection at 19 GHz during summer season over our dataset. It shows that the geographical distribution is related to the total number of melt event (Figure 3), meaning that all the areas are concerned by the differential detection at both frequencies. On average, 10 ± 8 days are detected only by SMOS. Moreover, over a total of about 117,000 melting days taking all pixels and summer seasons together detected at 1.4 GHz, 28% are not concurrently detected at 19 GHz. These melting days happen on 1 February \pm 23 days on average, i.e. at the end of summer season.

Conversely, over 225,000 melting days detected by 19 GHz during the same period, 66% are not concurrently detected at 1.4 GHz.

I also suggest to add Zheng et al. 2019 reference (and others) for mentioning scatterometer and radar capabilities compared to radiometers (not mentioned in the paper).

As you suggest in order to improve the context description in Introduction, we added sentences and provided references including Zheng et al. (2019) to highlight the capability of active sensors to detect melt on the ice sheet. We added in the text:

"Various detection algorithms have been developed for active sensors (e.g. Nghiem et al., 2001, 2005; Ashcraft and Long, 2006; Kunz and Long, 2006; Hall et al., 2009; Trusel et al., 2012; Zheng et al., 2019) and passive sensors (e.g. Mote et al., 1993; Ridley, 1993; Zwally and Fiegles, 1994; Abdalati and Steffen, 1997; Torinesi et al., 2003; Liu et al., 2005, 2006; Tedesco, 2007; Tedesco et al., 2007) and applied in the Greenland and Antarctica ice sheets."

The DMRT-ML analysis is a very good added-value to this paper.

Also, could you specify which ice/water mask do you used for SMOS? same as for resampled SSMI mask? source of error?

The mask used here is the mask associated to the EASEGrid 2.0 map projections. It is available on the NSIDC website: <https://nsidc.org/data/nsidc-0609>. Brodzik et al. (2011) derived this Land-Ocean-Coastline-Ice (LOCI) classification from the MODIS land cover product. We added this information to the SMOS observations description in Section 2.1.

As SMOS and SSMI datasets are not built in the same grid some collocation error can happen. We added a description of the used method to compare the two datasets in Section 2.2:

"To compare SMOS and SSMI datasets, the SSMI observations and products are collocated within the SMOS grid using the nearest neighbour method. If the nearest neighbour is not flagged as 'land' in the SSMI grid, the pixel was removed from our analysis to avoid the error of comparison between the two frequencies. In this way, about 50 pixels are excluded, which doesn't affect the statistical significance of the comparison results."

Note that the development of a Level 3 SMOS product within a polar stereographic projection is in progress by CATDS team, but up to now the official release is available from the February 2018 to present and the whole timeseries from 2010 is not yet ready.

Does the Fig. 5 cover the entire SMOS period and for the whole Antarctica?

Fig. 5a-c refers to the DMRT-ML simulations. On Fig. 5d, the histogram only includes SMOS pixels fulfilling the two conditions: 1) have been detected as 'melting' at least once over the period 2010-2018, and 2) the ice thickness is 1000 ± 50 m (cf. in the text LXXX). This is described in Section 5.2 at the beginning of the third paragraph. We added a cross-reference to text in the figure legend to find more information. Note that Fig. 5 in the first version is now Fig. 7 in the updated article.

Anonymous Referee #2

We appreciated very much your comments and efforts in reviewing this paper. The manuscript has been revised, according to comments and suggestions provided.

The authors have performed a study to detect the melt occurrence in Antarctica using SMOS observations. Authors have compared the SMOS detection results to those obtained using 19.7 GHz passive observations. This study provides very good results –showing the usefulness of SMOS observations for melt occurrence detection. Theoretical analysis explains well the differences between the L-band and 19.7 GHz observations and provided very nice basis on understanding the importance on having observations at both frequencies to better monitor the melt occurrences. The manuscript is well written and structured, it is easy to read and understand. The aim of the study is clearly explained, and conclusions are well provided. Scientifically, the paper is solid, it provides interesting and important new information on how to better detect and monitor the ice melt on Antarctica. I recommend this paper to be published and have only some minor comments to be considered before publishing.

The comments are listed below.

1) Line 46: I assume the authors are using CATDS data from 50 to 55 degrees.

Yes. We now specified in the text:

" T_B at vertical (V) and horizontal (H) polarizations for the 50-55° average range of incidence angle are used here."

2) Lines 120-121: The selected temperature profile is a little strange: From surface to 10 m: 273 K, then constant 263K to 500m depth. Are the authors really using this, or should it be from surface to 10 m dropping from 273K to 263 K?

There is a mistake in the text for the temperature profile description. In fact, the used profile is: from the surface to 5 m: 273 K, then constant 263 K to 500 m. We choose to fix the temperature at 273 K within the first 5 m in order to limit the temperature variations effect and highlight the LWC effect.

3) Figure 5: Based on the model results, the selected density profile has a large impact. T_b as a function of the liquid water content is totally different if a smooth density profile is applied. Daily winter SMOS observations are compatible with the third density profile (20 kg/m³). How much the density profile varies in real life, may there be an additional source of uncertainty for the SMOS based estimations?

It is really difficult to have a reliable estimation of the density variability range, due to the lack of in situ measurement and the large penetration depth of SMOS. For example, at Dome C, we estimated the density variability about 25-30 kg m⁻³ close to the surface (Leduc-Leballeur et al., 2015). However, the snowpack structure in Dome C area is typical of the dry snow region, which is completely different of the wet snow area.

Here, thanks to the simulations with 3 values of density variability and the comparison with the SMOS observations during winter, we can suggest that a variability lower than 10 kg m⁻³ is not very probable and 20 kg m⁻³ was selected (Figure 5). However, the standard deviation of the SMOS histogram (206.9±8.9 K) also suggests a variability which could be in part linked to a change in the

density variability of the profile. So, as you highlight, the lack of knowledge of the density variability can add uncertainty to simulate the SMOS observations.

4) Line 138: Odd sentence, maybe "have been selected" should not be there.

Thank you for the notice. We removed "have been selected".

5) Line 162: Maybe, to clarify for the readers, the authors could use: "The wet layer thickness" instead of "The layer thickness"

We added "wet" to clarify the sentence.

6) Line 174: The sentence is a bit confusing starting from words "or if the event was produce a lot..."

To clarify, we corrected this sentence part as:

"if water has percolated over a sufficient thickness to be detected by SMOS."

7) Figure 6: The caption text is not as informative as it could be. "as a function of the wet snow depth" => how about: "as a function of the wet snow layer depth". By adding the word layer, it is easier to understand that the simulation is done using constant layer thickness but in different depths. Also, consider adding the layer thicknesses here.

We changed the caption text for Figure 6 as:

"DMRT-ML brightness temperature at H polarization (K) for 55° of incidence angle as a function of the wet snow layer depth within the snowpack for a wet layer thickness of 1 m at 1.4 GHz (green) and 0.1 m at 19 GHz (blue)."

Melt in Antarctica derived from SMOS observations at L band

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Abstract. Melt occurrence in Antarctica is derived from L-band observations from the Soil Moisture and Ocean Salinity (SMOS) satellite between the austral summer 2010/11 and 2017/18. The detection algorithm is adapted from a threshold method previously developed for 19 GHz passive microwave measurements from Special Sensor Microwave Imagers (SSM/I, SSMIS). The comparison of daily melt occurrence retrieved from 1.4 GHz and 19 GHz observations shows an overall close agreement, but a lag of few days is usually observed by SMOS at the beginning of the melt season. To understand the difference, we performed a theoretical analysis using a microwave emission radiative transfer model that shows that the sensitivity of 1.4 GHz signal to liquid water is significantly weaker than at 19 GHz if the water is only present in the uppermost tens of centimeters of the snowpack. Conversely, 1.4 GHz measurements are sensitive to water when spread over at least 1 m and when present at depth, up to hundreds of meters. This is explained by the large penetration depth in dry snow and by the long wavelength (21 cm). We conclude that SMOS and higher frequency radiometers provide interesting complementary information on melt occurrence and on the location of the water in the snowpack.

1 Introduction

Melt occurs in coastal Antarctica and on ice shelves during the austral summer. Its duration and extent are useful climate indicators due to their connection to surface temperature and surface energy budget (e.g. Liu et al., 2006; Picard et al., 2007). Moreover, intense melting event has been identified as a precursor of some major ice shelf collapses (Scambos et al., 2000). Thus, monitoring of the melt season contributes to characterize the seasonal and inter-annual climatic variations in Antarctica and is important to assess the future stability of the ice-sheet (Golledge et al., 2015).

Remote sensing offers a particularly relevant means to obtain information over the entire Antarctic continent and over long-term periods, given the very rare in situ measurements related to melt or liquid water (Jakobs et al., 2019). Microwave radiometers-frequencies have been widely used to detect melt in polar regions exploiting the marked increase-of-brightness-temperature-variation-of-the-signal due to the high absorption of microwaves by water relative to that of dry snow. Various detection algorithms have been developed for active sensors (e.g. Nghiem et al., 2001, 2005; Ashcraft and Long, 2006; Kunz and Long, 2006; H and passive sensors (e.g. Mote et al., 1993; Ridley, 1993; Zwally and Fiegles, 1994; Abdalati and Steffen, 1997; Torinesi et al., 2003; Liu and applied in Greenland (e.g. Mote et al., 1993; Abdalati and Steffen, 1997; Tedesco, 2007) and Antarctica (e.g. Ridley, 1993; Zwally and They-the Greenland and Antarctica ice sheet.

In the case of radiometer, studies have mainly used 19 GHz and 37 GHz frequencies available since 1979 from several satellite sensors such as the Scanning Multichannel Microwave Radiometer (SMMR) on the Nimbus 7 satellite or the Special Sensor Microwave/Imager (SSM/I) and Special Sensor Microwave Imager Sounder (SSMIS) from the Defense Meteorological Satellite Program (DMSP) satellites. Since 2009, the Soil Moisture and Ocean Salinity (SMOS) satellite has provided
30 radiometric observations at L band(~~1.4 GHz~~), a frequency capable of penetrating much deeper in the ice sheets, on the order of several hundred meters at 1.4 GHz (Passalacqua et al., 2018) compared to only a few meters for the higher frequencies (Surdyk, 2002). This suggests that L-band observations could offer new information on melt.

The aim of this study is to retrieve melt in Antarctica from daily SMOS observations, and to investigate the similarities and differences with melt detected at 19 GHz. Section 2 introduces the data sets. Section 3 describes the method to detect
35 melt and Section 4 compares the daily melt occurrence obtained with 1.4 GHz and 19 GHz observations. Section 5 presents a modeling study to assess the liquid water sensitivity of brightness temperature (T_B) at 1.4 GHz and to discuss the differences with 19 GHz.

2 Data sets

2.1 SMOS observations

40 The SMOS mission was developed by the European Space Agency (ESA) in collaboration with the Centre National d'Etudes Spatiales (CNES) in France and the Centro para el Desarrollo Tecnológico Industrial (CDTI) in Spain. This satellite is operated by CNES and ESA and carries on board a L-band interferometric radiometer operating at 1.4 GHz (21 cm) with an averaged ground resolution of 43 km (Kerr et al., 2010). The radiometer provides multi-angular fully polarized T_B (Kerr et al., 2001).

The SMOS Level 3 product delivers multi-angular T_B at top of the atmosphere in the antenna polarization reference frame
45 (Al Bitar et al., 2017). The product is georeferenced on the Equal-Area Scalable Earth version 2.0 grid (EASE-Grid 2; Brodzik et al. (2012)), with an over-sampled resolution of about 628 km², which is distorted in the polar regions (around 100×6 km² as latitude×longitude). It comprises daily-average and incident angle-average with angle bins every 5° from 0° to 65°. T_B at vertical (V) and horizontal (H) polarizations ~~at 52.5°~~for the 50-55° average range of incidence angle are used here. They come from the RE04 reprocessed version between April 2010 and April 2015, and from operational version between ~~Mai~~May 2015
50 to March 2019, both distributed by CATDS (Centre Aval de Traitement des Données SMOS; www.catds.fr).

The gaps shorter than 3 days in the SMOS time series are filled by a linear interpolation. Longer gaps result in missing value in the product. If more than 60 days are missing over a year, the grid point is ignored for that year (about 7% of pixel every year, mainly south of 83°S).

The land-ocean mask used comes from the Land-Ocean-Coastline-Ice classification associated to the EASEGrid 2.0 map
55 projections and derived from the MODIS land cover product by Brodzik and Knowles (2011) (available on https://nsidc.org/data/nsidc-060

2.2 Observations at 19 GHz and daily surface melting

Satellite observations at 19 GHz were acquired by the Special Sensor Microwave/Imager (SSM/I) and Special Sensor Microwave Imager Sounder (SSMIS), processed by the National Snow and Ice Data Center (NSIDC, Maslanik and Stroeve
60 (2004, updated 2018)).

Daily T_B observations at H polarization are processed according to Picard and Fily (2006); Picard et al. (2007) to derive daily surface melt from 1979 to 2018 (data available from <http://gp.snow-physics.science/melting>). This data set provides daily melt status, i.e. presence or absence of liquid water, for every grid point on the Southern stereographic polar grid with a grid spacing of 25 km². The effective resolution of the product is coarser, of the order of 40 km, close to that provided by SMOS.

65 To compare SMOS and SSMI datasets, the SSMIS observations and products are collocated within the SMOS grid using the nearest neighbour method. If the nearest neighbour is not flagged as "land" in the SSMIS grid, the pixel was removed from the analysis to avoid the error of comparison between the two frequencies. In this way, about 50 pixels are excluded, which doesn't affect the statistical significance of the comparison results.

3 Melting detection method

70 The algorithm to detect melt occurrence from the 1.4 GHz observations is inspired by the work at 19 GHz of Torinesi et al. (2003), itself based on ~~Zwally and Fiegles (1994)~~Zwally and Fiegles (1994). The algorithm determines an optimal threshold for every year in every pixel, and considers that any daily T_B over this threshold indicate melting occurrence. T_B is measured at large observation angle (above 50°). In this configuration, the H polarization is favored because the emissivity of dry firn is usually significantly lower at H than at V polarization, while the emissivity of wet firn is always close to 1 at both polarizations.
75 It results that the increase in T_B from dry to wet snow is more significant at H polarization, and easier to detect.

The algorithm uses an adaptive threshold T in each grid point and for each year given by $T = M + a\sigma$, with M the time average and σ the standard deviation of T_B when snow is dry. According to the analysis of daily air surface temperature, Torinesi et al. (2003) found a suitable value of $a = 3$ so that most melting events correspond to daily maximum temperatures above -5°C. This value is also typical for outliers detection (e.g. von Storch and Zwiers, 2001).

80 To solve the circular problem of computing M and σ for non melting days in order to detect melting days, the initial step consists in calculating M in each grid point on a fixed period of one year – from 1 April to 31 March – and in setting $a\sigma$ to a first-guess fixed value. Previous studies for 19 GHz used $a\sigma = 30$ K. However, we found it unsuitable at 1.4 GHz, because of the weaker sensitivity to liquid water (Section 5). We instead propose a lower first guess value of $a\sigma = 15$ K.

With these assumptions, a first guess melt time series is detected and new estimates of M and σ are computed by removing
85 melting days from the T_B series, still limiting the period from 1 April and 31 March. Melt is then detected once again using the updated threshold. The process is iterated three times to ensure stable estimates. The algorithm returns a binary indicator for each day and each grid point, 0 for the absence and 1 for the present of liquid water.

This algorithm needs further correction for some false alarms found on the Antarctic Plateau where melt is known to never occur. These alarms are likely due to variations of T_B of the order of several Kelvin that were reported by ~~Brueker et al. (2014)~~

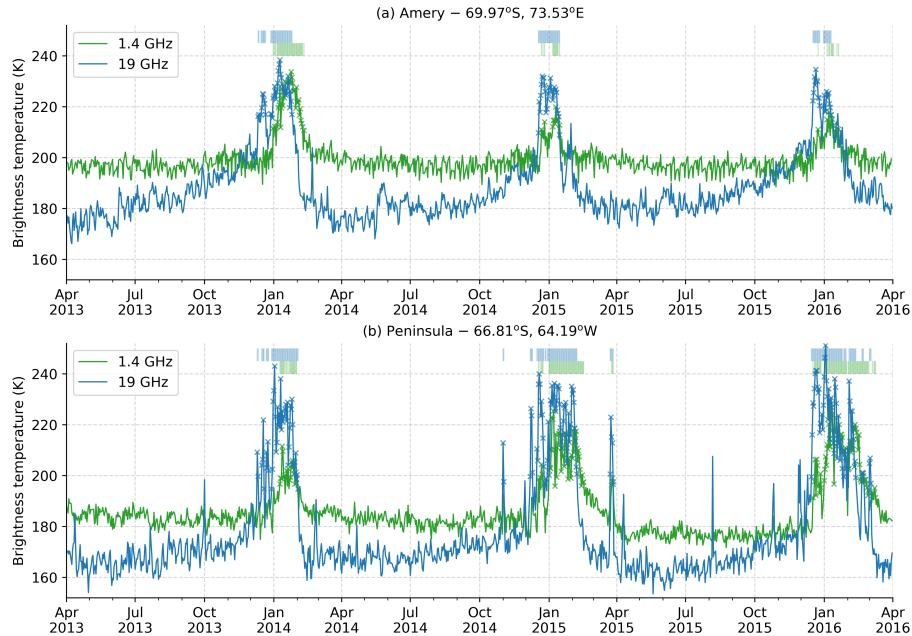


Figure 1. Brightness temperature at H polarization (K) at 1.4 GHz (green) and 19 GHz (blue) from April 2012 to March 2016 on (a) the Amery area and (b) the Antarctic Peninsula. The melting days detected by each frequency are depicted by crosses on the time series and recalled by pale lines above.

90 and Leduc-Leballeur et al. (2017) Brucker et al. (2014) and Leduc-Leballeur et al. (2017) and explained to result from the snow metamorphism and surface hoar removal by wind storms. Noting that these changes do not impact $T_B V$, although melt does, we consider here that the areas with low annual standard deviation of $T_B V$ are not subject to melt. We estimated a threshold standard deviation of 2.8 K based on the fact that it excludes 95 % of grid points with surface elevation higher than 1500 m. Thus, as a final step of the algorithm, the grid points with a $T_B V$ annual standard deviation lower than this threshold are masked
95 out that year.

4 Comparison with 19 GHz

Figure 1 shows two examples of two consecutive melt seasons in the Amery area (69.97°S, 73.53°E) and the Antarctic Peninsula (66.81°S, 64.19°W). For each event, melt is detected several days earlier at 19 GHz compared to 1.4 GHz. For instance, in 11 December 2013 on the Amery time series, a short melting event lasting 6 days is missed at 1.4 GHz while it is well detected
100 at 19 GHz. This suggests that this event was weak and only affected the superficial part of the snowpack. On the other hand, the short melting event during March 2015 on the Peninsula time series is detected by both frequencies, suggesting intense melt with percolation in a large upper part of the snowpack.

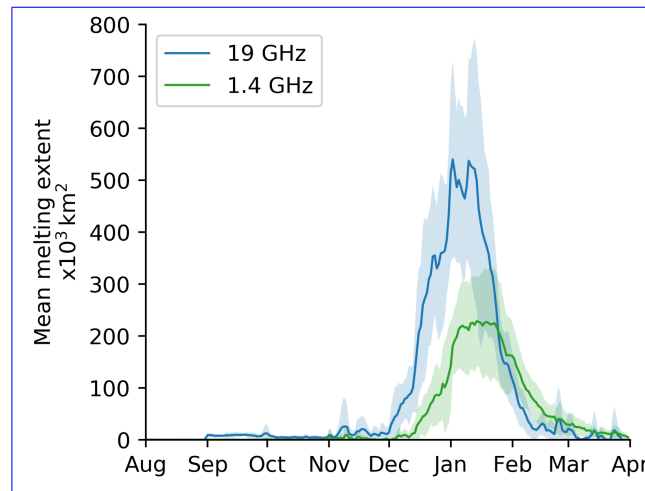


Figure 2. Daily mean melting extent from April 2010 to March 2018 detected with observations at 1.4 GHz (green) and at 19 GHz (blue). Standard deviation is in pale area.

The beginning of the melt season detected usually largely differs between both frequencies as illustrated in Figure 2. On average, the first melting day can be detected as early as September at 19 GHz, while it is rare to detect melt earlier than
 105 December at 1.4 GHz. For the pixel where melt is detected by both frequencies in a given year, the 19 GHz detection precedes by 1-5 days for 28% of the pixels and by 6-15 days for 26% of them. This lag is also observed for the end of the season with a remanence of the melt detected at 1.4 GHz until nearly April.

Figure 2 also highlights that the melt extent detected at 19 GHz is 3 to 6 times as large as at 1.4 GHz, depending on the years. The standard deviation maximum is reached in January at 250,000 km² and 110,000 km² for 19 GHz and 1.4 GHz,
 110 respectively.

~~Daily mean melting extent from April 2010 to March 2018 detected with observations at 1.4 GHz (green) and at 19 GHz (blue). Standard deviation is in pale area.~~

Spatial variation are illustrated by Figure 3, which shows the annual mean duration of melt season between April 2010 and March 2018 detected at both frequencies. Melting is concentrated on the coast with a maximum in the Antarctic Peninsula as
 115 previously reported for 19 GHz (Tedesco, 2009; Kuipers Munneke et al., 2012; Datta et al., 2018, 2019; Scott et al., 2019). The largest differences are observed in Filchner and Ross ice shelves where melt is detected to occur a few days every year at 19 GHz, but is insufficient to be detected at 1.4 GHz. The difference is certainly explained by the difference of sensitivity. Indeed, as these ice shelves only experience limited melt, the liquid water is likely concentrated in the uppermost few centimeters of the snowpack.

120 Figure 4 highlights 3 and 4 highlight that 19 GHz is more effective to detect short melting duration than 1.4 GHz. Indeed, more than 55% of the pixels where melt occurs remain wet for less than 10 days in a year according to 19 GHz observations, and about 20% remain wet between 11 and 20 days. At 1.4 GHz, the duration of the melt season is usually longer, in only

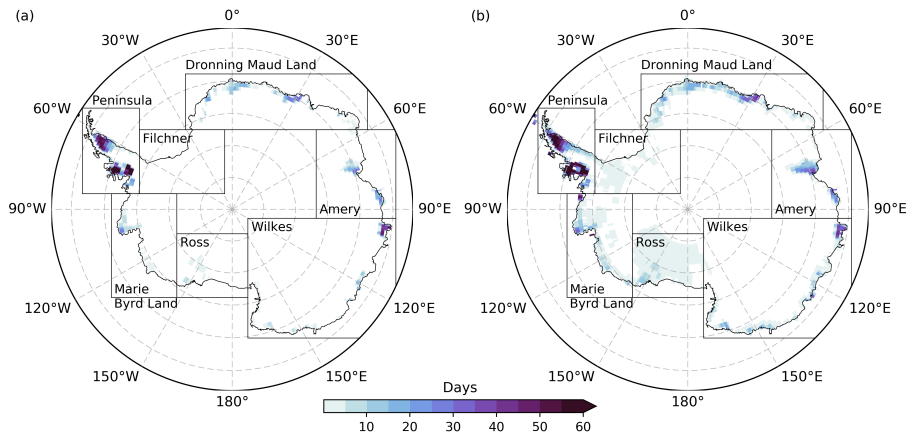


Figure 3. Annual mean of melting duration (days) from April 2010 to March 2018 detected with observations (a) at 1.4 GHz (SMOS) and (b) at 19 GHz (SSMIS). Seven regions are outlined.

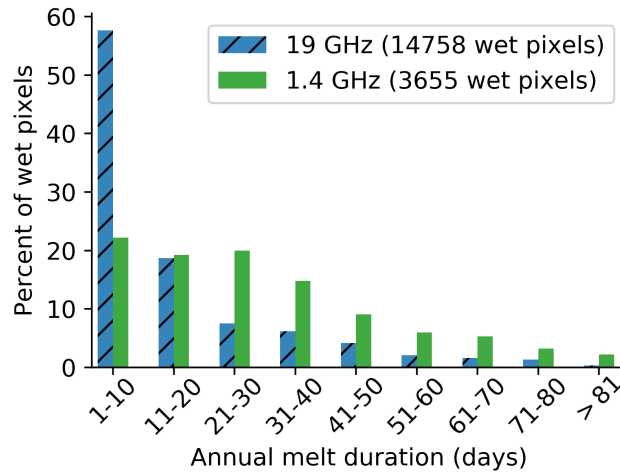


Figure 4. Annual melting duration distribution of wet pixels detected with 1.4 GHz (plain green) and 19 GHz (hatched blue) over the whole Antarctica for each summer season from 2010 to 2018.

20% of the pixels subject to melt, the season is 1-10 days, it is 11-40 days in 55% of the pixels. This hints that SMOS is only sensitive to long and intense melt seasons.

125 However, it also happens that some melting days are detected with the 1.4 GHz observations but not with the 19 GHz observations. This case is illustrated with the example of the Antarctic Peninsula provided by Figure 5 for the three summer seasons from 2013 to 2016. This area is known to be submitted each year to a long melting season, but an interannual variability is observed. Zheng et al. (2019) studied the Antarctic Peninsula with satellite radiometer and scatterometer as well as climate model. They found that over the period 2010-2017 the lower wet snow extend is observed during the 2013/14 summer season.

130 whereas the largest is observed during 2015/16. These minimum and maximum are also retrieved by SMOS and SSMIS during this period.

Figure 5 (bottom) shows the number of days detected as melting at 1.4 GHz but dry at 19 GHz. In 2013/14, 2.6 days on average are only detected as melting by SMOS over a surface of 35,625 km² (57 pixels). In 2015/16, 12.3 days on average are only detected as melting by SMOS over a surface of 83,125 km² (133 pixels), which is 57% and 24% larger than in 2013/14 and 2014/15, respectively. As 2015/16 is known to be submitted to an intensive melting event in Antarctic Peninsula due to a strong El-Niño event (Nicolas et al., 2017), this could suggest that 1.4 GHz provide another information than 19 GHz in the case of intense melting events. In this way, Wiesenekker et al. (2018) showed that a stronger than normal foehn wind, which is a hot, dry wind on the downwind side of a mountain range, happens over the Peninsula in 2015/16. This generates an increasing in melt near the foot of the Antarctic Peninsula mountains. This area matches the pixels where 1.4 GHz observations detected more than 20 days not detected by 19 GHz (Figure 5). Moreover, Datta et al. (2019) also found that high melt occurrence induced by foehn wind are observed in 2015/16, and they highlighted that this foehn wind increases the meltwater percolation up 2-m depth along the mountains. This suggests that SMOS observations could provide information about a part of snowpack in depth, which is not reached by SSMIS observations.

Figure 6 maps for the whole continent the mean number of melting days detected at 1.4 GHz without concurrent detection at 19 GHz during summer season over our dataset. It shows that the geographical distribution is related to the total number of melt event (Figure 3), meaning that all the areas are concerned by the differential detection at both frequencies. On average, 10±8 days are detected only by SMOS. Moreover, over a total of about 117,000 melting days taking all pixels and summer seasons together detected at 1.4 GHz, 28% are not concurrently detected at 19 GHz. These melting days happen on 1 February ± 23 days on average, i.e. at the end of summer season. Conversely, over 225,000 melting days detected by 19 GHz during the same period, 66% are not concurrently detected at 1.4 GHz.

5 Sensitivity to liquid water content

The sensitivity to liquid water at 1.4 GHz is investigated in order to understand the signal variations observed in Antarctica and to investigate the observed differences with the 19 GHz melt detection.

5.1 Microwave emission modeling

155 T_B is simulated with the multi-layered Dense-Medium Radiative Theory model (DMRT-ML, Picard et al., 2013), available online <http://gp.snow-physics.science/dmrtml>. This model is based on the radiative transfer theory (Tsang and Kong, 2001). The snowpack is represented by a stack of snow horizontal layers defined by their thickness, temperature, density, grain size, and liquid water content (LWC). Simulations are performed at 1.4 GHz and 19 GHz with an incidence angle of 55°.

A synthetic snowpack is assumed to run simulations. Its has a total thickness of 1000 m, and is divided in layers of 5 cm from the surface to 500 m and 50 m below. Temperature is 273 K from the surface to 105 m depth, then constant at 263 K up to 500 m depth and finally, linearly increasing to reach 273 K at the bottom. Density linearly increases from 300 kg m⁻³ at the

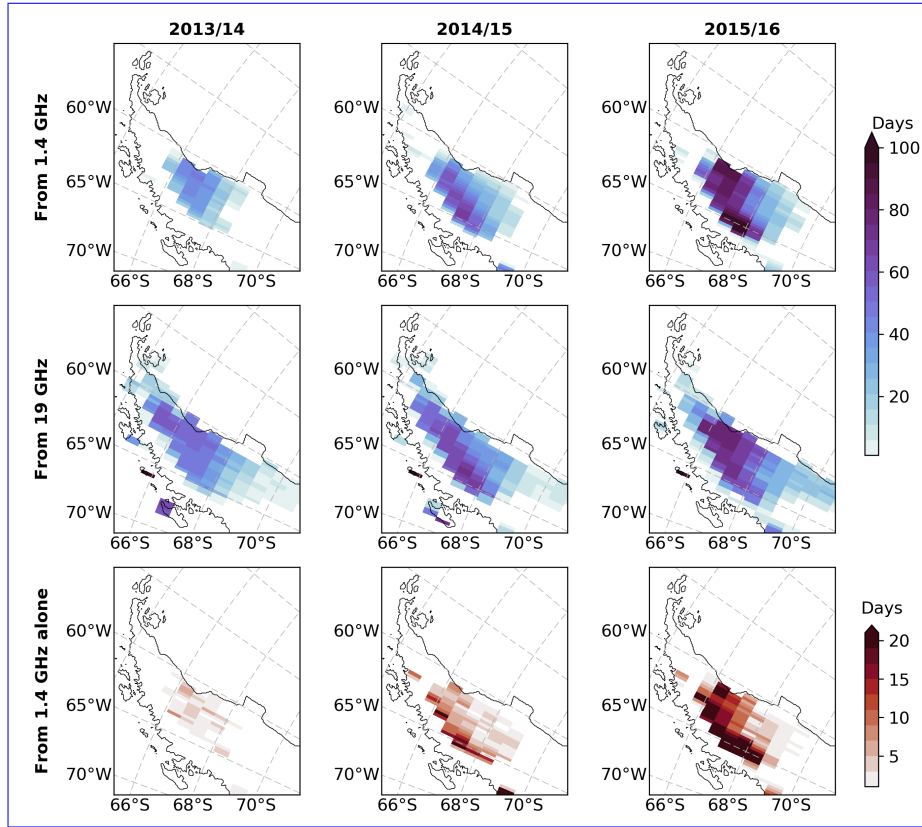


Figure 5. Annual melting duration (days) over the Antarctic Peninsula detected with observations (top) at 1.4 GHz and (middle) at 19 GHz from 2013/14 to 2015/16. (bottom) Number of days detected as melting at 1.4 GHz but dry at 19 GHz.

surface to 917 kg m^{-3} at 100 m in depth and is constant below (Leduc-Leballeur et al., 2015). Grain size is constant at 1 mm. [Picard et al. \(2013\)](#) [Picard et al. \(2013\)](#) showed that grain size has an effect on the sensitivity to LWC at 19 GHz. Nevertheless, it is not expected at 1.4 GHz because the wavelength is much larger than grain size and scattering by grains can be neglected (Mätzler, 1987).

5.2 Effect of snow density vertical variability

By modeling L-band emission at Dome C on the Antarctic Plateau, [Leduc-Leballeur et al. \(2015\)](#) [Leduc-Leballeur et al. \(2015\)](#) highlighted that layering must be considered to obtain reliable T_B estimation. To assess if this is also the case for wet snow, the simulations are performed with a smooth density profile and two density profiles with an added Gaussian noise of standard deviation of 10 kg m^{-3} and 20 kg m^{-3} , respectively, between the surface and 300 m depth. Figure 7 shows the DMRT-ML simulations at both 1.4 GHz and 19 GHz as a function of LWC, and for various thicknesses of wet snow.

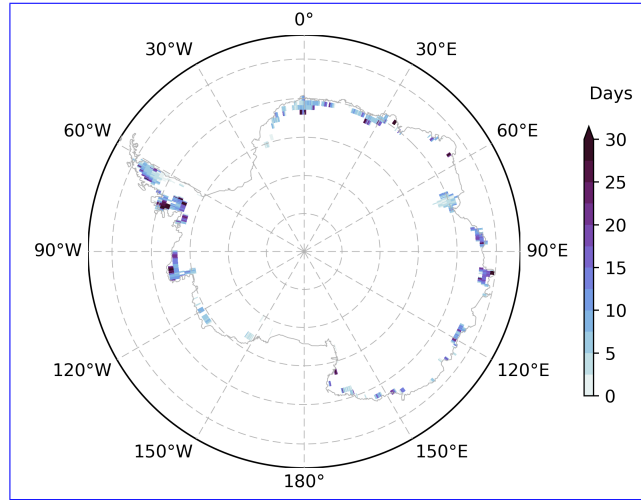


Figure 6. Mean melting days by summer season detected as melting at 1.4 GHz but dry at 19 GHz.

For the dry snowpack ($LWC = 0 \text{ kg m}^{-2}$), the layering significantly decreases T_{BH} from 248.1 K for the smooth density profile to 231.8 K and 196.9 K for the density profiles with standard deviation 10 kg m^{-3} and 20 kg m^{-3} , respectively. In wet snow condition, the layering effect becomes weaker as the LWC increases and is insignificant ($< 4 \text{ K}$ variations) for LWC larger than 1 kg m^{-2} or when water is spread over a large thickness. Thus, between dry and wet conditions, T_{BH} difference increases with the layering.

Figure 7d shows daily SMOS T_{BH} from June to August – a period when snow is expected to be always dry – in 2010-2018. The histogram only includes pixels where melting has been detected at least once ~~have been selected~~ and where ice thickness is $1000 \pm 50 \text{ m}$ to match with the snowpack configuration used for simulations. The SMOS T_{BH} average is $206.9 \pm 8.9 \text{ K}$. This suggests that simulations with a density variability lower than 10 kg m^{-3} overestimate the dry T_{BH} and thus underestimate the variations between dry and wet snow at 1.4 GHz. We thus now consider the case of a density variability of 20 kg m^{-3} only.

The simulations show that T_{BH} at 1.4 GHz increases from dry to wet by 19 K when the wet snow layer is 0.25 m and 53 K when it is 5 m (Figure 7c). While in both cases, the change is high and detectable, this highlights that not only the total column amount of liquid water is important but also the distribution in depth. Additionally, Figure 7c shows that the maximum of increase of T_{BH} is reached for LWC of 0.75 kg m^{-2} and 0.15 kg m^{-2} , respectively for the 0.25 m and 5 m thick wet snow layers. This means that the LWC sensitivity of 1.4 GHz T_{BH} is weaker when liquid water is confined in the uppermost tens of centimeters of the snowpack. This is rational for choosing a lower first guess $a\sigma$ for the detection algorithm at 1.4 GHz than at the higher frequencies (Section 3).

Additionally, Figure 7c shows that regardless of the wet layer thickness, T_{BH} reaches a maximum at a certain LWC value, which decreases when the wet layer becomes thicker. Thus, an increase in LWC is not detectable because of the T_B saturation. This jeopardizes the possibility of using microwave observations to estimate LWC values or even the wet layer thickness.

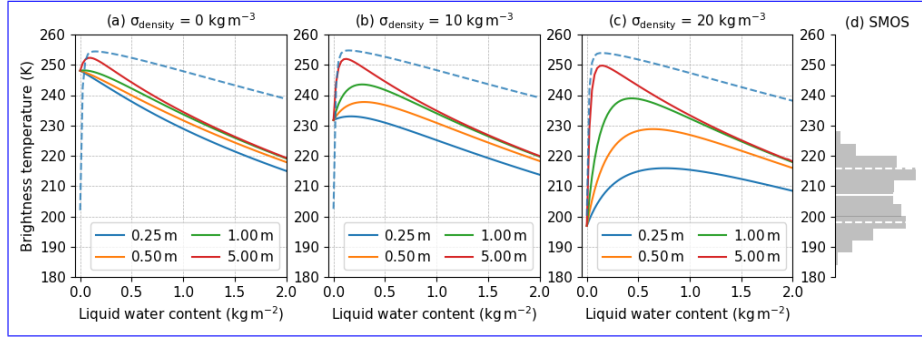


Figure 7. (a-c) DMRT-ML brightness temperature at H polarization (K) as a function of liquid water content for several wet snow thickness in the upper snowpack (colors) at 1.4 GHz (solid lines) and 0.25 m of wet snow at 19 GHz (dashed line) with three density variabilities (σ_{density}). (d) Daily winter SMOS observations distribution ([cf. text for details](#)) with mean (white solid) and standard deviation (white dashed).

By contrast, at 19 GHz, the density variability has no effect and the T_{BH} variations are mainly driven by LWC. A sharp increase of 54 K is observed and the maximum is reached for LWC of 0.15 kg m^{-2} . The thickness of the wet snow layer has no effect (not shown in Figure 7c).

195 As a conclusion, these simulations show that 19 GHz is more sensitive to liquid water than at 1.4 GHz and that other factors such as the vertical distribution of the water or the layering have a lesser influence. This indicates that detection of melt occurrence at the surface is more robust at 19 GHz.

5.3 Effect of the wet snow depth

We explore here the situation when the wet snow layer is buried under a layer of dry firn. This corresponds to the end of summer
 200 when the snowpack freezes up from the surface, or on the ice shelves where melt water enters the crevasses and accumulates at depth. The simulations are performed with a wet snow layer (0.2 kg m^{-2}), progressively moved down from the surface to 400 m depth. The [wet](#) layer thickness is 1 m at 1.4 GHz and 0.1 m at 19 GHz to moderate the sensitivity effect presented in the previous section. Results highlight that T_{BH} is maximum when wet snow is at the surface for both frequencies and decreases within a few meters at 19 GHz and more gradually at 1.4 GHz (Figure 8). T_{BH} is still more than 10 K higher than in dry
 205 conditions when the wet layer is at 60 m depth at 1.4 GHz. Deeper than 100 m, the difference between dry and wet T_{BH} is lower than 3 K, i.e. lower than the noise level with SMOS.

At 19 GHz, the simulation shows a T_{BH} variation of 2 K between dry and wet when the wet snow is at 5 m depth. Thus, the sensitivity to liquid water is relatively quickly lost at this frequency if the water percolate deep into the firn. However, observations at 19 GHz should still be suitable for the detection of remnant liquid water at the end of the season, and when the
 210 snowpack is continuous, i.e. without crevasse.

These results suggest that despite a lower sensitivity at 1.4 GHz, liquid water could be detected with SMOS up to several tens of meters at depth and this is a new information compared to that provided by existing melt product derived from 19 GHz

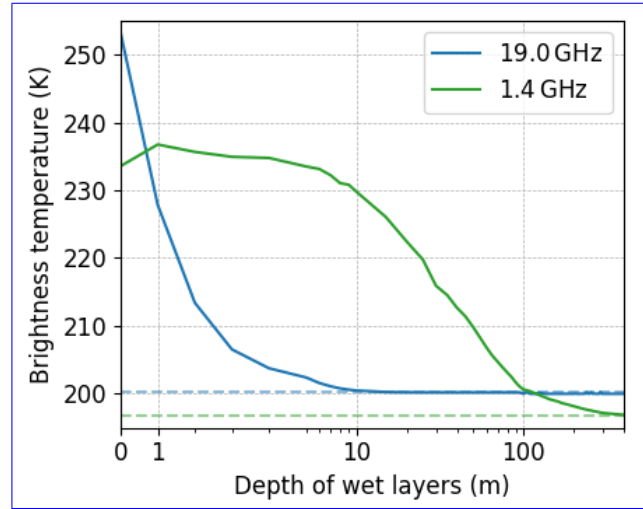


Figure 8. DMRT-ML brightness temperature at H polarization (K) for 55° of incidence angle as a function of the wet snow layer depth within the snowpack for a wet layer thickness of 1 m at 1.4 GHz (green) and 0.1 m at 19 GHz (blue). Values for a dry snowpack are in dashed lines.

and higher frequencies observations. The difference observed between 19 GHz and 1.4 GHz could be exploited to determine if the melt event was limited to the few first centimeters of snowpack or if ~~the event was produce a lot of water that~~ water has percolated over a sufficient thickness to be detected by SMOS.

~~Figure 6 maps the mean number of melting days detected at 1.4 GHz without concurrent detection at 19 GHz during summer season over our dataset. It shows that the geographical distribution is related to the total number of melt event (Figure 3), meaning that all the areas are concerned by the differential detection at both frequencies. On average, 10 ± 8 days are detected only by SMOS. Moreover, over a total of about 117,000 melting days taking all pixels and summer seasons together detected at 1.4 GHz, 28% are not concurrently detected at 19 GHz. These melting days happen on 1 February ± 23 days on average, i.e. at the end of summer season. Conversely, over 225,000 melting days detected by 19 GHz during the same period, 66% are not concurrently detected at 1.4 GHz. This is in agreement with the difference of sensitivity between both frequencies suggested by the results of DMRT-ML simulations.~~

~~Mean melting days by summer season detected as melting at 1.4 GHz but dry at 19 GHz.~~

6 Conclusions

The L-band brightness temperature (T_B) from SMOS satellite has been explored to retrieve information about the melt season in Antarctica. Daily melt occurrence can be retrieved using previously developed algorithms for higher frequencies (Zwally and Fiegles, 1994; Torinesi et al., 2003) after a slight adaptation to account for the lower sensitivity at 1.4 GHz. The comparison of melt detected at 1.4 GHz and 19 GHz (Picard and Fily, 2006) shows a lower rate of detection at 1.4 GHz. In particular, SMOS misses short, probably weak, events, which are in contrast perfectly detected at 19 GHz.

A theoretical analysis has been performed using a snowpack emission radiative transfer model (DMRT-ML) in order to estimate the sensitivity of T_B at 1.4 GHz and 19 GHz to liquid water content (LWC) and water distribution in the snowpack. As expected from previous studies, a clear increase in T_B happens when snow becomes wet. However, the simulations clearly demonstrate that 1.4 GHz is less sensitive than 19 GHz, especially when liquid water stays within the first centimeters of the snowpack. A thick wet layer ($>$ about 0.5 m) is required to trigger a sharp and detectable T_B increase. Despite this limited sensitivity, the simulations show that 1.4 GHz is suitable to detect wet snow buried under a dry surface. For instance, an increase in T_B higher than 10 K with respect to a dry snowpack can be observed with liquid water at up to 60 m depth according to the simulation configuration.

An avenue is a combined use of both frequencies to determine if a melt event was limited to the surface of snowpack or if it was intense enough to inject water at depth. However, further algorithmic work is needed to exploit this possibility of deep water detection with SMOS.

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Data availability. Daily occurrence of melt retrieved from SMOS available at www.catds.fr/Products/Available-products-from-CEC-SM/CryoSMOS-project

Competing interests. The authors declare that they have no conflict of interest.

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