

Response to Anonymous Referee #1: “Interactive comment on *A comparison of two Stokes ice sheet models applied to the Marine Ice Sheet Model Intercomparison Project for plan view models (MISMIP3d)*”

We thank the reviewer for the detailed comments, each of which is addressed in our response below.

### **Response to General Comments**

*I have several major concerns with the manuscript. First, I am questioning the novelty of this paper. The full-Stokes treatment of grounding lines has been investigated for almost 10 years, and a recent paper by Gagliardini et al. (2016) discusses the problem of numerical convergence due to the treatment of basal friction. The only new element introduced here is the development of grounding lines within FELIX-S, which I believe would be a better fit for Geoscientific Model Development.*

We disagree with the reviewer that the contribution is not novel – while grounding lines within Stokes models has been investigated for many years now, it has only been investigated in any amount of detail within a single model, Elmer/Ice. That same model has been used extensively as a metric for accuracy in community-wide, model intercomparison exercises, including two widely used and widely cited intercomparisons focused on marine ice sheet and grounding line dynamics. A stated goal of our contribution is to demonstrate how similar or different the solutions are from two Stokes models, which are based on significantly different, but equally valid implementations, in order to provide additional confidence in the use of Stokes models as an accuracy metric in past and future intercomparison exercises. As many of the results from these intercomparisons (and related papers) have been published in *The Cryosphere*, we are confident that our results will be of sufficient interest to warrant their publication therein.

*Second, I found the abstract in particular to be misleading, and to put emphasis on the “wrong” solutions to real questions. As mentioned by the authors, “as grid resolution increases the grounding line positions for FELIX-S and Elmer/Ice appear to converge”, which suggests that full-Stokes models (just like any numerical model) should do a convergence study to assess the impact of grid resolution on their results.*

We agree with the reviewer regarding the issue of convergence with respect to grid resolution (see additional discussion on this topic below). We add the “appear” qualifier here because it is not obvious that solutions from two different models can be shown to converge, in the formal sense, with increasing grid resolution. Further, with limited computing resources, such a study may not actually be feasible. What is feasible, and what we clearly demonstrate here, is that when the models are run at identical grid resolutions, and as that resolution increases, the model solutions become more and more similar to one another. While convergence of solutions between the two models is implied but not proven, we strongly believe that this result is worthy of publication in order to provide additional confidence in the use of Stokes models as accuracy metrics in intercomparison exercises. We have added additional figures and discussion in the revised manuscript to show that (1) the FELIX-S model is convergent with increasing

grid resolution (last paragraph of section 5.2 and new Figure 4), and (2) that the differences between the FELIX-S and Elmer/Ice models at their finest resolutions are generally near or below previously published estimates for the Elmer/Ice truncation error.

*The authors on the opposite suggest that “future model intercomparisons using full-Stokes models as a metric should include more than one model, to provide both additional confidence in the results from full-Stokes models and a measure of their uncertainty”. Comparing two different full-Stokes models will not allow quantifying the error in any of these models.*

Our intention is not to quantify the error in the Stokes models or between Stokes models and any other models. Our intention, which is clearly stated, is to provide additional confidence in the use of Stokes models by showing that two very different Stokes models give very similar solutions when model resolution is sufficiently high. Implicit is the understanding that any single model (Stokes or otherwise) is responsible for confirming numerical convergence with increasing grid resolution (see also next response below). In the revised version of the manuscript, we have also removed the suggestion that future intercomparison projects include more than one Stokes model.

*The only way to assess the error of each model is to do a convergence study, with varying grid resolution, to see if the results are converging, and if so, to quantify the error associated to the discretization. To my knowledge, this has never been properly done in three-dimensional models, and needs to be done instead of writing numerous papers on variations along the same subject (comparison of friction treatment around the grounding line, comparison of several full-Stokes models, ...).*

In fact, both models discussed here have previously published studies on solution convergence with increasing grid resolution. For the Elmer/Ice model, this has been discussed in detail in Gagliardini et al. (2013), section 7.1 and Gagliardini et al. (2016; see also Supp. Inf.). For the FELIX-S model, this has been discussed in detail in Leng et al. (2012), section 4.1 and Leng et al. (2013) section 4.2. This was not made explicit in the original version of the manuscript and we have added additional discussion to that end at the beginning of Section 3. As noted above, we have also added additional discussion and a new figure to address convergence of the FELIX-S model for the Stnd experiment of the MISMIP3d experiment suite.

*Finally, the results presented in this paper do not present major new results, as the conclusions are somewhat similar those of Gagliardini et al. (2016), which already discuss the impact of different treatment of basal friction around the grounding line.*

The fact that the results and conclusions of this paper are similar to those in Gagliardini et al. (2016) is precisely the point. The “major new result” is that we now have additional confidence when using Elmer/Ice (or FELIX-S) as a metric for high-fidelity model solutions in benchmarking exercises. Imagine the case where only one or the other of the Stokes models discussed here is to be used as a metric for solution accuracy in a model intercomparison (e.g., against which other reduced-order model solutions are to be compared). The community is already aware of solution errors resulting from under-

resolution. But both Gagliardini et al. (2016) and the present work demonstrate that seemingly arbitrary differences in implementation can also result in significant *differences* in model solutions. We emphasize *differences* here because it is not clear these can be characterized as errors – they result from a choice in implementation method. One or another model alone cannot be used to quantify such *differences* but multiple models can. And that characterization provides some estimate for how much confidence can be attached to the results from a single Stokes model.

*As errors in full-Stokes models start to be better estimated, and lower order approximations models also improved grounding line treatment during the past few years (Feldmann et al., 2014; Seroussi et al., 2014), a more interesting study would be to reassess the difference between full-Stokes and lower order approximations based on all these new data.*

We certainly agree with the reviewer on this point. However, this is an entirely different contribution than the present one. Again, our primary (and stated) goal here is to provide additional confidence in the use of Stokes models as accuracy metrics in model intercomparison exercises.

### **Response to Specific Comments**

*The convergence or absence or convergence with grid resolution should be rigorously assessed using a convergence study instead of providing statements like “appear to converge” in the abstract.*

As noted above, we have revised the manuscript to point to previous work where formal convergence studies have been conducted for both models, and to add discussion on a convergence study for the FELIX-S model applied to one of the standard MISMP3d experiments. The differences we are trying to quantify here result not strictly from grid resolution but from different implementation choices, which cannot necessarily be characterized as being relatively better or more correct in one model or the other.

*The description of the friction coefficient in section 3 is not clear. Figure 1 is also confusing, especially the friction coefficient along profile 2. This seems to be a straight line while there is a node in the middle of the profile. The details provided in the discussion should be moved in this section (p.5 l.15-16).*

See response to this same concern in the technical comment section below.

*p.8 l.3-7: For which model is there a 5 km difference?*

This statement was referring to FELIX-S. We’ve clarified this in revision.

*This paragraph also mentions that this distance is expected to decrease with increased grid resolution. Why not do these runs and provide an accurate answer? These positions should be the same for a model that has converged with grid resolution. So here again,*

*this seems to suggest that the results presented have not converged.*

A more complete convergence study of the sort suggested was done and is reported on in Gagliardini et al. (2016). Computing resource limitations prevented us from doing as exhaustive of a study here. We have re-worded this section slightly in order to make it clearer that we are speculating that FELIX-S would show similar results if we had done a similar study.

*How long is the steady-state run for? Could this difference be partly explained because the steady-state should be run longer to fully converge?*

For the steady-state Stnd experiments, FELIX-S simulations are started from the same initial condition used by Elmer/Ice, which is based on the boundary-layer theory solution of Schoof (2007). In this sense, it should already be close to equilibrium. We then integrate forward in time for ~1300 years (or ~1500 years, depending on whether starting from an advanced or retreated state). The criterion for an equilibrium configuration is the same as that used by Elmer/Ice (i.e., that the relative rate of volume change is below  $10^{-5}$ ). Thus, we are confident that the difference in steady-state GL positions is *not* due to the models not being fully converged and in equilibrium. The discussion of the Stnd experiment has been updated to provide more explicit information on these details.

*p.8 l.22-23: “the agreement between FELIX-S and Elmer/Ice increases for all of Elmer/Ice GL implementations”. This seems like another sign that the differences in the results are caused by the non-converged aspect of the results presented.*

We don't disagree with the reviewer on this point, and we discuss this in detail in the text already. At relatively coarser resolutions, the implementation choices that we discuss in detail have a relatively larger effect on model solution differences. At relatively finer resolution, these implementation differences are minimized, and the model solutions become more similar. We believe this is discussed and explained in adequate detail in the current version of the manuscript.

*p.1 l.2 (and other places in the text): full Stokes is commonly used in the literature, so there is no need to use “full” Stokes.*

In fact, the use of the term “full Stokes” is unique to the glacier / ice sheet modeling community. We apply the quotes in the first use as a way of indicating that this is somewhat mushy terminology. As suggested, we've removed the quotes after the first use.

*p.1 l.13: “appear to converge”: the convergence should be better studied to assess if there is convergence with grid resolution.*

See multiple responses to this same concern above.

*p.2 l.4: “inherent dynamic instabilities associated with marine-based ice sheets”. The marine instability should be briefly explained in a couple sentences.*

The marine ice sheet instability has been discussed in great detail in numerous previous papers (several of which have been added to the introductory section here as standard references) and in the original model intercomparison paper this work stems from. Moreover, readers interested in this contribution will already be familiar with the marine ice sheet instability. Therefore, we do not think it necessary to review that topic in additional detail.

## Technical Comments

*p.4 l.28-30: It should be stated here that errors in full-Stokes models and lower-order approximations should be accurately characterized to assess if the differences are within the error margins or if these models do lead to different results.*

We've added some additional discussion to this effect in the multiple sections of the revised paper. In particular, we point out in a number of different areas that, at highest resolution, the differences between Elmer/Ice and FELIX-S are within the estimated truncation error of the Elmer/Ice model.

*p.5 l.2: "Finite Element Methods" → "the Finite Element Method"*

Changed.

*p.5 l.30: What about the vertical resolution used in both models?*

Information about the vertical resolution has been added to section 3.

*p.6 l.4: "the prognostic, basal sliding perturbation experiment (P75S and P75R)": is that one or two experiments?*

We leave the description as in the original MISMIP3d paper, where it is described as a single experiment but with two parts (the "S" and "R" parts). To be clearer, "experiment" has been changed to "experiments".

*p.6 l.20: What resolution is used for the diagnostic experiment?*

Additional information on the meshes used for all experiments has been added Section 3.

*p.7 l.21: What is the vertical resolution?*

Information about the vertical resolution has been added to section 3.

*p.6 l.11: Replace "S", "R", ... by the experiment name.*

Presumably p.8 is meant. Changed as suggested.

*p.8 l.15: Why are the grid different for these experiments? If it is possible to use the same grid for experiments Stnd and P75D, it should also be possible to use a similar grid for*

*the other experiments (especially as they are much shorter than the Stnd experiment).*

As stated in the first paragraph of Section 5.3, for the P75S and P75R experiments the regionally refined portion of the mesh (for both models) is based on the steady-state grounding line at the end of the Stnd experiment. Because these locations are slightly different for the two models, the refinement region is also slightly different, and thus nodal coordinates are not identical as they are for the P75D and Stnd experiments.

*p.8 l.21: “the GL improves”: do you expect the grounding line to come back to its initial position on such a short time scale?*

No. Based on previous work, we expect that  $\gg 100$  yrs is required for this. We’ve added a parenthetical note and reference to the text to clarify this.

*p.8 l.27-29: “We attribute ...” I attribute it to the coarse grid used in the across flow direction.*

When we say differences, it is implied that we are talking about differences when using the same across and along-flow grid resolutions. If the models are using the same grid resolution, then presumably the differences are due to something *other than* the grid resolution.

*p.9 l.13-23: This paragraph should be moved to section 3.*

This is a matter of style in composing the manuscript and we disagree with the reviewer. If all of this information were given in section 3, it would not be at all clear to the reader what the context for so much detail was. Whereas, the context is much more clear in the discussion section.

*p.9 l.20: “basis functions”: a regular grid is used so the basis functions should have similar properties.*

If the both grids are quadrilateral (square element faces in map view), then yes. But FELIX-S uses tetrahedral elements (triangular element faces in map view, with two acute and one right angle). The basis functions that contribute to any node will depend on the shape and orientation of the surrounding triangles. Further, FELIX-S uses 2<sup>nd</sup>-order accurate basis functions whereas Elmer/Ice uses linear basis functions.

*p.10 l.32-33: I don’t agree with the conclusion that “two or more full-Stokes models should first conduct their own intercomparison”. I think that just like any numerical model, they should make sure that their results are not grid dependent and provide an error associated with their results.*

Please see responses and discussion above.

*p.11 l.4: What does “a more direct comparison between models” mean? The two models are already sharing lots of parameters, even the same grid. This should be detailed and not just mentioned.*

The details the reviewer requests are given in the lines following this statement (“This would include ...”).

*p.14 Tab.2: There are no Stnd results ( $x_{GO}$ ) provided for the 40 and 80 elements in the y direction. So what are the initial states used for the P75S experiments in these cases?*

The Stnd experiment is invariant in the across-flow direction (the initial conditions as well as the model solutions). Thus, adding additional resolution to the across-flow direction has no impact on the results of the Stnd experiment. This should be clear from the description of the experiments given in section 4, but we have also added a sentence to the caption for Table 2 to clarify this.

*p.15 Fig.1: The friction coefficient used along the profile is not totally clear, especially for Profile 2 (it looks like a straight line, which is surprising).*

This is because the friction coefficient used in these experiments is uniform and constant (see Table 1). The reasons why Elmer/Ice and FELIX-S “see” the friction coefficient at the nodes slightly differently is discussed in detail in the text. In the more general case of spatially varying friction coefficient,  $C=C(x,y)$ , and the friction profile for Elmer/Ice would also appear more complicated.

*Fig.4, 5 and 6: Thin (or thick) curves should be used consistently for the 4 panels to represent the same FELIX-S results. Also consider adding letters (a to d) for the panels, as mentioned in the captions.*

We’ve improved the different panels in Figures 4-6 (black bold is now always FELIX-S results, as suggested). The panels do contain letters, in the lower right corners. In revision, we’ve made them bold so they are easier to see.

*Fig.7: How can an absolute value be negative (right panel)?*

In response to similar comments from reviewer no. 2, we have completely revised this figure, the figure caption, and the related discussion in the text.

## References

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