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Manuscript resubmission: ' Modelling the future evolution of glaciers in the European Alps under the EURO-CORDEX RCM ensemble' (TC-2018-267)

Dear professor Vieli,

Thank you very much for the time and efforts you have put into providing initial feedback on our manuscript and for coordinating the review process. We were pleased to read the generally positive comments by both reviewers, and are grateful for their very useful and constructive feedback. All comments and suggestions by the reviewers have been answered in the attached rebuttal letter, and our manuscript has been updated accordingly.

We thank you for considering this updated manuscript for publication, and look forward to hearing from you.

Yours sincerely,

Harry Zekollari, on behalf of the authors

P.S.: as you may know, EGU's press office showed interest for this article to be featured during the next EGU General Assembly - we were told that the press office contacted the journal editors in this respect, but we are unsure whether this information was only passed to the chief editors.

Reviewer 1 – Ben Marzeion

General comment

[RC1.01] Zekollari and colleagues present projections for glaciers in the European Alps using a glacier model that explicitly resolves ice dynamics and is forced by GCM projections dynamically downscaled in the framework of CORDEX. The manuscript presents a timely step forward for modeling of glaciers on large regional scales. It is written well and succeeds to make the assumptions and limitations of the model accessible. I am particularly impressed with high quality of the presentation of the results in the Figures. Overall, I have no doubt that this is a valuable contribution to the literature and eventually should be published. However, there are a number of minor points that should be addressed by the authors, as well as three somewhat major issues

We thank the reviewer for taking the time to read our manuscript and for his positive (and very useful!) feedback. All points raised by the reviewer have been addressed and answered, and the manuscript has been updated accordingly.

Major comments

[RC1.02] Use of CORDEX data: This is the biggest issue I have: the authors use the projections from CORDEX, present a relatively thorough validation (some comments on this below), but do not at all address a question that seems very obvious to me: from the perspective of modeling glaciers, is there added value in CORDEX? I.e., what difference does it make applying the downscaled data opposed to applying the GCM data directly? I'm aware that because of internal variability, there is not much use in using the CORDEX (or GCM) data during the 2003-2017 validation period in the same way the E-OBS data are used. But there is still some insight to be gained concerning, e.g., temporally accumulated area and volume loss.

Also: through combination with different RCMs, the ensemble size of CORDEX is increased - however, there are GCMs not part of CORDEX. Taking the ensemble as a measure of uncertainty, how does the addition of the RCM "axis" affect the ensemble uncertainty? Is it equivalent to taking a larger GCM ensemble, or can insights be gained through the downscaling? Of course, this point is not a weakness of the manuscript. But I see the approach taken by the author as great opportunity to address some questions that are very relevant, since dynamical downscaling is very expensive, and its value is somewhat debated. I think it would be great if the authors took this opportunity.

We thank the reviewer for this suggestion, and agree that it can be instructive to compare the effect of directly forcing the glacier model with GCM outputs rather than RCM outputs (i.e. EURO-CORDEX RCMs, which are driven by a GCM). This is an analysis that we considered including when writing the original manuscript, but which we eventually decided not to include for the sake of conciseness and not to deviate too much from our main message.

We have now reconsidered this, and the updated manuscript now includes new simulations in which the glacier model is directly forced with GCM data. We have however decided to not go into too many details, as this would be beyond the scope of the study and is, probably more suited for a dedicated, more in-depth analysis. Such an in-depth analysis would require a comparison between the GCM and the GCM-RCM simulations themselves, rather than only focusing on the effect this has on the glacier simulations. In the end, the focus of our study is on the glacier model, and not necessarily on the data that drive it.

The focus of our new analyses with GCM forcing is on future glacier evolution, which is also the main period of interest in our paper. For the past, we have now performed an assessment of how the RCM model performs in response to a suggestion made by reviewer #2 (see our response to RC2.05). To stay in the framework of the original manuscript, we decided to only include GCM simulations that are used within EURO-CORDEX (in other

words: we do not consider GCMs that were never used to force EURO-CORDEX RCMs). For this, we considered the three GCMs with the corresponding RCM simulations in the EURO-CORDEX ensemble for a given realisation (CNRM-CM5 r1i1p1, HadGEM2-ES r1i1p1, MPI-ESM-LR r1i1p1).

The results from the GCM-forced simulations support our earlier findings, which indicated that the differences in future glacier evolution are mainly caused by differences in GCM outputs, rather than by differences in the RCMs forced by them (results from section 6.1.4.). In fact, for a given GCM, the spread between EURO-CORDEX simulations forced by the same GCM have a relatively narrow spread. As only few GCM-RCM simulations exist, it is not possible to determine whether these simulations spread evenly around the corresponding GCM simulation. The available simulations, however, do not indicate that any systematic over- or underestimation might occur. As such, we conclude that the ‘addition of the RCM axis’, as suggested by the reviewer, does not have a significant influence on the results. This suggests that, at least for our setting, using high-resolution RCM simulations forced with a GCM leads to relatively similar results compared to using the GCM forcing directly. As stated above, a more in-depth study would however be needed to further investigate this.

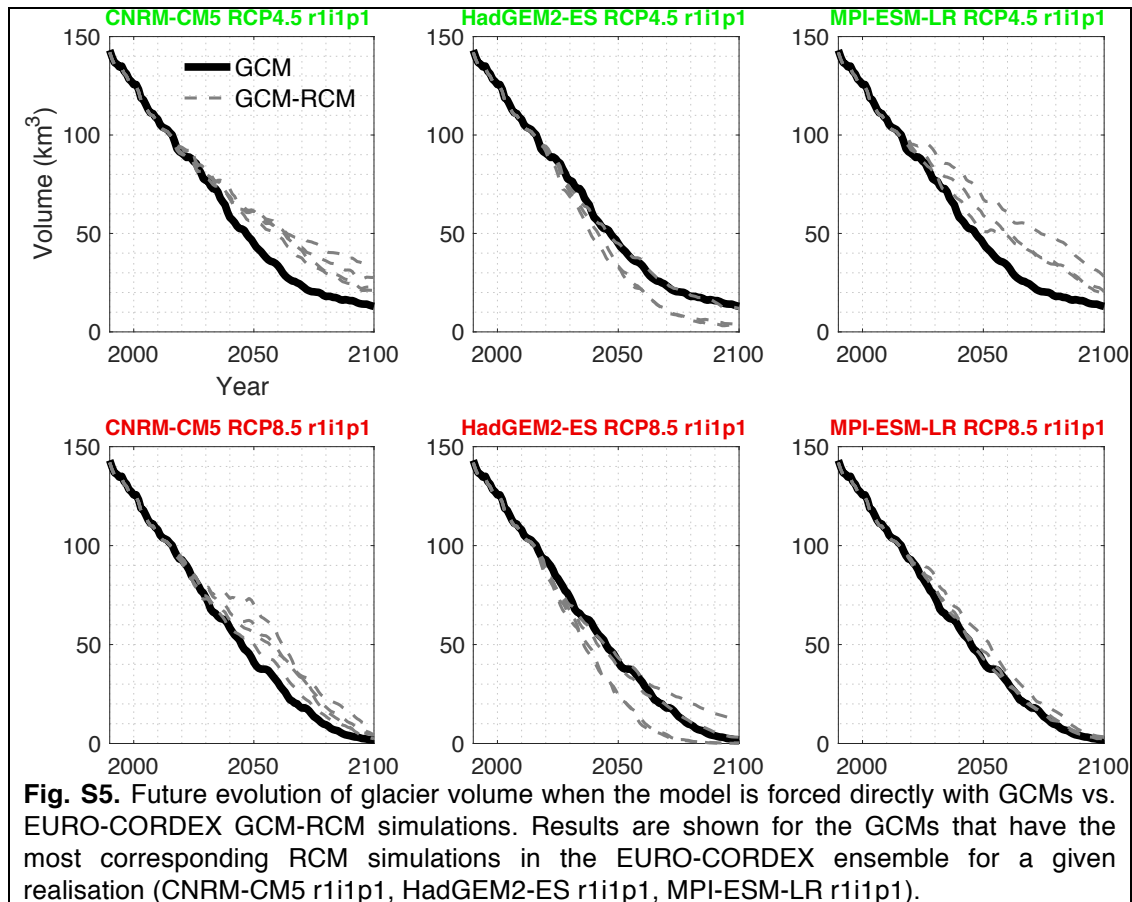
In the updated manuscript, we now introduce these new simulations and present their outcome in section 6.1.4:

The importance of the GCM-forcing also appears from additional simulations in which the original, low-resolution GCM output was used as model forcing. When comparing these results to the ones obtained by forcing the model with the corresponding EURO-CORDEX GCM-RCM combinations, a similar glacier evolution is obtained (with volume losses vs. present-day typically differing <10%, suppl. mat. Fig. S5). The limited number of GCM-RCM combinations, however, does not allow for a detailed comparison with the GCMs, but does not suggest any systematic over- or underestimation of the corresponding results.

And we now also mention this in the conclusion:

Additional simulations where the model is forced with the driving GCM only (i.e. no downscaling with an RCM) confirm the limited effect of the RCM on the modelled future evolution. More in-depth analyses on the effect of using downscaled RCM data vs. GCM data for glacier evolution modelling will be required, but our results suggest that the effect of such a downscaling on simulated glacier evolution is relatively limited – at least for the European Alps.

A figure in which these results are summarised was added to the supplementary material (suppl. mat. Fig. S5; see following page)



[RC1.03] Initialization: Why is glacier length chosen instead of glacier area? It seems to me that area is better constrained than glacier length, since the length is to some degree an arbitrary choice resulting from the representation of the flow line.

Also, using the 1961-1990 climatology, was variability preserved? Where the forcing timeseries during that period detrended? As the authors say, there is no assumption about an equilibrium state of the glacier, but an assumption that the glacier would be able to undergo the transition from an equilibrium state in 1990 to the observed transient state in (typically) 2003). Doesn't this correspond to an assumption that the response time of the glaciers is shorter than 13 years? You discuss this in Sect. 6.3, but it would be good to have some arguments presented already in Sect. 3.3.

We agree that the length has a dependence on the methodology used to derive it. However, for the calibration we aim at minimizing the difference between the 'reference' length and the 'calibrated' length. In this sense, considering the length or the area as a measure for this exercise is almost equivalent, as locally the area is the product of the glacier length and width. This is now explicitly mentioned in the updated manuscript and supported with quantitative information:

- We calibrate to the reference glacier length within 1%. The glacier length is thus very closely reproduced, with a standard deviation between the reference and the modelled lengths corresponding to 0.5%.
- For the glacier area, despite not being calibrated to it, the agreement between the reference and the modelled value is almost as good as for the length, with a standard deviation of 0.7%.

Although we agree that the area could have been used instead, we preferred to use the length as a criterion for our calibration, as this ensures that the position of the glacier terminus is correctly reproduced. We now explicitly mention this in the manuscript:

The glaciers are calibrated to match the length and volume at inventory date within 1% (σ)

between reference and modelled volume or length of 0.6% or 0.5% of the reference value, respectively). Despite not being calibrated to it, the observed glacier area is also closely reproduced (σ of 0.7%).

For the period 1961-1990, the variability is not preserved, nor is any detrending applied. This is not needed for our purpose, as this forcing is only used for creating the artificial steady state in 1990. In fact, the constant conditions correspond to the mean SMB over this time period (and an eventual bias), and we have now reformulated this passage to better reflect this (see updated text below)

Our setup does not assume that the glaciers have a response time of less than 13 years. In fact, we rather assume the opposite, i.e. that most glaciers have a response time of more than 13 years, so that the geometry in 2003 still depends on the geometry in 1990. This is important for our specific setup to be used. We argue that this is realistic, as most glaciers were not very far from equilibrium in the late 1980s, and since the typical response time of glaciers, in the order of a few years to decades, suggests that observed evolution in the 1990s and early 2000s was largely determined by their 1990 geometry. We have now emphasized this in section 3.3.:

The initialisation consists of closely reproducing the glacier geometry at the inventory date. At first, constant climatic conditions are imposed, until a steady state is created, which represents the glacier in 1990 (Fig. 3). These constant climate conditions correspond to the mean SMB under the 1961-1990 climate, to which a SMB perturbation is applied (detailed below). Subsequently, the glacier is forced with E-OBS data, and evolves transiently from 1990 until the glacier-specific inventory date (typically 2003). We opt for a 1990 steady-state glacier, as the glaciers in the European Alps were generally not too far off equilibrium around this period, with SMBs for many glaciers being close to zero (Huss et al., 2010a; WGMS, 2018). By imposing a steady state in 1990, the glacier length at inventory date can be influenced. Methodologically, choosing an initial steady state before 1990 would be problematic, as in this case the glacier geometry would not determine the glacier length at the inventory date anymore, as the period between the steady state and the inventory date exceeds the typical Alpine glacier response time of several years to a few decades (e.g. Oerlemans, 2007; Zekollari and Huybrechts, 2015).

[RC1.04] Validation: The geodetic mass balances used for calibration are most probably not independent of the in situ measurements used for validation. For those glaciers that have geodetic observations that do not temporally overlap with the in situ measurements, it would be good to recalibrate using these, and revalidated using the temporally independent in-situ values.

I'm also wondering about the choice of using geodetic observations for calibration, and in-situ for validation. The opposite would seem like the more natural choice to me, since geodetic MBs can cover longer time periods, and thus allow to include effects from ice dynamics in the total uncertainty. Is there a specific reason not to make the calibration based on in-situ observations, and validate using geodetic MBs?

We agree that in-situ measurements cannot be considered to be entirely independent from the geodetic measurements for cases where both overlap in time (despite relying on different sources and techniques used to derive these values). Following the reviewer's suggestion, the SMB validation has therefore been revised, and we now only consider in-situ measurements that do not overlap in time with the geodetic mass balance measurements. Note that some in-situ measurements refer to glaciers for which no geodetic mass balance exist; these measurements were thus included in the validation as well. These latter measurements are particularly interesting, as they also serve to validate the extrapolation of the geodetic mass balance (cf. comments RC2.02 and RC2.23 by the second reviewer). The text, Figure 4 and its caption have been revised to account for this new validation procedure:

In order to ensure that the validation procedure is independent from the calibration,

validation is only performed with observations that do not temporally overlap with the geodetic mass balances used for calibration (cf. sections 2.3 and 3.1) and for glaciers without geodetic mass balance observations.

and:

When only considering SMB measurements on glaciers that have no observed geodetic mass balance (i.e. glaciers for which the geodetic mass balance used to calibrate the model was extrapolated from other, nearby glaciers), the misfit between modelled and observed values increases only little (RMSE = 0.79 m w.e. yr⁻¹; MAD= 0.72 m w.e. yr⁻¹; mean misfit = -0.19 w.e. yr⁻¹), indicating that the method used to extrapolate the geodetic mass balances to unmeasured glaciers performs well.

Figure 4 was updated to account for this new validation, and so was its caption:

Fig. 4. Evaluation of modelled SMB against observations from the WGMS (2018) database. All observations are included, except those that do temporally overlap with the geodetic mass balance observations (used for calibration).

We use the geodetic mass balance for calibration because that is available for many glaciers (for ca. 1500, representing more than 60% of the total glacier area; cf. response to RC2.02). In contrast, only a few glaciers have in-situ measurements. We argue that it is more important to have a good coverage for calibration than for validation, and think that this strategy will be the only one applicable to other regions or the worldwide scale, since the availability of geodetic mass balances massively outgrows the availability of in-situ measurements by far (c.f. works by Brun et al., 2017, Nature Geoscience; Braun et al., 2019, Nature Climate Change). To clarify this, we added the following sentence in section 2.3. (that is where the mass balance data is introduced):

Note that we prefer using geodetic mass balance over SMB observations for calibration, as we argue that it is more important to have a good coverage for model calibration than for its validation. Furthermore, geodetic mass balances are becoming increasingly available at the regional scale (e.g. Brun et al., 2017; Braun et al., 2019) and outgrow the availability of in-situ measurements, making the adopted strategy applicable to other regions.

Minor comments

[RC1.05] P1 L10: ... ice flow processes, _of_ which the latter ...

This was modified.

[RC1.06] P1 L10: you could specify it is not included explicitly, since the (simple) parameterizations used are supposed to parameterize its effect.

[note that "it" in the reviewer comment refers to ice dynamics]

We have now specified that this effect was not included *explicitly* in previous studies:

..., of which the latter is to date not included explicitly in regional glacier projections for the Alps

[RC1.07] P2 L21: specify "glacier model parameters".

Two possible glacier model parameters, which are discussed in the manuscript, have now been added:

...(e.g. flow parameters and cross-section parameterization).

[RC1.08] P2 L17: either delete "using various methods", or briefly specify.

Deleted.

[RC1.09] P2 L18 (and P15 L27): volume/length/area or volume-length-area scaling

This was modified as suggested by the reviewer:

volume/length/area scaling (Marzeion et al., 2012; Radić et al., 2014)

[RC1.10] P2 L21: I suggest RCP 8.5 should not be called "extreme", since the different scenarios are not based on probabilities, nor is there a physical reason to view RCP8.5 above some limit value.

This was now modified to:

..., and an almost complete disappearance of glaciers under warmer conditions (RCP8.5).

[RC1.11] P3 L2-4: Not sure why glaciers in the Canadian Rockies should not be controlled by topography and local effects. Either specify, or delete; I think there is value in different approaches to similar problems by itself, so I don't see a need for a very strong justification of your study here.

This passage was deleted. The previous sentence now reads:

In an RGM study for western Canada, Clarke et al. (2015) showed that relative area and volume changes are well represented by such a model, but that large, local present-day differences between observed and modelled glacier geometries can exist after a transient simulation.

[RC1.12] P3 L9: you might also refer to Goosse et al. (2018), which has transient simulations (DOI: 10.5194/cp-14-1119-2018)

This is a good suggestion. We added:

This model was recently also used by Goosse et al. (2018) to simulate the transient evolution of 71 Alpine glaciers over the past millennium.

[RC1.13] P4 L7: delete "in these little-known connections" (or specify why they are lesser known than the rest of the glacier).

It is not the connections that are little-known, but rather the mass transfer between these connections. We have now reformulated this:

and potential problems related to solving the little-known mass transfer in these connections.

[RC1.14] P4 L12: I would prefer "Climate data" or "Atmospheric boundary conditions"- but that is maybe a matter of taste.

This section is now entitled: *2.2 Climate Data*

[RC1.15] P4 L19: "... has a higher resolution than the reanalysis data used in Huss & Hock (2015, ERA-INTERIM) and goes back further in time."

This was modified in response to RC2.19 and now reads:

We prefer using an observational dataset compared to a re-analysis product (e.g. ERA-INTERIM, as used in Huss and Hock, 2015), as the former has a higher resolution and goes further back in time.

[RC1.16] P4 L21: rephrase around "several chains used for", since it is not quite clear here

what "chains" you are referring to.

We now refer to these RCM combinations as *(RCM) simulations* here and throughout the manuscript.

[RC1.17] P4 L28 (and throughout the study): perhaps it would be better to call them "model combinations" than "chains" (these "chains" have only two links anyway...).

This comment was addressed in our previous response (to RC1.16): the "chains" have been changed to "RCM simulations" throughout the manuscript.

[RC1.18] P4 L30: "... a peak-and-decline scenario ..."

Modified as suggested.

[RC1.19] P4 L32: "Note that while country-specific ..."

while was added.

[RC1.20] P4 L32: "... such as the projections recently released for the CH2018 report, ..." (or something similar - i.e., distinguish between scenarios and projections).

This was reformulated to:

Note that while country-specific projections such as the ones recently released with the CH2018 report for Switzerland (CH2018, 2018) exist,...

[RC1.21] P5 L13: because of the difference in resolution between E-OBS and the RCMs, there is probably not a direct equivalent in the grid points. Please specify how you handle this.

The trends from the RCMs are imposed on the E-OBS grid to simulate the future SMB. For this, we rely on the nearest grid point. We now mention this in the first sentence of this paragraph:

For modelling the future SMB, debiased RCM trends from the EURO-CORDEX ensemble are imposed on the E-OBS grid based on the nearest corresponding grid cell.

[RC1.22] P6 L13: "closest to the glacier" - there are probably glaciers that are covered by multiple grid cells - are then multiple grid cells taken into account, or are you using the glacier center point? Please specify.

In such cases, the glacier centre point is taken into account, which we now also specify:

For every glacier, the model is forced with monthly temperature and precipitation series (section 2.2) from the E-OBS (past) or RCM (future) grid cell closest to the glacier's centre point.

[RC1.23] P6 L15 (and L19): "temperature-index melt model"

This was modified for both occurrences in the text:

temperature-index model → *temperature-index melt model*

[RC1.24] P6 L26-30: While precipitation is the least constrained boundary condition, the degree-day factors are probably the most potent parameters for tuning. Why is the order chosen like this, and how is the default degree-day factor chosen? Please specify.

We keep the same setup as in GloGEM, in which the precipitation is modified first, and the degree-day factor is potentially altered after that (a third step involves a change in temperature). The reason for this is that local precipitation is often least constrained and most variable in high-mountain areas (e.g. snow redistribution). This is now also mentioned:

In the first step, overall precipitation is multiplied with a scaling factor varying between 0.8 and 2.0. This initial step focuses on the precipitation, as this is the variable that is expected to be the most poorly reproduced due to resolution issues, spatial variability and local effects (e.g. snow redistribution) (e.g. Jarosch et al., 2012; Hannesdóttir et al., 2015; Huss and Hock, 2015).

The default degree-day parameter is set to $3 \text{ mm d}^{-1} \text{ K}^{-1}$, in line with the original GloGEM study (Huss and Hock, 2015) and is in agreement with literature values from various studies (Hock, 2003). This is now also mentioned in the text: *... (default value is $3 \text{ mm d}^{-1} \text{ K}^{-1}$; cf. Hock (2003)) and the degree-day factor...*

[RC1.25] P8 L25: It is fine to separate the validation of the SMB model from the ice dynamics, but there should not be much difference if the dynamics are behaving well. Also, the SMB observations are probably not taking into account the RGI outlines, such that there is some disagreement anyway. Have you tested how much the results differ if you switch on ice dynamics?

It is true that accounting for an evolving geometry while validating the SMB should work well if the glacier evolution model works well. However, we decided to not rely on a dynamically evolving glacier geometry for the SMB validation for the following reasons:

- By relying on a dynamically evolving glacier geometry, only SMB observations after 1990 (starting point of dynamic simulations) can be used for validation, This would reduce the total number of available measurements (note that the number was already reduced in the updated manuscript, to account for the interdependency issue of validation/calibration data raised by the reviewer in RC1.04)
- A related problem is that the changes modelled in glacier area shortly after 1990 are in general too small, as the glaciers needs to evolve away from the steady state (that is also the reason why our validation occurs mainly after the inventory date). Depending on the timing, additional observations may thus have to be removed from the validation dataset.

The sentence has been reformulated in order to reflect this reasoning:

As the aim is to evaluate the performance of the SMB model (rather than the coupled SMB – ice flow model) and to incorporate as many validation points as possible (which is only possible after 1990 for the dynamic simulations), these calculations are based on the glacier geometry at inventory date.

[RC1.26] P8 L29-30: I don't agree: this correlations measures the skill of the model to reproduce more positive mass balances at the upper part of the glacier than at the lower parts. A better measure for the SMB model's ability to represent the MB profile would be a comparison of the (temporally averaged) MB profiles, or correlating the deviations from the "climatological" (i.e., mean) profile.

We agree that the original formulation (*'the SMB model distributes the annual SMB relatively well over elevation'*) may be perceived as misleading. However, this analysis indicates that the SMB gradient is well reproduced. This has now been reformulated:

Furthermore, the good agreement between observed and modelled balances for glacier elevation bands ($r^2 = 0.60$; Fig. 4b,d) suggests that, despite not being calibrated to this, the modelled and observed SMB gradient are in reasonably good agreement

Additional measures, such as the ones proposed by the reviewer, could indeed be interesting to present, but given the limited data available for such analyses (we would

need continuous time series for a meaningfully large set of glaciers), these were not included.

[RC1.27] P10 L20: delete "1x".

This was deleted.

p-value <1x10⁻³ → p-value <10⁻³

[RC1.28] P10 L27: delete "In the literature".

By deleting *in the literature*, it gives the impression that this is something we have performed in this study. Although it becomes clearer when reading further that this is not the case, we want to avoid any possible confusion here. We have therefore rephrased this to:

Glacier area changes in the European Alps have been derived in various studies.

[RC1.29] P10 L30: "over the period 1973-1998/9".

This was modified.

[RC1.30] P11 L19: "evolution is independent of the scenario".

This has been reformulated to: *...this evolution is independent from the RCP.*

[RC1.31] P12 L6: I don't understand this sentence, please rephrase. Do you mean volume change?

We thank the reviewer for pointing this out, as this was a mistake. The sentence now reads:

...reveals that under RCP2.6, the relative volume loss has the highest correlation with the elevation range (Fig. 9 and suppl. mat. Table S3; $r^2 = 0.57$).

[RC1.32] P12 L11: "strong below 3200 m".

Modified.

[RC1.33] P12 L18: delete "may" (you already say it's only under certain model combinations).

may was omitted.

[RC1.34] P12 L21: "This is illustrated for Langtaler ..." Sect. 6.1.1: Just out of curiosity, it would be interesting to know about the committed mass loss past 2100.

Langtaler Ferner is projected to lose 89% of its 2017 volume by 2100 under 1988-2017 conditions. After 2100, almost no loss occurs anymore, and slightly less than 10% of its 2017 remains in the end (steady state under 1988-2017 conditions). We now also mention this in the section on the committed loss (6.1.1):

Under these conditions, the committed loss is particularly strong for small glaciers at lower elevations (e.g. Langtaler Ferner, with a committed volume loss of ca. 90% by 2100)

[RC1.35] P14 L6: correct Section number.

This was corrected:

...possible to the observed geometry (see section 4.2), which is...

[RC1.36] Appendix: P19 L16: delete "1" at the end of the line.

This was deleted and the sentence was changed to:

...previous guesses minus 1, e.g. the third guess...

[RC1.37] Table 1: The "committed loss" line is a bit confusing, since the committed loss should not be time-dependent. Perhaps you can call this, e.g., the "realized fraction of committed loss"?

This was indeed somewhat confusing. To clarify this, we now refer to 1988-2017 in the table and in the table caption:

The evolution under the mean SMB obtained from the 1988-2017 climatic conditions represents the committed loss.

[RC1.38] Generally - but particularly Fig. 9: I'm not a big fan of grids in figures. If there is a need to read numbers/differences from the figures, these numbers should be mentioned on the figure or in the text, and no grid would be necessary; if there is no such need, the grid only adds clutter. Please consider removing grids.

We agree that the grid on the maps in Fig. 9 was not needed and removed this in the updated manuscript. In the other figures we prefer to leave the grids, which we think makes it easier and more convenient to read values in general (without any specific 'highlight' value).

[RC1.39] P 27 L3: "relative to 1961-1990" (instead of "with respect to").

This was modified.

[RC1.40] P27 L4: is that the mean of all "alpine" EUROCORDEX grid cells, or just the ones that contain glaciers? If the latter, I think it would make more sense to also weight them by glacier area.

We agree with the reviewer that it makes more sense to show the mean temperature and precipitation weighed by the glacier area, and have updated Fig. 2 and its legend accordingly.

[RC1.41] Fig. 2: I have a hard time seeing the transparent bands; I suggest deleting them, since that information is already shown in the distribution of the individual (thin) lines.

The transparent bands were omitted in the updated manuscript.

[RC1.42] Figs. 5, 6: are there uncertainty estimates available for the observed velocities? If so, it would be good to include them (e.g., just a single error bar so that the observation uncertainty can be compared to the differences with to modeled velocities).

We agree with the reviewer that it is interesting to incorporate error estimates on surface velocities. Unfortunately, uncertainty estimates are often absent for the measurements that we sampled from the literature. Uncertainties in observed velocities are generally <10% (e.g. Berthier and Vincent, 2012; Zekollari et al., 2013; Stocker-Waldhuber et al., 2018). We, thus, argue that the general tendency in this validation will remain unaffected.

Reviewer 2 – Fabien Maussion

[RC2.01] The manuscript by Zekollari and colleagues presents new estimations of projected glacier change in the European Alps. It is a well conducted study, the paper is well written and the results are interesting. The inclusion of ice dynamics, the use of CORDEX data instead of coarser GCMs and the large amount of calibration data are the main novel points in this study. It will become the new reference study for future glacier change in the European Alps and as such, it is likely to receive a larger interest from the general public and the media. I have two major concerns that need to be addressed before publication, as well a several specific questions / recommendations.

We thank the reviewer for his generally positive appreciation of the paper. We have addressed the two major points as well as all other specific comments in the revised version of the manuscript.

General comments - Validation and uncertainty

I acknowledge the efforts realized to use so many different observational datasets, an exercise only possible in the European Alps. However, I have several issues with the model validation in this study:

[RC2.02] 1. there is no information about how many glaciers (and how much ice area/volume) are simulated without any calibration data. For these glaciers, the geodetic MB is "interpolated" and the effect of this interpolation is not assessed

In total, 1508 glaciers have a geodetic mass balance that can be used for SMB model calibration. By number, this corresponds to 38% of all glaciers. The distribution of glaciers that have a geodetic mass balance, however, is skewed towards larger glaciers, and as a consequence, 60% of the total Alpine glacier area has a geodetic mass balance. We have added this information in the updated manuscript:

About 1500 glaciers (ca. 38% by number) have a glacier-specific geodetic mass balance observation. Since larger glaciers are overrepresented in this sample, however, this corresponds to about 60% of the total Alpine glacier area.

What concerns the interpolation of the geodetic mass balance to glaciers without direct observations, the effect is now explicitly addressed (cf. RC1.04). In the updated manuscript, the following passage was added:

When only considering SMB measurements on glaciers that have no observed geodetic mass balance (i.e. glaciers for which the geodetic mass balance used to calibrate the model was extrapolated from other, nearby glaciers), the misfit between modelled and observed values increases only little ($RMSE = 0.79 \text{ m w.e. yr}^{-1}$; $MAD = 0.72 \text{ m w.e. yr}^{-1}$; $\text{mean misfit} = -0.19 \text{ w.e. yr}^{-1}$), indicating that the method used to extrapolate the geodetic mass balances to unmeasured glaciers performs well.

[RC2.03] 2. there is no indication as to the computation of the uncertainty ranges provided in the glacier changes (e.g. in the abstract). Does it originate from the forcing ensemble? The model RMSE? It is hard make further assessments without this information

It is true that the nature of the uncertainty ranges was not clearly formulated. These uncertainties result from the ensemble of RCM simulations, and this is now explicitly mentioned in the abstract:

We find that under RCP2.6, the ice loss in the second part of the 21st century is relatively limited and that about one-third ($36.8\% \pm 11.1\%$, multi-model mean $\pm 1\sigma$) of the...

And in the text (when the results are presented for the first time, in section 5):

Under RCP2.6, in 2100 about 65% of the present-day (2017) volume and area are lost ($-63.2 \pm 11.1\%$ and $-62.1 \pm 8.4\%$ respectively, multi-model mean $\pm 1\sigma$,...

[RC2.04] 3. the validation using observed traditional MB does not make sense to me, because the model has been calibrated on geodetic MB on the same glacier (both data are not exactly the same, but close - see also the comment of Ben Marzeion). If anything, you should use cross-validation here: when assessing the performance of the model on a given glacier, you remove the selected glacier from the calibration dataset, then use this data plus the traditional MB measurements to assess the model. This would also help to address point 1

We agree that the SMB calibration was not fully independent, and have therefore changed the calibration procedure as suggested by the first reviewer (cf. RC1.04). We now make a distinction between different types of validation data, and for validation we only consider SMB observations that do not temporally overlap with geodetic mass balance measurements. Additionally, a comparison between the observed and modelled SMBs is also made for glaciers without any geodetic mass balance observation, which shows that the extrapolation method for geodetic mass balance works well. For more details, we refer to our replies to RC1.04 and RC2.02, where the textual changes are also described.

[RC2.05] 4. it is problematic that the effect of the RCM forcing is not assessed at all. The plots all start in 2017, so any sceptic reader could say: "this is all extrapolated without test in the past". I understand the problems behind the validation of RCM forcing because of internal variability, but: since you are bias correcting over a reference period, at least the MB model bias (not RMSE) could be assessed when driven by RCMs as well for glaciers with long observation time series. These data would provide a much better estimate of the true uncertainty of the model driven by RCM data for the future. I'm leaving it open to the authors if they want to implement this validation or not - I believe it would make their paper much stronger.

The idea of adding an analysis of the RCM data in the past is an interesting one. We have incorporated this in part: Rather than performing such an analysis through an SMB validation procedure, we have added a comparison between:

- Past Alpine-wide SMBs obtained by forcing the SMB model with E-OBS data
- Past Alpine-wide SMBs obtained by forcing the SMB model with RCM data

For the latter, we decided to use the historical runs of the EURO-CORDEX models (instead of forcing with ERA-INTERIM). This ensures that the RCM-model skill is assessed, rather than the quality of ERA-INTERIM, and allows for a long comparison period. The comparison shows that, the general tendency and interannual spread in SMB obtained when forcing the SMB model with historical RCM simulations, is comparable to the one when forcing the SMB model with E-OBS data.

This is now described in the manuscript, and a figure was added to the supplementary material (suppl. mat. Fig. S2 in the updated manuscript):

Finally, sensitivity tests were performed with the SMB model being forced with historical RCM output (instead of E-OBS). The tests indicate that the RCMs, despite not being forced with reanalysis data, are producing general SMB tendencies that are relatively close to those obtained when forcing the model with E-OBS data (similar mean values, see suppl. mat. Fig. S2; similar interannual variability: $\sigma_{SMB,E OBS} = 0.66 \text{ m w.e. yr}^{-1}$; mean $\sigma_{SMB,RCM} = 0.58 \text{ m w.e. yr}^{-1}$).

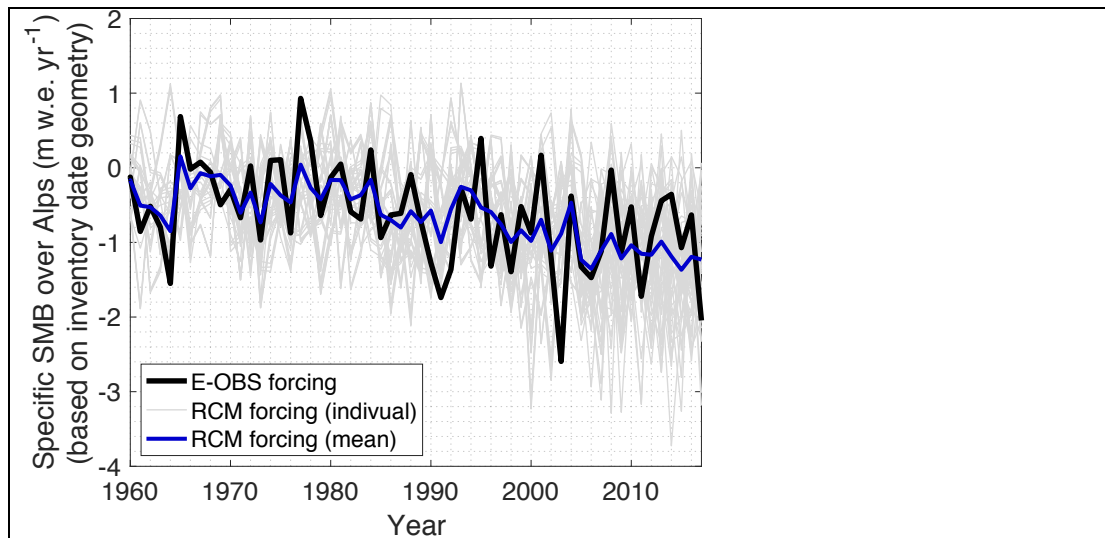


Fig. S2. Past specific surface mass balance (SMB) over glaciers in the European Alps, as derived from E-OBS data and from historical RCM simulations. SMB calculations are based on reference geometry at inventory date.

General comments – Glacier geometry

[RC2.05] The Huss and Farinotti (2012) approach (HF2012), which is to "squeeze" glaciers into elevation bands is an interesting compromise parametrization, simpler than the multiple flowline algorithm followed by OGGM (Maussion et al., 2018) but still allowing for ice flow considerations. It has some advantages (I don't necessarily agree with the ones listed in the paper): it is programmatically more efficient, arguably more elegant (because simple), and it is probably less sensitive to uncertainties in glacier outlines or topography. It also has some disadvantages (mostly, the lost of geometrical information for more complex MB models, and the over simplification of the mass flow along multiple branches).

In an attempt to reproduce the method following the algorithm description by HF2012, I consistently obtain shorter glaciers than provided by the authors (e.g. as shown in Fig. 5). See

https://nbviewer.jupyter.org/github/fmaussion/misc/blob/master/simplified_flowline_tests.ipynb for some code and graphics.

I wonder why I can't reproduce the authors' results, and I therefore have a few questions:

- what motivated the choice of 10m for the δz elevation bands? This is quite a narrow range and I get better results with larger bands (depending on the underlying map resolution)

The reviewer points out some interesting differences between the flowline approach used by OGGM and the one we use. We acknowledge that some of these points were not included in our original submission, and now do so in the reformulated text:

Subsequently, the glacier geometry is interpolated to a regular, horizontal grid along flow. Through this approach, possible glacier branches and tributaries are not explicitly accounted for, avoiding complications and potential problems related to solving the little-known mass transfer in these connections. As such, this approach is less sensitive to uncertainties in glacier outlines and topography compared to methods in which glacier branches are explicitly accounted for (e.g. Maussion et al., 2018), but may in some cases oversimplify the mass flow for complex glacier geometries (e.g. with several branches).

In this and the following answers, we argue why the reviewer may have obtained other

glacier lengths compared to us, and explain how we updated the manuscript to further clarify the H&F method applied:

- For the difference in obtained glacier lengths, we refer to our response to RC2.07
- The 10-m elevation bands were chosen to ensure that the method is consistently applicable, also for small glaciers.

- **[RC2.06]** what do you do when there is no glacier grid point in a 10m band? This happens quite often depending on the underlying map resolution (see graphs).

Having 10-m elevation bands without a glacier grid is not a problem in our case, as the geometric representation with elevation is transformed to a grid with a constant horizontal spacing. This is mentioned in the manuscript:

The horizontal distance (Δx) between the elevation bands is determined from the elevation difference (Δy) and the local surface slope (s):

$$\Delta x = \Delta y / \tan s \quad (1)$$

Subsequently, the glacier geometry is interpolated to a regular, horizontal grid along flow.

In case values are missing (i.e. no area and volume for a particular elevation band), these are simply neglected during this interpolation procedure.

- **[RC2.07]** do you do any kind of filtering for large slopes? The skewed slope distribution towards high slopes can affect the mean and, together with the missing bands, could explain why I get shorter glaciers.

A filtering of the local slopes is performed to get the average slope of elevation bands (that are subsequently used to compute glacier length). This filtering was indeed not described in detail in the original publication (Huss and Farinotti, 2012), thus hampering complete reproducibility. To determine band-average slope, all values below the 5% quantile are discarded, as well as all values above a threshold (typically around the 80 to 90% quantile) determined based on the skewness of the slope distribution function. The approach reduces the effect of very steep cells within an elevation band on average band slope and, hence, glacier length, and has been optimized based on comparisons to flowline glacier length.

This is now formulated after Eq. (1):

To determine the band-average slope s , all values below the 5% quantile are discarded, as well as all values above a threshold (typically around the 80 to 90% quantile) determined based on the skewness of the slope distribution function.

- **[RC2.08]** do you do apply any smoothing on the resulting band widths and areas? They appear quite noisy in my case (depending on the underlying map resolution).

No smoothing is applied of the glacier bands and widths. Despite the fact that the band widths and areas can strongly vary in space (being 'noisy'), they do not lead to any numerical problems when solving the transport equation.

[RC2.09] I'd like to see these questions answered in this manuscript, unless I missed them from either HF2012 or Huss and Hock (2015), in which case I'm happy to be corrected and pointed to the location where the algorithm is described.

Similarly, there are some locations in the current manuscript where I find that the algorithm description is too vague to allow reproducibility (see specific comments below).

By having addressed the comments formulated above and having updated the manuscript accordingly, we hope that the reader will understand the various steps. All specific comments formulated below have been addressed.

Specific comments

[RC2.10] Abstract L10 : "which the latter" sounds strange. Rephrase?

This has been reformulated to:

...ice flow processes, of which the latter is to date...

[RC2.11] Abstract L20 "RCM that is coupled to it" → the RCM is not "coupled" to the GCM (this suggests two-way nesting) ; maybe "nested in", or "driven by" the GCMs? Also revise other occurrences in the text.

We have now changed this by omitting the 'coupling' part:

...determined by the driving global climate model (GCM), rather than by the RCM, and...

This was also updated for other occurrences in the manuscript:

... an RCM driven by a GCM... (second last paragraph of introduction)

... on the driving GCM than the RCM, and ... (last sentence of section 6.1)

...driving GCM (rather than the RCM), and... (conclusion)

[RC2.12] P2L13 "the evolution of the glacier" → "glacier evolution"

Modified as suggested.

[RC2.13] P2L21 "moderate" and "extreme" are subjective adjectives → be more precise, e.g. RCP or similar

This was now modified to:

These regional and global studies generally suggest a glacier volume loss of about 65-80% between the early 21st century and 2100 under a moderate warming (RCP2.6 and RCP4.5), and an almost complete disappearance of glaciers under warmer conditions (RCP8.5).

[RC2.14] Legend Fig 1 updated version OF Huss and ...

Modified as suggested.

[RC2.15] P3L23 "we aim at reducing the considerable uncertainties" → I'm yet to be convinced that increased complexity reduces uncertainty, and I'm not sure your study really deals with this topic or even actually shows that uncertainties are reduced. It's okay if you leave this sentence as is, but you don't need this paragraph to justify your study

We understand the point raised by the reviewer, and now state that we aim at improving future projections and at examining how this could affect global glacier projections (which is indeed more what we do instead of 'reducing the uncertainties'):

Through novel approaches in terms of (i) climate forcing, (ii) inclusion of ice dynamics, (iii) the use of glacier-specific geodetic mass balance estimates for model calibration, and by (iv) relying on a vast and diverse dataset on ground-truth data for model calibration and validation, we aim at improving future glacier change projections in the European Alps. As a part of our analysis, we explore how the new methods and data utilized could affect other regional and global glacier evolution studies.

[RC2.16] P4L3 what is the "local surface slope"? According to HF2012 it is the bin average

for each elevation band. Be more precise in the formulation here (see also general comment about that).

This comment has been addressed in our reply to RC2.07. In particular, the manuscript was updated in order to clarify how the local surface slope is determined.

[RC2.17] P4L7 "little-known connections" → I don't understand what you mean. Connections are maybe more complex in a dynamical sense but so are other locations on the glacier as well. Furthermore, "ignoring" these connections is not making them less complex, it's just avoiding them. So, I suggest to remove this sentence (see also general comment)

The first reviewer also pointed this out, and we agree that the formulation was not very precise. It is not the connections that are little-known, but rather the mass transfer in these zones. The sentence now reads:

...complications and potential problems related to solving little-known mass transfer in these connections.

[RC2.18] P4L9 trapezoidal sections: how does this go together with the ice thickness inversion? What cross-sections are used in HF2012? If rectangular (I assume), by using a trapeze you are either reducing the sections volume or increasing the thickness h_0 , i.e. you are not physically consistent between the inversion and the forward model.

This is a valuable comment, and we agree that it was not clearly formulated how we treat the different cross section parameterizations. In Huss and Farinotti (2012), a rectangular cross section is used, while we rely on various cross section representations (trapezium with different shapes and rectangular cross section to test for sensitivity to this). In all cases, the cross-section transformation is performed by preserving the area and volume for the particular location. This can lead to slightly different bedrock elevations in this representation, although the differences are in general minor. This is now clarified in the updated manuscript:

Glacier cross-sections are represented as symmetrical trapezoids. The bedrock elevation is determined in order to ensure local volume and area conservation.

[RC2.19] P4L17 "close representation of past temperature and precipitation and certain events" → Reanalysis datasets also represent weather events well thanks to data assimilation. It's okay to use ENSEMBLES, but you should argue otherwise, maybe because of uncertainties in quantitative precipitation estimates or the coarse resolution of reanalysis data, for example.

In line with the reviewer's suggestion, this has now been reformulated to:

This E-OBS product represents past events closely (for example the heat wave of the summer of 2003, Fig. 2b), allowing for detailed comparisons between observed and modelled surface mass balances (section 4.1). We prefer using an observational dataset compared to a re-analysis product (e.g. ERA-INTERIM, as used in Huss and Hock, 2015), as the former has a higher resolution and goes back further in time.

[RC2.20] P4L24 I think this whole justification paragraph is more confusing than helping. I think it's okay to use an observational dataset for calibration and validation instead of reanalysis, consider shortening this paragraph.

The paragraph was shortened when addressing the reviewer's previous comment (see RC2.19).

[RC2.21] P4L28 is "chains" the commonly used word for this? I thought that "realisation" or

"simulations" would be more appropriate. See also other occurrences in text.

This was now modified to '*simulations*' throughout the text. The wording is classically used in the literature (e.g. Kotlarski et al., 2014, GMD). See also our replies to RC1.16 and RC1.17.

[RC2.22] P5 Eq. (2) I have several questions here. First, you don't say over which observational period you compute the averages for the monthly bias correction. Is it 1961-1990? The entire observation period? I assume that σ_{obs} and σ_{sim} is computed for the same reference period as the bias. Then, why choosing a 25-yr period, and not a period of the same length as the reference period?

Please also add a sentence as to why you don't apply such a correction for precipitation. I understand that the arithmetics are not so easy for multiplicative bias corrections, but in theory some kind of correction would also be possible (and might be needed by looking at Fig. 02).

The bias was evaluated over the longest possible period where both RCM data and E-OBS are available. Some RCMs are available from the 1950s on, while others only start in 1970. The period considered for computing the averages for the monthly bias correction thus ranges from 1970 to 2017, as we now explicitly mention:

This correction is applied over the period 1970-2017, which is the overlap period for which all RCM simulations and E-OBS data are available.

A similar correction is not applied for precipitation, as this is a "cumulative" quantity: i.e. monthly differences in variability will not be that relevant at the annual scale (mass budget). Furthermore, variabilities in precipitation do not have a direct effect on the calibrated parameters (as is the case for temperatures via the degree-day factors). This has now been formulated as:

For precipitation, which enters the SMB calculations as a cumulative quantity, no correction for interannual variability is applied, as the monthly differences in variability are not that relevant at the annual scale. Furthermore, variability in precipitation does not have a direct effect on the calibrated SMB parameters (as is the case for temperatures via the degree-day factors, see section 3.1.).

[RC2.23] P5L26 "based on a combined criterion weighting both horizontal distance and the difference in area." Can you be more specific here? (reproducible science versus "black box"). How many glaciers have Geodetic and traditional MB observations? Which area does it represent? How many glaciers needed this kind of interpolation?

As we stated in our responses to RC1.04 and RC2.02, we now provide more information about the number of glaciers (and the area) that have geodetic mass balance observations. We also added a more elaboration explanation about the procedure that is used to derive the geodetic MB for glaciers without such observations:

In case no geodetic mass balance observation for the specific glacier is available, an observation from a nearby glacier is chosen. The respective observation is selected based on the two criteria horizontal distance (in km) and relative difference in area (unitless). We multiply the two criteria and consider the minimum as the most suitable glacier to supply a mass balance observation for the unmeasured glacier. The replacement thus represents a nearby glacier that is relatively similar in size. The effect of this approach is evaluated in section 4.1

[RC2.24] P7L25 what kind of numerical solver are you using? It's not an harmless choice, as shown by Jarosch et al 2013.

We agree that it is important to consider stability and mass conservation issues, which are strongly related to the type of numerical solver. Implicit methods allow for using larger time

steps, while explicit methods are intrinsically less stable and need smaller time steps. The latter are however computationally less demanding, and therefore more efficient (see e.g. Schäfer et al., 2007, JGlac). We use a semi-implicit solver. For the calculation of the continuity equation (eq. 6), it relies on an intermediate time step during which the geometry is adapted. We now explicitly mention this in the manuscript.

The continuity equation is solved using a semi-implicit forward scheme by relying on an intermediate time step (i.e. sub-time step update) in which the geometry is updated.

[RC2.25] P8L10 "Notice that through this approach, the glacier is not assumed to be in steady state at any point in time, but that an artificially modelled steady state is obtained by imposing a MB offset." → I don't understand what you want to say here. I'm also quite confused at the statement "A determines volumes, SMB bias determines the length". Is this based on your own experience, or is there a physical explanation? Finally (and most importantly), why is length used as convergence criterion instead of area, which is the only variable which is almost perfectly known at the inventory date?

With the sentence formulated on P8L10 in the original manuscript, we want to stress that the steady state that we produce is an artificial one, which we impose for our calibration procedure (to match the geometry at inventory date, see also our response to RC1.03), but we do not assume that the glacier was in steady state with any climatic conditions. In hindsight, we agree that the original sentence was not very clear, and we have decided to omit it altogether.

The second statement ("[parameter] A determines volumes, [the] SMB bias determines the length"), is based on physics, where the rate factor (A) determines the stiffness of the ice, and through this the local ice thickness and thus the ice volume. This is also evident from the equations: if A increases, the local velocity or flux increases, resulting in lower ice thickness. By modifying the SMB bias to create the artificial steady state, the length of the steady state is modified (this is because the SMB needs to be zero when integrated over the glacier). A different steady-state length, in turn, causes the length of the modelled glacier to be modified at inventory as well. We have now clarified this as follows:

The glacier volume and length at inventory date are matched by calibrating two variables (Fig. 3). The first calibration variable is the deformation-sliding factor A, which mainly determines the volume of the glacier at the inventory date. The reason for this resides in the role that A has on the local velocity/flux, which in turn affects the local ice thickness and thus the ice volume; see Eqs. (4-7). The second calibration variable is an SMB offset in the 1961-1990 climatic conditions used to construct a 1990 steady-state glacier, which mainly determines the length of the steady-state glacier (as the geometry is such that the integrated SMB equals zero). Note that a change in steady-state length causes the glacier length to change at inventory date as well.

For the comment related to the use of lengths (vs. areas) for calibration, refer to RC1.03.

[RC2.26] Model initialisation needless to say, the iterative initialisation procedure is... unconventional. I'm not asking to change it, because it serves one purpose: find a transient glacier which is consistent with the forward model at a reference date. This is necessary because the ice-thickness inversion model and the forward model in GloGEMFlow are probably not consistent between each other (different MB profiles, different A, different bed shapes).

However, I would like to add that I don't really think that this iterative method has much to do with finding an "appropriate" A for each glacier. Let's take the first step as an example: since you drive your model with an SMB such that the present day geometry is in equilibrium, modifying A so that your glacier has to grow will always tend towards lower values of A in order to create a thicker, longer equilibrium glacier in 1990.

The reviewer suggests that by modifying A , the glacier length will be modified. This is rarely the case, as A mainly determines the glacier thickness. Through this, it can slightly influence the glacier length (through the SMB – elevation feedback), but this effect is much smaller than the effect that the SMB bias has. We have now clarified this by adapting our manuscript, as we explain in our previous response (reply to RC2.25).

[RC2.27] P8L23 this cannot be considered an "independent" validation (see general comment)

See RC1.04: We agree and have now reworked the evaluation procedure by discarding observations that temporally overlap with geodetic mass balances

[RC2.28] P8L25 "rather than the coupled SMB – ice flow model" → this is a bit of a missed opportunity, because there are chances that the varying geometry actually improves the SMB validation, by taking geometry changes into account which are present in observations but not in the static model.

See RC1.25: There are several reasons for which we decide not to rely on a dynamically evolving glacier geometry for the SMB validation, and these are now mentioned in the text.

[RC2.29] Fig 4 Legend r^2 is the "coefficient of determination"

This was modified.

[RC2.30] P8L29 elevation bands and correlation → I agree with Ben Marzeion

See RC1.26.

[RC2.31] Fig 5 intuitively, I would swap the glacier flow direction so that the distance on model grid (x-axis) is starting from zero at the glacier top. This would also allow to read the length of the glacier directly on the x-axis

Swapping the glacier direction may indeed be an option. But as the figures does not start at zero (it rather shows the distance along the model grid, to ensure a consistency with the figures that will be added as supplementary material), we decided to leave this as it was.

[RC2.32] P9L21 how did you compute the surface velocity out of the depth-integrated velocity given by the shallow-ice approximation?

As basal sliding is not treated explicitly in our approach, and given that we assume that the mass transport is defined by the local geometry (SIA), the surface velocities (\bar{u}) are equal to the 1.25 x depth-integrated velocities (u_s) ($\bar{u}/u_s = 0.8$) (see e.g. Cuffey and Paterson, 2010, p.310). This is now specified:

In the lower parts, where many glaciers have a distinct tongue, a comparison between observed and modelled surface velocities is possible (surface velocities correspond to 1.25 times the depth-integrated velocities, since we treat basal sliding implicitly, see e.g. Cuffey and Paterson (2010, p.310)).

[RC2.33] P10L12 note that other length records are also available for the non-swiss glaciers (WGMS or Leclercq database)

We now mention the existence of other datasets:

Note that other length records are also available for non-Swiss glaciers (e.g. Leclercq et al., 2014), but that these were not considered to ensure a consistency in derived length

records.

[RC2.34] P10L20 remove "highly significant" and the p-value to read "the correlation is $r^2 = 0.37$ ($p < 1e-3$)"

This was modified as suggested.

[RC2.35] P11L4 unit km² yr⁻¹

Indeed! This was modified.

[RC2.36] P12L6 "highest correlation with the maximum glacier elevation" → is this sentence correct?

This should have read *highest correlation with the glacier elevation range* (cf. Table S3). We thank the reviewer for spotting this!

[RC2.37] Fig 9 Legend remove the "two" in "two present day"?

This was modified.

[RC2.38] Fig. S3 Consider adding Fig. S3 to the main manuscript.

Fig. S3 from the original manuscript was added to the main text and is now Fig. 10. The figure numbering the main text and in the supplementary material has been updated accordingly.

[RC2.39] P14L10 what do you mean with "ice is more pronounced"?

Indeed, this sentence was not clear, as we referred to *ice* as being *more pronounced*, while it should have read *ice loss...more pronounced*. We now modified this accordingly.

[RC2.40] P15L12 when the variable IS considered? I'm not sure I fully understood this section.

We thank the reviewer for pointing this out. This should indeed be 'IS considered' (vs. is not considered in the original manuscript). The text now reads:

In such an analysis, all independent variables are replaced by dummy variables, which have a value of one when the variable is considered, ...

Modelling the future evolution of glaciers in the European Alps under the EURO-CORDEX RCM ensemble

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Abstract. Glaciers in the European Alps play an important role in the hydrological cycle, act as a source for hydroelectricity and have a large touristic importance. The future evolution of these glaciers is driven by surface mass balance and ice flow processes, of which the latter is to date not included explicitly in regional glacier projections for the Alps. Here, we model the future evolution of glaciers in the European Alps with GloGEMflow, an extended version of the Global Glacier Evolution Model (GloGEM), in which both surface mass balance and ice flow are explicitly accounted for. The mass balance model is calibrated with glacier-specific geodetic mass balances, and forced with high-resolution regional climate model (RCM) simulations from the EURO-CORDEX ensemble. The evolution of the total glacier volume in the coming decades is relatively similar under the various representative concentrations pathways (RCP2.6, 4.5 and 8.5), with volume losses of about 47-52% in 2050 with respect to 2017. We find that under RCP2.6, the ice loss in the second part of the 21st century is relatively limited and that about one-third ($36.8\% \pm 11.1\%$, multi-model mean $\pm 1\sigma$) of the present-day (2017) ice volume will still be present in 2100. Under a strong warming (RCP8.5) the future evolution of the glaciers is dictated by a substantial increase in surface melt, and glaciers are projected to largely disappear by 2100 ($94.4 \pm 4.4\%$ volume loss vs. 2017). For a given RCP, differences in future changes are mainly determined by the driving global climate model (GCM), rather than by the RCM ~~that is coupled to it~~, and these differences are larger than those arising from various model parameters (e.g. flow parameters and cross-section parameterization). We find that under a limited warming, the inclusion of ice dynamics reduces the projected mass loss and that this effect increases with the glacier elevation range, implying that the inclusion of ice dynamics is likely to be important for global glacier evolution projections.

25

1 Introduction

In the coming century, glaciers are projected to lose a substantial part of their volume, maintaining their position as one of the main contributors to sea-level rise (Slangen et al., 2017; Bamber et al., 2018; Marzeion et al., 2018; Moon et al., 2018; Parkes and Marzeion, 2018). In the European Alps the retreat of glaciers will have a large impact, as glaciers play an important role for river runoff (e.g. Hanzer et al., 2018; Huss and Hock, 2018; Brunner et al., 2019), hydroelectricity production (e.g. Milner et al., 2017; Patro et al., 2018) and for touristic purposes (e.g. Fischer et al., 2011; Welling et al., 2015; Stewart et al., 2016).

10 | In order to understand how the ca. 3500 glaciers of the European Alps (Pfeffer et al., 2014) (~~Fig. 1~~~~Fig. 1a~~) will react to changing 21st century climatic conditions (e.g. Gobiet et al., 2014; Christidis et al., 2015; Frei et al., 2018; Stoffel and Corona, 2018), to date, models of various complexity have been used. Regional glacier evolution studies in the Alps (Zemp et al., 2006; Huss, 2012; Salzmann et al., 2012; Linsbauer et al., 2013) have focused on methods in which ice dynamics are not explicitly accounted for and the ~~evolution-of-the-glacier~~glacier evolution is based on parameterisations. One of the first studies to estimate the future evolution of all glaciers in the European Alps, ~~was performed by Haeberli and Hoelzle~~ (1995), ~~who used glacier inventory data and combined this with a parameterization scheme to predict the future evolution of the Alpine ice mass. In other study, -was performed by~~Zemp et al. (2006), ~~who used~~utilized a statistical calibrated equilibrium-line altitude (ELA) model to estimate future area losses. ~~In another study~~More recently, Huss (2012) modelled the future evolution of about 50 large glaciers with a retreat parameterisation, and extrapolated these findings to the entire European Alps ~~using various methods~~. The future evolution of glaciers in the European Alps was also modelled as a part of global studies, relying on methods that parameterise glacier changes through volume/~~length~~-area scaling (Marzeion et al., 2012; Radić et al., 2014) and methods in which geometry changes are imposed based on observed changes (Huss and Hock, 2015). These regional and global studies generally suggest a glacier volume loss of about 65-80% between the early 21st century and 2100 under a moderate warming (RCP2.6 and RCP4.5), and an almost complete disappearance of glaciers under ~~an~~ extreme warming scenario ~~warmer conditions~~ (RCP8.5).

For certain well-studied Alpine glaciers, 3-D high-resolution ice flow models have been used to simulate their future evolution (e.g. Le Meur and Vincent, 2003; Le Meur et al., 2004, 2007, Jouvét et al., 2009, 2011; Zekollari et al., 2014). These studies are of large interest to better understand the glacier dynamics and the driving mechanisms behind their future evolution, but individual glacier characteristics hamper extrapolations of these findings to the regional scale (Beniston et al., 2018). Given the computational expenses related to running such complex models, and due to the lack of field measurements needed for model calibration and validation (e.g. mass balance, ice thickness and surface velocity measurements), these models cannot be applied for every individual glacier in the European Alps. A possible alternative consists of using a regional glaciation model (RGM), in which a surface mass balance (SMB) component and an ice dynamics component are

coupled and applied over an entire mountain range, i.e. not for every glacier individually (Clarke et al., 2015). However, running a RGM at a high spatial resolution remains computationally expensive, and the discrepancy between the model complexity and the uncertainty in the various boundary conditions persists. ~~Furthermore, Clarke et al. (2015) showed~~ In an RGM study for western Canada, Clarke et al. (2015) showed that relative area and volume changes are well represented by such a model, but that ~~that~~ large, local present-day differences between observed and modelled glacier geometries can ~~locally~~ exist after a transient simulation. ~~For relative area and volume changes this was found to not be problematic, as they are relatively unaffected by these discrepancies (Clarke et al., 2015). However, for the European Alps, with many small glaciers that are largely controlled by topography and local effects, this discrepancy is expected to have a larger effect and impede a more detailed analysis of future individual glacier changes.~~ To date, the most adequate and sophisticated method to model the evolution of all glaciers in the European Alps thus consists of modelling every glacier individually with a coupled ice flow – surface mass balance model. A pilot study in this direction was ~~recently~~ undertaken by Maussion et al. (2018), with the newly released Open Global Glacier Model (OGGM), in which steady-state simulations are performed for every glacier worldwide based on standard (i.e. non-calibrated) model parameters under the 1985-2015 climate. This model was recently also used by Goosse et al. (2018) to simulate the transient evolution of 71 Alpine glaciers over the past millennium.

Here, we explore the potential of using a coupled SMB – ice flow model for regional projections, by modelling the future evolution of glaciers in the European Alps with such a model. For this, we extend the Global Glacier Evolution Model (GloGEM) of Huss and Hock (2015) by introducing an ice flow component. We refer to this model as GloGEMflow in the following. Our approach is furthermore novel, as glacier-specific geodetic mass balance estimates are used for model calibration and the future glacier evolution relies directly on regional climate change projections from the EURO-CORDEX (COordinated Regional climate Downscaling EXperiment applied over Europe) ensemble (Jacob et al., 2014; Kotlarski et al., 2014). This is, to our knowledge, the first regional glacier modelling study in the Alps directly making use of this high-resolution regional climate model (RCMs) output. In contrast to a forcing with a general circulation model (GCM), an RCM driven ~~coupled to by~~ a GCM can provide information on much smaller scales, supporting a more in-depth impact assessment and providing projections with much detail and more accurate representation of localised events.

Through novel approaches in terms of (i) climate forcing, (ii) inclusion of ice dynamics, (iii) the use of glacier-specific geodetic mass balance estimates for model calibration, and by (iv) relying on a vast and diverse dataset on ground-truth data for model calibration and validation, we aim at improving future glacier change projections in the European Alps. As a part of our analysis, we explore how the new methods and data utilized could affect other regional and global glacier evolution studies.

~~reducing the considerable uncertainties in projections of future glacier evolution in the European Alps (Beniston et al., 2018).~~

2 Data

2.1 Glacier geometry

5 For every individual glacier in the European Alps, the outlines are taken from the Randolph Glacier Inventory (RGI v6.0) (RGI Consortium, 2017) (Fig. 1). These glacier outlines are mostly from an inventory derived by Paul et al. (2011) using Landsat Thematic Mapper scenes from August and September 2003 (for 96.7% of all glaciers included in the RGI). The surface hypsometry is derived from the Shuttle Radar Topography Mission (SRTM) version 4 (Jarvis et al., 2008) Digital Elevation Model (DEM) from 2000 (RGI Consortium, 2017).

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The ice thicknesses of the individual glaciers is calculated according to the method of Huss and Farinotti (2012) in 10-m elevation bands, which relies on ice volume flux estimates. The horizontal distance (Δx) between the elevation bands is determined from the elevation difference (Δy) and the band-average local surface slope (s):

$$\Delta x = \frac{\Delta y}{\tan s} \quad (1)$$

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To determine the band-average slope s , all values below the 5% quantile are discarded, as well as all values above a threshold (typically around the 80 to 90% quantile) determined based on the skewness of the slope distribution function. Subsequently, the glacier geometry is interpolated to a regular, horizontal grid along flow. Through this approach, possible glacier branches and tributaries are not explicitly accounted for, avoiding complications and potential problems related to solving the little-known mass transfer in these connections. As such, this approach is less sensitive to uncertainties in glacier outlines and topography compared to methods in which glacier branches are explicitly accounted for (e.g. Maussion et al., 2018), but may in some cases oversimplify the mass flow for complex glacier geometries (e.g. with several branches).~~Subsequently, the glacier geometry is interpolated to an along-flow regular horizontal grid. Through this approach, possible glacier branches and tributaries are not explicitly accounted for, avoiding complications and potential problems related to solving the mass transfer in these little known connections.~~ Glacier cross-sections are represented as symmetrical trapezoids. The bedrock elevation is determined in order to ensure local volume and area conservation.~~parameterised through a volume and area conserving approach in which they are represented as symmetrical trapezoids.~~ These symmetrical trapezoids deviate from a rectangular cross-section by an angle α (see suppl. mat. Fig. S1). A value 45° is taken for α , the effect of which is assessed in the uncertainty analysis (section 6.3).

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2.2 Climate data

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2-m air temperature and precipitation are used to represent the climatic conditions at the glacier surface for SMB calculations (section 3.1). For the past (1951-2017), we rely on the ENSEMBLES daily gridded observational dataset (E-OBS v.17.0) on

a 0.22° grid (Haylock et al., 2008). [This E-OBS product represents past events closely \(for example the heat wave of the summer of 2003, Fig. 2b\)](#), allowing for detailed comparisons between observed and modelled surface mass balances (section 4.1). We prefer using an observational dataset compared to a re-analysis product (e.g. ERA-INTERIM, as used in Huss and Hock, 2015), ~~in order to ensure a close representation of past temperature and precipitation and certain events (e.g. the heat wave of the summer of 2003 (Beniston, 2004), cf. Fig. 2b)~~, allowing for detailed comparisons between observed and modelled surface mass balances on short time scales (section 4.1). Furthermore, ~~as~~ the ~~observational product~~ [former](#) has a higher resolution ~~than the original reanalysis data (ERA-INTERIM)~~ and goes ~~back~~ further [back](#) in time. Additionally, relying on higher-resolution RCM simulations forced with reanalysis data is not possible, as for several ~~chains used for the future simulations~~ [future simulations](#) (see next paragraph), a related simulation is not available. This would furthermore complicate the model validation for the past, as the past climatic conditions would be different for every model ~~chain~~ [RCM simulation](#), while the observational data provides a single past temperature and precipitation forcing.

For the future, we use climate change projections from the EURO-CORDEX ensemble (Jacob et al., 2014; Kotlarski et al., 2014), from which all available simulations at 0.11° resolution (ca. 12 km horizontal resolution) are considered. This corresponds to a total of 51 ~~chains~~ [simulations](#), consisting of different combinations of nine RCMs, six GCMs and various realisations (r1i1p1, r12i1p1, r2i1p1, r3i1p1), forced with three representative concentration pathways (RCPs; [Fig. 2](#) ~~Fig. 2~~ and suppl. mat. Table S1) (van Vuuren et al., 2011; IPCC, 2013). The three considered RCPs are (i) a peak-~~and-decline~~ decline scenario with a rapid stabilisation of atmospheric CO₂ levels (RCP2.6), (ii) a medium mitigation scenario (RCP4.5) and (iii) a high-emission scenario (RCP8.5). ~~Notice~~ [Note](#) that [while](#) country-specific projections ~~exist~~, such as the [ones recently released with CH2018 report](#) ~~recently released CH2018 scenarios~~ for Switzerland (CH2018, 2018) [exist](#), which rely on simulations from the EURO-CORDEX ensemble, ~~but~~ these cannot be applied in a uniform way over the entire Alps.

[For modelling the future SMB, debiased RCM trends from the EURO-CORDEX ensemble are imposed on the E-OBS grid based on the nearest grid cell.](#) To ensure a consistency between the observational (E-OBS, used for past) and RCM (EURO-CORDEX, used for future) climatic data, a debiasing procedure is applied (Huss and Hock, 2015). Here, additive (temperature) and multiplicative (precipitation) monthly biases are calculated to ensure a consistency in the magnitude of the signal over the common time period. These biases are assumed to be constant in time and are superimposed on the RCM series. Furthermore, RCM temperature series are adjusted to account for differences in year-to-year variability between the observational and the RCM time series. Accounting for the differences in interannual variability is crucial to ensure the validity of the calibrated model parameters for the future RCM projections (Hock, 2003; Farinotti, 2013). For each month m , the standard deviation of temperatures over the common time period is calculated for both the observational ($\sigma_{obs,m}$) and the RCM data ($\sigma_{RCM,m}$). For each month m and year y of the projection period, the interannual variability of the RCM air temperatures $T_{m,y}$ is corrected as:

$$T_{m,y,\text{corrected}} = \overline{T_{m,25}} + (T_{m,y} - \overline{T_{m,25}})\phi_m \quad . \quad (2)$$

Here $\overline{T_{m,25}}$ is the average temperature in a 25-year period centered around y , and ϕ_m corresponds to $\sigma_{obs,m}/\sigma_{RCM,m}$. [This correction is applied over the period 1970-2017, which is the overlap period for which all RCM simulations and E-OBS data are available.](#) This procedure ensures consistency in interannual variability, while allowing for future changes in the temperature variability given by the RCMs ([Fig. 2](#)~~Fig. 2~~). [For precipitation, which enters the SMB calculations as a cumulative quantity, no correction for interannual variability is applied, as the monthly differences in variability are not that relevant at the annual scale. Furthermore, variability in precipitation does not have a direct effect on the calibrated SMB parameters \(as is the case for temperatures via the degree-day factors, see section 3.1\).](#)

2.3 Mass balance

The SMB model component is calibrated (section 3.1) with glacier-specific geodetic mass balances taken from the World Glacier Monitoring Service (WGMS) database (WGMS, 2018). Most of these geodetic mass balances were derived by Fischer (2011) (Austria), Berthier et al. (2014) (France, Italy and Switzerland) and Fischer et al. (2015b) (Switzerland).

~~Many Alpine About 1500 glaciers (ca. 38% by number) have a glacier-specific geodetic mass balance observation. Since larger glaciers are overrepresented in this sample, however, this corresponds to about 60% of the total Alpine glacier area glaciers have a glacier-specific geodetic mass balance observation.~~ For glaciers for which several geodetic SMB observations are available, the one closest to the reference period 1981-2010 is selected for model calibration. In case no geodetic mass balance observation for the specific glacier is available, an observation from a nearby glacier is chosen. The respective observation is selected based on the two criteria horizontal distance (in km) and relative difference in area (unitless). We multiply the two criteria and consider the minimum as the most suitable glacier to supply a mass balance observation for the unmeasured glacier. The replacement thus represents a nearby glacier that is relatively similar in size. The effect of this approach is evaluated in~~In case no geodetic mass balance observation for the specific glacier is available, an observation from a nearby glacier is chosen, based on a combined criterion weighting both horizontal distance and the difference in area~~ section 4.1.

For model validation (section 4.1), we rely on in situ SMB observations provided by the WGMS Fluctuations of Glaciers Database (WGMS, 2018), consisting of 1672 glacier-wide annual balances and 12'097 annual balances for specific glacier elevation bands. Note that we prefer using geodetic mass balance over SMB observations for calibration, as we argue that it is more important to have a good coverage for model calibration than for its validation. Furthermore, geodetic mass balances are becoming increasingly available at the regional scale (e.g. Brun et al., 2017; Braun et al., 2019) and outgrow the availability of in-situ measurements, making the adopted strategy applicable to other regions.

3 Methods

GloGEMflow consists of a surface mass balance component (section 3.1), which is taken from GloGEM (Huss and Hock, 2015), and an ice flow component (section 3.2). These two components are combined to calculate the temporal evolution of the glacier (section 3.3).

3.1 Surface mass balance modelling

Here, we briefly describe the SMB model component, with an emphasis on the settings specific to this study. For a more elaborate description, we refer to the description in Huss and Hock (2015).

For every glacier, the model is forced with monthly temperature and precipitation series (section 2.2) from the E-OBS (past) or RCM (future) grid cell closest to the ~~specific~~ glacier centre's point. Accumulation is computed from precipitation and a threshold is used to differentiate between liquid and solid precipitation. This threshold is defined as an interval from 0.5°C to 2.5°C, within which the snow/rain ratio is linearly interpolated. The melt is calculated for every grid cell from a classic temperature-index melt model (Hock, 2003), in which a distinction between snow, firn and ice melt is made based on different degree-day factors. Refreezing of rain and melt water is also accounted for and calculated from snow and firn temperatures based on heat conduction (see Huss and Hock, 2015). Huss and Hock (2015) showed that the added value of using a simplified energy balance model (Oerlemans, 2001) was limited, and that it did not perform better than the temperature-index melt model when validated against SMB measurements.

For every individual glacier the climatic data is scaled from the gridded product to the individual glacier at a rate of 2.5% per 100 m elevation change for precipitation and by relying on monthly temperature lapse rates derived from the RCMs. Subsequently, model calibration parameters (degree-day factors, precipitation scaling factor) are adapted as a part of a glacier-specific three-step calibration procedure that aims at reproducing the observed geodetic mass balance. In the first step, overall precipitation is multiplied with a scaling factor varying between 0.8 and 2.0. This initial step focuses on the precipitation, as this is the variable that is expected to be the most poorly reproduced due to resolution issues, spatial variability and local effects (e.g. snow redistribution) (e.g. Jarosch et al., 2012; Hannesdóttir et al., 2015; Huss and Hock, 2015). If this step does not allow reproducing the observed geodetic SMB within a 10% bound, in a second step the degree-day factors for snow and ice are modified. Here, the degree-day factor of snow is allowed to vary between 1.75 and 4.5 mm d⁻¹ K⁻¹ (default value is 3 mm d⁻¹ K⁻¹; cf. Hock (2003)) and the degree-day factor of ice is adjusted to ensure a 2:1 ratio between both degree-day factors. In an eventual third and final step, the air temperature is modified through a systematic shift over the entire glacier (see Figure 2a in Huss and Hock, 2015 for more details).

3.2 Ice flow modelling

The ice flow is modelled explicitly with a flowline model for all glaciers longer than 1 km at the RGI inventory date. These 795 glaciers represent ca. 95% of the total volume and 86% of the total area of all glaciers in the European Alps (Fig. 1 inset). For glaciers shorter than 1 km, mass transfer within the glacier is limited, and the time evolution is modelled through the Δh -parameterisation (Huss et al., 2010b), in line with the original GloGEM setup (Huss and Hock, 2015).

The dynamics of the ice flow component are solved through the Shallow-Ice Approximation (SIA) (Hutter, 1983), in which basal shear (τ) is proportional to the local ice thickness (H) and the surface slope ($\frac{\partial s}{\partial x}$):

$$\tau = -\rho g H \frac{\partial s}{\partial x} \quad (3)$$

$g=9.81 \text{ m s}^{-2}$ is gravitational acceleration, while the ice density ρ is set to 900 kg m^{-3} . In our model, mass transport is expressed through a Glen (1955) type of flow law, in which the depth-averaged velocity \bar{u} (m yr^{-1}) is defined as:

$$\bar{u} = \frac{2A}{n+2} \tau^n H. \quad (4)$$

Here $n = 3$ is Glen's flow law exponent, and A is the deformation-sliding factor ($\text{Pa}^{-3} \text{ yr}^{-1}$) that accounts for the effects of the ice rheology on its deformation, sliding and various others effects (e.g. lateral drag). Basal sliding is implicitly accounted for through this approach and not treated separately from internal deformation, given the relatively large uncertainties associated with it. Basal sliding and internal deformation are both linked to the surface slope and the local ice thickness and have been shown to have similar spatial patterns on Alpine glaciers (e.g. Zekollari et al., 2013), justifying an approach in which both are combined (e.g. Gudmundsson, 1999; Clarke et al., 2015).

10 3.3 Time evolution and initialisation

The glacier geometry is updated at every time step through the continuity equation:

$$\frac{\partial H}{\partial t} = \nabla \cdot f + b, \quad (5)$$

where b is the surface mass balance (m w.e. yr^{-1}) and $\nabla \cdot f$ is the local divergence of the ice flux ($f = D \frac{\partial s}{\partial x}$). For a transect with a trapezoidal shape, with a basal width w_b and a surface width w_s (suppl. mat. Fig. S1), this becomes (cf. Oerlemans, 1997):

$$\frac{\partial H}{\partial t} = -\frac{1}{w_s} \left[\left(\frac{w_b + w_s}{2} \right) \frac{\partial \left(D \frac{\partial h}{\partial x} \right)}{\partial x} + \left(D \frac{\partial h}{\partial x} \right) \frac{\partial \left(\frac{w_b + w_s}{2} \right)}{\partial x} \right] + b, \quad (6)$$

where D is the diffusivity factor ($\text{m}^2 \text{ yr}^{-1}$):

$$D = A \left(\frac{2}{n+2} \tau^n H^2 \right) \left(\frac{\partial s}{\partial x} \right)^{-1}. \quad (7)$$

[The continuity equation is solved using a semi-implicit forward scheme by relying on an intermediate time step \(i.e. sub-time step update\) in which the geometry is updated.](#)

20 The initialisation consists of closely reproducing the glacier geometry at the inventory date. At first, ~~a constant climate is imposed~~ [conditions are imposed](#), until a steady state is created, which represents the glacier in 1990 ([Fig. 3](#)~~Fig-3~~). ~~This~~ [These](#) constant climate [conditions](#) corresponds to the [mean SMB under the](#) 1961-1990 climate, to which a SMB perturbation is applied (detailed below). Subsequently, the glacier is forced with E-OBS data, and evolves transiently from 1990 until the glacier-specific inventory date (typically 2003). ~~In this study, we~~ [We opted for a 1990 steady-state glacier, as the glaciers in the European Alps were generally not too far off equilibrium around this period, with SMBs conditions for many glaciers being close to zero \(Huss et al., 2010a; WGMS, 2018\). By imposing a steady state in 1990 \(through an offset in the 1961-](#)

~~1990 climatic conditions), the glacier length at the inventory date can be influenced. Methodologically, choosing an initial steady state before 1990 would be problematic, as in this case the glacier geometry would not determine the glacier length at the inventory date anymore, as the period between the steady state and the inventory date exceeds the typical Alpine glacier response time of several years to a few decades. By relying on an earlier time (before 1990) for the steady state, in some cases the steady state glacier geometry does not determine the glacier length at the inventory date anymore, as the period between the steady state and the inventory date exceeds the typical Alpine glacier response time of several years to a few decades (e.g. Oerlemans, 2007; Zekollari and Huybrechts, 2015).~~

The glacier volume and length at inventory date are matched by calibrating two variables. ~~The glacier volume and length at the inventory date are matched by modifying two calibration variables (Fig. 3 Fig. 3).~~ The first calibration variable is the deformation-sliding factor A , which mainly determines the volume of the glacier at the inventory date. The reason for this resides in the role that A has on the local velocity/flux, which in turn affects the local ice thickness and thus the ice volume; see Eqs. (4-7). The second calibration variable is an ~~The deformation-sliding factor A , the calibration of which mainly determines the volume of the glacier at the inventory date.~~

~~A SMB offset in the 1961-1990 climatic conditions used to construct a 1990 steady-state glacier, which mainly determines the length of the steady-state glacier (as the geometry is such that the integrated SMB equals zero). Note that a change in steady-state length causes the glacier length to change at inventory date as well. at the inventory date. Notice that through this approach, the glacier is not assumed to be in steady state at any point in time, but that an artificially modelled steady state is obtained by imposing a MB offset.~~

An optimisation procedure is used, in which at each iteration the deformation-sliding factor and the SMB offset are informed from previous iterations (see Appendix A for details). This results in a fast convergence to the desired state, i.e. a glacier with the same length and volume as the reference geometry (from Huss and Farinotti, 2012) at the inventory date. It should be noticed that the reference volume is itself a model result (Huss and Farinotti, 2012) and thus also holds uncertainties. The choice for the 1990 steady state and the effect this has on the calibration procedure is assessed in the uncertainty analysis (section 6.3).

4 Model validation

4.1 Surface mass balance

The modelled SMB is evaluated by using independent, observed glacier-wide annual balances and annual balances for glacier elevation bands (Fig. 4 Fig. 4). In order to ensure that the validation procedure is independent from the calibration, validation is only performed with observations that do not temporally overlap with the geodetic mass balances used for

calibration (cf. sections 0 and 3.1) and for glaciers without geodetic mass balance observations. As the aim is to evaluate the performance of the SMB model (rather than the coupled SMB – ice flow model) and to incorporate as many validation points as possible (which is only possible after 1990 for the dynamic simulations), these calculations are based on the glacier geometry at inventory date. ~~As the aim is to evaluate the performance of the SMB model in this section, rather than the coupled SMB – ice flow model, these calculations are based on the glacier geometry at the inventory date.~~ The observed glacier-wide annual mass balances are in general well reproduced, with a root-mean-square error (RMSE) of 0.741 m w.e. yr⁻¹, a Median Absolute Deviation (MAD) of 0.674 m w.e. yr⁻¹ and a systematic error (mean misfit) of -0.095 m w.e. yr⁻¹ (Fig. 4a,b). Furthermore, the good agreement between observed and modelled balances for glacier elevation bands ($r^2 = 0.6360$; Fig. 4b,d) suggests that, despite not being calibrated to this, the modelled and observed SMB gradient are in reasonably good agreement. ~~SMB model distributes the annual SMB relatively well over elevation.~~ When only considering SMB measurements on glaciers that have no observed geodetic mass balance (i.e. glaciers for which the geodetic mass balance used to calibrate the model was extrapolated from other, nearby glaciers), the misfit between modelled and observed values increases only little (RMSE = 0.79 m w.e. yr⁻¹; MAD = 0.72 m w.e. yr⁻¹; mean misfit = -0.19 w.e. yr⁻¹), indicating that the method used to extrapolate the geodetic mass balances to unmeasured glaciers performs well. Finally, sensitivity tests were performed with the SMB model being forced with historical RCM output (instead of E-OBS). The tests indicate that the RCMs, despite not being forced with reanalysis data, are producing general SMB tendencies that are relatively close to those obtained when forcing the model with E-OBS data (similar mean values, see suppl. mat. Fig. S2; similar interannual variability: $\sigma_{\text{SMB,E OBS}} = 0.66$ m w.e. yr⁻¹; mean $\sigma_{\text{SMB,RCM}} = 0.58$ m w.e. yr⁻¹).

4.2 Glacier geometry

The glaciers are calibrated to match the length and volume at inventory date within 1% (σ between reference and modelled volume or length of 0.6% or 0.5% of the reference value, respectively). Despite not being calibrated to it, the observed glacier area is also closely reproduced (σ of 0.7%). ~~The glaciers are calibrated to match the length and volume at the inventory date~~ In the calibration procedure the distribution of ice, ~~but the distribution of ice~~ with elevation is unconstrained, ~~but nonetheless the~~. ~~Despite this, the~~ reference volume-elevation distribution of ~~the various~~ glacier, based on Huss and Farinotti (2012), updated to RGI v6.0, is well reproduced ~~at the inventory date~~. We use two well-studied glaciers to illustrate this (~~Fig. 5~~ ~~Fig. 5~~), namely the Grosser Aletschgletscher (Valais, Switzerland) and the Mer de Glace (Mont-Blanc massif, France). Also for the other 793 glaciers longer than 1 km, a good match is obtained in general (see section 8).

4.3 Glacier dynamics

In our approach the mass transport between grid cells is linearly dependent on the deformation-sliding factor A , and is thus important for the ice dynamics. The calibrated values of A for every individual glacier do not have a distinct spatial pattern, nor do they correlate with glacier length or glacier elevation (suppl. mat. Fig. S32). It is not straightforward to compare the values of the deformation-sliding factor to other values from literature used to describe ice deformation and mass transport (such as rate/creep factors), as different formulations and approaches are utilised, e.g. the inclusion/exclusion of a shape factor, explicit/implicit treatment of basal sliding, different geometry representations, etc. However, it appears that the spread in the modelled deformation-sliding factors, which results from the fact that this value represents several physical processes and uncertainties in our approach, largely falls within the literature range values of rate/creep factors (suppl. mat. Fig. S32). Furthermore, the calibrated median ($1.1 \times 10^{-16} \text{ Pa}^{-3} \text{ yr}^{-1}$) and mean ($1.3 \times 10^{-16} \text{ Pa}^{-3} \text{ yr}^{-1}$) values are relatively close to the widely used rate/creep factor from Cuffey and Paterson (2010) based on several modelling studies ($0.8 \times 10^{-16} \text{ Pa}^{-3} \text{ yr}^{-1}$).

In the lower parts, where many glaciers have a distinct tongue, a comparison between ~~modelled-observed~~ and ~~observed modelled~~ surface velocities ~~is possible~~ (surface velocities correspond to 1.25 times the depth-integrated, since we treat basal sliding implicitly, see e.g. Cuffey and Paterson (2010, p.310)). ~~;~~ This is more complicated for the higher parts of the glaciers, where glaciers may be broad and have various branches, which we do not explicitly account for in our approach. In general, our model is able to reproduce the observed surface velocities for the lower glacier parts despite its simplicity. Based on a set of surface velocity observations from the literature (see ~~Fig. 6~~ ~~Fig. 6~~ and suppl. mat. Table S2), a large range of surface velocities, ranging from 1 m yr^{-1} to $> 200 \text{ m yr}^{-1}$ is well reproduced ($r^2=0.76$; $\text{RMSE} = 31.8 \text{ m yr}^{-1}$), without a tendency for consistent under- or overestimation. This is illustrated for Grosser Aletschgletscher and the Mer de Glace (~~Fig. 5~~ ~~Fig. 5~~). Some discrepancies may be likely linked to the simplicity of our model and uncertainties in various boundary conditions, but they may in part also be related to the different time periods between the observations and the modelled state.

4.4 Past glacier evolution

Modelled past glacier length and area changes are compared to observations for the time period between the inventory date (typically 2003) and present-day (2017). Periods before 2003 are not considered, as the effect from the imposed 1990 steady state may still be pronounced on the initial glacier evolution (1990-2003). Furthermore, before the inventory date, length and area changes from the Δh -parameterisation (which we apply for glaciers <1 km) are not available, as here the starting point is the observed geometry at the inventory date. ~~Notice-Note~~ that past glacier volume changes are available (e.g. Fischer et al., 2015b), but that these are not used for validation, as they were utilized for calibrating the SMB model component.

4.4.1 Glacier length

The modelled length changes between the inventory date (2003) and 2017 are compared to observations for all 52 Swiss glaciers longer than 3 km that are included in the Swiss glacier monitoring network (GLAMOS) (Glaciological Reports, 1881-2017) (~~Fig. 7~~~~Fig. 7~~). ~~Note that other length records are also available for non-Swiss glaciers~~ (e.g. Leclercq et al., 2014), ~~but that these were not considered to ensure a consistency in derived length records~~. Despite the model's simplicity, the general trends in glacier retreat are relatively well reproduced and there is no general tendency for over- or underestimation. A few outliers exist (highlighted in ~~Fig. 7~~~~Fig. 7~~), of which the underestimations can be attributed to a detachment of the lower and upper parts of the glacier, which cannot be captured in our modelling setup. Overestimated retreat rates (Ferpècle, Montminé and Stein) occur for glaciers where the modelled ice thickness in the frontal region at the inventory date is likely to be lower than the reference state and/or where the ice thickness is underestimated in the reference case. When the three glaciers with underestimations due to a disconnection are omitted, the correlation between the observed and modelled glacier retreat is $r^2 = 0.37$ (~~is highly significant~~ (p-value $< 1 \times 10^{-3}$; ~~$r^2 = 0.37$~~). For large glaciers, the retreat is particularly well reproduced: e.g. for glaciers longer than 8 km the root-mean-square error (RMSE) between the observed and modelled 2003-2017 retreat is only 155 m, corresponding to ca. 30% of the mean observed (490 m) and modelled (540 m) retreat over this time period.

4.4.2 Glacier area

~~In the literature,~~ ~~g~~ Glacier area changes in the European Alps have been derived ~~from various sources~~ ~~in various studies~~. Depending on the time period considered and the ensemble of glaciers studied, estimated glacier area changes vary broadly from $-1.5\% \text{ yr}^{-1}$ to $-0.5\% \text{ yr}^{-1}$. Paul et al. (2004) derived area changes for 938 Swiss glaciers and used this to extrapolate a loss of 675 km^2 for all glaciers in the European Alps over ~~period~~ 1973-1998/9 ~~period~~ (corresponding to a 22% mass loss, or about $-0.85\% \text{ yr}^{-1}$ / $26 \text{ km}^2 \text{ yr}^{-1}$). For Austria, area changes of $-1.2\% \text{ yr}^{-1}$ were observed for the period 1998-2004/2012 (Fischer et al., 2015a). On longer time scales, Fischer et al. (2014) derived a relative area loss of $0.75\% \text{ yr}^{-1}$ for the period

1973-2010 over Switzerland, while for the period 2003-2009 an area loss of $1.3\% \text{ yr}^{-1}$ was obtained for glaciers in the eastern Swiss Alps. French glaciers lost about one quarter of their area between 1967/1971 and 2006/2009, corresponding to a change of $-0.7\% \text{ yr}^{-1}$ (Gardent et al., 2014), while Italian glaciers lost about 30% of their area over the 1959/1962-2005/2011 period (i.e. average of $-0.6\% \text{ yr}^{-1}$) (Smiraglia et al., 2015).

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Between 2003 and 2017, we model a glacier area loss of 223 km^2 ($16 \text{ km}^2 \text{ yr}^{-1}$), corresponding to a relative area loss of 11.3% (vs. mean area over this time period), or $0.8\% \text{ yr}^{-1}$. These numbers are difficult to directly compare with values from the literature, as different time periods are considered (implying also a different reference area), and as the area losses strongly depend on size of the considered glaciers (e.g. Paul et al., 2004; Fischer et al., 2014), which also varies between studies. However, a qualitative comparison suggests that the modelled area changes are in general slightly lower than the observations. This discrepancy is mostly related to the fact that many present-day glaciers have frontal regions and ablation areas with almost stagnant ice, and in some cases also consist of disconnected ice patches, which our model is not able to capture with a simple cross-section parameterisation. By modifying the cross section through increasing λ , a higher modelled area loss is obtained, in closer agreement with observations. However, a higher value of λ may be unrealistic (i.e. produce an area change close to observations for the wrong reasons), and the effect of a different λ value is found to have a very limited effect on the future modelled volume and area changes (this is addressed in section 6.3).

15

5 Future glacier evolution

Our projections suggest that from 2017 to 2050 a total volume loss of about 50% and area loss of about 45% will occur, and that this evolution is independent from the ~~followed~~-RCP (Fig. 8 Fig. 8 and Table 1 Table 1). This evolution is related to the fact that the annual and summer temperature differences between the RCPs increase with time and are thus relatively limited in the coming decades (see Fig. 2 Fig. 2a,b). Furthermore, a part of the future evolution is committed, i.e. being a reaction to the present-day glacier geometry, which is too large for the present-day climatic conditions for most glaciers in the European Alps (e.g. Zekollari and Huybrechts, 2015; Gabbud et al., 2016; Marzeion et al., 2018; cf. discussion in 6.1.1).

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By the end of the century the modelled glacier volume and area are largely determined by the RCP that was used to force the climate model (Fig. 8 Fig. 8). Under RCP2.6, in 2100 about 65% of the present-day (2017) volume and area are lost ($-63.2 \pm 11.1\%$ and $-62.1 \pm 8.4\%$ respectively, multi-model chain mean $\pm 1\sigma$; Table 1 Table 1, Fig. 8 Fig. 8a). Most of the ice loss occurs in the next three decades, corresponding to about 70-75% of the total changes for the period 2017-2100 (Table 1 Table 1), after which the ice loss clearly reduces (Fig. 8 Fig. 8). For an intermediate warming scenario (RCP4.5), by the end of the century about three-quarters of the present-day volume ($-78.8 \pm 8.8\%$) and area ($-74.9 \pm 8.3\%$) are lost (Fig. 8 Fig. 8, Table 1 Table 1). In contrast to the glacier evolution under RCP2.6, under RCP4.5 a substantial part of the loss takes place in the second part of the 21st century. However, the largest changes still occur in the coming three decades with about 60% of the

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total changes for the period 2017-2100 (see [Table 1](#)). For RCP8.5, the rates of volume loss ($-1.5 \text{ km}^3 \text{ yr}^{-1}$) and area loss ($-25 \text{ km}^2 \text{ yr}^{-1}$) are relatively constant until 2070 ([Fig. 8](#)), after which they decrease to ca. $-0.5 \text{ km}^3 \text{ yr}^{-1}$ and $-15 \text{ km}^2 \text{ yr}^{-1}$, respectively. By 2100, the Alps are largely ice-free under RCP8.5, with volume losses of $-94.4 \pm 4.4\%$ and area losses of $-91.1 \pm 5.4\%$ with respect to 2017 (see [Table 1](#)).

An analysis in which the relative volume loss is compared to present-day glacier characteristics (volume, area, length, median elevation, mean elevation, minimum elevation, maximum elevation, centre of mass and elevation range) reveals that under RCP2.6, the [elevation range](#) relative volume loss has the highest correlation with the [glacier maximum glacier elevation](#) [elevation range](#) ([Fig. 9](#) and suppl. mat. Table S3; $r^2 = 0.57$). The maximum glacier elevation, which is strongly related to the glacier elevation range, also describes the volume changes well (suppl. mat. Table S3, $r^2 = 0.38$). This also appears from the spatial distribution of the relative volume loss, where the losses are the most limited for mountain ranges that reach above 3600-3700 m (from West to East): the Écrin massif, the Mont Blanc Massif, the Monte Rosa Massif, the Bernese Alps, the Bernina Range, in the Dolomites, in the Ötztal Alps and the High Tauern ([Fig. 9a](#)). The ice loss is particularly strong [under below](#) 3200 m a.s.l., where (for a given elevation band) more than half of the present-day volume disappears by 2100 under RCP2.6 ([Fig. 10](#)) (suppl. mat. [Fig. S3](#)). The remaining ice at these lower elevations is typically from medium-sized and large glaciers, which maintain a relatively large accumulation area that supplies mass to the lower glacier regions. This is for instance the case for the Mer de Glace (France) and Grosser Aletschgletscher (Switzerland), where ice is still present below 2500 m a.s.l. by the end of the century under most EURO-CORDEX RCP2.6 [chains simulations](#) ([Fig. 11a,b](#)). However, both glaciers lose a considerable part of their length throughout the century, but whereas Grosser Aletschgletscher ([Fig. 11a](#)) will likely still be retreating by the end of the century, Mer de Glace will be relatively stable in 2100 under most EURO-CORDEX [chains simulations](#), and [may](#) under certain [chains simulations](#) even experience re-advance episodes after 2080 ([Fig. 11b](#)). Glaciers that spread over a higher elevation range are likely to suffer even less changes, and in some cases only lose their low-lying tongues ([Fig. 9b](#)). In contrast, glaciers at low elevation mostly disappear by the end of the century, even under the moderate RCP2.6 scenario. This is for illustrated for Langtaler Ferner (Austria), which is situated below 3300 m a.s.l. and is projected to (almost) entirely disappear somewhere between 2050 and 2100 depending on the followed [chain simulation](#) ([Fig. 11c](#)).

The glacier elevation range is also the variable with the highest correlation with respect to the future relative volume changes under RCP4.5 ($r^2 = 0.63$) and RCP8.5 ($r^2 = 0.51$) (suppl. mat. Table S3). Under these RCPs, except for the related maximum elevation, also the present-day glacier length correlates significantly with the 2017-2100 volume loss ($r^2 = 0.23$ and $r^2 = 0.20$ respectively). This indicates that under more extreme scenarios the ice loss is very pronounced at all elevations (see also [Fig. 11d,e](#)) and the remaining ice in 2100 is mainly a relict of the present-day ice distribution, i.e. ice at the end of the century is only remaining where there is much ice at present at relatively high elevation.

6 Discussion

6.1 Drivers of future evolution

5 6.1.1 Committed loss

Part of the future mass loss is committed and related to the present-day glacier distribution of ice. Many glaciers have a present-day mass excess at low elevation, where locally the flux divergence cannot compensate for the very negative SMB, resulting in a negative thickness change (see equation (5.5)) (e.g. Johannesson et al., 1989; Adhikari et al., 2011; Zekollari and Huybrechts, 2015; Marzeion et al., 2018). To assess the importance of this committed effect, we investigate the glacier evolution under present-day climatic conditions. For this, the model is constantly forced with the mean 1988-2017 SMB (Fig. 8). ~~Under these conditions, the glaciers lose about 35% of their present day volume and area by the end of the century.~~ Under these conditions, the committed loss is particularly strong for small glaciers at lower elevations (e.g. Langtaler Ferner, with a committed volume loss of ca. 90% by 2100), while for larger glaciers this effect is more limited. Overall, the Alpine glaciers are projected to lose about 35% of their present-day volume and area by the end of the century. Simulations with other recent reference periods (e.g. 2008-2017) resulted in relatively similar committed ice losses. This suggests that under RCP2.6, about 60% of the ice losses for the period 2017-2100 are committed losses, while the remaining 40% are related to additional warming.

20 The committed losses are in agreement with simulations performed by Maussion et al. (2018). In steady-state experiments with the Open Global Glacier Model in which all glaciers, starting from their geometry at the inventory date (typically 2003), are subjected to the 1985-2015 randomised climate, Maussion et al. (2018) project ice volume losses of around 55% over a 100-year time period for the European Alps. In our simulations, over the period 2000-2100, about 50% of the ice mass is lost for an experiment in which the model is forced with the E-OBS product until 2017 and subsequently with a constant 25 | 1988-2017 mean SMB (grey line on Fig. 8a).

6.1.2 Role of ice dynamics

Our model setup allows us to analyse the effect of including ice dynamics, compared to the classic GloGEM setup (Huss and Hock, 2015), in which glacier changes are imposed based on the Δh -parameterisation (Huss et al., 2010b) at the regional scale. Comparisons are performed for the period 2003-2100, as the simulations with the Δh -parameterisation start from the geometry at the inventory date (2003 for >96% of all glaciers).

All dynamically modelled glaciers (GloGEMflow) are also run with the Δh -parameterisation (GloGEM). A comparison between the (i) difference in the 2003-2100 relative volume loss (between GloGEMflow and GloGEM) and (ii) various glacier characteristics, reveals that the effect of including ice dynamics is particularly linked to the glacier elevation range ($r^2 = 0.27$; $p < 1 \times 10^{-3}$), and to a lesser extent to other (related) glacier characteristics, such as glacier length ($r^2 = 0.08$), mean slope ($r^2 = 0.04$), minimum elevation ($r^2 = 0.07$) and the maximum elevation ($r^2 = 0.20$) (all values based on multi-chain model mean for RCP2.6). Under RCP2.6, glaciers with a large elevation range (typically > 1000 m) experience less loss in the dynamic model on average compared to when being forced with the Δh -parameterisation (Fig. 12 Fig. 14). The mechanism behind this is the following:

(i) At the inventory date, the glacier geometry is very similar in both approaches, as the dynamically modelled glacier is as close as possible to the observed geometry (see section 4.2.4.2), which is the starting point for the Δh -parameterisation.

(ii) Initially, the total glacier volume evolution is relatively similar in both approaches, as the glaciers are subject to the same climatic conditions and their geometry does barely differ.

(iii) However, for glaciers with a large elevation range, relatively more ice is removed at middle and high elevation in the Δh -parameterisation, while in the dynamic model the ice loss at the lowest glacier elevations is more pronounced.

(iv) As a consequence, the geometry starts evolving differently between both approaches, and the larger ice mass at lower elevation in the Δh -parameterisation (and lower ice mass at high elevation) translates into a more negative specific glacier mass balance for the Δh -parameterisation (vs. the dynamic model), resulting in a higher mass loss.

(v) In the second half of the 21st century, most glaciers stabilize under a limited to moderate warming (their glacier-wide mass balance evolves towards zero). Given the lower mass and area at middle to high elevations (i.e. around the ELA and higher) for the glaciers modelled with the Δh -parameterisation, these will be slightly smaller to ensure a near-zero SMB.

As glaciers with a large elevation-range are typically the largest glaciers, which make up for a substantial fraction of the total volume, the overall mass loss is thus attenuated when ice dynamics are considered compared to simulations with the Δh -parameterisation (Fig. 13 Fig. 12, suppl. mat. Table S4). The same holds under RCP4.5 (suppl. mat. Fig. S44a,b), though being less pronounced due to the more intense melting, which also causes glacier changes to occur at higher elevation, and largely disappears under RCP8.5, where the future evolution is largely the same when glaciers are modelled dynamically or with the Δh -parameterisation (suppl. mat. Fig. S44c,d and Fig. 13 Fig. 12).

6.1.3 Role of glacier-specific geodetic mass balance estimation

In this study we use direct geodetic mass balance observations from individual glaciers to calibrate the SMB model component. This contrasts with the original GloGEM setup (Huss and Hock, 2015), in which the calibration is based on regional mass balance estimates. To assess the effect of the SMB calibration source, we perform additional simulations in which the model is forced with a region-wide average geodetic mass balance estimate. In order to allow for a direct

comparability, we use a region-wide estimate based on the same geodetic mass balance data as used for our glacier-specific calibration. A value of $-0.54 \text{ m w.e. yr}^{-1}$ is obtained for the period 1981-2010.

5 | Compared to the reference simulations (with the SMB model calibrated using glacier-specific geodetic mass balances), the
simulations in which a region-wide SMB estimate is used for model calibration result in a lower future mass loss ([Fig. 13](#)
10 | [Fig. 12](#), suppl. mat. Table S4). The difference is the largest under RCP2.6, where the glacier volume change for the 2003-
2100 period is -70% (vs. -65% in the standard simulations). The lower mass loss results likely from the fact that for larger
glaciers the region-wide SMB estimate is typically higher than their mass balance. By utilising region-wide estimates, the
mass balance is thus overestimated in general for these glaciers that make up for a large fraction of the total volume,
resulting in a lower mass loss.

6.1.4 Simulated future climate

15 | To assess the role of climate on the modelled future glacier state, we performed a multilinear regression analysis for
categorical data between the RCM ~~chain-simulation~~ characteristics (RCP, RCM, GCM and realization) and the glacier
volume in 2100. In such an analysis, all independent variables are replaced by dummy ~~indicator~~-variables, which have a
value of one when the variable is ~~not~~ considered, and are equal to zero otherwise (e.g. Liang et al., 1992; Tutz, 2012). An
analysis in which all possible linear combinations are considered, explains most of the variations in the 2100 volume, as the
degrees of freedom are relatively low (cf. suppl. mat. Table S5). An analysis of variance suggests that most of the variance is
20 | described by the RCP (suppl. mat. Table S5; p-value of F-test $<10^{-3}$), as expected, and described earlier (see [Fig. 8](#)~~Fig-8~~).
The only other term that is significant at the 1% level is the GCM ($p < 10^{-3}$), followed by the RCM, which is significant at the
5% level ($p = 0.04$), and finally the realization ($p = 0.13$) (suppl. mat. Table S5). This indicates that modelled future glacier
evolution depends more importantly on the driving GCM than the RCM ~~that is coupled to it~~, and that the realization has a
non-significant effect. The importance of the GCM-forcing also appears from additional simulations in which the original,
25 | low-resolution, GCM output was used as model forcing. When comparing these results to the ones obtained by forcing the
model with the corresponding EURO-CORDEX GCM-RCM combinations, a similar glacier evolution is obtained (with
volume losses vs. present-day typically differing $<10\%$, suppl. mat. Fig. S5). The limited number of GCM-RCM
combinations, however, does not allow for a detailed comparison with the GCMs, but does not suggest any systematic over-
or underestimation of the corresponding results.

6.2 Comparison to projections from other Alpine glacier modelling studies

The future evolution of glaciers in the European Alps has been modelled with models of various complexity and by relying on diverse climate projections. By using a statistical calibrated model in which the ELA is related to summer temperature and winter precipitation, Zemp et al. (2006) estimated an area loss of about 40, 80, and 90% for a respective temperature increase of 1°C, 3°C and 5°C (2100 v. 1971-1990 mean). Based on 50 glaciers modelled with a retreat parameterisation and subsequent extrapolation Huss (2012) found that between 4% (RCP8.5) and 18% (RCP2.6) of the glacier area will remain by 2100 (vs. 2003). Results from global studies relying on volume/length-area scaling (Marzeion et al., 2012; Radić et al., 2014) and methods in which geometry changes are parameterised (Huss and Hock, 2015) suggest that Alpine glaciers will be subject to volume changes of about –65% to –80% under RCP2.6; between –80% and –90% under RCP4.5; and around –90% to –98% under RCP8.5 (all values between refer to time period between about 2000 and 2100).

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Our simulated volume changes are situated between the lowest projected volume losses (Marzeion et al., 2012) and the highest projected volume losses (Huss and Hock, 2015), and are relatively close to the estimates of (Radić et al., 2014) ([Fig. 14](#) [Fig. 13](#); all changes are considered over the same reference period as study from the literature). Given the different models and inputs, a direct comparison is however difficult with the results of Marzeion et al. (2012) and Radić et al. (2014). Differences in initial volume estimates may play an important role (e.g. Huss, 2012), and so does the climatic forcing and translation into mass balance, which is study-dependent. The lower losses compared to the results of GloGEM (Huss and Hock, 2015) suggest that the effect of including ice dynamics (reducing the mass loss, section 6.1.2), combined with a slightly lower temperature increase (from EURO-CORDEX RCM ensemble vs. CMIP5 simulations over Europe used in Huss and Hock (2015)), dominate over the effect of using glacier-specific geodetic mass balances (section 6.1.3)

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To our knowledge, three studies have been performed in which the future evolution of an individual Alpine glacier is simulated with 3-D simulations accounting for longitudinal stresses, i.e. with higher-order and full-stokes models (Jouvet et al., 2009, 2011; Zekollari et al., 2014). Simulations with our flowline model agree well with those for the Rhonegletscher and Grosser Aletschgletscher (Jouvet et al., 2009, 2011), and project a slightly higher mass loss compared to those for the Vadret da Morteratsch complex (Zekollari et al., 2014). More details are provided in the supplementary material (Table S6). Given the differences in boundary conditions and model specifications (e.g. bedrock geometry, SMB model etc.) these findings should not be overinterpreted, but give a qualitative indication that our model is able to relatively well reproduce changes obtained from more complex and detailed studies on individual ice bodies.

30 **6.3 Sensitivity experiments and uncertainty analysis**

6.3.1 1990 steady state assumption and deformation-sliding factor

In this study, we opted for a 1990 steady state glacier, as the glaciers in the European Alps were generally not too far off equilibrium around this period, with SMB conditions for many glaciers being close to zero (Huss et al., 2010a; WGMS, 2018). By imposing a steady state in 1990 (through an offset in the 1961-1990 climatic conditions), the glacier length at the inventory date can be influenced. By relying on an earlier time (before 1990) for the steady state, in some cases the steady state glacier geometry does not determine the glacier length at the inventory date anymore, as the period between the steady state and the inventory date exceeds the typical Alpine glacier response time of several years to a few decades (e.g. Oerlemans, 2007; Zekollari and Huybrechts, 2015). In such a case, only the glacier volume at inventory date can be matched, through a modification of the deformation-sliding factor.

In order to assess the effect of the 1990 steady state assumption and the specific calibration procedure utilized in this study, we performed alternative simulations starting in 1950, in which only the volume at the inventory date is matched (no check on glacier length) through a modification of the deformation-sliding factor. Through this approach, the calibrated deformation-sliding factor is lower than in the two-step approach used as the reference (mean value of $0.6 \times 10^{-16} \text{ Pa}^{-3} \text{ yr}^{-1}$ vs. $1.3 \times 10^{-16} \text{ Pa}^{-3} \text{ yr}^{-1}$; see suppl. mat. Fig. S3)2), and as such, this experiment also provides an insight into the effect of variations in the deformation-sliding factor on future evolution. This is furthermore of interest, as the deformation-sliding factor depends on the reference glacier volume, which is itself a model result (Huss and Farinotti, 2012) with its own uncertainties. The lower deformation-sliding factors (vs. the two-step-parameter calibration approach) result in slightly shorter glaciers at present (vs. observations), as they represent the same volume at the inventory date. As a consequence, the glaciers are located slightly higher and have a somewhat less pronounced future ice loss (Fig. 15 Fig. 14). Despite this, the effect on future evolution is rather limited: under RCP2.6 the 2017-2100 the difference in computed volume change is in the order of 5% between classic volume-length calibration and the ‘volume only calibration’. Under RCP4.5 and RCP8.5 the differences in calibration procedure and rate factors barely translate in a different 2100 volumes.

6.3.2 Glacier cross section

In all simulations, a trapezoidal cross section with an angle λ of 45° was used (suppl. mat. Fig. S1). Simulations with a very pronounced trapezium shape ($\lambda = 80^\circ$), cf. a V-shaped valley, result larger area changes for the period 2003-2017 of $-1.2\% \text{ yr}^{-1}$, which is in better agreement with observations ($-0.8\% \text{ yr}^{-1}$ in classic case) (Fig. 15 Fig. 14b). However, on the longer term, the effect on the volume and area loss is very limited, and the area in 2100 is only slightly lower compared to the standard run ($\lambda = 45^\circ$), typically in the order of 2-3% (vs. present-day area, Fig. 15 Fig. 14b). The same holds for the volume, which is about 2% lower (vs. present-day volume Fig. 15 Fig. 14a). In the case a rectangular cross section is used ($\lambda = 0^\circ$), the differences in projected volume and area changes are also very small (in the order of 1-2%) compared to standard run ($\lambda = 45^\circ$). This is in line with the results obtained in the original GloGEM study (Huss and Hock, 2015) on the global scale,

where sensitivity tests with other cross-sectional shapes suggested that projected mass losses would may decrease/increase by 1-4%.

In general, our results indicate that the differences in projected volume and area changes from the various RCM ~~chains~~ [simulations](#) (for a given RCP) are much larger than differences obtained from model parameters. This is in agreement with other glacier evolution studies, as for instance highlighted by Goosse et al. (2018) on the centennial glacier length fluctuation modelling of an ensemble of alpine glaciers with OGGM, and by Marzeion et al. (2012), who also find that the ensemble spread within each RCP is the biggest source of uncertainty for the modelled future mass changes.

10 7 Conclusions and outlook

In this study, we extended an existing glacier evolution model (GloGEM) through the incorporation of an ice flow component. The so-extended model, GloGEMflow, was used to simulate the future evolution of individual glaciers in the European Alps. In contrast to previous simulations over the European Alps, we used a glacier-specific geodetic mass balance estimate for model calibration. A new initialisation procedure was proposed, in which model parameters were calibrated to match the reference glacier length and volume at the inventory date. This novel model setup and its calibration were validated with a broad range of in-situ data, including SMB measurements, glacier length changes, glacier area changes and ice surface velocity measurements.

The calibrated model was used to simulate the future evolution of the glaciers in the European Alps under high-resolution RCM future climate scenarios from the EURO-CORDEX ensemble. These simulations of future glacier change can be of interest for various applications (e.g. runoff projections, hydroelectricity production, natural hazards, touristic value, etc.) and are available in an online repository for every individual glacier (see section 8 for details). Our simulations indicated that under RCP2.6, by 2100 about a two-thirds of the present-day glacier volume ($-63\pm 11\%$) and area ($-62\pm 8\%$) will be lost. Under a strong warming, the European Alps will be largely ice-free by the end of the century, with projected volume losses of $-79\pm 9\%$ under RCP4.5 and $-94\pm 4\%$ under RCP8.5 (2017-2100 period). The future glacier evolution is mostly controlled by the imposed RCP. For a given RCP, the spread in future projections from different ~~model chains~~ [RCM simulations](#) is mainly determined by the driving GCM (rather than the RCM ~~coupled to it~~), and was found to be much larger than the differences resulting from model parameter variability. [Additional simulations where the model is forced with the driving GCM only \(i.e. no downscaling with an RCM\) confirm the limited effect of the RCM on the modelled future evolution. More in-depth analyses on the effect of using downscaled RCM data vs. GCM data for glacier evolution modelling will be required, but our results suggest that the effect of such a downscaling on simulated glacier evolution is relatively limited – at least for the European Alps.](#)

This study focused on the European Alps, for which a vast dataset on glacier data is available. By relying on this unique dataset and by combining it with a novel glacier modelling setup, we were able to quantify a part of the uncertainties related to assumptions that are widely used in regional and global glacier modelling studies, such as the use of region-wide SMB estimates for model calibration and the implicit treatment of ice dynamics. The inclusion of ice dynamics reduced the projected ice loss compared to simulations relying on a retreat parameterisation and this effect was found to be particularly important for glaciers that extend over a large elevation range. This implies that the inclusion of ice dynamics is likely to be important for global glacier evolution projections, indicating that there is still a relatively large potential to improve these projections.

10 8 Data availability

The following material will be available in an online repository once/if this study is accepted for publication: (1) modelled glacier geometries at inventory date for all dynamically modelled glaciers as individual figures, and (2) modelled future (2017-2100) glacier volume and area evolution for every individual glacier (multi-model mean for RCP2.6, RCP4.5 and RCP8.5) as comma-separated value files (.csv). All other data presented in this paper will be available upon request.

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Appendix A: Model initialisation

As a first guess a deformation-sliding factor of $1 \times 10^{-16} \text{ Pa}^{-3} \text{ yr}^{-1}$ is used (A_1). This is combined with a SMB bias, which is expressed as a change in ELA (ΔELA_1) and chosen in order to ensure a zero mass balance over the present-day glacier geometry. These parameter values are imposed until a steady-state glacier is obtained, and this geometry is subsequently used to model the glacier evolution between 1990 and the inventory date (typically 2003) (Fig. 3). After the first step, a glacier with a volume V_1 is obtained. Subsequently, this setup is repeated by modifying the deformation-sliding factor, until

the reference glacier volume at the inventory date (V_{ref}) is matched (within 1%). The second guess for the deformation-sliding factor (A_2 , i.e. second step of optimization procedure) corresponds to:

$$A_2 = A_1 \left(\frac{V_{ref}}{V_1} \right)^{-4} \quad (89)$$

Subsequent guesses of A are derived from a polynomial fit between glacier volume (independent variable) and all previous estimates of A (dependent variable). The order of this polynomial fit corresponds to the number of previous guesses – [+minus 1](#), e.g. the third guess for A relies on the previous two attempts, for which a first order polynomial (i.e. a linear function) is constructed. This leads to a quick convergence to reference glacier volume at inventory date, typically within 3-4 attempts.

Once a match for the glacier volume is obtained, a check on the glacier length is performed. If the glacier length (L_1) deviates more than 1% from the reference glacier length (L_{ref}), the volume calibration is reapplied, for which the ELA bias (ΔELA_1) is increased/decreased with 10 m. The volume calibration is performed again (see above), where the first guess for the deformation-sliding factor is now equal to the last guess that resulted in a volume match. Once the volume is matched (typically within one or two attempts), a new check on the glacier length at inventory date is performed. If the length is not matched at the second attempt, from the third attempt onwards the ΔELA is estimated based on a linear fit between the previous two attempts (independent variables) and the glacier length (dependent variables), or a shift of 10 m if both attempts resulted in the same glacier length (which can occur due to the discretization of the glacier geometry). All together, this methodology results in a fast convergence, and in general the entire simulation (creating steady state and running glacier from 1990 to inventory date) needs to be performed about 3-10 times. This takes on average about 10-20 seconds per glacier on a single core on a modern laptop.

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Tables

	Volume in km ³ (and relative change vs. 2017)		Area in km ² (and relative change vs. 2017)	
	2050	2100	2050	2100
Committed loss <u>1988-2017</u>	71.4 (-25.9 ± 7.4%)	60.8 (-36.9 ± 6.3%)	1277.9 (-23.3 ± 7.7%)	1091.2 (-34.5 ± 6.5%)
RCP 2.6	51.7 (-47.0 ± 10.3%)	35.9 (-63.2 ± 11.1%)	1037.6 (-43.9 ± 9.7%)	701.7 (-62.1 ± 8.4%)
RCP 4.5	50.0 (-48.8 ± 9.2%)	20.7 (-78.8 ± 8.8%)	1006.9 (-45.6 ± 8.0%)	464.2 (-74.9 ± 8.3%)
RCP 8.5	47.1 (-51.8 ± 11.5%)	5.4 (-94.4 ± 4.4%)	948.2 (-48.8 ± 9.2%)	165.4 (-91.1 ± 5.4%)

Table 1: Overview of multi-model chain mean future glacier evolution based on RCM chains-simulations from the EURO-CORDEX ensemble. The evolution under the mean SMB obtained from the 1988-2017 climatic conditions represents the committed loss.

~~The committed loss corresponds to the loss obtained by permanently applying the mean SMB obtained from 1988-2017 climatic conditions.~~

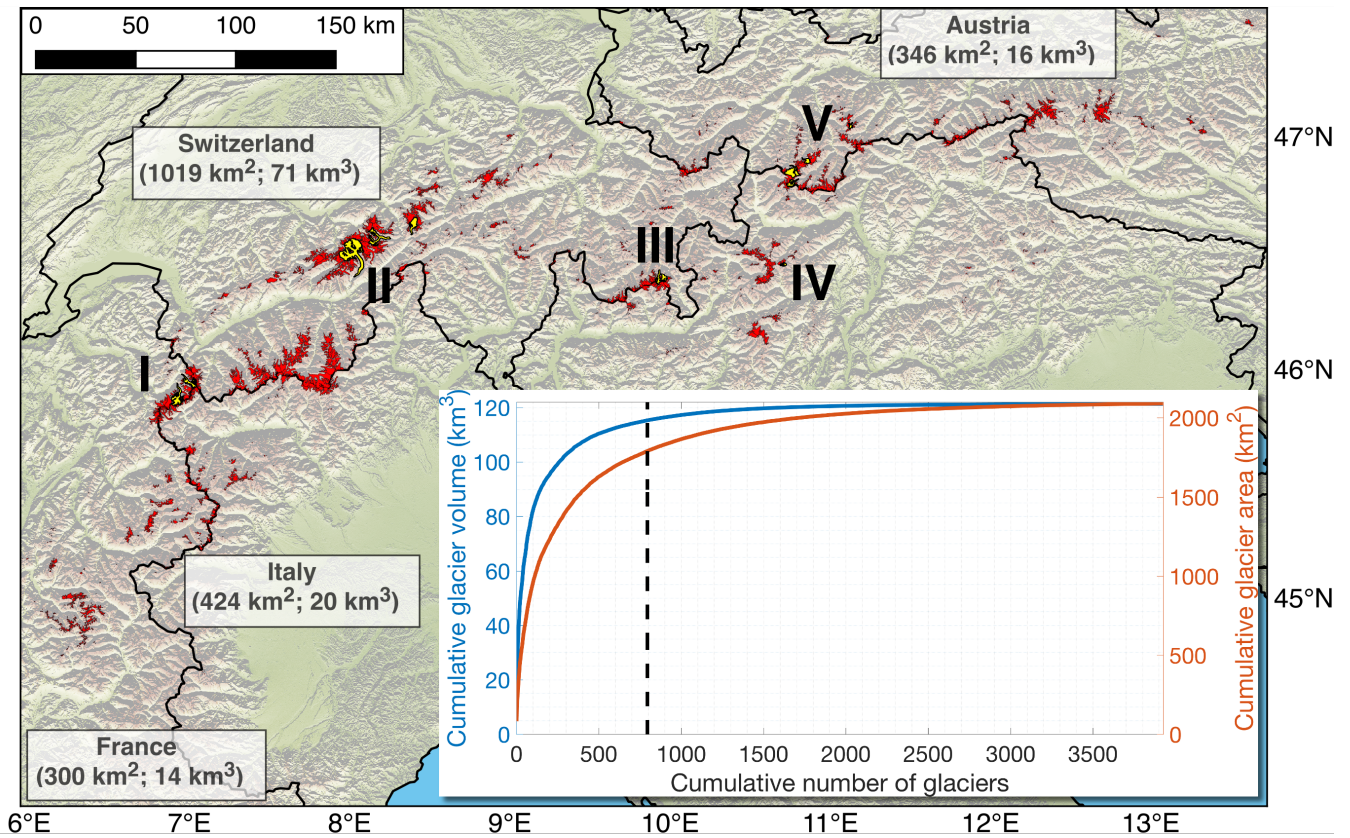
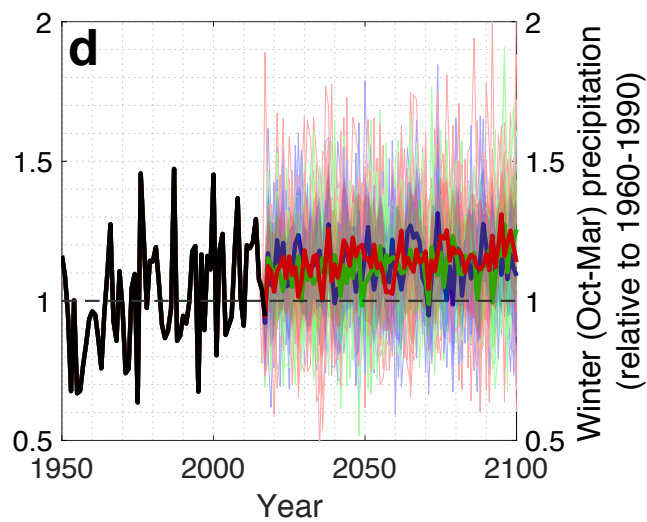
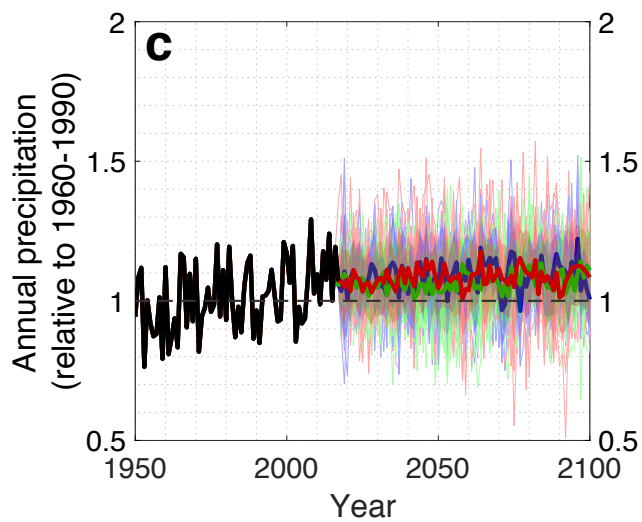
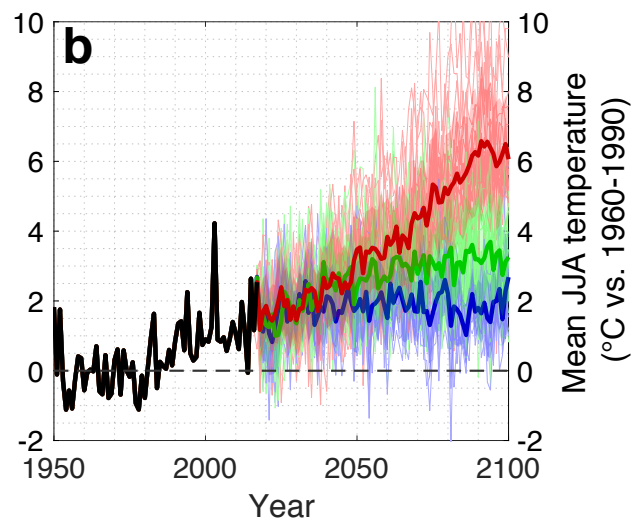
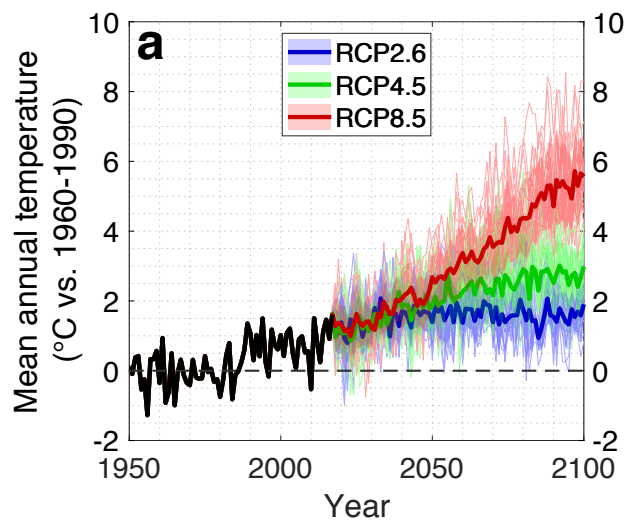


Fig. 1. Distribution of glaciers (red areas) in the European Alps. Outlines correspond to the glacier geometries at the Randolph Glacier Inventory (RGI v6.0) date (typically 2003) (Paul et al., 2011; RGI Consortium, 2017). The hill shade in the background is from the Shuttle Radar Topography (SRTM) DEM (Jarvis et al., 2008). Glaciers discussed in this manuscript and the supplementary material are highlighted in yellow: (I) Mer de Glace & Argentière; (II) Grosser Aletsch, Unteraar & Rhone, (III) Morteratsch, (IV) Careser, (V) Hintereisferner, Kesselwandferner, Taschachferner, Gepatschferner and Langtaler Ferner. The inset shows the cumulative glacier area and volume, sorted by decreasing glacier length. The dotted line is the division between glaciers longer (left) and shorter (right) than 1 km. Glacier area is from the Randolph Glacier Inventory (RGI v6.0) (RGI Consortium, 2017); volume and length are as derived by an updated version of Huss and Farinotti (2012).



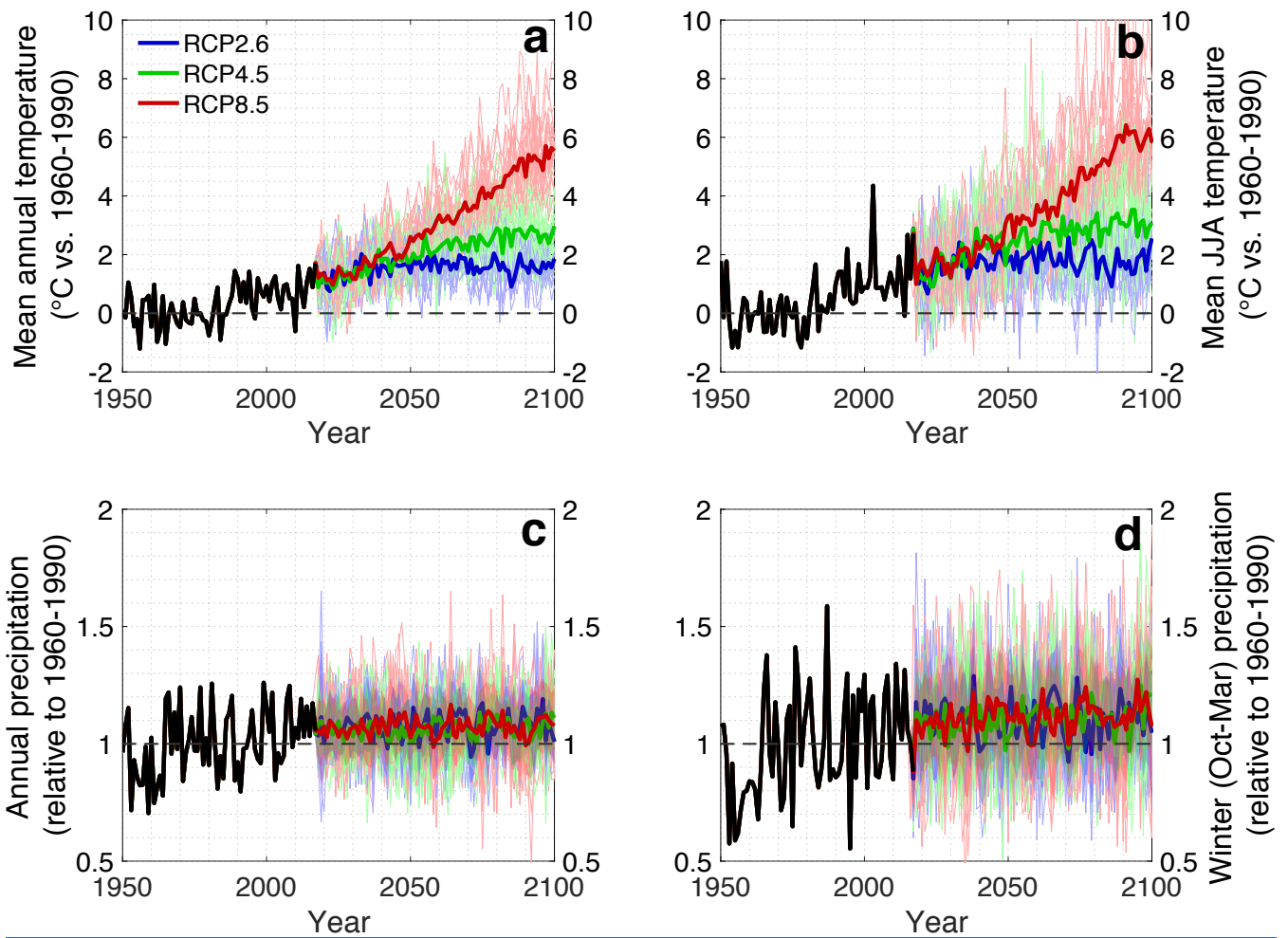


Fig. 2. Debiased temperature anomaly (a: annual & b: June-July-August) and debiased precipitation anomaly (c: annual & d: October-March) between 1950 and 2100 relative with respect to 1961-1990 (horizontal dotted line). All values correspond to the mean over all grid cells used in this study, weighed by the glacier area (at inventory date) in every cell. The thick black line represents the evolution of the variables for observational period (E-OBS dataset). The coloured thin lines represent the evolution for individual ~~model chains~~RCM simulations from the EURO-CORDEX ensemble (51 in total, see suppl. mat. Table S1), the thick lines are the ~~chain~~RCM simulation means (one per RCP). ~~Transparent bands correspond to one standard deviation.~~

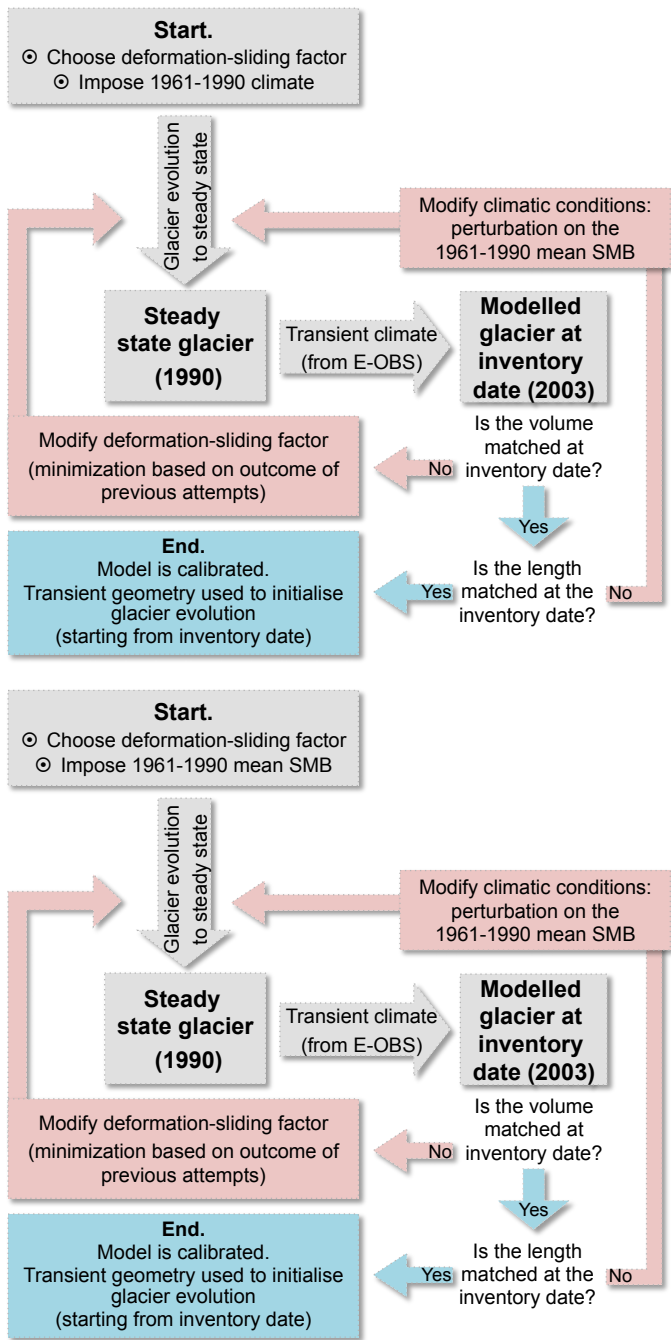


Fig. 3. Model initialization for creating a glacier with the reference length and volume at the inventory date.

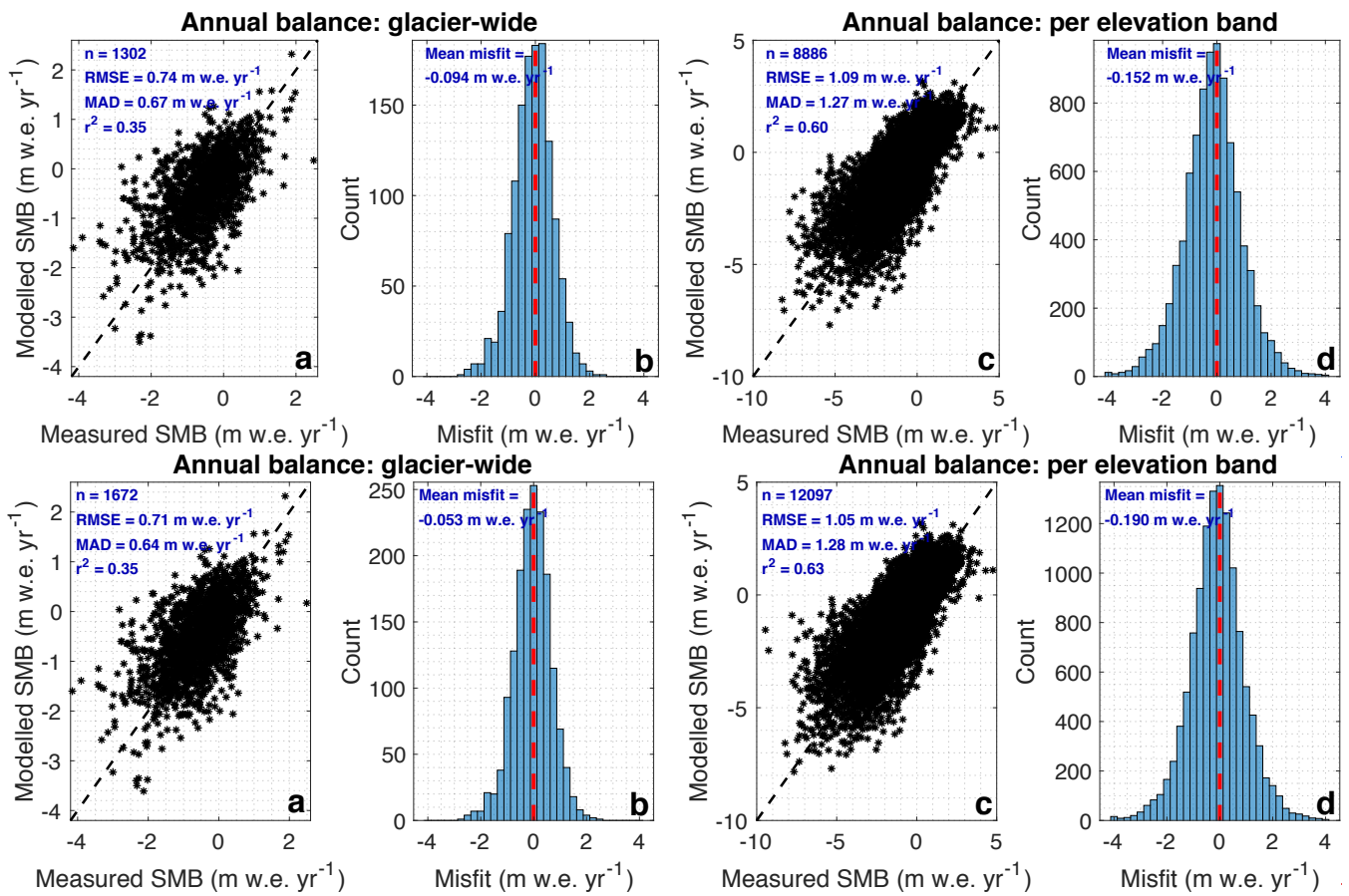


Fig. 4. Evaluation of modelled SMB against observations from the WGMS (2018) database. All observations are included, except those that do temporally overlap with the geodetic mass balance observations (used for calibration). Scatterplots (a & c) and frequency of misfits (b & d) of modelled vs. measured glacier-wide annual balances (a & b) and annual mass balances per elevation band (c & d). Dashed red lines in panels b & d represent the zero misfit. In panel a & c, n corresponds to the number of observations, RMSE is the root-mean-square error, MAD is the Median Absolute Deviation and r² is the correlation coefficient coefficient of determination.

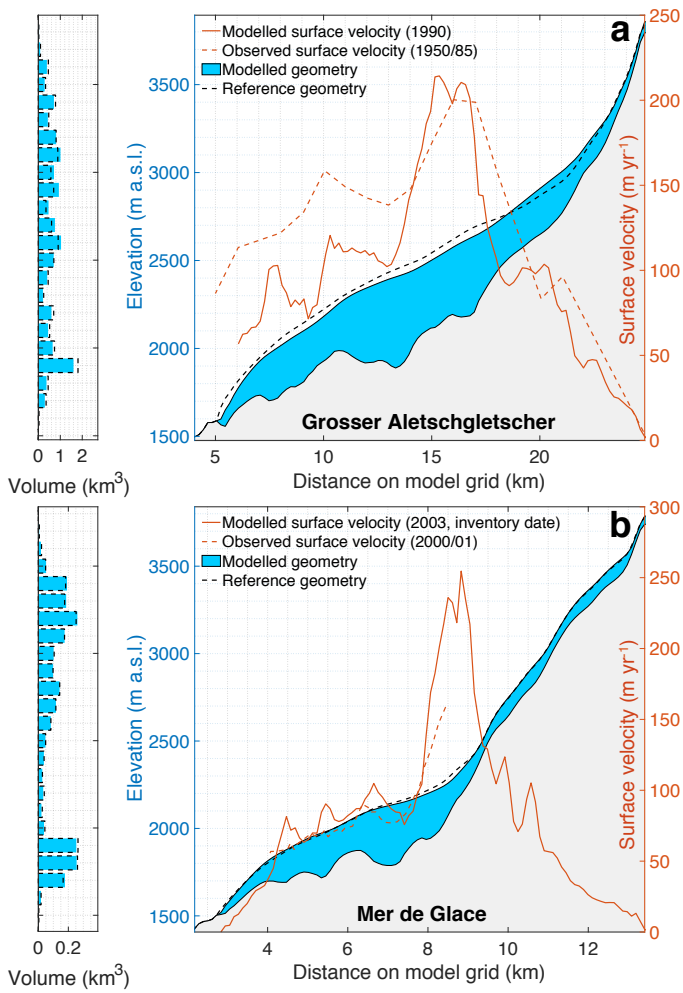


Fig. 5. Comparison between reference and modelled (i) glacier geometry, (ii) volume-elevation distribution and (iii) surface velocities for Grosser Aletschgletscher (a) and Mer de Glace (b). Reference geometries and volume elevation distribution are at inventory date (2003) and based on Huss and Farinotti (2012). Observed surface velocities for Grosser Aletschgletscher are from Zoller (2010), and correspond to a 1950/1985 point averages, while observed velocities for the Mer de Glace are derived from 2000/2001 SPOT imagery (Berthier and Vincent, 2012).

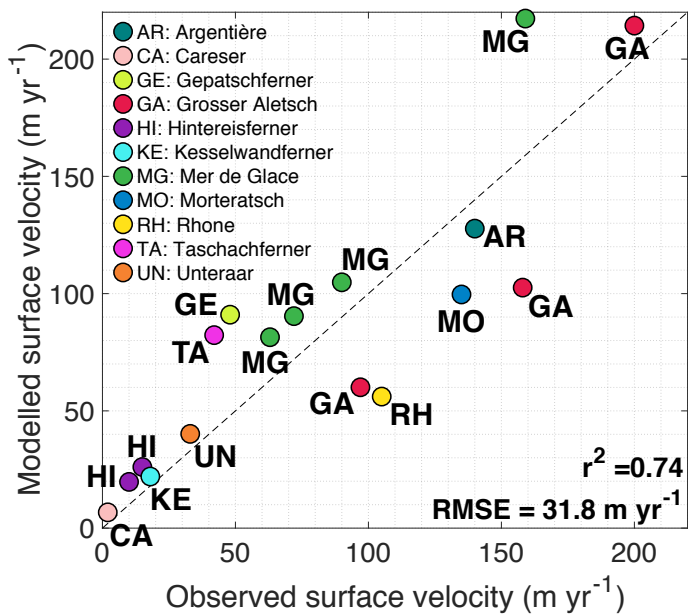


Fig. 6. Observed vs. modelled surface velocities for selected glaciers in the European Alps. For some glaciers several data points exist, consisting of different locations on the glacier. More information concerning the surface velocities and corresponding references are given in the supplementary material (Table S2). For glacier location, see [Fig. 1](#).

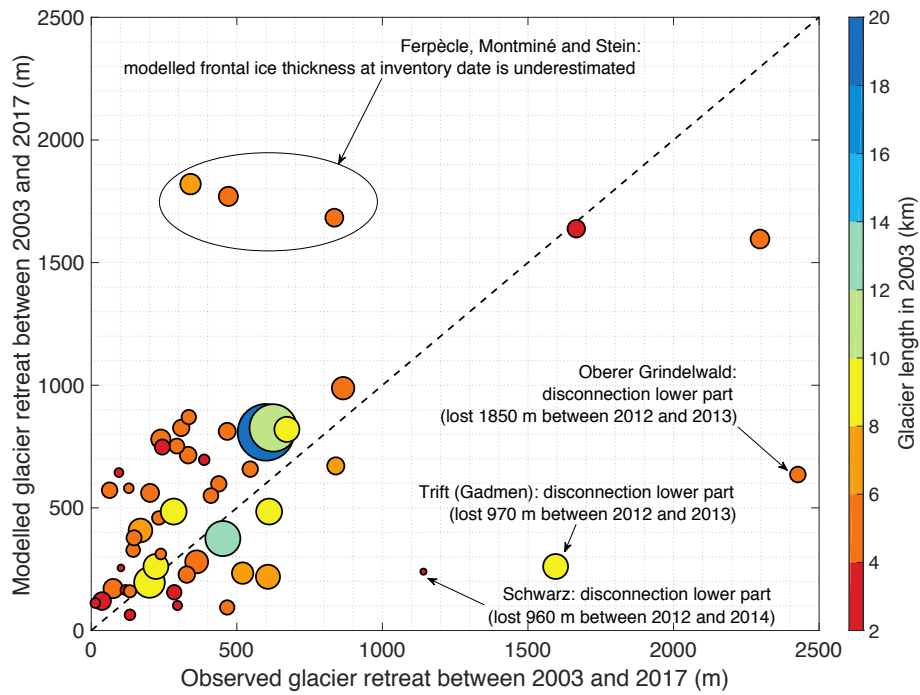


Fig. 7. Observed vs. modelled glacier retreat (length change) between 2003 and 2017 for all 52 glaciers longer than 3 km monitored by GLAMOS (Glaciological Reports, 1881-2017). Point size is proportional to glacier area (cf. colour bar).

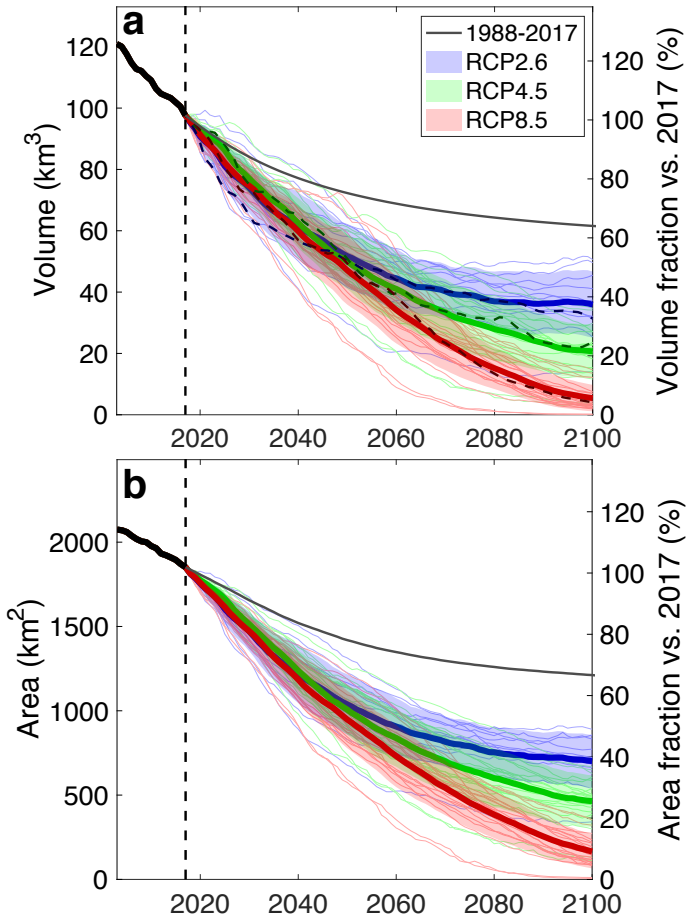
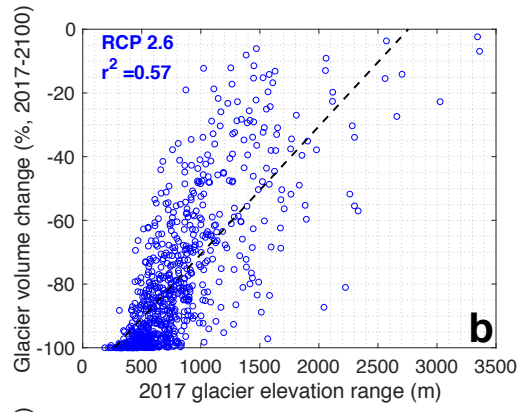
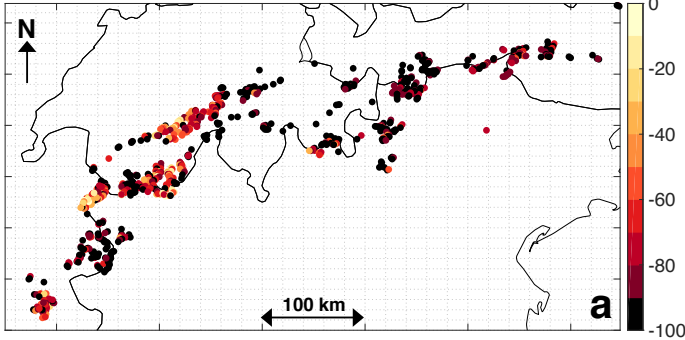
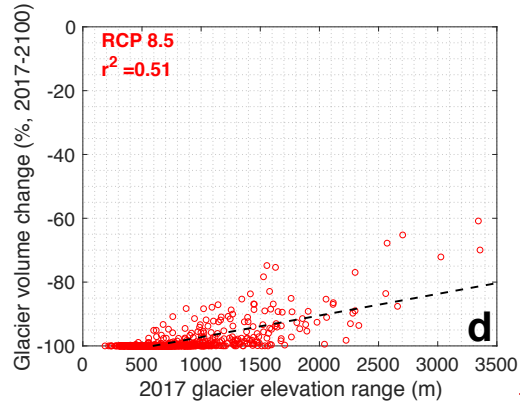
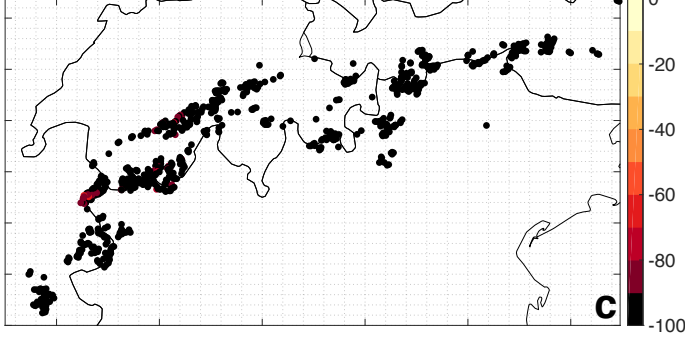


Fig. 8. Ensemble (a) volume and (b) area evolution for various EURO-CORDEX RCM simulations and committed loss (mean 1988-2017 conditions). Thin lines are individual ~~model-chains~~ RCM simulations (51 in total, see suppl. mat. Table S1). The thick line is the RCP mean and the transparent bands correspond to one standard deviation. In panel (a), the coloured dotted lines correspond to the model ~~chains-simulations~~ that are closest to the multi-model mean. The vertical dotted line represents the year 2017 and marks the transition between E-OBS and EURO-CORDEX forcing.

Relative volume change under RCP2.6 (% , 2100 vs. 2017)



Relative volume change under RCP8.5 (% , 2100 vs. 2017)



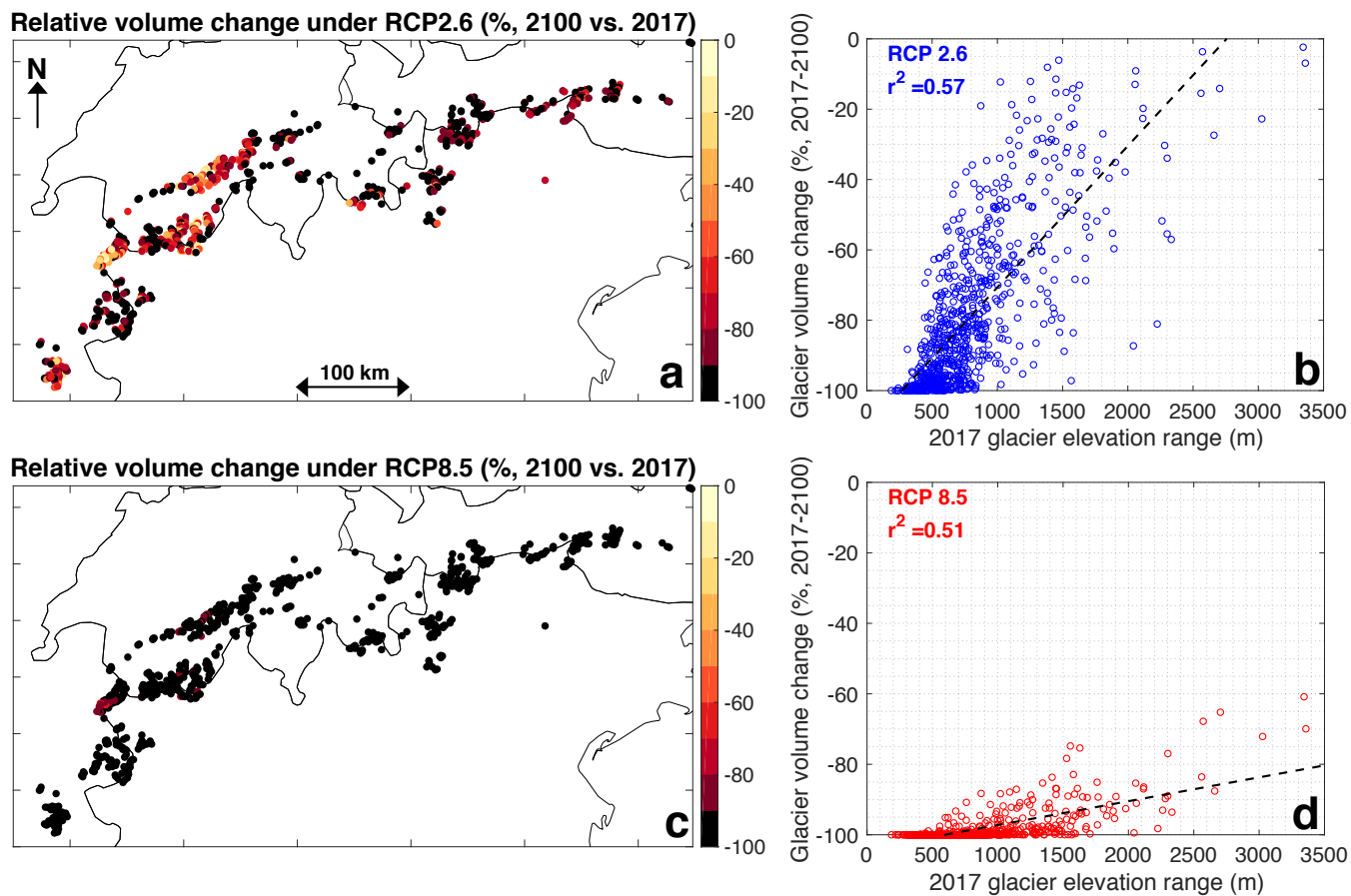
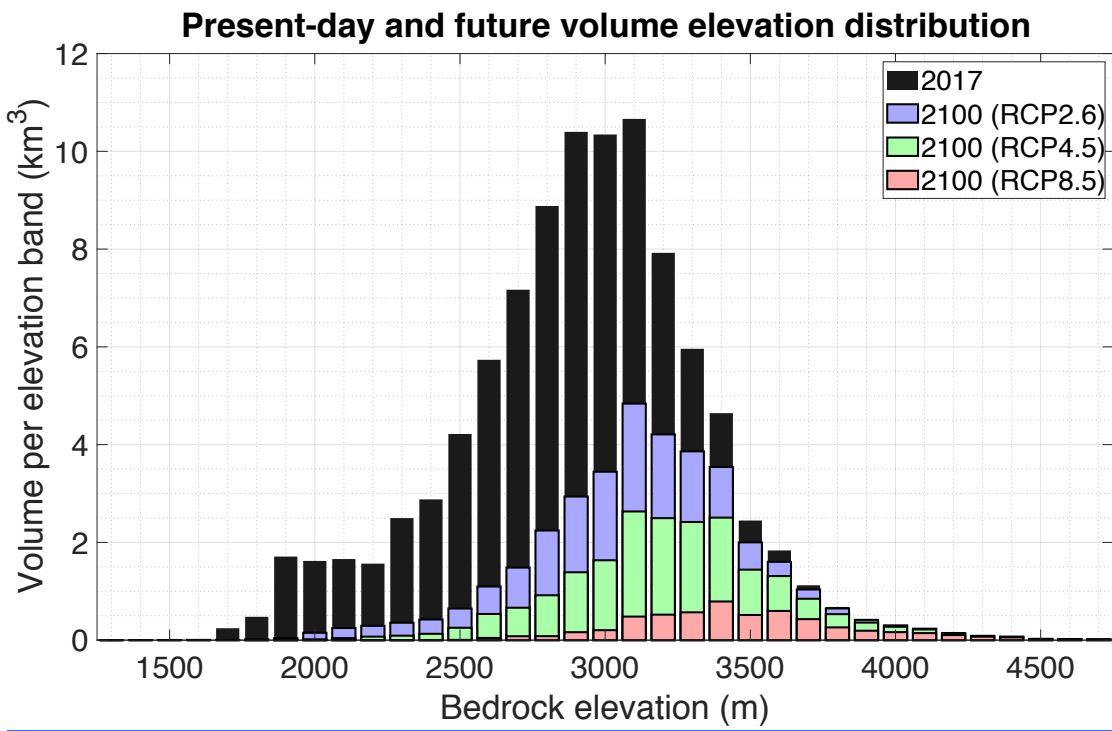


Fig. 9. Relative volume changes between 2017 and 2100 under RCP2.6 (multi-model mean, panel a&b) and a RCP8.5 (multi-model mean, panel c&d). Results are shown for all 795 glaciers for which the future evolution is simulated with the dynamic model. Panel (b) and (d) represent the volume change as a function of the present-day glacier elevation range.



[Fig. 10. Modelled volume elevation distribution in 2017 and in 2100 under various representative concentration pathways \(RCPs\). The values in 2100 correspond to the multi-model mean under a specific RCP.](#)

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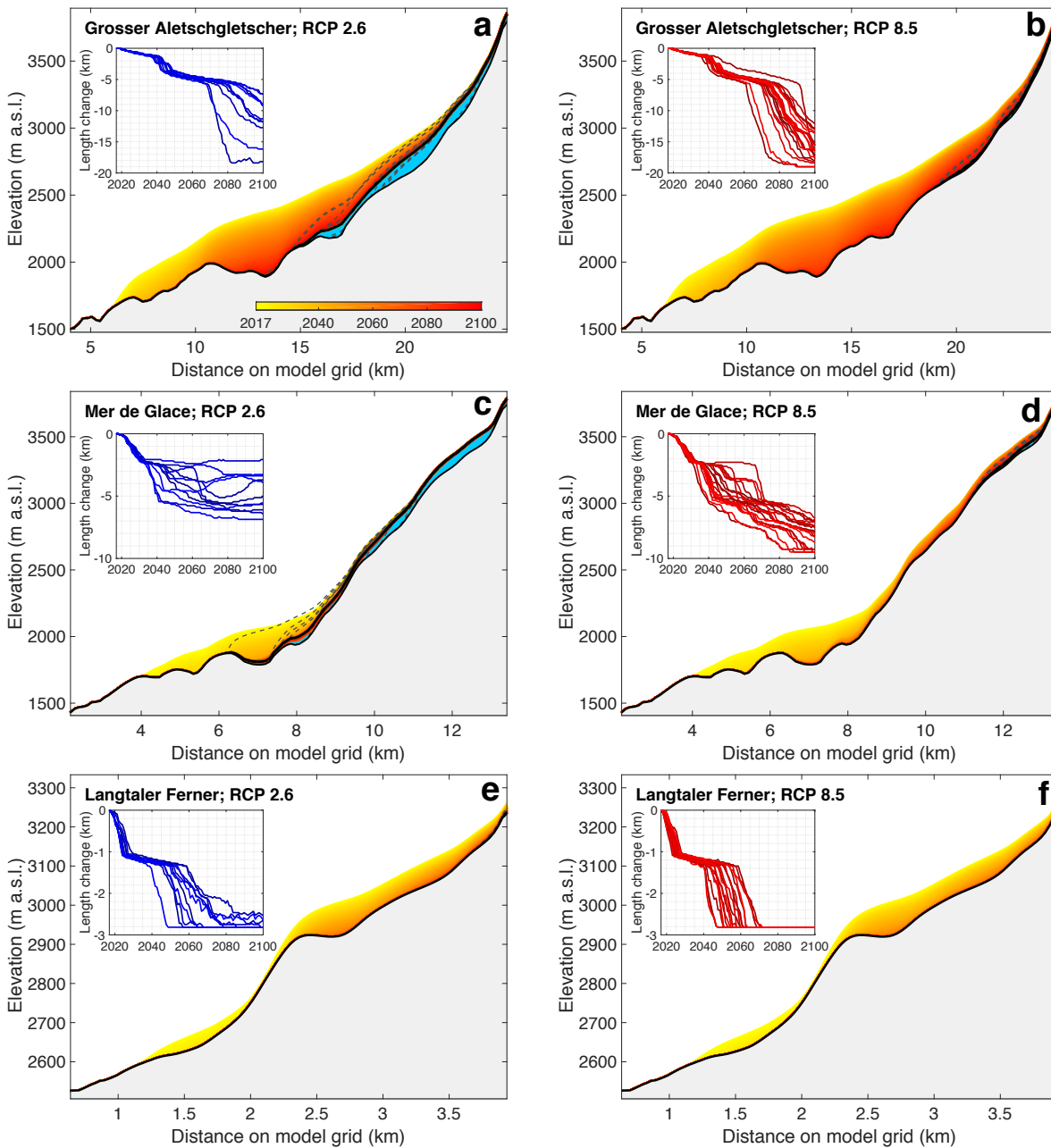


Fig. 1140. Future evolution of the Grosser Aletschgletscher (a,b), Mer de Glace (c,d), and Langtaler Ferner (e,f) under RCP2.6 (a,c,e) and RCP8.5 (b,d,f). The 2017-2100 evolution corresponds to the multi-model mean surface evolution, while the blue area is the multi-model mean glacier geometry at the end of the century. The dotted lines represent the 2100 glacier geometries for individual **model-chains** RCM simulations (cf. suppl. mat. Table S1). The insets represent length changes over the 2017-2100 time period for every individual RCM **chain** simulation.

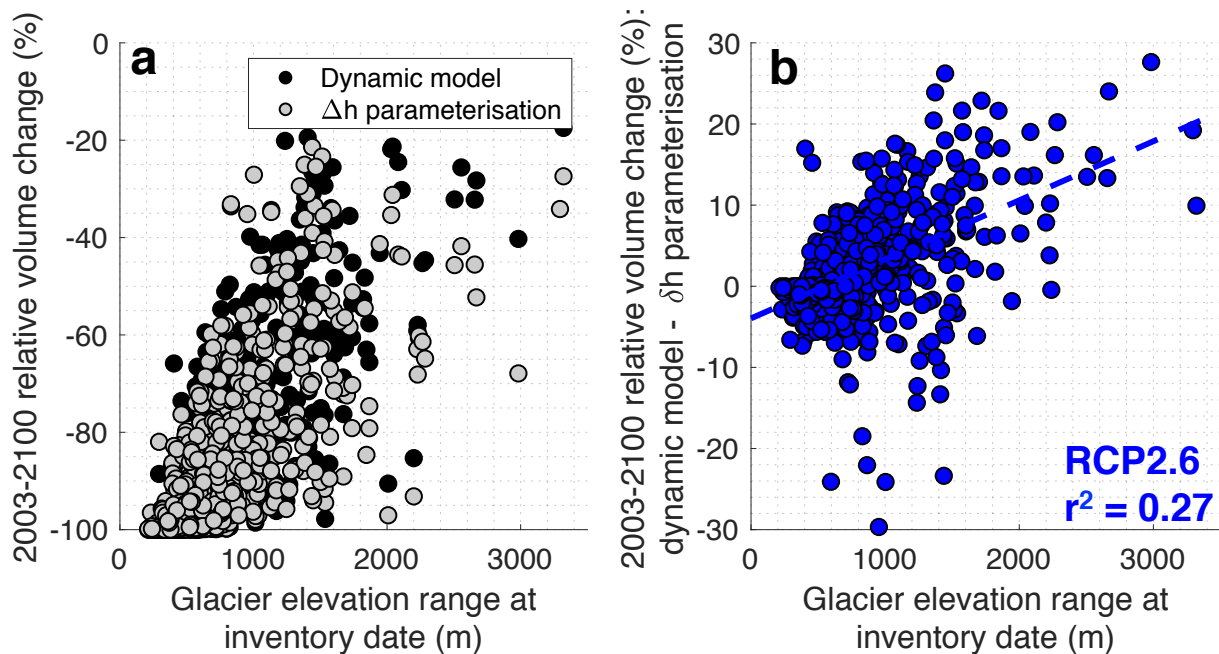


Fig. 1211. Future glacier evolution under RCP2.6 for individual glaciers with the dynamic model and corresponding glacier simulation with the Δh -parameterisation. All values correspond to RCP2.6 multi-model chain-mean values.

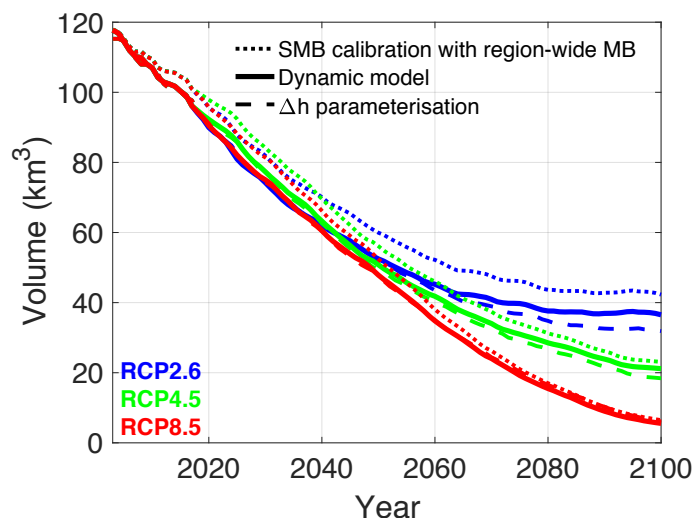


Fig. 1312. Future glacier volume evolution as simulated with (i) the dynamic model forced with an SMB calibrated to individual glaciers (standard run), (ii) the Δh -parameterisation (Huss et al., 2010b), and (iii) the dynamic model, where the SMB model component is calibrated with a region-wide MB estimate. Results are shown for glaciers longer than 1 km at inventory date and correspond to the multi-model chain values from RCM chains-simulations from the EURO-CORDEX ensemble (for a given RCP).

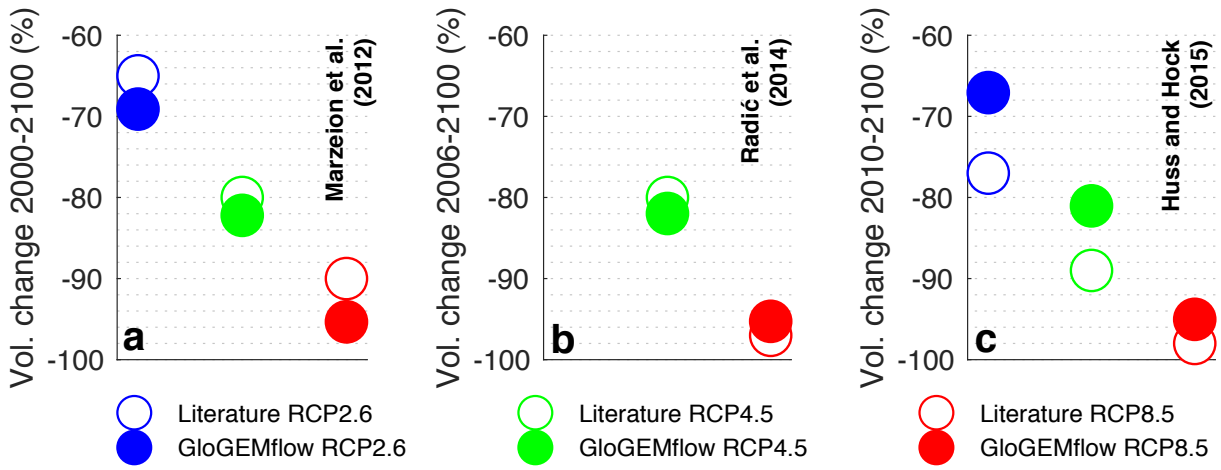
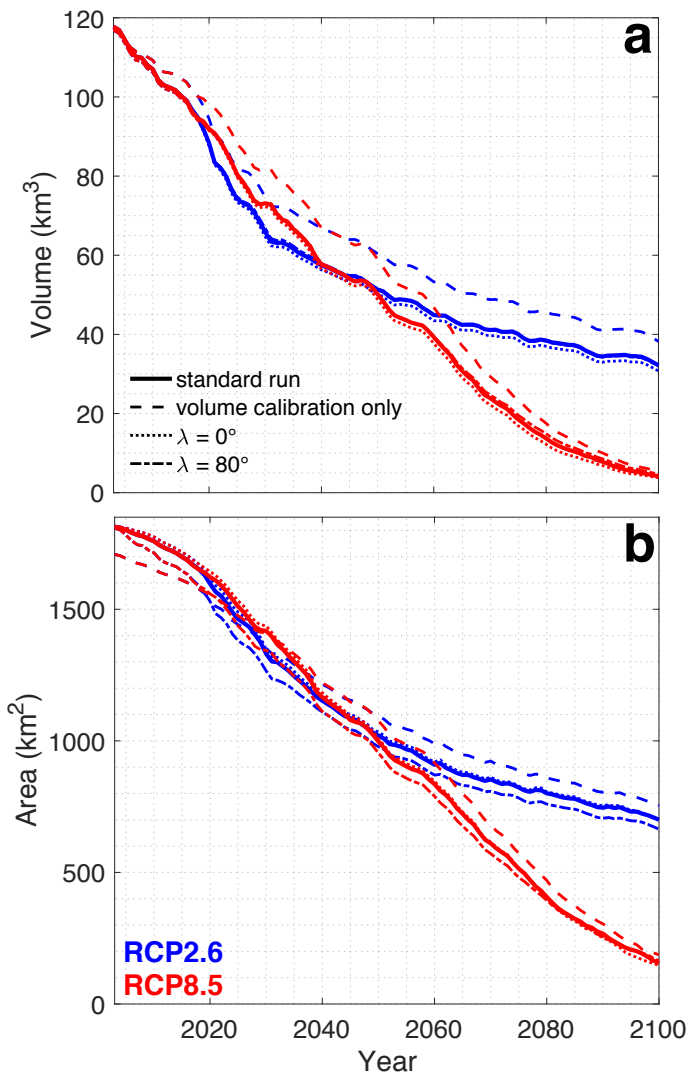


Fig. 1413. Modelled volume changes and comparison with values from the literature (Marzeion et al., 2012; Radić et al., 2014; Huss and Hock, 2015). The considered time period is in line with the considered study and spans from the early 21st century to 2100.



5 | **Fig. 1514.** Sensitivity of volume (a) and area (b) for different cross-sectional geometries and under a different calibration procedure. Results are shown for all 795 glaciers for which the future evolution is simulated with the dynamic model. The standard calibration with $\lambda = 45^\circ$ corresponds to the classic setup. The colours correspond to different RCPs. Only the ~~model~~ chain-RCM simulation closest to the multi-model mean volume evolution is shown (dotted line in [Fig. 8](#)~~Fig. 8~~a; see also suppl. mat. Table S1).