Note: Reviewer's comments are in italics. Changes to manuscript text are in blue.

Reply to reviewers:

"Glaciological characteristics in the Dome Fuji region and new assessment for 1.5Ma old ice"

Reviewer #2 (K. Matsuoka) Main points

#1

The main shortcoming of this paper is incomplete description of the survey, data processing, and data properties. Main lacking information is:

- a. Survey: line spacing (mean, or range/max/min, it's hard to read from the figure), flight mode (constant elevation or constant clearance to the ice), nominal data-collection spacing along survey profiles.
- b. b. Data gridding: see #2 below.
- c. c. Lake detection: see #3 below.
- d. d. Continuity index: depth range analyzed for the index, see #5 below too.

Response to 1a:

The following lines have been added in Section 2.1

"The spacing between the radarlines is 10 km for the grid and the mean data-collection spacing along the flight direction is approximately 5m although it varies with aircraft speed which is influenced by wind speed and direction. The 7-fold stacked thereby get a spacing of approximately 35m."

[...]

"The spacing between the OIR radarlines is 10 km with the exception of the radarlines southeast of Dome Fuji that were flown with a 15 km spacing, and the lines acquired while leaving or approaching the OIR camp where the distance between radarlines is much smaller. The mean data-collection spacing along the flight direction was also approximately 5m leading to the same spacing on the 7-fold stacked data as the GEA data, i.e., 35m. The radar data in both campaigns were collected using AWI's EMR (Electromagnetic Reflection) system (Nixdorf et al., 1999) with a constant distance to the ice surface."

#2

The presented ice thickness map could include many artifacts due to unrealistically small grid size and smoothing to a large degree. Is the grid size of 0.5 km justifiable? Radar profiles are separated by > 5-10 km, and the authors admit that the large standard deviation (142 m) between gridded values and previous German/Japanese radar data is inevitable result of the smoothing (P4L11). I am afraid that this grid size gives a false impression that the bed topography is known better than we actually know. No details are

given about smoothing or data interpolation. This is a key aspect of the final product presented here, however.

The reviewer raises two important but separate issues: 1) is the kriging routine robust, i.e., is there a risk that topographic features in the thickness maps are artefacts from the interpolation? and 2) do we know the details of the topography in high enough resolution to capture variations over 500m spatial scales?

Issue #1: We consider it unlikely that artefacts have been introduced in the final gridded product by the kriging routine. While radar profiles indeed are separated by 10 km, the along track resolution is very high. Thus, we have detailed geostatistical information on the behaviour of the observations. We assume that this information may be applied to the area as a whole, given that we have no reason to suspect a directional anisotropy in the data. We test this hypothesis further in two ways.

Firstly, we construct 1km, 5km and 10km grids for comparison with the 500m (see below). Even for the coarse resolution maps, the different topographic features are consistent. From the histograms, we also see a very similar distribution of ice thickness values. Indeed, the 500m and 1km maps are almost indistinguishable. We examine the difference between the two maps by linearly interpolating the 1km to 500m resolution. This re-interpolated map should contain fewer details than the original 500m. The mean difference between the two maps is -0.16m with a standard deviation of 8.6m. This confirms that details present in the 500m map are also present in the 1km map.





Secondly, we perform two kriging calculations on a 10km grid, which is on the same spatial scale as the spacing between the radarlines. In one of the calculations, we only include 10% of the data points. The mean difference between the two resulting products is 2.2m with a standard deviation of 18m. Thus, with substantially fewer data points we obtain a very similar result. Performing the same test with two 1km grids returns a mean difference of 2.1m and a standard deviation of 18m.

From these tests, we conclude that our kriging scheme is robust and produces consistent outputs given different resolutions and different amounts of information (data points).

Issue #2: From the investigations above it is evident that we do not gain much additional information by increasing the resolution from 1km to 500m. However, in some regions of our study area, the spacing is indeed 5-10km but in other regions we have substantially more data (including ground-based data). We have clarified this by adding a figure showing the radarlines that were used for constructing the OIR dataset (Fig. 2A). Areas with better data coverage include the area around Dome Fuji where data from several Japanese surveys form a dense grid, and the approach lines to OIR camp and (to some extent) the candidate site northwest of Dome Fuji.

We will take the following actions to address the reviewer's concerns:

We will present our results on a 1km grid but still make the 500m grid available online. In addition, we will present results from a 500m grid in the area around Dome F (shown in Fig. 6) where we have more data and this higher resolution is better justified.

However, we note that changing from 1km to 500m do not change our results or conclusions.

We will provide more information on the kriging routine by adding the following lines to the "Observations and Methods" section:

"The data were subsequently regridded to a 500m and a 1km resolution grid using a kriging interpolation scheme. Based on the experimental variogram, the lag is set to 80km. The experimental variogram is then fitted to an exponential model whose parameters are found by minimising the mean squares difference between the observational variogram and the model. The result of the kriging -- the gridded ice thickness -- is merged with the Bedmap2 topography."

We leave it to the discretion of the editor if the figures showing maps and histograms for different resolution grids should be included in the supplementary material.

#3

Very little information is given about lake identification. Nobody can reproduce or assess author's arguments in a meaningful way. Radargrams of at least several lakes should be presented. Do they look like definite lakes, or more like dim lakes? Are all known lakes along the new radar profiles found in this study?

A figure has been added showing an example of a lake along with layer continuity and the calculated Delta G from the model. In addition, four figures have been added to the appendix also showing different lakes identified in the data as well as layer continuity and ΔG .

Further, lakes identified by Siegert and Fujita have now been added to the figures.

The following lines have been added to the "Basal conditions and internal layering" section

"An example of a radargram with two clear lakes is shown in Fig.5 along with the corresponding layer continuity (cf. Fig. 4B) and the value of ΔG from the model (cf. Fig. 3). Four additional radargrams showing examples of lakes and the layer continuity can be seen in the supplementary material. Previous studies have also identified lakes in the region (Siegert et al., 2005; Fujita et al., 2012) but our analysis adds several new locations. A few of the lakes from the above-mentioned do not appear in our dataset. This might be due to the uncertain geolocation from the old radar data or to the angle of interception of the new radarlines."

#4

Sections 2.2 and 2.3 should be better organized. Section 2.2 are written in a way to examine uncertainty of the new data but also to examine old data, which is confusing for me. Section 2.3 presents spatial patterns of the difference between OIR and BEDMAP2, which can be better presented if Sections 2.2 and 2.3 are more efficiently organized/integrated.

We agree that the description of the uncertainties was unclear and we thank the reviewer for their suggestions on how to improve it. We have reorganised and merged the sections 2.2 and 2.3, and have added more details about the crossover analysis. The section now reads as follows:

"2.2 Results and Uncertainties

The resulting ice thickness is displayed in Fig. 2A and in the following we refer to this dataset as the OIR (ice thickness) data although it is based on data from several surveys (cf. the radarlines shown in Fig. 2A). The denser data coverage from the GEA and OIR surveys reveals a landscape with ice thicknesses varying between 2000 m and 4000 m with an average ice thickness of 3021 m. Immediately south of the Dome Fuji

is an area with shallow ice thicknesses while the ice further to the south and to the southeast and is significantly thicker. A complex terrain with a patchwork of thick and thin ice has now become visible north and west of Dome Fuji. Since the surface topography in this part of Antarctica is relatively flat, ice thicknesses are good indicators of bed topography, thus thick ice indicates valleys while shallower ice indicates mountains or highlands. The OIR dataset shows a system of valleys surrounded by high plateaus.

The difference between the OIR and the Bedmap2 datasets is shown in Fig. 2C. The largest differences appear to the west of Dome Fuji between 30°W and 35°W, and 77°S. In the immediate vicinity of the station, differences are smaller due to the high-resolution data from Japanese ground-based surveys that were included in the Bedmap2 and the OIR compilations. The difference between the new ice thickness map and Bedmap2 is upwards of 800 m in some areas, with a mean difference of 20 m, a mean absolute difference of 136 m, and a standard deviation of 177 m. This difference is undoubtedly due to the geolocation uncertainty of the Soviet data included in Bedmap2.

We examine the uncertainties of our result by comparing the gridded ice thickness map with point measurements from the individual radarlines, and through crossover analysis of the radarlines. In the latter analysis, we consider all points within 50 m of each other to be crossover points following Fretwell et al. (2013). For the GEA-OIR radarlines, 2453 points were found to be crossover points. The mean difference in ice thickness between the radarlines is -13 m with a standard deviation of 79m. For 18% of the crossover points the difference exceeded 100 m. We ascribe this difference to geometrical effects of flightline orientation since we observe that radarlines intersecting each other at oblique angles have a larger thickness difference than those that are almost parallel.

Turning to the gridded ice thickness map, the mean difference between the GEA-OIR point measurements along the radarlines and the gridded map and is 1.5 m (cf. Fig. 3), indicating that the gridded ice thickness is slightly underestimating the ice thickness on this spatial scale. The standard deviation is 117 m. The mean difference between the gridded ice thickness and the individual data points from the older German survey is -11 m and the standard deviation is 162 m. For the Japanese surveys the mean difference and standard deviation is -16 m and 187 m, respectively. The overall high value for the standard deviation is an inevitable result of the smoothing introduced by the kriging interpolation scheme. Indeed, the negative mean difference between the high-resolution ground-based survey data and the gridded map indicates that the gridded data tend to overestimate the ice thickness in some areas, most likely because subglacial valleys are made broader by the kriging. This is a direct result of the smoothing introduced by the kriging scheme. This is also evident from the standard deviation in the grid points calculated by the kriging scheme (Fig. 2D). The standard deviation lies typically between 110-120 m close to the data points and increases with distance. Towards the margin of data coverage area the values exceed 200 m. We note that 110–120 m is still smaller than the difference between the OIR data and Bedmap2.

The decision to exclude the Soviet data was partly based on results from a crossover analysis. Comparison between the Soviet radarlines and the OIR and GEA surveys shows that only slightly more than 100 points is within 50m of each other. For these points, the mean difference in ice thickness between the points is -5 m with a standard deviation of 193 m. This larger standard deviation is likely due the poorly resolved bed rock and the large navigational uncertainty in the Soviet radarlines.

We performed a similar crossover analysis of the surface elevation measured in the GEA-OIR surveys. Here, we find a mean difference of less than 1 m with a standard deviation of 2.5 m. Thus, the uncertainties in the surface reflection measurements are negligible compared to uncertainties in the bed picking. Based on

this we assign an average uncertainty of 150[~]m to the OIR ice thickness although we note that uncertainties increase with distance from data point are likely larger along the edge of the survey grid."

#5

Continuity index presented in Fig. 5 should be shown only along the radar profiles and should not interpolate between profiles.

Fig. 5 (now 5B) has been changed to show continuity index along the lines instead of a gridded version.

#6

It is necessary to show radargrams that represent several typical features in this region (e.g., region with high continuity index, lake, transition from the cold base to thawed base) together with continuity index, lake appearance, Delta G, etc. The manuscript shows only limited aspects of the data properties and it is hard for readers to make a comprehensive assessment.

Four figures have been added to the Appendix showing different kinds of basal conditions and layer continuity. In the section "Basal conditions and internal layering" we add the following sentences:

"An example of a radargram with two clear lakes is shown in Fig. 6 along with the corresponding layer continuity (cf. Fig. 5B) and the value of ΔG from the model (cf. Fig. 4). Four additional radargrams showing examples of lakes the layer continuity can be seen in the supplementary material."

#7

One of main conclusions is that the most promising sites for the oldest ice is in the box I and II. I agree with the authors about this conclusion in general but data should be better presented to fully support this argument. First, why do the authors recommend two separate regions Box I and Box II, instead of one large box that includes both I and II? Second, what defines the boundaries of these boxes? These two are just examples showing the lack of full argument of the main conclusion.

Thank you for pointing out this issue. We realise that without including a zoom-in on the model results it is difficult for the reader to assess the background for our choices.

We have enlarged the figure and included a zoom-in on the model results. We have also clarified that the two boxes "I" and "II" do not refer to the entire area within the box but rather are meant to indicate that within the boxes, some areas are promising. The section now reads:

"For this region, we favour two areas outlined with white/black rectangles in Fig.7, that each contain two local maxima where ΔG is elevated. Although the entire region has a value of ΔG >5mW m⁻², we pinpoint the two areas in particular for two reasons: 1) The value of ΔG approaches and exceeds 12mW m⁻², thus the uncertainty in geothermal heat flux is less important for the robustness of the prediction. 2) The bed topography appears to consist of high plateaus rather than rugged mountain terrain. The second reason is important for layer continuity and to avoid disturbances to the lowermost part of the ice, that would inevitably impact the stratigraphy. The proximity to the ice core site also implies that extending the age-depth information from the ice core to a new drill site would be relatively straightforward."

Please enlarge figures, and consider grouping some figures into a single figure (panel a, b, c,). it's hard to compare several data properties together in the current form.

We agree that some of the figures are a bit small, but unfortunately the width of the figures is fixed for The Cryosphere the only option is making all figures the width of two columns. We have changed some of the figures to fill column width. We hope that in the final layout we will have larger figures than the Discussion format. We disagree with the suggestion of merging some of the figures into one. In our opinion, the figures are already quite busy and contain a lot of information. We leave it to the discretion of the editor if this suggestion should be followed.

We have taken the following actions: We have changed the figure showing the modelling result to full two column width and have repositioned the figures showing the hydropotential and the continuity index so that they are next to each other, hopefully making comparison between them easier.

#9

Mention data availability.

Following has been added to the Conclusion

"The gridded thickness data and the thickness picked along the radarlines will be made available through the pangaea.de website."

Minor points

Figure 1: include surface topography (with contours or background color) in both panels. I recommend enlarge both panels for clarity.

Surface topography has now been included as contours. The figure is now full width in The Cryosphere lay out.

Figure 2: it's hard to distinguish fully saturated colors and half-transparent. Please modify the figure.

We assume that this refer to Fig. 3 rather than Fig. 2. The difference between full saturation and half-transparent has been more clear with a red contour line and different colour scheme.

Figure 3: The candidate sites should have Delta G > 5 mW/m2. Is it better if the colorbar shows Delta G between 5 and 18 (instead of 0 and 18)?

The colorbar has been changed.

Figure 4: Consider larger intervals of the contours. Many features are smaller than the radar-profile separations and thus could be artifacts. It's hard for me to see water paths.

The intervals have been changed and the figure updated to show water paths and lakes more clearly.

#8

P3L22: "Echo-free zone" is defined as the deep ice on which radar returned power decreases in a short vertical distance much more than expected with geometric spreading and englacial attenuation (Fujita et al., 1999). The echo-free zone is not identical with a zone that shows no return signals, which can be caused by limited radar performance.

The sentence has been changed to

"...was discarded in the calculation to avoid surface noise and the reduced signal from the deepest part of the ice"

P3L25: Is this true? I think that it is the case, but there is no evidence. Probably better to say something like "because the data were collected in late 1980s without modern GPS positioning system."

We have changed the sentence to make it clearer how we arrived at this conclusion:

"We have not included the Soviet data from the Bedmap2 data in our compilation because the data were collected without Global Positioning System information and thus have a high associated uncertainty in location (pers. comm., Fujita 2017, see also Lythe et al., 2001). "

P3L29: Pulse widths determine a vertical resolution (capability to distinguish two objects separately) but irrelevant to the precision of the range measurement. The observed elevation change is about 0.01% of a typical ice thickness in the study area (2 km), which is below the known accuracy of the radio-wave propagation speed.

The sentence has been changed to:

"...a reasonable assumption given that elevation changes at Dome Fuji are less than 0.25m/a (e.g., Helm et al., 2014), thus the observed elevation changes are below the known accuracy of the radio-wave propagation speed."

P4L5: show the number of cross-over points analyzed here.

The following sentence is now included in the new section about results and uncertainties:

"For the GEA-OIR radarlines, 2453 points were found to be crossover points"

P4L3: please mention clearly at the beginning of this paragraph "the uncertainties are analyzed by crossover analysis of the new datasets and by the comparison of the gridded map product with previous data that were not used in the map product." Many uncertainty analyses are presented here and it's hard to see the overall analytical setup.

The section about uncertainties have been rewritten and should now be clearer.

P4L8-9: consider showing a histogram of cross-over errors. Also, it makes more sense to show first and third quartile, instead of the standard deviation.

A histogram of the difference between the GEA-OIR radarlines and the gridded ice thickness map is now included in the manuscript.

P4L10: unclear what negative number means here (which data were subtracted from which).

This has now been clarified in the new section.

P4L11: radarlines? Confusing because JARE data are ground based.

Has been changed to radarlines.

P4L13-19: Comparison with the BEDMAP2 data shows large discrepancy, and the authors argue that it mainly caused by poor positioning of the earlier Soviet data (again: no evidence of the poor positioning). So, these statements are not for determining uncertainties of the newly collected data.

The uncertainty section has been rewritten to make this clearer.

P4L24: characteristics of what?

The section title has been changed to Results and Uncertainties. Thank you for pointing out the lack of clarity.

P5L15: include the mean and range of geothermal flux in the study area taken from these datasets. I believe that the geothermal flux is a predicted field of this model (rather than an input field) and these geothermal flux datasets are used to derive delta G. So, I think that geothermal flux is mentioned at a wrong place.

The geothermal heat flux is not predicted by the model. The model predicts the minimum required geothermal heat flux that will cause the bed to reach the pressure melting point and uses the already existing fields to estimate how likely it is that the bed is melting. As such the heat fluxes are inputs.

P6 Equation: it's confusing to see G_min and G_mean, as G_min is a model prediction and G_mean is the mean of three datasets. How about G_min(predicted) and G_mean(datasets) or such?

The parameters have been changed to G_min^pred and G_mean^data

P6L2: Why is Sigma_G < 25 mW/m2 considered as low? Geothernal flux in this region is roughly 50 mW/m2, so I understand that the standard deviation of 25 mW/m2 means that the geothermal flux has +/- 50% uncertainty. In other words, the margin of geothermal flux with which the bed is kept frozen is much less than the geothermal flux dataset uncertainty (i.e. Delta G of 5 mW/m2 is much smaller than the range of the dataset, 25 mW/m2). I understand that the full description of this modeling is given in Van Liefferinge and Pattyn (2013) but still key information should be given here.

The threshold value of 25 mW/m2 is there to evaluate the dispersion of the GHF data sets. We consider that beyond that value the dispersion is too high between data sets and then we cannot constrain the GHF well enough (based on the mean value of GHF and Sigma of the whole interior ice sheet). The threshold value of 5 for Δ G is there to restrict our choice of oldest ice sites and improve our confidence in these sites. However, it is arbitrary chosen.

We have added to the section:

"These two threshold values are chosen according to mean geothermal heat flux values for the whole interior Antarctic Ice Sheet. The values restrict the dispersion of geothermal heat flux values between data sets and reduce the likelihood of melting."

P7L10: don't use several words in interchangeable ways; Lakes, wet areas, water-filled areas,

We have added the following caveat in the section:

"In the following we refer to these areas as ``lakes'' although in our preliminary analysis it is not possible to distinguish between a lake or, for example, water-filled sediments."

And we will refer to wet areas as lakes in the manuscript.



New figure 3



New figure 5



New figure 6

