



Spatial variability of snow precipitation and accumulation in COSMO–WRF simulations and radar estimations over complex terrain

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Abstract. Snow distribution in complex alpine terrain and its evolution in the future climate is important in a variety of applications including hydro-power, avalanche forecasting and fresh water resources. However, the relative importance of processes such as cloud-dynamics and pure particle-flow interactions is still barely known and models are essential to investigate these processes. Here, we present very high resolution Weather Research and Forecasting model (WRF) simulations, which are initialized by 2.2 km resolution Consortium for Small-scale Modeling (COSMO) reanalysis (COSMO–WRF). To assess the ability of COSMO–WRF to represent spatial snow precipitation patterns, they are validated against operational weather radar measurements. Estimated WRF precipitation is generally higher than estimated radar precipitation, most likely due to an over-estimation of orographic precipitation in the model. The high precipitation also leads to a higher spatial variability in the model at the scale of 10 km. Overall, an autocorrelation and scale analysis of radar and WRF precipitation patterns show that WRF captures the variability relative to the domain wide variability of precipitation patterns down to the scale of few kilometers, but misses quite substantial variability on the smallest scales of a few 100 meters. However, differences of precipitation between 2830 m above sea level and the ground indicate that near-surface processes are active in the model.

1 Introduction

In many regions of the world, e.g. the Alps or the Californian Sierra Nevada, snow is the main source of fresh water. Additionally, it is an important resource for hydro-power and is essential for winter tourism in skiing areas (Schmucki et al., 2017). Thus, especially in a changing climate, it is essential to improve the understanding of processes forming the seasonal snow cover. Improving the ability of forecast models to represent the spatial variability of snowfall is further crucial to efficiently



manage fresh water and hydro-power. Moreover, as snow is a potential danger in terms of avalanches, improved knowledge about the distribution of snow is crucial for avalanche forecasting and prevention.

Snow accumulation patterns at a mountain-range scale are known to be strongly dependent on blocking and lifting processes including large-scale orographic enhancement (e.g. Houze, 2012; Stoelinga et al., 2013), which is related to the large-scale atmospheric circulation. However, for a long time little knowledge was available about the spatial distribution of snow on a mountain-slope or river-catchment scale. Only in recent years improvements in technology allowed the investigation of mountain-slope scale snow distribution (e.g. Grünewald et al., 2010; Prokop, 2008; Deems et al., 2006). Terrestrial and airborne laser scanning reveal annually persistent patterns of peak-of-winter snow accumulation distribution on river-catchment scales (Schirmer et al., 2011; Scipión et al., 2013), which is found to be consistent with few dominant snowfall events of the season. Driving processes of snow accumulation on a mountain-ridge scale were addressed in numerous studies, which reveal two main pre-depositional processes. On one hand, mountain-ridge scale precipitation and accumulation are influenced by local cloud-dynamic processes (Choularton and Perry, 1986; Dore et al., 1992; Zängl, 2008; Zängl et al., 2008; Mott et al., 2014). On the other hand, pure particle-flow interactions determine snow accumulation patterns in mountainous terrain (Colle, 2004; Zängl, 2008; Lehning et al., 2008; Dadic et al., 2010; Mott et al., 2010, 2014). On a mountain-ridge scale, Mott et al. (2014) could document the occurrence of a local event of orographic enhancement of snowfall due to the occurrence of a low-level cloud acting as a feeder cloud, giving evidence for the local occurrence of small-scale orographic enhancement by the seeder-feeder mechanism (e.g. Bergeron, 1965; Purdy et al., 2005). On similar scales, preferential deposition (Lehning et al., 2008) was found to cause enhanced snow accumulation on leeward slopes (e.g. Mott et al., 2010; Mott and Lehning, 2010). However, snow depth measurements in very steep terrain and corresponding local flow field measurements reveal even more complex particle-flow interactions (Gerber et al., 2017) than previously suggested based on model studies. On even smaller scales the main driver of snow accumulation patterns is post-depositional snow transport by drifting and blowing snow, which is dependent on local topographic features and wind gusts (Mott et al., 2010; Lehning and Fierz, 2008).

Complex topography-flow-precipitation interactions, especially on a mountain-ridge scale, still leave the relative importance of the different processes for snow accumulation and the frequency of occurrence barely known (Mott et al., 2014; Vionnet et al., 2017). Running a coupled simulation of the snowpack model Crocus and the atmospheric model Meso-NH in large eddy simulation (LES) mode, Vionnet et al. (2017) address the question of the relative importance of these different processes including snow redistribution by wind. Their results show that post-depositional snow transport dominates snow accumulation variability, but leaves the question of the relative importance of pre-depositional processes open.

To further investigate the relative importance of these processes, accurate model results and radar measurements on high resolution are essential. Here, we present a validation of very high resolution WRF simulations, which are forced by 2.2 km resolution Consortium for Small-scale Modeling (COSMO) reanalysis, with point measurements of temperature, relative humidity, wind speed and direction. Combining these WRF simulations with operational radar measurements we further present a variability analysis for snow precipitation on regional to mountain-ridge scale to address the question: How much snow precipitation variability is represented by very high resolution WRF simulations?



Remote sensing techniques are the most, or perhaps the only, practical mean for obtaining relevant distributed measurements of the atmosphere. They permit us to obtain information about both the small- and the large-scale properties of the atmospheric processes. The particular place among these techniques belongs to the weather radar, due to its wide coverage, fine spatial resolution, and interaction of microwaves with the precipitation. These properties have been used in inferring the orographic mechanisms, particularly in the case of liquid precipitation (Panziera et al., 2015). In this contribution, we are making use of the recently renewed MeteoSwiss radar network (Germann et al., 2015), and its adequate technical performances which allow observing precipitation in a very challenging, complex alpine environment.

In many studies the variability of small-scale snow accumulation has been addressed, reporting scale breaks in fractal analysis of snow accumulation patterns (e.g. Deems et al., 2008; Mott et al., 2011; Schirmer and Lehning, 2011). Reported scale breaks are mainly at scales <100 meters and represent the occurrence of a change in dominant processes (e.g. Deems et al., 2008). On very small-scales snow accumulation patterns are due to wind redistribution of snow (e.g. Vionnet et al., 2017). Vegetation effects were found to be dominant at smaller scales and terrain effects dominate on scales up to 1 km (Deems et al., 2006). Different dominant scales are reported for different slope expositions relative to the wind direction (Schirmer and Lehning, 2011). Furthermore, Schirmer et al. (2011) could show that snow accumulation smooths the underlying terrain, reducing the small-scale spatial variability of a certain slope. While most studies addressed variability of snow accumulation, the combined scale analysis of snow accumulation and snow precipitation patterns by Scipión et al. (2013) reveals much smoother patterns in snow precipitation at about 300–600 meters above ground compared to final snow accumulation at the ground on scales up to 2 km, stressing the importance of post-depositional processes for snow accumulation patterns.

While scale analysis has been performed multiple times for snow accumulation patterns on a local scale, we address measured and modeled snow precipitation patterns at the approximate elevation of the operational weather radar on Weissfluhgipfel at 2830 meters above sea level (m asl) on a mountain-ridge to regional scale. Additionally, we analyze modeled ground precipitation without taking into account any post-depositional processes. Given the different scales of analysis compared to previous studies, here we address scales on which local cloud dynamics and pure particle-flow interactions are expected to occur but leave out scales on which snow accumulation is expected to be dominated by post-depositional snow redistribution.

2 Data and Methods

2.1 WRF model setup

Atmospheric simulations are performed with the non-hydrostatic and fully compressible Weather Research and Forecasting (WRF) model (Skamarock et al., 2008) version 3.7.1 for the region of Eastern Switzerland (Figure 1). Simulations are set up with four one-way nested domains (d01–d04, Figure 1). Domain d01 has a horizontal resolution of 1350 meters, with 40 vertical levels and covers a region of about 250 times 320 kilometers including eastern Switzerland and a portion of the neighboring countries (Figure 1, Table 1). The three nests have horizontal resolutions of 450 meters, 150 meters and 50 meters using a nesting ratio (dx_{parent}/dx_{nest}) of 3. Domains d02–d04 have 40, 60 and 90 vertical levels, respectively, with the model top at 150 mb using a preliminary version of vertical nesting (Daniels et al., 2016). To make sure that there is plenty of domain

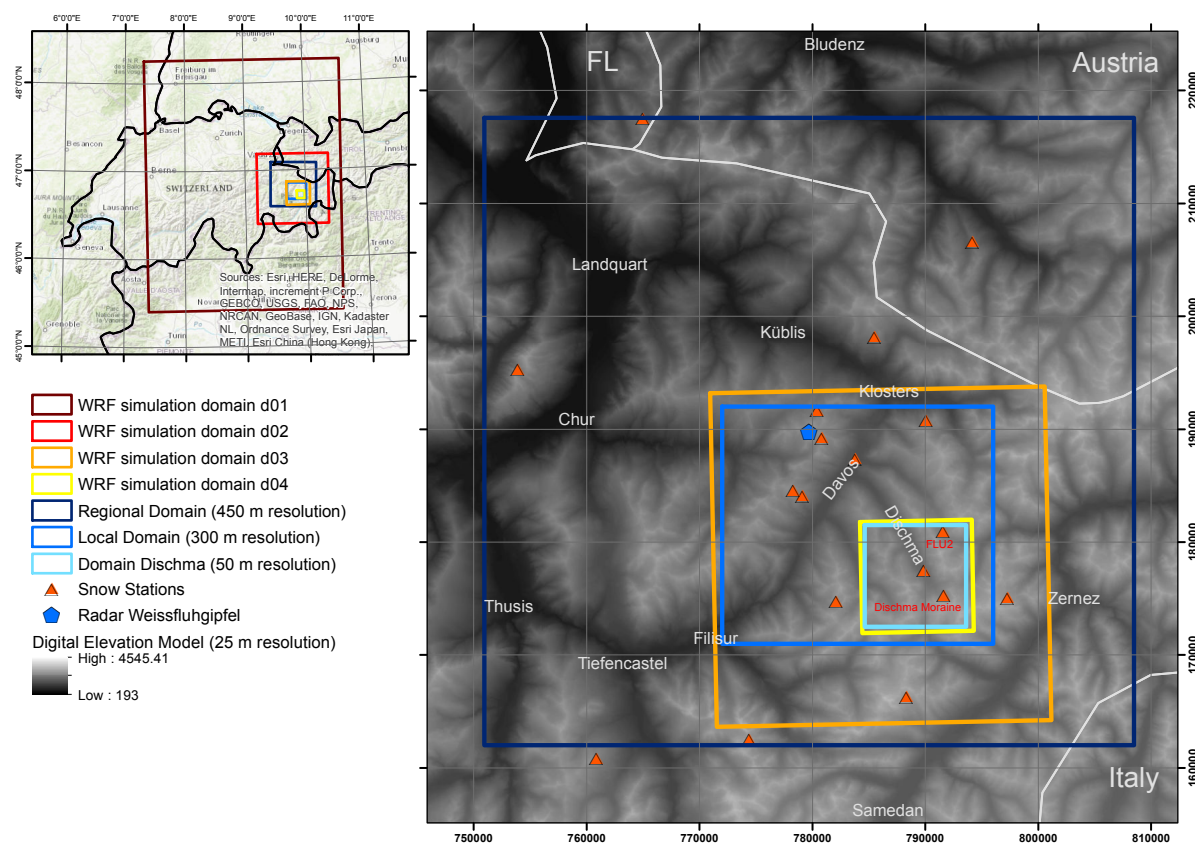


Figure 1. Overview over the study area in the eastern part of Switzerland surrounding Davos. WRF simulation domains (d01–d04, dark red to yellow) and evaluation domains (blue) give information on the simulation and evaluation setup. The 18 meteorological stations (red triangles) are within or very close to the regional domain. The two stations *Dischma Moraine* and *FLU2*, which are used to validate the model, are within domain *Dischma*. The operational weather radar is located on Weissfluhgipfel at approximately 2830 m above sea level (m asl, blue pentagon). Coordinates in the right panel are in Swiss coordinates CH1903LV03 (unit: meters). Shaded topography: dh25 © 2018 swisstopo (5740 000 000).

for the model to adapt to the refined topography, domain d02 is shifted toward the eastern boundary of domain d01 as dominant wind directions are from a north-westerly and southerly direction. Domain d02 covers the north-western part of Canton Grison (CH), while domains d03 and d04 cover the surroundings of Davos and the upper Dischma valley, respectively (Figure 1). For domain d04 the boundary layer is setup with refined vertical levels. Simulations are performed for three snow precipitation events in January, February and March 2016.

The parent domain is run with a planetary boundary layer (PBL) scheme, while the three nests are run in the large eddy simulation mode (WRF-LES). No strong differences were found when running domains d02 and d03 in mesoscale mode (not shown). Therefore and as we are interested in having an as good as possible representation of small-scale winds, we



decided to run our simulations in the LES mode for all nested domains. Additionally, this setup is consistent with previous very high resolution simulations by Talbot et al. (2012), except that they perform separate simulations for the mesoscale and LES domains, while we run a nested simulation with one-way feedback for all four domains. A combined simulation turned out to be necessary for precipitation to evolve properly in the LES domains, as hydrometeors cannot be used as a boundary condition in WRF simulations. Subgrid scale turbulence is parametrized by the 1.5 order turbulent kinetic energy closure. For the mesoscale setup the Yonsei University PBL parameterization (YSU PBL, Hong et al., 2006) is used, which is considered to be one of the schemes showing the best performance over complex terrain (Gómez-Navarro et al., 2015). An adapted version of YSU PBL was shown to perform even better when taking into account subgrid-scale variability of the terrain (Jiménez and Dudhia, 2012; Gómez-Navarro et al., 2015). However, given our high model resolution we decided to keep the model simple and run the simulations with the standard YSU PBL. Landuse data is taken from the Corine dataset (European Environmental Agency, 2006) and translated to the USGS conventions (Arnold et al., 2010; Pineda et al., 2004). Soil type is set to *silty clay loam* for the whole domain. The link between the soil, which is modeled by the Noah land surface model with multi-parameterization options (Noah-MP, Niu et al., 2011; Yang et al., 2011), and the atmosphere is given by the MM5 Monin-Obukhov surface model (Paulson, 1970; Dyer and Hicks, 1970; Webb, 1970; Beljaars, 1994; Zhang and Anthes, 1982), which is based on the Monin-Obukhov similarity theory (Obukhov, 1971). For microphysics the Morrison 2-moment precipitation scheme (Morrison et al., 2005, 2009) is used, which was found to be one of the schemes, which most adequately simulate snow precipitation over complex terrain (Liu et al., 2011). Details about processes in the Morrison parameterization are given in Appendix A. An investigation of different microphysical parameterizations would be interesting, but is beyond the scope of this study. Given the high horizontal resolution no sub-grid parameterizations for cumulus clouds is used.

As initial and boundary conditions for the parent domain we use reanalysis of the 2.2 km horizontally resolved Consortium for Small-scale Modeling (COSMO-2) model by MeteoSwiss. For COSMO-2 reanalysis data to be readable by the WRF pre-processing system a regridding of the rotated COSMO-coordinates to latitude-longitude coordinates is required. COSMO preprocessing, model adaptations and details about the model simulations are given in Gerber and Sharma (2018).

Topography in the model is based on the Aster Global Digital Elevation Model V002 with a resolution of one arc-second (METI/NASA, 2009). Due to the very complex terrain in the simulation area, topography smoothing has been applied for all domains. Four cycles of the WRF 1–2–1 smoothing (i.e. a moving window filter with a window length of 3 and weights of 1:2:1 for the grid points $i-1$, i and $i+1$) have to be applied to keep all slopes in the 50-meter resolution domain below 45° . Additionally, the boundaries of the parent domain are smoothed to match COSMO-topography (Gerber and Sharma, 2018). Test simulations are run with 14 cycles of WRF 1–2–1 smoothing, which allows for a longer computational timestep and therefore saves computational time (Table 1). Maximum slope angles for all domains and different smoothing are given in Table 1. Simulations with different precision of topography further allow us to address the importance of the representation of topography in the model. To allow the simulations to adapt to higher resolution topography domains d01–d04 are run with a spin-up of 24h, 12h, 6h and one hour, respectively.

As the snow cover in complex alpine terrain is likely rougher than for a flat field and to account for non-resolved topography and additional smoothing, snow surface roughness length has been changed to 0.2 m. The chosen roughness length is much



Table 1. Setup for the four nested domains (d01–d04) used in the WRF simulations. For the planetary boundary layer (PBL) the simulation mode is given, distinguishing between mesoscale and large eddy simulation (LES) settings. For mesoscale setting the PBL scheme is given. dx , dy give the horizontal resolution. *Vertical levels* gives the number of vertical levels in the different domains. The time step (dt) and the *maximum slope angle* are given for simulations with 4 (14) smoothing cycles.

Domain	PBL mode	PBL scheme	dx , dy (m)	Vertical levels	dt (s)	Max. slope angle °
d01	mesoscale	YSU ¹	1350	40	1 (6)	17.5 (9.9)
d02	LES	-	450	40	1/3 (2)	35.2 (26.5)
d03	LES	-	150	60	1/9 (1/2)	39.8 (36.8)
d04	LES	-	50	90	1/27 (1/4)	44.5 (37.4)

¹YSU: Yonsei University PBL scheme

larger than roughness lengths assumed by e.g. Mott et al. (2015). However, grid spacing in our simulations is larger and the roughness length is chosen such that it accounts for roughness elements in complex terrain (e.g. large rocks) and non-resolved topography, which are assumed to have an average size of about 2 m. This estimate is based on a comparison of a 2-meter digital terrain model (DTM-AV © 2018 swisstopo (5704 000 000)) to a 25 m resolution digital elevation model (dhm25 © 2018 swisstopo (5740 000 000)), which reveals an average difference on the order of 2.5 meters for bare ground conditions in domain d04 between 2200 and 2700 m asl. Hence, the estimate of 2 meters is rather conservative but takes into account smoothing of the terrain by the snow cover.

For the model validation (Sect. 3.1) WRF variables are linearly interpolated to the coordinates of the meteorological station (see Sect. 2.2). Temperature is corrected for elevation due to topographic smoothing using a moist-adiabatic temperature gradient of $-0.0065 K m^{-1}$. As wind measurements at the automatic weather stations are not taken at 10 meters but 4 or 5 meters above ground (Sect. 2.2), wind speed is corrected for elevation by applying a logarithmic wind profile. For simulation domains d01–d03 10-meter wind speeds are corrected, while for domain d04 wind speeds at the lowest model level (approximately 3 meters above ground) are used for the correction. The dynamic reference roughness length is chosen to be 0.2 m (corresponding to the surface roughness length in the model simulations). For wind direction comparisons wind directions at 10 meter and 3 meter above ground are chosen for the simulation domains d01–d03 and d04, respectively. As a reference COSMO-2 variables of the closest grid point to the station are included. Two-meter temperature and 10-meter wind speed of COSMO-2 are corrected for elevation by the same procedure as for WRF simulations.

2.2 Automatic weather stations

Snow depth measurements from a total of 18 automatic weather stations in the northwestern part of the canton Grison (Figure 1) are used. Two stations, (*Dischma Moraine* and *Dischma Dürrboden*), were installed as part of the Dischma Experiment (DISCHMEX), in which processes of snow accumulation and ablation in the Dischma valley near Davos (Switzerland) are ad-



dressed (Gerber et al., 2017; Mott et al., 2017; Schlögl et al., submitted). 16 stations are part of the Intercantonal Measurement and Information System (IMIS). The 18 stations are located between 1560 m asl and 2725 m asl. The stations measure snow depth in addition to the standard meteorological parameters. All stations have unshielded and unheated sensors. Biased temperatures during noon and occasional data gaps due to iced instruments may therefore occur. Two stations (*Dischma Moraine* and *FLU2*), which are located in the 50 m resolution WRF domain, are used for the model validation. The variables evaluated are two-meter temperature, two-meter relative humidity, wind speed and wind direction. Wind measurements at IMIS stations are taken about 5 meters above ground, while the wind sensor at station *Dischma Moraine* is located at about 4 meters above ground.

2.3 Operational weather radar data

- Weather radar datasets employed in the presented analyses are acquired by the MeteoSwiss operational radar located at the Weissfluhgipfel (2850 m asl), in the proximity of Davos. It is a dual-polarization Doppler weather radar, providing complementary information about the detected hydrometeors by considering their interaction with the incident electromagnetic radiation in both, horizontal and vertical, polarization planes. This complementary information leads to an enhanced clutter detection, which makes the radar measurements in such a complex mountainous terrain significantly more reliable. The polarimetry also makes it possible to identify the type of hydrometeors (Besic et al., 2016), which allows us to be confident that in the zone of interest for the presented study we deal with solid precipitation, consisting mostly of aggregates and crystals, and partly of rimed ice particles.

The radar operates in 5 minutes cycles during which it scans the surrounding atmosphere by performing complete rotations at twenty different elevations, from -0.2° to 40° (Germann et al., 2015). Operationally, the size of a radar sampling volume is 500 m in range, whereas the size observed in the perpendicular plane depends on the half-power beamwidth and increases with range. The acquired data undergo an elaborated procedure of corrections (Gabella et al., 2017). Before the quantity of precipitation at the ground level is estimated by averaging over 1 km^2 the observations are corrected for the Vertical Profile of Reflectivity (VPR) with the weight assigned to volumes being inversely proportional to their height above the ground (Germann et al., 2006).

- In the framework of our study, rather than relying on the operational radar product, we use data with the highest available resolution of 83 m in range. We also adopted a more conservative, non-operational method of clutter identification, which relies exclusively on the polarimetry and leaves very little residual clutter, however, sometimes at the expense of removing some precipitation. Given that we consider only radar measurements at low elevation angles in the vicinity of the radar and that the bright band is not present in our case studies (we observe above 2800 m during the winter season), the observations are not corrected for the VPR. Furthermore, given the strong influence of wind on the snow precipitation, we restrict our precipitation estimate on only four elevations, from the second to fifth (0.4° , 1° , 1.6° , 2.5°), avoiding the very first one, judged to contain too little information due to the abundant rejected ground clutter areas.

Polarimetry helps to identify non-meteorological scatterers, to distinguish between different types of hydrometeors, to correct for signal attenuation and to make quantitative estimates of intense to heavy rainfall. For snowfall measurements it is



common to use reflectivity Z at horizontal polarization and convert it into snow water equivalent S using a so-called Z-S relationship (Saltikoff et al., 2015):

$$Z = 100S^2. \quad (1)$$

The coefficients used in this formula account for the dielectric properties and fall velocities of snow and convert reflectivity Z in snow water equivalent S . The radar provides an indirect estimate of snowfall, rather than a direct measurement. Applied on each radar sampling volume scanned by the four selected elevations in the zone of interest (up to 40 km around the radar), the formula gives an estimate of liquid precipitation in the three-dimensional volume. By vertically averaging estimates from the four elevation sweeps using equal weights, we obtain the estimate of precipitation in polar (range, azimuth) coordinates at a flat plane at the height level of the radar. These estimates are summed up over 24h to get the accumulation maps used in the study.

Further on, the polar accumulation maps are re-sampled by means of the bi-linear interpolation to the Cartesian grid of the regional domain (450 m resolution) and the local domain (300 m resolution). The obtained Cartesian maps are finally processed to remove the residual clutter using a 3×3 median filter, partly or entirely. The former means that only the isolated high values in the original map are replaced with the corresponding value of the filtered map, at the positions where the difference between the original and the filtered map appears to be larger than 5 mm. The latter means that the entire map is influenced by the median filtering (denoted by "Radar all filtered" in the figures in the results).

2.4 Autocorrelation and variogram analysis

To investigate the variability of snow precipitation and accumulation patterns and their relation to topography a scale analysis, based on 2-dimensional (2D) autocorrelation maps and variograms, is performed. 2D-autocorrelation maps and variograms are further used to relate variability in radar and WRF precipitation. Given the resolution restriction by the radar measurements (Sect. 2.3) we analyze three different domains using horizontal resolutions of 450 m, 300 m, 150 m and 50 m, respectively. The domain with a resolution of 450 m covers about 30 km surrounding the radar on Weissfluhgipfel (hereafter regional domain, Figure 1). The domain with a resolution of 300 m covers an area of 24 km times 21 km to the south of Davos (Switzerland) including the Dischma valley (hereafter local domain). Radar data and WRF precipitation on all resolutions are additionally, evaluated on domain Dischma to address the influence on the spatial resolution of variability. Domain Dischma covers the upper Dischma valley with an extent of 9 km times 9 km.

The semivariance (γ) at 50 logarithmic lag distance bins (h) is calculated by

$$\hat{\gamma}(h) = \frac{1}{2|N(h)|} \sum_{(i,j) \in S(h)} (a_j - a_i)^2, \quad (2)$$

where $S(h)$ are the point pairs (i, j) and $N(h)$ gives the number of point pairs of the evaluated variable a . WRF and radar snow precipitation and topography are evaluated at 450 m and 300 m resolutions with a maximum lag distances of 25 km and 10 km, respectively. Variograms for domain Dischma are calculated with a maximum lag distance of 5 km. Minimum numbers



of point pairs in one lag distance bin for the local and regional domain are 18317 and 8035, respectively. For domain Dischma the minimum number of point pairs is between 677 and 55419, depending on the resolution.

To determine scaling properties an empirical log-linear model is fit to the variogram by least square optimization (Schirmer et al., 2011). The model used is not a valid variogram model but used to describe the experimental variograms and chosen to be consistent with Schirmer et al. (e.g. 2011). For all variograms three empirical log-linear models are fit:

$$y(x) = \begin{cases} \alpha_1 * \log(h) + \beta_1, & \text{for } \log(h) < l_1 \\ \alpha_2 * \log(h) + \beta_2, & \text{for } l_1 \geq \log(h) < l_2 \\ \alpha_3 * \log(h) + \beta_3, & \text{for } \log(h) \geq l_2 \end{cases} \quad (3)$$

using the constraint that each log-linear model needs to contain a minimum of four data points and the continuity constraint(s)

$$\begin{aligned} \alpha_1 \log(l_1) + \beta_1 &= \alpha_2 \log(l_1) + \beta_2 \\ \alpha_2 \log(l_2) + \beta_2 &= \alpha_3 \log(l_2) + \beta_3, \end{aligned} \quad (4)$$

where $\alpha_{1,2,3}$ and $\beta_{1,2,3}$ are the slopes and intercepts of the three log-linear models, respectively. Scale breaks (l_1, l_2) are the lag distances of the intersections of the first and second, and second and third log-linear model, respectively. Scale breaks were previously found to determine the scale of a change of dominant processes (e.g. Deems et al., 2006). To address the variability with respect to the overall variability of values, all variograms are normalized by the total domain-wide variance.

2D-autocorrelation is calculated based on Pearson's correlation coefficient r of all grid point pairs for a maximum lag distance of ± 40 grid points in x- and y-direction. This results in maximum lag-distances of 18 km for the regional domain.

2.5 Snowfall events

This study is based on three precipitation events in winter 2016. On 31 January 2016 the Azores high and a low-pressure area over Scandinavia induce westerly flow over central Europe and relatively mild temperatures with about -3°C at 2500 m asl. A shift of the Azores high toward northern Spain and a trough over eastern Europe lead to a change in wind direction toward northerly advection and a decrease of temperature (about -12°C at 2500 m asl) on 4 February 2016. On 5 March 2016 a low-pressure area over France, which is part of a large depression area over central Europe, causes southerly advection over Switzerland. Temperatures are about -7°C at 2500 m asl. Given the relatively high temperatures on 31 January 2016, which resulted in quite substantial liquid precipitation on the lowest elevations, total (solid and liquid) ground precipitation is evaluated. This does not make a big difference for the precipitation events on 4 February 2016 and 5 March 2016 but is essential for the precipitation event on 31 January 2016. For precipitation patterns at the elevation of the radar (2830 m asl) we only analyze solid precipitation from WRF.

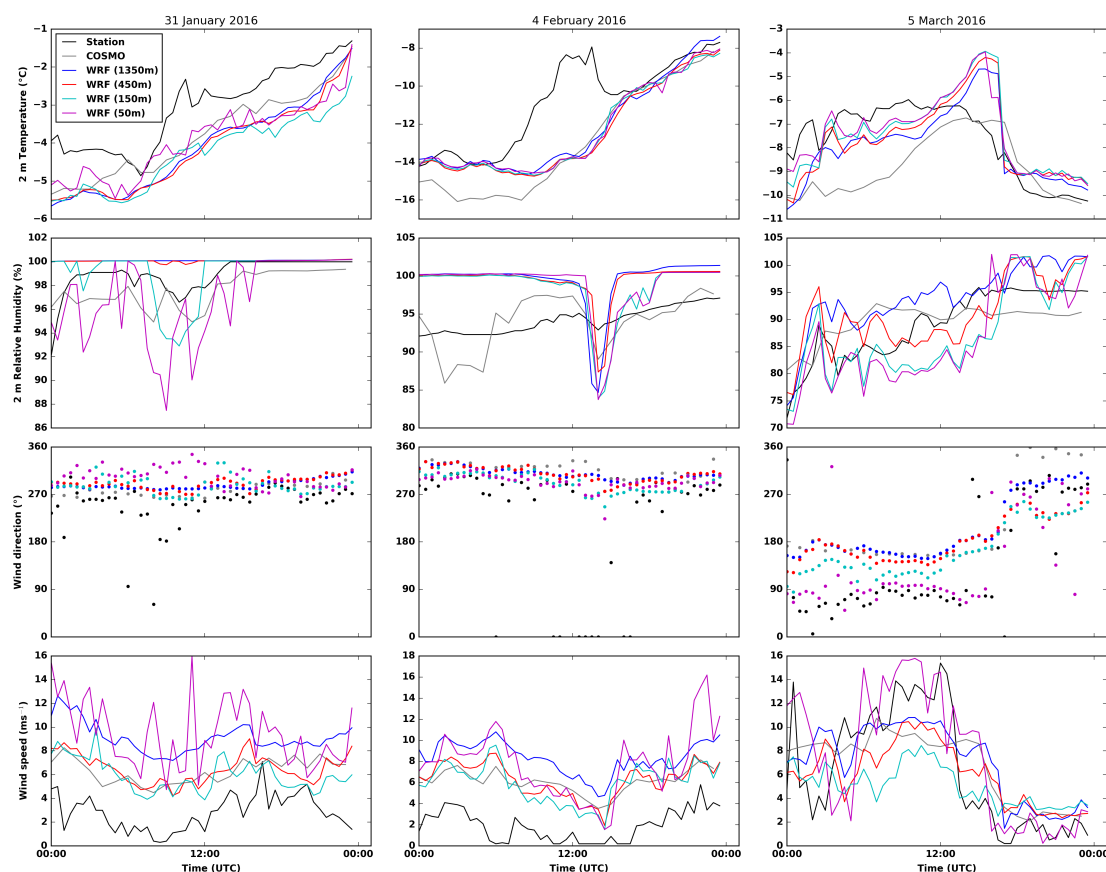


Figure 2. Comparison of two-meter temperature ($^{\circ}\text{C}$), two-meter relative humidity (%), 4-meter wind speed (ms^{-1}) and wind direction ($^{\circ}$) at station *Dischma Moraine* (black) to WRF simulations interpolated to the coordinates of station *Dischma Moraine* for the three precipitation events on 31 January 2016, 4 February 2016 and 5 March 2016 for all four simulation domains (d01: blue, d02: red, d03: cyan, d04: magenta). For comparison COSMO-2 is added for the closest grid point (gray). Two-meter temperature in WRF and COSMO are corrected for elevation based on a moist-adiabatic temperature gradient.

3 Results and Discussion

3.1 Point validation of WRF simulations

Two-meter air temperature, and 4- or 5-meter wind speed and direction at two stations (Sect. 2.2) are compared to WRF to validate the model (Figure 2 and Figure 3). For all stations two-meter temperature matches well with observations. Deviations

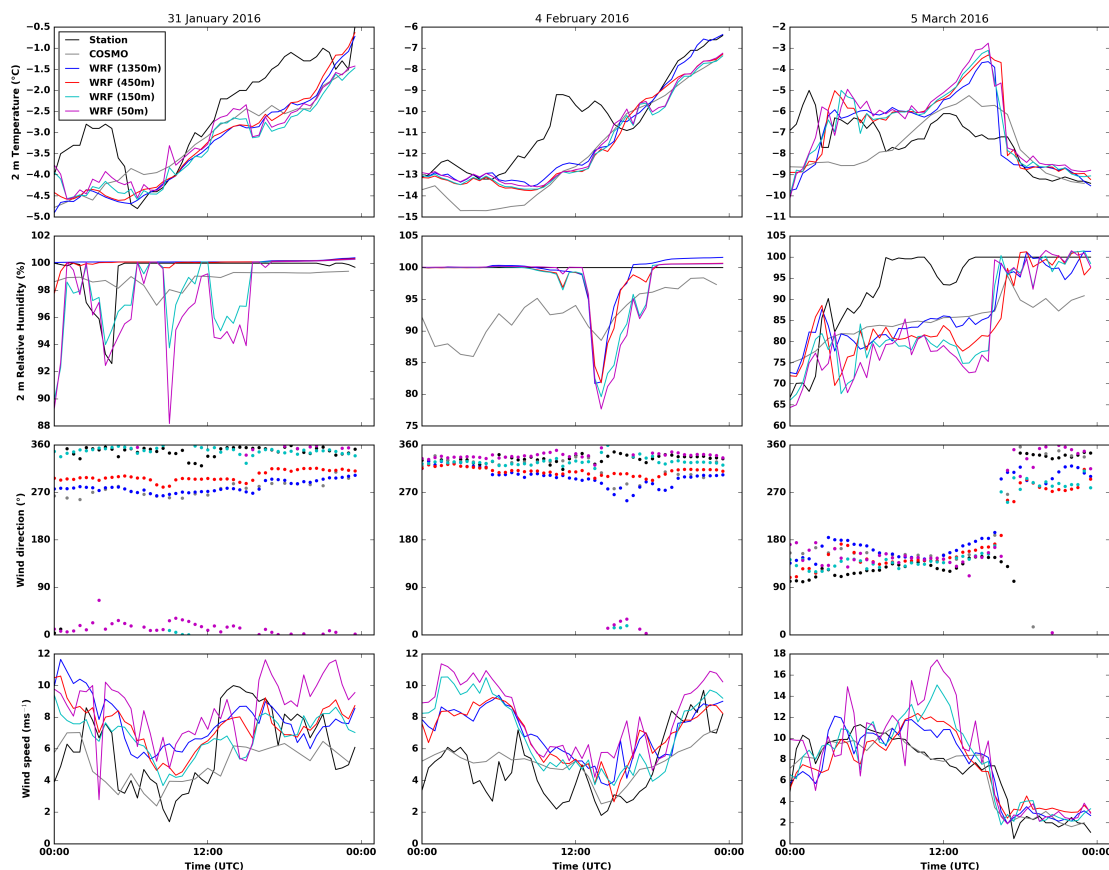


Figure 3. As Figure 2 but for the station *FLU2* on the Flüelapass with 5-meter wind speed and direction.

of the WRF model from station measurements during midday are likely due to errors in station measurements due to radiative heating of the multiplate shielded temperature sensors (Huwald et al., 2009, Sect. 2.2). Additionally, offsets in temperature are linked to offsets in the input by COSMO–2.

Relative humidity shows partially good agreement, but shows a strong temporal variability. Some disagreement compared to station measurements is likely induced by COSMO input, which for some cases shows an offset compared to station measurements. This bias can sometimes be reduced by WRF simulations but for other cases WRF introduces an additional bias. WRF is generally able to capture main drops in relative humidity at stations, but it introduces additional drops compared to measurements. The introduction of drops in relative humidity by WRF may be due to an overestimation of subsidence in the model.



Simulated wind direction shows very good agreement with measured wind direction. In complex terrain, simulations are often limited to resolutions too coarse to resolve smaller scale terrain features that affect near-surface wind direction (e.g. due to lack of high resolution terrain data, or computational resources), and thus cannot accurately capture changes in wind direction close to the surface where weather stations are located. Good agreement in wind direction modeling in our COSMO–WRF simulations in complex terrain is likely due to the high resolution of topography. For some stations additional improvement of wind direction comparisons is visible for higher resolutions although for others terrain smoothing is likely to have adverse effects on modeled wind direction.

Compared to the good agreement of wind direction, wind speeds show only partially good agreement with station measurements. The use of a snow surface roughness length of 0.2 m, representing the combined roughness of snow and surface features (e.g. rocks), could partially reduce overestimated wind speeds. For some stations and dates an overestimation of wind speed is already observed in COSMO–2, which is the most likely reason for wind speed overestimation at these stations. Additional reasons for an overestimation of wind speeds may be manifold. Strong wind speeds due to speed up in ridge areas are a known problem for model simulations (Gómez-Navarro et al., 2015). Therefore, the exact location of the station relative to the ridge is important to verify wind speeds.

As an example, station *Dischma Moraine* is located on a moraine on the northern side of the ridge between Piz Grialetsch and Scalettahorn. Station *FLU2* is located on the northern side of Flüelapass above a small rock face and to the east of a terrain knoll. Due to the resolution and additional terrain smoothing the small-scale features (moraine, small rock face and terrain knoll) are not represented in WRF topography even at 50 m resolution. Such small-scale features introduce very local flow features and may either induce local speed-up effects or can reduce wind speeds due to enhanced roughness. An exact estimation of wind speeds at stations in the model is therefore not expected from the model and reasons for deviations may be manifold.

3.2 Spatial snow precipitation and accumulation patterns

Overall, radar precipitation maps of the regional domain covering about 30 km surrounding the radar on Weissfluhgipfel (Figure 1) tend to show wind direction (Figure 2, Figure 3 and Figure 4d-f) dependent precipitation patterns (Figure 4). A strong south-north gradient in precipitation is observed for precipitation on 31 January 2016, while precipitation on 4 February 2016 shows a more homogeneous distribution. For the precipitation event on 5 March 2016 radar precipitation maxima are observed over the mountain ridges in the southern part of the domain. Although our regional domain is located within the Alps, a north-south gradient in precipitation for southerly advection and a south-north gradient for northerly advection are in good agreement with large-scale orographic precipitation enhancement (Houze, 2012; Stoelinga et al., 2013), which favors precipitation on the upwind side of a mountain range due to topographically induced lifting and a drying due to sinking air masses downwind of the mountain range. These large-scale patterns of orographic enhancement of precipitation are partially captured in the WRF simulations (Figure 4). Especially, for southerly advection (precipitation event on 5 March 2016) this large-scale effect is well represented in COSMO–WRF, where precipitation maxima occur over terrain ridges in the southern part of the domain and a south-north precipitation gradient is present. For northerly to north-westerly advection (precipitation



events on 31 January and 4 February 2016), however, snow precipitation maxima are shifted eastward, i.e. toward the outflow boundary, in the model compared to radar estimations. Based on this visual comparison for all three events we hypothesize that both, radar and WRF precipitation patterns are driven by wind direction and topography.

Disagreement of patterns may be connected to the strong smoothing of topography. Additionally, microphysics and precipitation dynamics in the model are likely to be a limiting factor in terms of small-scale precipitation patterns. Despite of the high resolution of our simulations, slope angles are relatively low with maximum slope angles of 35.2° in the regional domain due to the application of topographic smoothing (Table 1). Given even flatter slopes in domain d01 precipitation fed to domain d02 may already be too weak and thus needs to develop. As mountains in the north-western part of the domain are shallower than mountains in the south-eastern area lifting condensation may not be strong enough in the north-western area of the domain, leading to precipitation generation further downstream in the domain, where steeper and higher mountains may even lead to too strong precipitation enhancement. Additionally, the tendency of an overestimation of wind speeds in the model may lead to an overestimation of the advection in the microphysics scheme (Morrison et al., 2005), which may result in a downstream shift of the precipitation maximum. However, we do not expect this to have a strong impact on the regional scale precipitation distribution. Thus, there are likely additional reasons for the observed downstream shift of precipitation, which remain difficult to explain.

On a mountain-valley scale (local domain) the same tendencies emerge with good agreement in overall gradients for southerly advection and partially reversed gradients for northerly to north-westerly advection (not shown). WRF precipitation patterns generally show a stronger dependence to topography expressed in an elevation gradient. Radar precipitation patterns additionally reveal small-scale precipitation patterns. Very small-scale patterns are visible on the partially filtered radar maps (not shown), while in median-filtered radar estimations (Figure 4a-c) smallest scale patterns are eliminated but patterns of about 1 km size emerge. Patterns in the median-filtered data could be small-scale precipitation cells, while the very small-scale patterns are most likely noise in the radar data (see Sect. 3.4).

The depth of new snow measured at 18 automatic weather stations in the regional domain (Figure 4k-m) over 24 hours shows a distinct elevation gradient, which is quite well represented by WRF total ground precipitation (Figure 4g-i). For 31 January 2016 and 5 March 2016 the large scale precipitation trend observed in the radar data is generally represented in station measurements. On 4 February 2016 station measurements suggest a precipitation peak in the upper Dischma valley (lower left quadrant in Figure 4l), which agrees with WRF simulations. Radar estimations, however, show a more homogeneous distribution of precipitation on 4 February 2016. Snow depth changes at the stations are very local and strongly affected by wind redistribution of snow, which may disturb the large-scale gradient. Additionally, the distribution of stations is not homogeneous over the regional domain and fewer stations are available in the western part of the domain.

3.3 Mean variability

Radar precipitation distribution on the regional domain (450 m resolution) shows a larger interquartile range (IQR) than radar precipitation on the local domain (300 m resolution), confirming that local precipitation is more uniform than regional precipi-

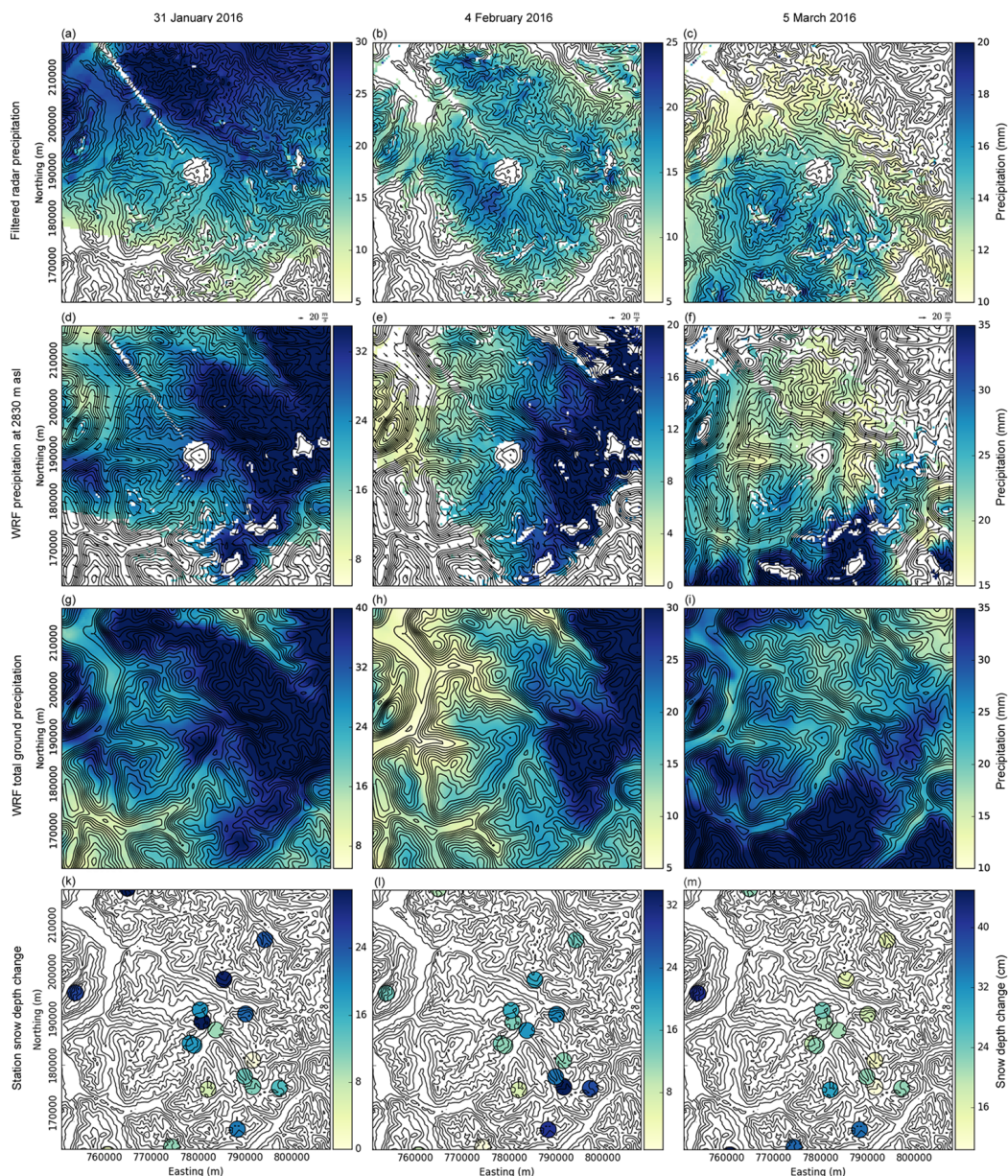


Figure 4. Twenty-four hour snow precipitation (mm) from a-c) MeteoSwiss filtered radar measurements, d-f) Weather Research and Forecasting (WRF) snow precipitation at 2830 m above sea level (m asl), g-i) WRF total ground precipitation and k-m) 24 h snow depth changes (cm) at meteorological stations on 31 January 2016 (left), 4 February 2016 (middle) and 5 March 2016 (right) with a resolution of 450 m in the regional domain (Figure 1). Radar precipitation is estimated from different radar elevations (Sect. 2.3). White areas in a-f mark areas where clutter is removed and small values in the radar data are masked. The same mask is applied for WRF solid precipitation at 2830 m asl (approximate elevation of the radar, d-f), for which additionally areas where WRF topography is higher than 2830 m asl are masked. Arrows in d-f indicate wind direction and speed at an elevation of 2830 m asl. Northing and easting are given in the swiss coordinate system (CH1903LV03). Note different colorbars. Contour lines in a-c) and k-m): dh25 (c) 2018 swisstopo (5740 000 000).

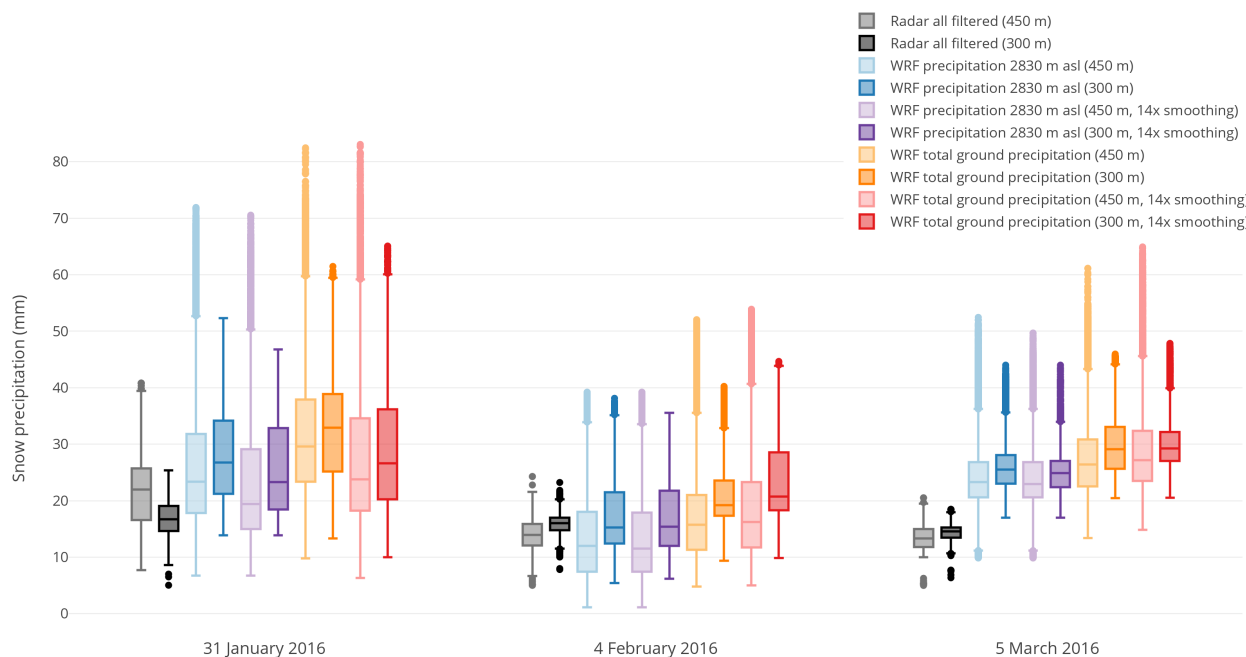


Figure 5. Domain-wide 24 h precipitation statistics for the regional (450 m resolution, light colors) and local (300 m resolution, dark colors) domain (Figure 1) for the three precipitation events on 31 January 2016, 4 February 2016 and 5 March 2016. Gray colors show filtered radar precipitation. WRF precipitation at 2830 m above sea level (m asl) for simulations with weak terrain smoothing (Sect. 2.1) and strong terrain smoothing are given in blue and violet, respectively. Orange (red) shows boxplots of WRF total ground precipitation for weak (strong) terrain smoothing. Radar precipitation and WRF precipitation at 2830 m asl are masked (as shown in Figure 4).

tation (Figure 5). Median precipitation in the local domain depends strongly on the large-scale precipitation distribution (Figure 4), i.e. a higher median if the large-scale precipitation distribution is such that precipitation in the local domain is strong.

Even though main precipitation areas for the two snowfall events on 31 January 2016 and 4 February 2016 are shifted toward the outflow boundaries of the radar domain, spatial median precipitation in the COSMO–WRF simulations is in reasonable agreement with radar median precipitation (Figure 5). However, for the precipitation event on 5 March 2016 the median of precipitation in the regional domain is higher in WRF simulations compared to radar measurements even though the large-scale precipitation gradient is in good agreement. The IQR of precipitation for this event is matching better with the IQR of radar precipitation, but the precipitation distributions in WRF simulations have longer tails. The domain-wide median and IQR of precipitation at radar elevation in WRF simulations with weaker terrain smoothing and stronger terrain smoothing (Sect. 2.1) are similar with a slight tendency of higher median values for weaker smoothing, indicating that the accuracy of topography does not have a strong influence on the domain-wide statistics of precipitation on the regional scale. Enhanced precipitation



for weaker terrain smoothing could be explained by enhanced precipitation production due to steeper topography. On the local domain (300 m resolution) differences between medians in WRF and radar estimations tend to be larger compared to differences on the regional domain, which supports the hypothesis that the model tends to overestimate precipitation for higher resolution with steeper and more complex topography.

5 An overestimation of precipitation in WRF simulations was previously reported (e.g. Leung and Qian, 2003; Mass et al., 2002; Silverman et al., 2013) and could be due to various reasons. Leung and Qian (2003), Mass et al. (2002) among others report that WRF tends to show stronger overestimation of precipitation for higher model resolutions but also find a dependency on the intensity of precipitation. An overestimation of orographic enhancement of precipitation in more complex terrain or an overestimation of moisture in the model were further reported by Silverman et al. (2013). An overestimation of orographic
10 enhancement would be in agreement with a stronger overestimation of precipitation for the local domain and for weaker smoothing. Furthermore, it is likely to occur for simulations with high horizontal resolutions as higher peaks and steeper slopes are preserved (Silverman et al., 2013). Higher peaks and steeper slopes may cause stronger lifting and subsidence, which is also a likely cause for additional drops in relative humidity in WRF compared to measured relative humidity (Sect. 3.1, Figures 2 and 3). However, this tendency seems to be only represented at the highest elevations, while at lower elevations
15 strong smoothing may not allow for precipitation to evolve (Sect. 3.2). As additional reasons for precipitation overestimation in WRF an overestimation of precipitation in the driving model (Caldwell et al., 2009) and underlying landuse characteristics (Silverman et al., 2013) were mentioned. The latter was, however, previously found to only have a weak influence on the precipitation amount (Pohl, 2011). Humidity in COSMO-2 is an unlikely reason as COSMO-2 show rather a tendency of underestimating relative humidity compared to station measurements (Figures 2 and 3). Even though there are many possible
20 reasons for overestimation of precipitation in WRF, the estimation of solid precipitation from radar measurements is also subject to uncertainties (e.g. Cooper et al., 2017). Given uncertainties in radar precipitation estimations the comparison of median domain-wide precipitation should be taken with care. An in depth analysis of spatial variabilities is given in Sect. 3.4.

WRF snow precipitation at the ground level tends to show higher median values of precipitation compared to WRF precipitation at radar elevation for both domains. The IQR is similar. From this we hypothesize that there are precipitation formation
25 or enhancement processes taking place between the elevation of the radar and the ground. This is in good agreement with the fact that near-surface processes can strongly enhance snow precipitation (e.g. riming).

3.4 Spatial variability

To address spatial patterns and variability of precipitation a scale analysis is performed augmented with a 2D-autocorrelation analysis (Sect. 2.4). Given the overestimation of precipitation in the model and the large differences in domain-wide variability
30 between the model and radar precipitation estimations (Sect. 3.3), all variograms are shown as normalized variograms, which allows analysis of spatial patterns with respect to the overall range of precipitation values. From the analysis of precipitation patterns (Sect. 3.2), we further know that there are strong large-scale precipitation gradients in the regional domain. Due to large-scale gradients, small and intermediate scale structures in the variogram analysis may be hidden by the large-scale gradient. To avoid this and non-stationarity of patterns, variograms of detrended precipitation fields are presented (Sect. 3.4.2).



Table 2. Large-scale linear trends of radar and WRF precipitation patterns on the regional domain (Figure 1). *Orientation* gives the direction of the slope and *Intensity* the strength of inclination. 0° would indicate a slope pointing toward the East. WRF snow precipitation is from simulations with weak terrain smoothing (Sect. 2.1).

	31 January 2016		4 February 2016		5 March 2016	
	Orientation	Intensity	Orientation	Intensity	Orientation	Intensity
Radar filtered	86.9°	0.17	-125.9°	0.01	-114.8°	0.04
WRF precip. at 2830 m asl	16.7°	0.22	-5.1°	0.21	-98.2°	0.12
WRF total ground precip.	25.0°	0.18	5.4°	0.26	-103.3°	0.19

However, to assess processes acting at different scales, variograms of non-detrended precipitation patterns are also analyzed in a scale analysis (Sect. 3.4.3). Finally, a 2D-autocorrelation analysis is used to comment on directional dependencies of patterns (Sect. 3.4.4).

3.4.1 Large-scale precipitation trends

5 Large-scale patterns show a strong gradient of precipitation (Figure 4). Therefore a linear trend is fit to the precipitation fields (Table 2). The trend on the 31 January 2016 roughly points toward the North. For the precipitation event on 5 March 2016 the trend points roughly to the South. Given a southerly advection on 5 March 2016 this direction corresponds to the main wind direction and therefore agrees with the theory of large-scale orographic enhancement or rather the drying trend due to sinking further downstream within the mountain range. The north-south gradient on 31 January 2016 roughly agrees with the
 10 main wind direction but points out that regional trends of larger scale patterns may not exactly be aligned with wind direction. For the precipitation event on 4 February 2016 the inclination of the linearly fitted plane is, however, very weak and therefore the direction of the slope is arbitrary. For this day, we hypothesize that either dynamics were more variable preventing the evolution of a strong gradient or lifting condensation due to the orography was not as efficient as for the other two events. For two events (31 January 2016 and 4 February 2016) the model has trouble reproducing the trend. For 31 January 2016 the
 15 deviation of orientation between the trends of radar precipitation and WRF precipitation at 2830 m asl is about 70° but with a similar intensity of the trend. For 4 February the model shows a strong trend of precipitation, while the intensity of the trend is very weak in the filtered radar data. However, for the precipitation event on 5 March 2016 the trend is reasonably captured by the model with a deviation of the direction of 16.6° and a slightly stronger intensity of the trend in the model.

Disagreement in patterns, trend direction and intensity on 4 February 2016 (quite homogeneous precipitation distribution in
 20 the radar estimation (Figure 4) compared to the strong downstream shift of precipitation in WRF) and the overestimation of precipitation in the model give evidence for a too idealistic representation of precipitation in the model (i.e. simplified micro-physics and particle dynamics), which tends to overestimate the effect of highest topographic features but misses precipitation over shallower areas. Good agreement in the intensity of the trend on 31 January 2016 and good agreement of the direction

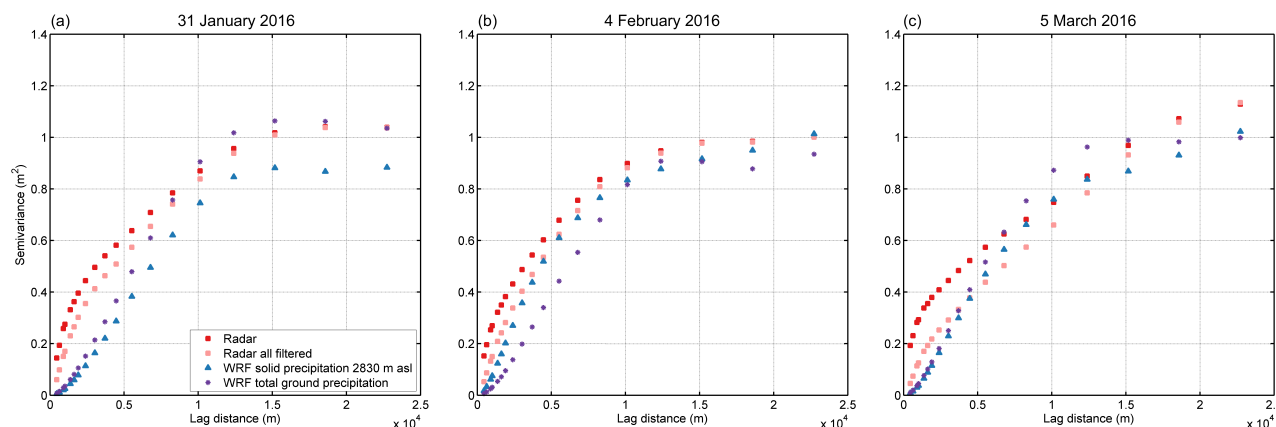


Figure 6. Normalized variograms of detrended snow precipitation for the precipitation events on a) 31 January 2016, b) 4 February 2016 and c) 5 March 2016 for the regional domain (Figure 1). Variograms are given for partly filtered (red) and filtered (orange) radar snow precipitation, WRF snow precipitation at 2830 m above sea level (m asl, blue) and WRF total ground precipitation (violet). WRF precipitation is from simulations with weak terrain smoothing (Sect. 2.1). All precipitation fields are masked.

of the trend on 5 March 2016, however, show that the model is able to capture large-scale precipitation trends, which may be connected to a large-scale orographic enhancement.

3.4.2 Spatial variability of detrended precipitation fields

On the smallest scales a strong difference is visible in variograms of detrended filtered and detrended partially filtered radar precipitation, with weaker variability for filtered data (Figure 6). Smallest scale structures in the radar data are very likely an indicator of residual noise in the partially filtered radar data (Sect. 2.3). However, it could also imply micro-scale precipitation features. This stresses the challenge of processing high resolution radar data (Sect. 2.3) to get a reasonable radar precipitation field. In any case the filtered radar precipitation estimations may be regarded as clean concerning residual clutter and will therefore be used for all subsequent analysis.

Variograms of filtered and detrended radar precipitation show a steep increase of variability on the smallest scales, while the increase in variability gets weaker for larger scales (less steep slope in the variograms). Small-scale patterns are likely driven by small-scale precipitation cells induced by local cloud dynamics and microphysics. Such small-scale structures are repeated on intermediate scales and lead to a weaker increase in variability, as less new spatial features are added. At larger scales variability reaches the total variability of the detrended data.

WRF precipitation at 2830 m asl shows a lower variability and a flatter increase in variability at small scales giving evidence for a smoother precipitation distribution at the smallest scales compared to radar precipitation patterns. The lack of small-scale patterns clearly shows that the radar sees more variability at the smallest scales, while WRF likely misses the smallest scale processes. Variability of radar and WRF precipitation at 2830 m asl at large scales (>5 km), especially on 4 February

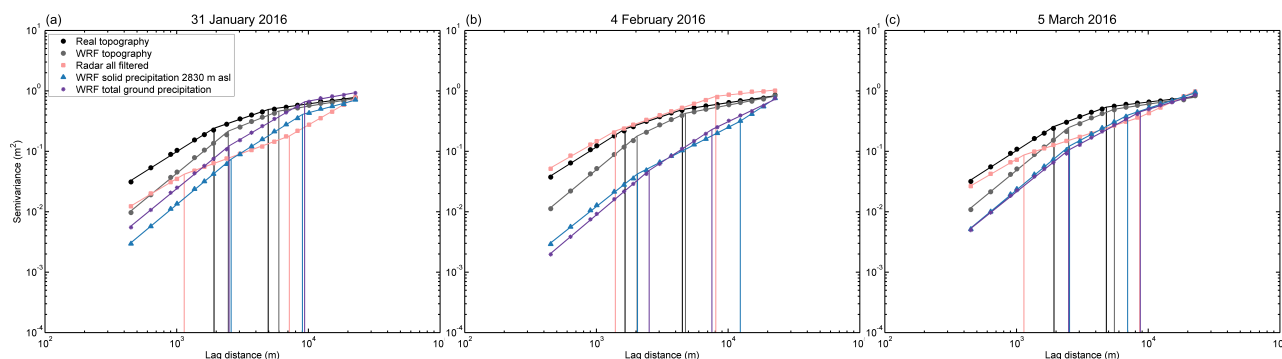


Figure 7. Normalized variograms of the snow precipitation events on a) 31 January 2016, b) 4 February 2016 and c) 5 March 2016 for the regional domain (Figure 1). Variograms are given for filtered radar snow precipitation (orange), WRF snow precipitation at 2830 m above sea level (m asl, blue) and WRF total ground precipitation (violet). Additionally, variograms are given for real topography (based on dh25 © 2018 swisstopo (5740 000 000), black) and WRF topography (gray). WRF topography and precipitation are from simulations with weak terrain smoothing (Sect. 2.1). All precipitation fields are masked.

2016, is similar. This indicates that, with respect to total variability, patterns at these scales are well represented. Total ground precipitation shows a higher variability compared to precipitation at 2830 m asl (except for 4 February 2016), which is an indication that near-surface processes are active in the model.

Variograms of precipitation in the local domain (300 m resolution, Figure 1) look similar to variograms of the regional domain (450 m resolution), but reach domain-wide variability at about 5 km lag distance (Supplementary Information S1), while on the regional scale the domain-wide variability is reached at a distance of about 15–20 km (Figure 6). Furthermore, the difference between radar and WRF precipitation variability at small scales is larger at the local domain compared to the regional domain. This further shows that the model does not properly reproduce small-scale precipitation and deposition patterns, i.e. the radar sees more variability at the smallest scales.

10 3.4.3 Scale breaks and dominating processes

Scale breaks were previously found to be connected to changes in processes (e.g. Deems et al., 2006). To include variability due to large-scale processes, we present variograms of non-detrended precipitation fields, being aware that a certain portion of the small and intermediate scale variability may become hidden. As precipitation patterns are known to be driven by topography and wind, we present variograms of topography together with the variograms of precipitation. Variograms of topography clearly reveal two scale breaks (Figure 7). The first scale break is between 1 and 2.5 km depending on the resolution, the second scale break is at 5 km and 6 km for real topography and weakly smoothed WRF topography, respectively. For topography the two scale breaks are separating the mountain-slope scale ($< \sim 1\text{--}2$ km), mountain-ridge-to-valley scale (between $\sim 1\text{--}2$ km and ~ 5 km) and the scale of repeated mountain ridges and valleys (> 5 km).



For consistency reasons, all variograms in Figure 7 are presented with two scale breaks. Even though for precipitation some scale breaks are arbitrary, as the data do not reveal a clear scale break, the scale breaks for all events and both resolutions are basically grouped in two areas ($\sim 1\text{--}2.5$ km and $5\text{--}10$ km for 450 m resolution, Figure 7 and ~ 800 m– 1.2 km and $2.5\text{--}5$ km for 300 m resolution, Supplementary Information S1). Even though scale breaks of precipitation do not exactly match scale breaks of topography, breaks at similar scales as well as similar slopes of topography and precipitation at small scales support the interpretation of topography dependent precipitation patterns. On the smallest scales ($< 1\text{--}2$ km) the slopes of precipitation variograms are similar to the slopes of the variograms of corresponding topography on these scales. This is an indication that precipitation patterns on mountain-slope scales may be terrain-driven. The most likely reason for this is an elevation gradient in precipitation. Additional processes acting on these scales could be small-scale cloud-dynamical processes such as the seeder-feeder mechanism (Bergeron, 1965; Purdy et al., 2005) or preferential deposition (Lehning et al., 2008). The latter is, however, for most mountain ridges unlikely to be seen in precipitation fields at 2830 m asl as it happens very close to the ground. On scales $> 5\text{--}7$ km, i.e. for the scales above the second scale break, for the precipitation event on 5 March 2016 the slopes of the normalized variograms of radar and WRF precipitation at radar elevation are similar. Large-scale gradients at these scales are most likely driven by large-scale orographic enhancement (e.g. Stoelinga et al., 2013). Good agreement of the slopes in normalized variograms between radar and WRF precipitation is an indicator that the model has the potential to properly represents the strength of the large-scale gradient with respect to the overall variability, i.e. large-scale orographic enhancement. Disagreement of variograms of precipitation and topography on these scales further support the hypothesis that largest scale precipitation is mainly determined by orographic enhancement, which introduces an increase in variability of precipitation at large scales, while large-scale topography reveals a repeated pattern of valleys and peaks (i.e. constant variability).

3.4.4 2-dimensional variability patterns

The combined influence of topography and general wind direction on snow precipitation patterns in the radar domain is assessed by spatial 2D-autocorrelation maps (Figure 8). Like variograms, autocorrelation is dependent on large scale trends. The general direction of 2D-autocorrelation patterns is the same for detrended (Figure 8) and non-detrended (not shown) precipitation patterns. However, autocorrelation patterns of detrended precipitation fields show much shorter decorrelation lengths. This is due to the spatial coherence introduced by large-scale trends in precipitation. To avoid biased autocorrelation data, only 2D-autocorrelation maps of detrended precipitation fields are shown. However, we keep in mind that large-scale trends are present.

Autocorrelation maps of topography (Figures 8a and 8e) represent a north-west to south-east oriented pattern which is, although weaker, repeated in south-west to north-east and west to east direction. For snow precipitation events with dominating north-westerly to northerly advection, the main axis of the snow precipitation 2D-autocorrelation pattern is oriented in a north-west to south-easterly direction and therefore in alignment with both topography and the main wind direction (Figures 8b-c and 8f-g). Patterns of WRF precipitation at 2830 m asl are rotated toward a north-south direction on 4 February 2016. For dominating southerly advection the 2D-autocorrelation map of radar precipitation shows a more homogeneous pattern but



a weak south-west to north-east orientation of larger scale patterns (Figures 8d). For the WRF simulations a strong south-west to north-east orientation is present in the autocorrelation map (Figure 8h). Even though isotropic variograms reveal good agreement in domain-wide variability, 2D-autocorrelation maps show that this may not necessarily go along with good agreement of the orientation of patterns. Best agreement in the orientation of patterns is found for 31 January 2016. For the three events, 2D-autocorrelation maps of detrended precipitation reveal a smoother distribution of precipitation on the smallest scales in the model compared to radar data, due to less small-scale structures in the model. On the other hand, a strong decrease in autocorrelation in east-west direction is visible for 5 March 2016. This shows that WRF simulations have a stronger dependence on both wind direction and topography and tend to generate strong precipitation bands in the main wind direction, confirming the overly idealistic behavior of the model.

For ground precipitation patterns tend to be repeated in south-west to north-east and west to east direction as seen for topography (Figures 8j-g). This stresses the hypothesis that the influence of topographic features on WRF ground precipitation is stronger than at radar elevation and gives evidence that these results are likely produced by near-surface topographically driven pre-depositional processes such as e.g. preferential deposition or the seeder-feeder mechanism in the model.

3.5 Dependence of spatial variability on model resolution and smoothing

Geostatistical analysis show that precipitation on the regional scale ($> 5\text{km}$) is reasonably represented in the WRF model, while small-scale variability drops for model simulations at a resolution of 450 m (Sect. 3.4). Variograms up to a maximum distance of 5 km on domain Dischma (Figure 1) reveal an increase of variability for increasing model resolution (Figure 9). However, simulated variability stays far below the variability of filtered radar precipitation. Depending on the event an increase in variability is present for 150 m and 50 m resolution. Smallest scale dynamics are still not resolved at 50 m resolution. A comparison of variograms for simulations with strongly smoothed terrain compared to simulations with weaker terrain smoothing (Sect. 2.1) reveal that a stronger terrain smoothing may result in less explained variability in normalized variograms (not shown). Even though this signal is not consistent for all events, we can show that a better representation of topography due to higher resolution and less smoothing has the potential to increase the explained variability of precipitation patterns. An increase in variability is mainly present at the smallest scales, indicating that more small-scale patterns are represented in the model. Our simulations are currently limited to the presented resolutions and strong terrain smoothing due to model instabilities. However, based on the presented results, once available, the immersed boundary model version of WRF (e.g. Lundquist et al., 2010, 2012; Arthur et al., 2016; Ma and Liu, 2017), will likely be a good tool to allow for steeper slopes in the simulation and going toward higher resolution LES simulations to resolve further small-scale wind fields, which drive the precipitation structures.

4 Conclusions

The implementation of COSMO–WRF is a step toward performing very-high resolution precipitation simulations in complex alpine terrain to address the question of the relative importance of cloud-dynamics and pure particle-flow interactions on a

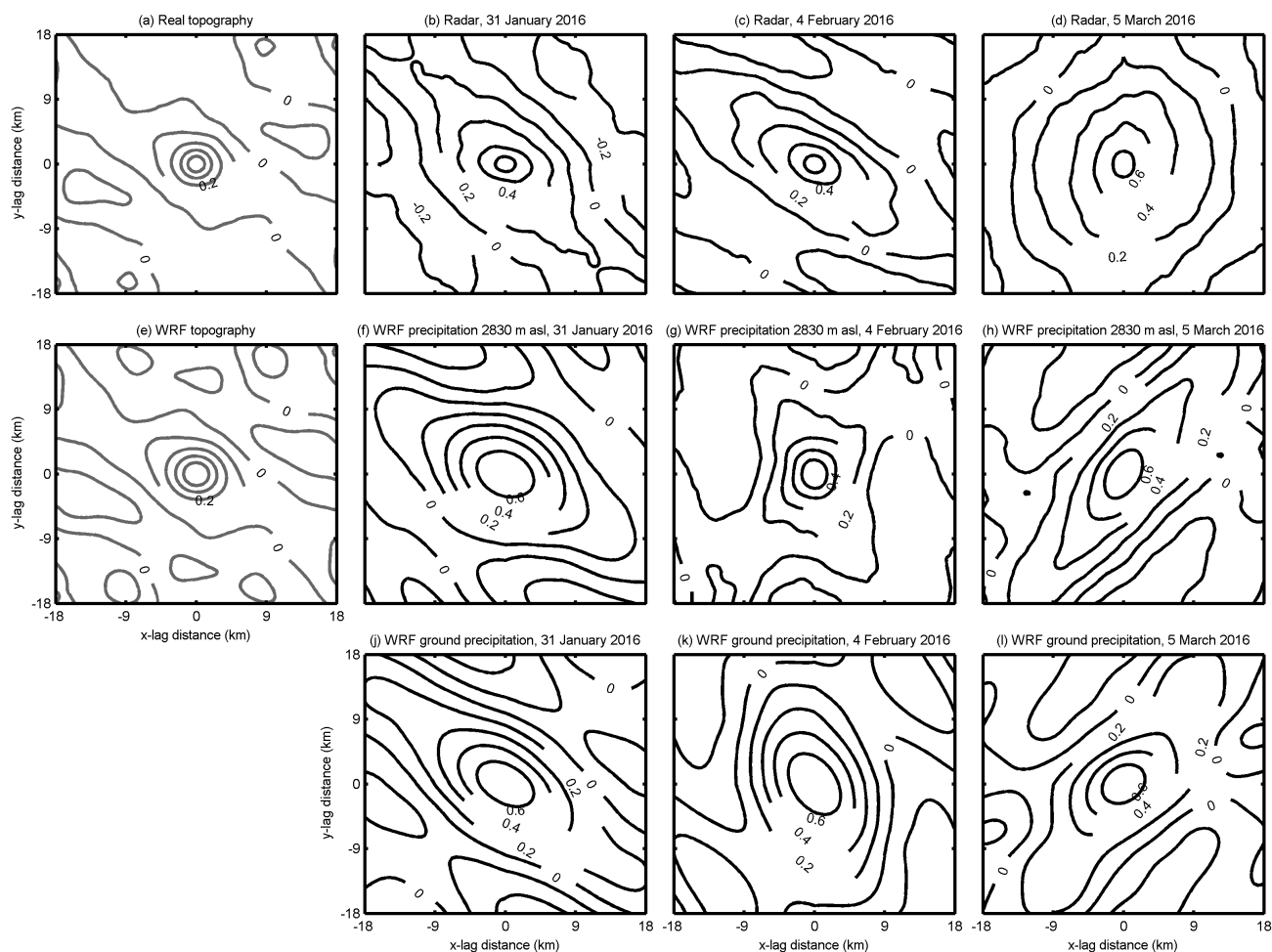


Figure 8. Spatial 2D-autocorrelation maps for the regional domain (450 m resolution) of detrended a) real topography (based on dh25 © 2018 swisstopo (5740 000 000)), b-d) radar snow precipitation, e) WRF topography, f-h) WRF snow precipitation at 2830 m above sea level (m asl) and j-l) WRF total ground precipitation. Autocorrelation maps of snow precipitation are for the three snow precipitation events on 31 January 2016, 4 February 2016 and 5 March 2016. WRF topography and precipitation are from simulations with weak terrain smoothing (Sect. 2.1). Radar precipitation and WRF precipitation at 2830 m asl are masked (as shown in Figure 4).

mountain-ridge scale. We show that COSMO–WRF is able to reasonably simulate atmospheric conditions, but tends to overestimate wind speeds, which may be due to many reasons from an overestimation of speed-up effects to an underrepresentation of topographic features. Relative humidity patterns are highly variable and may be a sign of overestimated subsidence and lifting in the model.

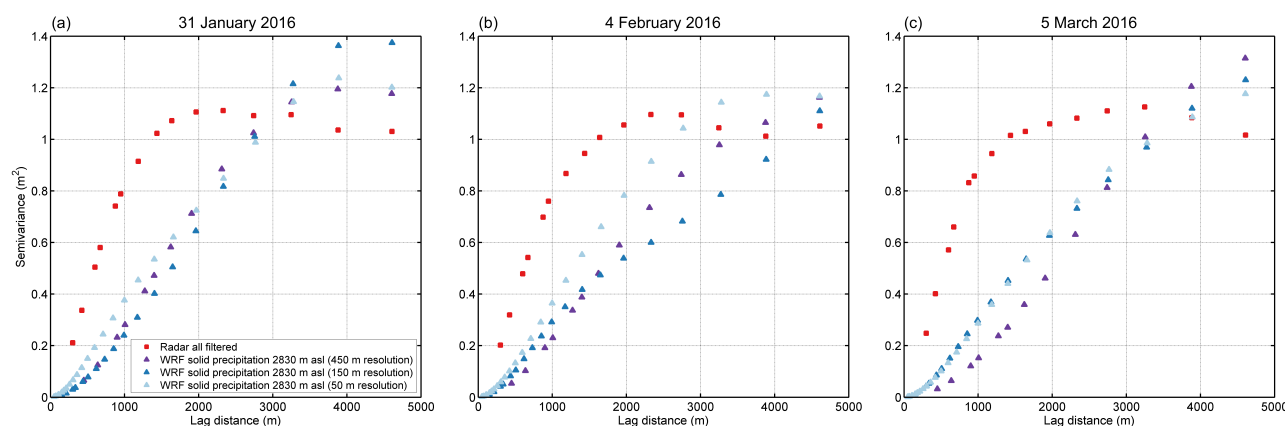


Figure 9. Normalized variograms of detrended snow precipitation for the precipitation events on a) 31 January 2016, b) 4 February 2016 and c) 5 March 2016 for domain Dischma (Figure 1). Variograms are given for filtered radar snow precipitation (red), and WRF snow precipitation at 2830 m above sea level (m asl) with 450 m (violet), 150 m (blue) and 50 m (light blue) resolution. WRF snow precipitation is from simulations with weak terrain smoothing (Sect. 2.1). Radar precipitation is masked.

Regional and local scale precipitation patterns in the COSMO–WRF simulations are in partially good agreement with MeteoSwiss operational radar measurements and automatic weather stations. For the three events analyzed here, precipitation estimations from WRF simulations are higher compared to precipitation estimation from radar measurements. A general overestimation of precipitation produced by WRF is consistent with overestimation of subsidence and lifting. Overestimation of precipitation in WRF simulations has, however, been documented previously for snow precipitation over complex terrain (e.g. Silverman et al., 2013), likely due to the high model resolution and therefore more complex topography and higher peaks compared to common high resolution simulations.

An autocorrelation and scale analysis of radar and WRF snow precipitation reveals a good agreement of precipitation patterns on regional scales (> 5 km), which are topography and wind driven. These large-scale patterns are in good agreement with the theory of large-scale orographic enhancement (e.g. Stoelinga et al., 2013). Disagreement in precipitation patterns i.e. a downwind shift of snow accumulation in the WRF simulations is likely due to lifting condensation being too weak in the north-western part of the domain, where topography is lower and strong smoothing leads to an underrepresentation of topography. On the other hand, over peaks, which are high and steep enough in the model to allow for lifting condensation, the effect of orographic enhancement tends to be overestimated. An increase of this overestimation of precipitation over high elevations for higher resolution simulations as well as for weaker terrain smoothing supports this hypothesis. Smallest-scale patterns in the radar measurements are likely dominated by noise, which is removed by the application of a median filter. Given these uncertainties the radar data cannot be considered as the absolute reference. When observing with a critical eye, an estimation of high resolution radar precipitation is, however, very useful to improve the understanding of precipitation processes in complex terrain and to validate and improve model simulations. On a local to mountain-valley scale WRF simulations show much less



variability of precipitation compared to radar estimations. This indicates that the model is not able to represent the full spectrum of small-scale patterns, which are present in the radar measurements as most likely the representation of cloud dynamics and microphysics in the model is too idealistic, due to the given resolution. This is supported by the fact that precipitation patterns in the model show a stronger dependence on topography and wind direction. However, an increase in variability at scales < 5 km is visible for higher resolution WRF simulations. Furthermore, for simulations with steeper terrain an increase in variability for all resolutions is found. This shows that especially for small-scale variability a better representation of the complex terrain is essential to reproduce precipitation variability. Although the model cannot represent the full variability measured by the radar at small scales, an increase in precipitation between 2830 m asl and the ground is an indication that the model captures a certain portion of near-surface processes.

To specifically address processes such as the seeder-feeder mechanism or preferential deposition an analysis of hydrometeors and precipitation distributions in vertical profiles across mountain ridges is needed. To connect pre-depositional processes with post-depositional processes even higher resolution WRF simulations would be needed. This might be achieved by employing the immersed-boundary method version setup of WRF. A parameterization of post-depositional processes in WRF or using WRF simulations as a boundary condition for simulations with the Alpine surface processes model Alpine3D (Lehning et al., 2008), would then allow validation of modeled snow accumulation patterns compared to measured snow accumulation patterns. Furthermore, simulations of precipitation patterns in complex terrain need to be analyzed with higher temporal resolution (e.g. on the order of minutes), as contributing processes show high temporal variability. Future work will include addressing the temporal variability of precipitation patterns using radar observations, along with an analysis of precipitation growth with respect to topography and wind direction.

Code and data availability. A COSMO–WRF documentation is published as Gerber and Sharma (2018). Data can be made available upon request.

Appendix A: Morrison microphysics in WRF

The Morrison microphysics scheme includes prognostic equations of number concentration and mass mixing ratio of 5 precipitation species (rain, snow, ice, graupel and cloud droplets). The parametrization of rain, snow, ice and cloud droplets is based on Morrison et al. (2005). The implementation of graupel follows Reisner et al. (1998), except for minimum mixing ratios, which are required to produce graupel from the collision of rain and snow, snow and cloud water, and rain and cloud ice, which are based on Rutledge and Hobbs (1984).

The kinetic equations include advection, sedimentation and turbulent diffusion as well as source and sink terms of ice nucleation and droplet activation, condensation and deposition, coalescence and diffusional growth, collection, melting and freezing as well as ice multiplication (Morrison et al., 2005). For graupel deposition, collection, collision, accretion, freezing and melting processes are parameterized (Reisner et al., 1998).



Size distribution functions are gamma functions:

$$N(D) = N_0 D^\mu e^{-\lambda D}, \quad (\text{A1})$$

where D is the particle diameter, μ is the shape parameter of the distribution function, which is $\mu = 0$ for rain, snow, ice and graupel, resulting in an exponential function for $N(D)$. λ and N_0 are the slope and intercept, respectively, of the size distribution, evaluated by the predicted number concentration N and mass mixing ratio q :

$$\lambda = \left[\frac{cN\Gamma(\mu + d + 1)}{q\Gamma(\mu + 1)} \right]^{1/d} \quad (\text{A2})$$

and

$$N_0 = \frac{N\lambda^{\mu+1}}{\Gamma(\mu + 1)}, \quad (\text{A3})$$

where Γ is the gamma-function. c and d are the parameters of the power-law function $m = cD^d$ indicating the mass-diameter relationship. Terminal fallspeeds are as well assumed to have a power-law form of $v(D) = \frac{\rho_{sur}}{\rho} aD^b$, with individual parameters a and b for the different species. ρ is the air density and ρ_{sur} the air density at sea level. For simplification all species are assumed to be spheres. Additionally, the particles do not have any particle inertia.

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