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Interactive comment on "The impact of melt ponds on summertime microwave brightness temperatures and sea ice concentrations" *by* S. Kern et al.

Referee #3, Georg Heygster

Review of TCD manuscript Kern et al. The impact of melt ponds...

The manuscript constructs a data set of 100% sea ice concentrations (SIC) from the summer 2009 based on optical observations (MODIS) and analyzes the influence of varying melt pond fraction (MPF) on the satellite observed microwave brightness temperatures (TBs) and resulting SIC retrievals.

The manuscript treats an important subject in an exhaustive way, and also development in time of TB and SIC is considered. I suggest to accept the manuscript after small changes.

Title and abstract well reflect the content.

My main comments are:

The sea ice and melt pond concentrations based on the MODIS data are considered as ground truth. It should be mentioned that this assumption is the base of the complete investigation (in fact it is the best we currently have). However, the MODIS based retrieval is a static one which is not able to reflect potential developments of the optical melt pond signatures over the melting season (The MODIS retrieval algorithm does not have tie points but its retrieval is based on a neural network described by a larger set of parameters). This point is mentioned in the last paragraph of P8 (first two sentences), but it should be added that this is a central assumption of all subsequent analyses.

The paragraph continues 'The spectral properties of melt ponds are likely to approach those of leads and openings as melt season progresses.' This may be true for ponds on first-year ice, but it is not the case for blue ponds which typically appear on multi-year ice where the ice below the pond is thick. This aspect will not cancel the complete manuscript (the used data are the best we have currently), but this assumption should be mentioned. It is essential for the (except this point excellent) discussion of the temporal development in Figs. 7 and 8.

The subsequent part of the same paragraph states that a misclassification between melt ponds and open water would have no implications for the net sea-ice surface fraction. It would affect only the melt pond or the open-water fraction. This is correct for the net sea-ice surface fraction. However, an error in the open water fraction would also affect the MODIS sea ice concentration which is used in Fig. 4. Should be mentioned.

We do really appreciate the work of the reviewer taking the time to read our manuscript carefully. We thank the reviewer in particular for pointing us to some critical information missing in the above three paragraphs. We have changed the text accordingly as follows:

"More important is the potential misclassification of one of the surface types. The reflectance values used are fixed for the entire summer season and the entire Arctic domain. Therefore the MODIS sea-ice parameter retrieval does not account for the spatiotemporal variability in the spectral properties of the melt ponds or the non-ponded sea ice. These spectral properties change as a function of ice type and melt-season duration. The spectral properties of melt ponds on first-year ice are likely to approach those of leads and openings as melt season progresses while for melt ponds on multiyear ice these change less due its larger thickness and different internal structure. This could result in an over-estimation of the melt-pond fraction relative to the open-water fraction for first-year ice or vice versa, because the spectral space between sea ice and water is larger than between melt ponds and open water (leads). Such a misclassification would have, however, no implications for the net sea-ice surface fraction. It would affect only the melt pond or the open-water fraction. Therefore such a misclassification is likely not influencing the main results of the present paper but should be kept in mind when interpreting MODIS sea-ice concentrations (see sub-section 3.2)."

and further:

At the time of our analysis and writing this MODIS product was the best we could have, despite the above-mentioned limitations due to cloud cover and spatiotemporal variation of the ice-type dependent spectral properties of the summer sea-ice cover. The results of our quality analysis and the results of Marks (2015) confirm that we can take the MODIS sea-ice parameters as kind of the ground truth against which we compare brightness temperatures and sea-ice concentrations in Sections 3 and 4.

In Figure 6 (which I find impressively instructive and rich of information), among other the parameter space of the Bootstrap_f algorithm is shown, which is used in the Bootstrap algorithm for low ice concentrations only. It might be more relevant to show the parameter space diagram for an algorithm which claims to work at high ice concentrations. If you keep showing Bootstrap_f, then explain the reason in the manuscript.

The same comment applies to Fig. 8 (Bootstrap_f) which could be replaced by Fig. S01 (Bootstrap_p) and it applies to the whole Section 4.3.2.

Although we agree that at first glance Bootstrap_f is not used at high ice concentrations we would like to point the reviewer to a few key points.

First of all, both modes of the Bootstrap algorithm are widely used in the community. It is hence a well-known algorithm which needs to be shown here. We feel that we do not repeat this information in the manuscript.

Secondly, we feel that it is important to show both modes of the algorithm because the threshold sea-ice concentration at which the sea-ice concentration retrieval switches between the two modes depends on season and ice type – even though it seems to be close to 90%. Also, we feel that it is an important piece of information to show whether for a particular sea-ice situation one of the modes provides a biased sea-ice concentration value while the other does not.

Third, the two other hybrid algorithms used, OSISAF and SICCI either use Bootstrap_f or CalVal (which is identical to Bootstrap_f) for low ice concentrations. While it might be less interesting to consider the Bootstrap_f mode in case of the OSISAF algorithm, for which the switch between Bootstrap_f and Bristol (used at high ice concentrations) is occurring in the range 40% to 80%, it is more interesting and relevant to consider the Bootstrap_f mode for the SICCI algorithm because the above-mentioned switch occurs in the range 70% to 90%. Actually we have added the thresholds where the switches occur in sub-section 2.3 on page 10: "For the high sea-ice concentrations we focus on in this paper, these two hybrid algorithms are almost identical to the algorithm, which is employed at high sea-ice concentrations, that is Bristol in case of the OSI-SAF (zero weight at < 40%, full weight at \geq 80%) and SICCI (zero weight at < 70%, full weight at \geq 90%) algorithms and Bootstrap_p in case of the Comiso Bootstrap algorithm."

Finally, AMSR-E sea-ice concentrations retrieved with the two modes of the Bootstrap algorithm show the lowest and highest sensitivity to the melt-pond fraction (see page 15, first paragraph of Section 4) which we think by itself is a good enough reason to focus as much on the Bootstrap_f mode as we focus on the Bootstrap_p mode. Again, since we give this information in the text already we don't think that we need to argument more for why we include the Bootstrap_f mode.

Detail comments:

Section headings 3 (Results?) and 4 (Discussion?) missing

We added the missing section headings like the reviewer did suggest.

Have consistent denoting of supplement figures, not mixing e.g. S1 and S01.

We found that supplement figures are denoted S1 to S4 in the text but S01 to S04 in the supplements document. We have changed the latter to comply with the main manuscript.

Abstract P(age) 1 L(ine)16: consider replacing 'between the melt ponds' by 'starting well before formation of melt ponds when temperatures are still below zero' or so.

We don't agree with this suggestion. The reviewer seems to have understood that we are referring to snow and sea-ice properties before melt did commence. In fact, we are referring to the sea ice between the melt ponds (locally). The point we wish to address in this paper is that not only the pure presence of melt ponds, i.e. open water on top of sea ice, but also and in particular the properties of the sea ice (with snow or bare) between the melt puddles change and cause (apparently) exactly those changes in surface emissivity which makes ponded sea ice to look like it is 100% sea ice without

liquid water on top. In order to avoid confusion we changed "between the melt ponds" to "itself" to make clear that we refer to the sea ice properties.

P2L14 since over 35 years -> for more than 35 years

Changes as suggested.

P5 L15 delete 'JGR-C'

We removed JGR-C and other journal abbreviations which we left accidentally in the text of the previous version of the manuscript.

P7 L24 'We use only reflectance values with the highest quality score. This ensures that cloudy pixels and pixels with cloud shadows, pixels with sun zenith angles > 85° and pixels with sensor viewing angles > 60°, plus pixels complying with four additional flag criteria are not used.': - scores not defined. No need to mention because criteria are described in the subsequent text. Omit 'score'?

- where from cloud shadows known? Visual inspection?

- 'four additional flags': which ones?

We deleted "score". We are more specific with the quality flags now and added all to the manuscript so that these sentences now read: "We use only reflectance values with the highest quality. This ensures that cloudy pixels and pixels with cloud shadows, pixels with sun zenith angles $> 85^{\circ}$ and pixels with sensor viewing angles $> 60^{\circ}$, data from faulty or poorly corrected L1B pixels, pixels containing the default or the highest aerosol level and pixels without any correction for the atmospheric influence are not used."

We refer the reviewer to the documentation of the MODIS data set for the details regarding how these flags are derived, e.g. cloud shadows.

P8 L11 'we set the few negative melt-pond fractions ...to zero: Were other surface type concentrations also changed in order to keep them summing up to 1?

Yes. This is evident from Figure 3 where the net open water fraction and the net ice surface fraction add to 100%.

P9 L25 'Only data with footprints which center I located within 5 km...' Unclear. Do you mean 'Only data with footprints with centers located within 5 km...'? Yes. We have changed the text accordingly.

P17 L28 '(5-day periods)': shift to first occurrence of pentad on P 12.

We moved 5-day periods to page 12 now. The first sentence where "pentad" occurs reads now as follows: "Then the melt-pond fraction starts to increase, first slowly: days 20-30 (5th and 6th 5-day period or pentad of June), then rapidly: days 30-45 (1st to 3rd pentad of July)."

P18 L32 '... and the MODIS ice-surface fraction is over-estimated.': where from known? I cannot read this from Fig. 8a or 6c. I only read from Fig. 8b that Bootstrap_f will find SIC>100%, not MODIS. Explain.

This was a misunderstanding borne out of sub-optimal formulation. The sentence now reads: "Most Bootstrap_f sea-ice concentrations exceed 100% and over-estimate the MODIS ice-surface fraction."

P20 L1 'at this side of the parameter space': meaning unclear. Which side? Of what? Which figure?

We have changed two sentences to make clearer what we are referring to. These two sentences now read: "The distance between the cyan line and the winter ice lines in proximity to the FYI tie point, measured along the dashed white line (Figure 6 c), suggests that we would reduce Bootstrap_f sea-ice concentrations by 10% to 15%. Therefore, at the FYI side of the parameter space, Bootstrap_f sea-ice concentrations would be ~100%."

Reference Tschudi et al. (2016): Replace '[indicate subset used]' appropriately.

We added the respective information.

In addition, we carried out a spell check of the manuscript and went through it, deleting one or two superfluous half-sentences, and tried to be clearer where we thought additional information might be needed. We also added one reference.

1 The impact of melt ponds on summertime microwave

- 2 brightness temperatures and sea ice concentrations
- 3

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12

13 Abstract

Sea-ice concentrations derived from satellite microwave brightness temperatures are less 14 accurate during summer. In the Arctic Ocean the lack of accuracy is primarily caused by melt 15 16 ponds but also by changes in the properties of snow and the sea-ice surface itselfbetween melt ponds. We investigate the sensitivity of eight sea-ice concentration retrieval algorithms to 17 melt ponds by comparing sea-ice concentration with melt-pond fraction. We derive gridded 18 daily sea-ice concentrations from microwave brightness temperatures of summer 2009. We 19 derive the daily fraction of melt-ponds, open water between ice floes and ice-surface fraction 20 21 from contemporary Moderate Resolution Spectroradiometer (MODIS) reflectance data. We only use grid cells where the MODIS sea-ice concentration, which is melt-pond fraction plus 22 ice-surface fraction, exceeds 90%. For one group of algorithms, e.g., Bristol and Comiso 23 24 Bootstrap frequency mode (Bootstrap f), sea-ice concentrations are linearly related to the MODIS melt-pond fraction quite clearly after June. For other algorithms, e.g., Near90GHz 25 and Comiso Bootstrap polarization mode (Bootstrap p), this relationship is weaker and 26 27 develops later in summer. We attribute the variation of the sensitivity to the melt-pond fraction across the algorithms to a different sensitivity of the brightness temperatures to snow-28 property variations. We find an under-estimation of the sea-ice concentration by between 29

14% (Bootstrap_f) and 26% (Bootstrap_p) for 100% sea ice with a melt-pond fraction of 1 40%. The under-estimation reduces to 0% for a melt-pond fraction of 20%. In presence of 2 3 real open water between ice floes, the sea-ice concentration is over-estimated by between 4 2614% (Bootstrap f) and 1426% (Bootstrap p) at 60% sea-ice concentration and by 20% across all algorithms at 80% sea-ice concentration. None of the algorithms investigated 5 performs best based on our investigation of data from summer 2009. We suggest, that those 6 7 algorithms which are more sensitive to melt ponds, could be optimized easier because the influence of unknown snow and sea-ice surface property variations is less pronounced. 8

9

10 **1** Introduction

Sea-ice area and extent are derived from data of the sea-ice concentration, i.e. the fraction of a 11 given area of the ocean covered with sea ice. Observations of the brightness temperature by 12 13 satellite passive microwave sensors have been the backbone for sea-ice concentration retrieval for more thansince over 35 years because these are independent of daylight and quite 14 insensitive to the cloud cover. These satellite sensors used for sea-ice concentration retrieval 15 measure the brightness temperature at window frequencies between 6 GHz and ~90 GHz at 16 both, vertical and horizontal polarization, at a constant incidence angle of ~53° which we use 17 for the present paper. Numerous sea-ice concentration retrieval algorithms have been 18 19 developed during the past decades (see e.g. Ivanova et al., 2015). To retrieve the sea-ice 20 concentration Aall algorithms exploit in some way the contrast in the microwave brightness temperature between open water and sea ice to retrieve the sea-ice concentration. During cold 21 conditions, i.e. as long as freezing conditions prevail, sea-ice concentrations are retrieved with 22 these algorithms as accurate as 2% to 5% for the near 100% ice cover (Ivanova et al., 2015, 23 2014; Andersen et al., 2007; Meier, 2005). However, during melting conditions the retrieval 24 accuracy is reduced substantially and sea-ice concentrations can be biased low compared to 25 26 the actual sea-ice concentration (Ivanova et al., 2013; Rösel et al., 2012b; Comiso and Kwok, 1996; Cavalieri et al., 1990). 27

One potential reason for the reduced accuracy is the change in microphysical properties inside the sea ice, for instance, the desalination of the sea ice during the melt process or the flushing of air voids in multiyear ice with melt water and other melt processes <u>as</u> for example described in Scharien et al. (2010). Another potential reason is the change in surface properties of the sea ice. The three key surface features of summer melt on Arctic sea ice are a metamorphous, wet snow cover, a porous, wet sea-ice surface, and melt ponds. During 1 summer, the snow cover on sea ice is usually wet or even saturated with melt water (Garrity,

1992). Its density is usually considerably larger during summer than during winter (Warren et
al., 1999; Maykut and Untersteiner, 1971). Diurnal <u>melt-re</u>freeze-thaw cycles, i.e. episodes of
intermittent melting and refreezing of the snow, which is a common phenomenon during late

5 spring, result in an increase of the snow grain size.

6 Wet snow is an efficient absorber of microwave radiation and has a microwave emissivity

7 close to 1. It can effectively block microwave emission from underneath and thereby masks

8 differences in volume scattering between first-year and multiyear ice. Therefore microwave
9 brightness temperatures of sea ice covered with wet snow usually are close to its physical

temperature during melt (e.g. Stiles and Ulaby, 1980; Eppler et al., 1992; Hallikainen and

11 Winebrenner, 1992; Garrity, 1992).

During the meltthaw phase of melt-refreeze-thaw cycles, coarse-grained snow can be 12 regarded to behave similar to wet snow due to its wetness. During the refreeze phase, 13 14 however, when it is dry, it absorbs less microwave radiation than wet snow and there is more scattering from within the snow. Therefore, dry coarse-grained snow does not block or mask 15 microwave emission and volume scattering differences of the sea ice and/or snow underneath 16 as efficiently as wet snow does. The amount of volume scattering depends on microwave 17 frequency and polarization, and on the vertical location of the coarse-grained snow layers 18 relative to the snow surface. Because the electromagnetic wavelengths are closer to the snow 19 grain size at higher frequencies, i.e. at 37-90 GHz, volume scattering in snow is larger for the 20 21 higher than the lower microwave frequencies (Fuhrhop et al., 1998; Eppler et al., 1992; 22 Hallikainen and Winebrenner, 1992; Gogineni et al., 1992). In Tables 1 to 3 we give some 23 sensitivities of microwave brightness temperatures with respect to changes in snow wetness, density, and grain size. These tables are not meant to be exhaustive. Instead we will use the 24 sensitivities for our discussion of the results (section 4). 25

Melt ponds are puddles of melt water on top of sea ice. They form during summer from 26 melting snow and sea ice. Their areal fraction, size and depth is determined by the onset, 27 28 length and severity of the melting season, the sea-ice type and topography, and the snowdepth distribution at the beginning of melt (Landy et al., 2014; Polashenski et al., 2012; 29 Petrich et al., 2012; Eicken et al., 2004; Perovich et al., 2002). The melt-pond water salinity is 30 close to zero ppt. Typically, the melt-pond fraction on Arctic sea ice varies between 10% and 31 40% but can also exceed 50%, for instance, early in the melt season or on land-fast sea ice 32 (Webster et al., 2015, JGR O; Divine et al., 2015, TC; Landy et al., 2014; Polashenski et al., 33

2012; Sankelo et al., 2010, POLRES; Tschudi et al., 2001 (JGR-D; Yackel and Barber, 2000;
 Fetterer and Untersteiner, 1998, JGR-O).

The penetration depth into liquid water of microwave radiation at the frequencies used here, 3 i.e. between 6 and 89 GHz, into liquid water is in the order of one millimeter (Ulaby et al., 4 1986). We use the penetration depth here as the depth from which most of the microwave 5 radiation originates. Because of the above-mentioned very low penetration depth, a water 6 7 layer with a depth of a few millimeters is opaque enough to completely block the microwave signal from the sea ice underneath. A melt pond on sea ice has the brightness temperature 8 signal of open water and is therefore indistinguishable from open water in cracks or leads 9 between the sea-ice floes (Gogineni et al., 1992; Grenfell and Lohanick, 1985). At 6 GHz and 10 higher frequencies the signature of fresh water and salt water are indistinguishable. Satellite 11 microwave sensors which have been used for sea-ice concentration retrieval allow for 12 footprint sizes between ~ 5 km and ~ 70 km. Melt ponds, cracks and leads are therefore sub-13 14 footprint size surface features and cannot be resolved individually. A satellitespace borne brightness temperature measurement of a mixed scene is therefore composed of contributions 15 from the open water, i.e. cracks, leads, melt ponds, and from the (snow covered) sea ice. This 16 has two main consequences for a sea-ice concentration product computed from such coarse 17 resolution satellite measurements. The sea-ice concentration in the presence of melt ponds is 18 likely to be underestimated – because melt ponds are seen as open water. Whether the 19 footprint contains, for example, A) 100% sea ice with 40% melt ponds or B) 60% sea ice with 20 21 40% open water from leads and openings, is ambiguous. In both cases satellite microwave 22 radiometry retrieves 60% sea-ice concentration because the net sea-ice surface fraction of sea 23 ice in the grid cells is 60%. If during summer, a sea-ice concentration retrieval algorithm over-estimates the net sea-ice surface fraction in case A, for example because of a specific 24 summer-time microwave signature of the sea ice, and provides, e.g., ~90% sea-ice 25 concentration, then the same algorithm would most likely also overestimate the net sea-ice 26 surface fraction in case B. The algorithm would hence under-estimate the actual sea-ice 27 28 concentration in case A but over-estimate the actual sea-ice concentration in case B. 29 This has consequences for climate research. For example, the sea-ice area, which is defined as the sum of the area of all sea-ice covered grid cells weighted by the sea-ice concentration, will 30

be <u>under-estimated</u> correctly from case A) but will be <u>undov</u>er-estimated from case
B). Approaches have been developed, which permit to derive the melt-pond fraction on sea

33 ice from satellite observations in the visible/near-infrared frequency range (Istomina et al.,

1 2015a, 2015b; Zege et al., 2015; Rösel et al., 2012a). Their results could be used to correct the 2 above-mentioned ambiguity by quantifying how much of the open water seen (30% in the 3 example above) is actually caused by melt ponds. However, the time-series of melt-pond 4 fraction data computed so far (2002-2009 and 2002-2011) are too short to apply such a 5 correction for the entire <u>over</u> 35 years long sea-ice concentration data set from satellite 6 microwave radiometry. In addition, such data may have limitations due to cloud cover and the 7 viewing geometry at high latitudes (see sub-section 2.1).

The ambiguity in the actual surface properties related to behind the sea-ice concentration value 8 of 60% in the example above is also challenging for the initialization and evaluation of 9 numerical models, and the assimilation of sea-ice concentration data into such models. An 10 unambiguous sea-ice concentration is required for, e.g., the correct computation of the sea-ice 11 volume. In the terminology of the more advanced thermo-dynamic and dynamic sea-ice 12 models or model components which treat leads and melt ponds separately (e.g. Holland et al., 13 14 2012, JC; Flocco et al., 2010, JGR C), the fraction of sea ice covering the open ocean is called 15 sea-ice concentration and includes melt ponds. The fraction of the latter is given separately as the area of the sea-ice surface covered by melt ponds and is called melt-pond fraction. It is 16 obvious, that such models would have difficulties using a sea-ice concentration product which 17 is biased like described above for cases A and B. Even numerical models, which are not as 18 advanced and which do not treat melt ponds separately, would have difficulties to use such a 19 product. 20

21 This calls for a better quantification of the uncertainty and/or of potential biases in the sea-ice 22 concentration. How sensitive are present-day sea-ice concentrations algorithms to the melt-23 pond fraction? How do these algorithms differ with respect to the expected bias due to melt ponds and how can we explain these differences? We hypothesize that microwave brightness 24 temperatures and sea-ice concentrations derived from them change linearly with the increase 25 in surface-water fraction or the decrease in net sea-ice surface fraction due to melt ponds. To 26 the authors' best knowledge, an inter-comparison of different algorithms which incorporates 27 contemporary information of the melt-pond fraction and an independent sea-ice concentration 28 estimate, as is the aim of this study, has not previously been carried out. 29

WIn the present paper we illustrate how satellite microwave brightness temperature
 measurements vary with the net sea-ice surface fraction derived from satellite visible/near infrared (VIS/NIR) imagery. We compare the sea-ice concentration obtained with different
 sea-ice concentration retrieval algorithms from these brightness temperatures with the sea-ice

concentration and with the net sea-ice surface fraction from VIS/NIR imagery. We isolate the 1 influence of melt-pond fractions on the net sea-ice surface fraction by limiting our analysis to 2 VIS/NIR imagery sea-ice concentrations > 90%. We demonstrate how these brightness 3 4 temperatures change with progression of melt and discuss the implications of this change for sea-ice concentration retrieval. 5 6 The paper is organized as follows. The next section (2) describes the data sets and methods 7 used for the inter-comparison of brightness temperatures and sea-ice concentrations derived with several algorithms and the melt-pond fraction. In section 3 we are going to present the 8 results of this inter-comparison which we discuss in section 4. Section 5 concludes ourthe 9 findings. 10

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12 2 Data and Methods

The paper focuses on the melt season, i.e. months June, July, and August, of the year 2009.
The spatial domain of our investigations is a region of the Arctic Ocean (see Figure 1). This
region-and it is determined by the area and data which we chose to compute the sea-ice cover
parameters from satellite VIS/NIR imagery, described in the following sub-section 2.1.

17 **2.1 Sea-ice parameters from VIS/NIR satellite imagery**

2.1.1 Data sets and methodology

We derive the open water fraction, melt-pond fraction, and net sea-ice surface fraction from 19 20 reflectance measurements of the Moderate Resolution Imaging Spectroradiometer (MODIS) aboard the Earth Observations Satellite TERRA. We use the "MODIS Surface Reflectance 21 dailv L2GGlobal 500 т and 1 km" product (MOD09GA, 22 http://reverb.echo.nasa.gov/reverb/). We obtain the L2G data on the sinusoidal tile grid used 23 for MODIS L2 data from http://modis-land.gsfc.nasa.gov/MODLAND_grid.html. We project 24 25 the MODIS reflectance data together with land, cloud, and ancillary information onto the NSIDC polar stereographic grid with tangential plane at 70°N with a grid resolution of 0.5 26 27 km. Subsequently, we use all re-projected tiles to compose an Arctic mosaic of the MODIS wavelength bands 1: 459-479 nm, 3: 620-670 nm, and 4: 841-876 nm. We apply a spectral 28 29 un-mixing approach to classify the fractions of open water (between the ice floes), melt ponds, and sea ice, which can be barren or snow covered. For this we use typical reflectance 30 values of these surface types in the above-mentioned wavelength bands (Tschudi et al., 2008). 31 32 The methodology is explained in more detail together with validation results in Rösel et al.

(2012a) and yields the distribution of the fractions of open water, melt ponds, and net sea-ice 1 surface fraction at 0.5 km grid resolution. We average these distributions onto a NSIDC polar-2 stereographic grid with 12.5 km grid resolution. Together with the above-mentioned fractions 3 4 the standard deviation of the melt-pond fraction per grid cell and the number of clear-sky 0.5 km grid cells contributing to each 12.5 km grid cell are stored in netCDF file format. The 5 number of clear-sky grid cells is taken as a measure of the cloud fraction later. The grid 6 resolution of 12.5 km is chosen in accordance to the 8-day MPF data set derived with the 7 same approach but using 8-day composite MODIS reflectance data for years 2000-2011 8 (Rösel et al., 2012a). We compute the MODIS sea-ice concentration by subtracting the open-9 water fraction from 100%; note that the MODIS sea-ice concentration includes the sea ice 10 covered by melt ponds while the net sea-ice surface fraction does not. Open-water fraction, 11 melt-pond fraction, and net sea-ice surface fraction add to 100%. For the comparison with the 12 microwave brightness temperatures (sub-section 2.2) and sea-ice concentrations derived from 13 14 these (sub-section 2.3) we average the MODIS sea-ice parameter data set to 100 km x 100 km grid resolution. In addition, in order to mitigate the influence by variations in the actual sea-15 ice concentration on our results, we only use grid cells with MODIS sea-ice concentration > 16 90% unless stated otherwise. Throughout the paper we use the term "ice-surface fraction" for 17 net sea-ice surface fraction. 18

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2.1.2 Quality assessment of the MODIS sea-ice parameters

The quality of MODIS reflectance measurements carried out at high latitudes may be 21 degraded from high sun zenith angles, long pathways through the atmosphere, cloud shadows, 22 and, in addition, shadows caused by ridges in the sea-ice cover. We use only reflectance 23 24 values with the highest quality-score. This ensures that cloudy pixels and pixels with cloud shadows, pixels with sun zenith angles $> 85^{\circ}$ and pixels with sensor viewing angles $> 60^{\circ}$, 25 26 data from faulty or poorly corrected L1B pixels, pixels containing the default or the highest aerosol level and pixels without any correction for the atmospheric influenceplus pixels 27 complying with four additional flag criteria are not used. 28

Mäkynen et al. (2014) hypothesized that our daily MODIS melt-pond fractions are positively biased by about 5-10 % during early melt. In-situ observations carried out north of Greenland revealed a melt-pond fraction of 0% and a sea-ice concentration of 100 % during the first two weeks of June 2009 (Mäkynen et al., 2014). Melt onset dates given in Perovich et al. (2014)

support this observation. In order to confirm this notion, we derived histograms of the 1 MODIS melt-pond fraction and the MODIS sea-ice concentration using the data with 12.5 km 2 grid resolution for latitudes north of 83°N for all days before June 7, 9, 11, and 13, 3 respectively (Figure 2). MODIS melt-pond fractions peak at 8%. There are no grid cells with 4 a melt-pond fraction below 4 %. The MODIS sea-ice concentration peaks at 98 % without any 5 grid cell with values > 98%, suggesting a bias of 2%. We can also confirm the magnitudes of 6 the above-mentioned biases from version 01 of the 8-day MODIS melt-pond fraction product 7 (Kern et al., 2015) and conclude the presence of a systematic bias. Therefore we apply a bias 8 correction and subtract 8% from the melt-pond fractions and add 2% to MODIS sea-ice 9 concentrations. A similar correction (minus 8% and plus 3%) was applied to melt-pond 10 fraction and sea-ice concentration of version 01 of the 8-day MODIS melt-pond fraction 11 product (Rösel et al., 2012a; DOI:10.1594/WDCC/MODIS Arctic MPF) vielding version 02: 12 DOI:10.1594/WDCC/MODIS Arctic MPF V02). For the daily product used here, we set the few 13 14 negative melt-pond fractions resulting from the bias correction to zero.

15 Even though a state-of-the-art cloud masking scheme has been applied to the MODIS reflectance data before the MODIS sea-ice parameter retrieval (Rösel et al., 2012a), there is 16 17 still a substantial number of misclassified grid cells. It has been demonstrated that even with a multi-channel instrument such as MODIS, cloud classification is a challenge over bright 18 surfaces such as sea ice or snow (Chan and Comiso, 2013; Karlsson and Dybbroe, 2010). In 19 order to mitigate the influence from misclassifications due to residual clouds, we only use 100 20 km grid cells with a cloud cover < 5%. About 15 500 grid cells remain for the analysis. We 21 22 note that for MODIS collection 6 data (we use collection 5) a further improvement of cloud cover properties in the high latitudes is not foreseen (King et al., 2013; Baum et al., 2012) We 23 24 find that by changing the cloud-cover threshold to 2% or to 10% (not shown), the number of co-located grid cells dois changeing but the results shown in Section 3 do not. We estimate 25 26 the average uncertainty in the melt-pond fraction, net sea-ice surface fraction and MODIS sea-ice concentration due to cloud-induced misclassifications to $\sim 5\%$. 27

More important is the potential misclassification of one of the surface types. The reflectance values used are fixed for the entire summer season and the entire Arctic domain. Therefore the MODIS sea-ice parameter retrieval does not account for the spatiotemporal and do not take into account the variability in the spectral properties of the melt ponds or the non-ponded sea ice. These spectral properties change as a function of ice type and melt-season duration.

The spectral properties of melt ponds on first-year ice are likely to approach those of leads 1 and openings as melt season progresses while for melt ponds on multiyear ice these change 2 3 less due its larger thickness and different internal structure. This could result in an over-4 estimation of the melt-pond fraction relative to the open-water fraction for first-year ice or vice versa, because the spectral space between sea ice and water is larger than between melt 5 ponds and open water (leads). Such a misclassification would have, however, no implications 6 for the net sea-ice surface fraction. It would affect only the melt pond or the open-water 7 fraction. Therefore such a misclassification is likely not influencing the main results of the 8 9 present paper but should be kept in mind when interpreting MODIS sea-ice concentrations (see sub-section 3.2). 10

Rösel et al. (2012a) report RMSD values between MODIS melt-pond fraction and 11 independent melt-pond fraction observations of 4% to 11%. We compare the MODIS sea-ice 12 concentration with visual ship-based sea-ice concentration observations from seven ship 13 14 expeditions into the Arctic Ocean and obtain an average RMSD of $(10.3 \pm 3.3)\%$ (range: 15 6.0% to 15.2%). A comparison of our daily MODIS melt-pond fraction data set with contemporary daily melt-pond fraction estimates based on Envisat MERIS data derived with 16 17 the approach of Istomina et al (2015a) revealed a consistent agreement (Marks, 2015Istomina, Institute of Environmental Physics, University of Bremen, personal communication, May 18 $\frac{2016}{2016}$). Based on these results we are quite confident, that the average uncertainty of the melt-19 pond fraction is better than 10% and that the MODIS ice-surface fraction is as accurate as \sim 20 5%. 21

At the time of our analysis and writing this MODIS product was the best we could have, despite the above-mentioned limitations due to cloud cover and spatiotemporal variation of the ice-type dependent spectral properties of the summer sea-ice cover. The results of our quality analysis and the results of Marks (2015) confirm that we can take the MODIS sea-ice parameters as kind of the ground truth against which we compare brightness temperatures and sea-ice concentrations in Sections 3 and 4.

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2.2 Satellite microwave brightness temperatures

We use brightness temperatures measured by the Advanced Microwave Scanning Radiometer aboard the Earth Observation Satellite (EOS) TERRA: AMSR-E. The AMSR-E data used are from the 6.9 GHz, 10.7 GHz, 18.7 GHz, 36.5 GHz, and 89.0 GHz channels, which we abbreviate with 6, 10, 19, 37, and 89 GHz henceforth. We take the AMSR-E swath data from

the AMSR-E/Aqua L2A Global Swath Spatially-Resampled Brightness Temperatures data 1 2 set, version 2: http://nsidc.org/data/docs/daac/ae_l2a_tbs.gd.html, (Ashcroft and Wentz, 2013). We resample the brightness temperatures of all channels to the resolution of the 6 GHz 3 channel, which has a 3-dB footprint of 43 km x 75 km, and co-locate these to the MODIS sea-4 ice parameters provided at 100 km grid resolution (sub-section 2.1). We include data from all 5 6 AMSR-E passes of the same day as the MODIS data. Only data with footprints which centers 7 Hocated within 5 km of the center of a MODIS sea-ice parameter grid cell are used. AMSR-E sampling is approximately every 10 kilometers so this gives us approximately 1 data point 8 9 from each AMSR-E pass.

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2.3 Sea-ice concentration algorithms

We compute sea-ice concentrations from this set of co-located AMSR-E brightness 12 temperatures (sub-section 2.2) using eight selected sea-ice concentration retrieval-algorithms 13 investigated in the European Space Agency Climate Change Initiative - Sea Ice (SICCI) 14 project. The full suite of sea-ice concentration SIC-algorithms used in the SICCI project is 15 documented in the SICCI project reports: PVASR (Ivanova et al., 2013) and ATBD (Ivanova 16 17 et al., 2014), together withwhere also the tie points for open_-water and sea_-ice-tie points can be found. The tie pointsse represent winter conditions. The motivation for this is two-fold. 18 One is our wish to inter-compare the eight algorithms independently of individual tie points 19 being specifically selected in the original algorithms. We want to use one universal set of tie 20 points (see also Ivanova et al., 2015). This implies the second reason why we use winter tie 21 points in the present study. For the derivation of the sea-ice tie points Ivanova et al. (2015) 22 used high ice concentration areas of convergent ice motion during winter. This ensures that i) 23 24 the areas from which tie points are retrieved are large enough and ii) the areas have indeed 25 100% sea-ice concentration. Such an approach does not work under summer conditions because openings / leads in the ice cover do not freeze over. In the present study we focus on 26 a selected number of different (representative) types of algorithms (Ivanova et al., 2015) and 27 do not include algorithms where a methodology is duplicated. The selected algorithms are 28 summarized in Table 4. 29 We categorize the algorithms into four types based on the way brightness temperatures are 30 31 used: 1) algorithms based on one polarization and one frequency (e.g. One channel 6H); 2)

algorithms based on different frequencies but the same polarization such as the frequency

33 mode of the Comiso Bootstrap algorithm (Bootstrap f); 3) algorithms based on different

1 polarizations but the same frequency such as the polarization mode of the Comiso Bootstrap

2 algorithm (Bootstrap p); 4) algorithms based on at least two frequencies and/or polarizations

3 like the NASA-Team algorithm (NASA_Team).

A fifth type of algorithms are is given by the so-called hybrid algorithms. These combine two 4 or more of the above-mentioned types of algorithms such like the Eumetsat OSI-SAF 5 algorithm (Eastwood et al., 2012) or SICCI (Ivanova et al., 2015), which combine Bristol and 6 Bootstrap f or CalVal which is identical to Bootstrap f, and the Arctic version of the Comiso 7 Bootstrap algorithm (Comiso et al., 1997; Comiso 2009), which combines Bootstrap_f and 8 Bootstrap p. For the high sea-ice concentrations we focus on in this paper, these two hybrid 9 algorithms are almost identical to the algorithm, which is employed at high sea-ice 10 concentrations, that is Bristol in case of the OSI-SAF (zero weight at \leq 40%, full weight at \geq 11 80%) and SICCI (zero weight at < 70%, full weight at \geq 90%) algorithms and Bootstrap p in 12 case of the Comiso Bootstrap algorithm. Therefore we do not show the analysis for the hybrid 13 14 algorithms in this paper.

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2.4 Sea-ice age data set

Brightness temperature changes over Arctic sea ice are different for first-year ice (FYI) and 17 multiyear ice (MYI) (Eppler et al., 1992). In order to separate these two sea-ice types we use 18 the Arctic sea-ice age data set (Tschudi et al., 2016). This data set is available with weekly 19 temporal resolution, has a grid resolution of 12.5 km x 12.5 km and is based on sea-ice drift 20 21 trajectory analysis (Tschudi et al., 2010; Fowler et al., 2003). We prefer this data set over other approaches beingcause the latter are usually limited to the winter period (e.g. Comiso, 22 2012; Swan and Long, 2012). We co-locate the sea-ice age data set with the MODIS sea-ice 23 parameter data set as follows. For each MODIS data set grid cell we first find the sea-ice age 24 grid cell which center has the smallest distance to the center of the MODIS data set grid cell. 25 Secondly, we select a 7 x 7 grid cell array around that first co-located grid cell from the sea-26 ice age data set. Subsequently, we count the numbers with which a certain sea-ice age occurs 27 28 within the co-located 7x7 grid cell array and divide by the total number (for every ice age) of counts. We assign the ice type FYI to the respective MODIS data-set grid cell only if more 29 than 90% of the counts indicate a sea-ice age of 1 year. We correspondingly assign the ice 30 type MYI only if more than 90% of the counts indicate a sea-ice age of 3 years or older. All 31 other grid cells are kept without any classification into an ice type. In our co-located data set, 32 FYI is assigned to MODIS data set grid cells in the northern Chukchi Seas and parts of the 33

central Arctic Ocean as well as north of Franz-Josef Land (Figure 1 a). Multi-year ice is
 assigned to MODIS data set grid cells north of the Canadian Arctic Archipelago (Figure 1 b).
 The latter region is also the area where the largest number of co-locations is found whereas
 only few co-locations are found in the northern Chukchi Sea (Figure 1 c).

5

6 3 Results

7 3.1 MODIS sea-ice parameters

8 We show the temporal development of the daily sea-ice parameters obtained with MODIS (subsection 2.1) for June to August 2009 in Figure 3. These include MODIS sea-ice 9 concentration, the net sea-ice surface fraction, the net surface-water fraction, which is the 10 open-water fraction plus the melt-pond fraction, and the melt-pond fraction for each day and 11 each co-located grid cell. No further averaging is applied and we show all grid cells regardless 12 of ice type. Gaps in the time series and the varying number of data points are caused by daily 13 variations in cloud cover and the decrease in sea-ice cover from June to August. Only grid 14 15 cells with MODIS sea-ice concentration > 90% are shown; the number of grid cells fulfilling this criterion is decreasing with progressing melt season. 16

During the first 2-3 weeks the MODIS melt-pond fraction in our data set remains near zero. 17 Then the melt-pond fraction starts to increase, first slowly: days 20-30 (5th and 6th 5-day 18 period or pentad of June), then rapidly: days 30-45 (1st to 3rd pentad of July). After a short 19 20 plateau, where the melt-pond fractions remains near 35%, it first declines rapidly to about 20% at days 55-60 (last pentad of July) and then more slowly to about 15% until the end of 21 22 our study period (Aug. 31). Throughout June, MODIS sea-ice concentrations are close to 100% (until day 30), and then there is more variability around 90-95% after day 55. Net total 23 water fraction and net sea-ice surface fraction, are linked to the previous two parameters and 24 25 add up to 100%.

26 **3.2 AMSR-E sea-ice concentration compared to MODIS sea-ice** 27 **concentration**

We first compare sea-ice concentrations derived with the algorithms listed in Table 4 from AMSR-E brightness temperatures (sub-sections 2.2 and 2.3) with MODIS sea-ice concentrations (sub-section 2.1) with the aim to illustrate how summer-time AMSR-E sea-ice concentrations compare to an independent sea-ice concentration estimate. We include all data

with MODIS sea-ice concentrations > 20%. We find different agreement between AMSR-E 1 and MODIS sea-ice concentrations for the different algorithms for June (Table 5), July 2 (Figure 4, Table 6) and August (Table 7) of the year 2009. Common forto all algorithms is a 3 cluster of data, which is more or less centered at an AMSR-E sea-ice concentration of 100%. 4 Slopes of a linear regression forced through the point (0,0) range from 0.90 for Bootstrap p 5 (Figure 4 e) to 1.12 for Bootstrap f (Figure 4 b). Values of the root mean square difference 6 (RMSD) between AMSR-E and MODIS sea-ice concentrations vary between 7.4 % for NT2 7 (Figure 4 f) and 18.1 % for Bootstrap_f. Only few values of MODIS sea-ice concentrations < 8 9 80% exist. For these, AMSR-E sea-ice concentrations are generally biased low by between 10 and 20% - except for the NT2-algorithm (Figure 4 f). The ASI and NT2 algorithms cut off 10 sea-ice concentrations once they exceed 103% and 100% ice concentration, respectively. We 11 exclude these two algorithms therefore out of the following quality ranking. 12 We take the slope (the closer to 1 the better), the correlation (the higher the better) and the 13 14 RMSD (the lower the better) as a quality measure and find the NASA-Team algorithm to 15 outperform all other algorithms listed in Table 4 for June (Table 5) – no matter whether we use all grid cells or only FYI or MYI grid-cells (see sub-section 2.4). For July (Table 6), the 16 NASA-Team algorithm is as good as the Near90 lin algorithm. For August (Table 7), best 17 slopes are obtained for the Bootstrap p algorithm while lowest RMSD values are obtained for 18 the NASA-Team algorithm. Note that the number of FYI grid cells is extremely low for 19 August and that the numbers given in Table 7 for FYI should not be over-interpreted. 20 21 The average correlation, computed from six algorithms, decreases from June: 0.72 ± 0.07 over 22 0.53 ± 0.18 in July to 0.42 ± 0.10 in August. We believe this can partly be attributed to the 23 known limitations of AMSR-E and other passive microwave sea-ice concentration retrieval algorithms during melting conditions due to varying snow properties and due to melt ponds. It 24 is difficult to quantify the sensitivity of such algorithms to snow-property variations, because 25 their magnitude and spatiotemporal distribution is unknown. In contrast, it should be possible 26 to quantify the sensitivity of such algorithms to melt ponds, because these should theoretically 27 be detected as open water. Consequently, such algorithms should provide an open-water 28 29 fraction which is the sum of the fractions of leads and openings between the ice floes and of the melt ponds on the sea ice. In order to isolate the influence of the melt ponds one needs to 30 investigate only the high ice concentration areas. The MODIS sea-ice parameter data set (sub-31 section 2.1), which we use, is ideal for this purpose, because it provides the open-water 32

fraction (in leads and openings), the melt-pond fraction (on sea ice) and the net sea-ice surface

fraction. By limiting our investigation to MODIS sea-ice concentrations > 90% we can take
the MODIS ice-surface fraction as an inverse measure of the melt-pond fraction.

3

3.3 AMSR-E sea-ice concentration compared to MODIS ice-surface fraction

We compare AMSR-E sea-ice concentration (sub-section 3.2) with the MODIS ice-surface 4 fraction (sub-section 2.1) for grid cells with MODIS sea-ice concentration > 90%. For the 5 range of observed MODIS ice-surface fractions between about 50 and 100%, we find quite 6 different ranges of AMSR-E sea-ice concentrations (Figure 5). For the Bootstrap f and 6H 7 algorithm, AMSR-E sea-ice concentrations range between 80 and 150% and 75 and 125%, 8 9 respectively, and suggest a relatively well-defined linear relationship (Figure 5 a,b). For July, we find a slope between AMSR-E sea-ice concentration and MODIS ice-surface fraction of 10 1.44 and 1.34, respectively. The respective correlation coefficients are 0.855 and 0.820. For 11 the Bootstrap p and NASA Team algorithm, AMSR-E sea-ice concentrations tend to cluster 12 in a point cloud with a shallower slope and a less well defined linear relationship (Figure 5 13 c,e). For July, the corresponding slopes are 1.14 and 1.23, respectively, and the respective 14 correlation coefficients are 0.428 and 0.666. AMSR-E sea-ice concentrations derived with the 15 ASI and the NT2 algorithm stay within 75 and 100% and within 85 and 100%, respectively 16 17 (Figure 5 d,f); the small range in AMSR-E sea-ice concentrations of these two algorithms can clearly be attributed to the cut off mentioned in the sub-section 3.2. 18

We obtain slope, correlation coefficient, and RMSD values of all eight algorithms (see Table 19 4) separately for i) all grid cells, and iii) only the FYI grid cells, and iii) only the MYI grid cells 20 (see sub-section 2.4) and summarize these in Tables 8 to 10 for June, July, and August. For 21 August we exclude all values obtained for FYI grid cells because of their low count of 44 22 (Table 10). We find an increase in the slopes from June to July for all algorithms, which is 23 24 followed for July to August by a decrease for 6H, Bootstrap f and Bristol algorithms but a 25 further increase for Bootstrap p and Near90 lin algorithms from July to August. Correlations between AMSR-E sea-ice concentrations and MODIS ice-surface fractions are below 0.4 in 26 June (Table 8) <u>independent of using all, FYI, or MYI grid cells</u>. In contrast, for July (Table 27 9) we obtain correlations > 0.8 for 6H, Bootstrap f, and Bristol algorithms – together with the 28 largest slopes. These suggest a considerable sensitivity of these algorithms to the melt-pond 29 30 fraction. This does also apply to MYI grid cells. For July, the lowest correlation of 0.43 is obtained for the Bootstrap p algorithm - together with the smallest slope (Table 9). This 31 suggests the weakest sensitivity to the melt-pond fraction amongfor the investigated 32 algorithms. 33

We carried out the same inter-comparison using a MODIS sea-ice concentration threshold of 1 98% (not shown) instead of 90%. By using 98%, no results can be obtained for August 2 3 because of too few valid data. For June and July slopes remain similar to those in Tables 8 4 and 9. For June, correlations are considerably smaller compared to using 90%. Correlations are a bit higher for July. Despite this better correlation in July, the peak melting period (see 5 Figure 3), we decided to keep the 90% threshold to ensure a large enough number of data 6 points. The results of the previous paragraph remain the same for 90% and 98% MODIS sea-7 ice concentration threshold. 8

We conclude: For one type of algorithms, AMSR-E sea-ice concentration is linearly related to
the MODIS ice-surface fraction, as we hypothesized in the introduction, i.e., AMSR-E sea-ice
concentrations are sensitive to the melt-pond fraction. These are the 6H, Bootstrap_f, and
Bristol algorithms. For the other algorithms investigated, such a linear relationship is
increasingly less pronounced in the following, descending order: NASA-Team, Near90_lin,
Bootstrap_p.

15

17

16 4 Discussion

4.1 Sea-ice concentration algorithm parameter space

To explain the different sensitivities to the melt pond fraction (sub-section 3.2), we start with 18 an illustration of the distribution of AMSR-E brightness temperatures and contemporary 19 20 MODIS ice-surface fractions of July 2009 in the parameter spaces of four of the algorithms (Figure 6). These algorithms are: NASA-Team, ASI or Near90 lin, as both rely on brightness 21 temperatures near 90 GHz, and the two Bootstrap algorithms. Bootstrap f and Bootstrap p 22 are the two algorithms with the highest and the lowest sensitivity of AMSR-E sea-ice 23 concentrations to melt-pond fraction, respectively (Figure 5, Tables 8 to 10). The NASA-24 Team algorithm is among the most used ones and the ASI and Near90 lin algorithm have the 25 advantage of a substantially finer grid resolution thanks to using the near 90 GHz channels. In 26 27 every parameter space we show the following items:

I. A winter-time AMSR-E brightness temperature distribution for open water (black dots) and AMSR-E NT2 sea_-ice concentration > 90% (white dots). The spread of the black dots results from the weather influence over open water. We refer to these as winter data points or winter brightness temperatures in the following text.

II. Winter-time open water (white cross) and sea ice (black crosses) tie points obtained
 from Ivanova et al. (2015) and used to compute the AMSR-E sea-ice concentration
 (see sub-section 2.3 for an explanation of why we use winter tie points).

4 III. Red arrows denote the direction of increasing sea-ice concentration.

IV. AMSR-E brightness temperatures of our data set, i.e. only for MODIS sea-ice
 concentration > 90% for the month of July, color coded with the contemporary
 MODIS ice-surface fraction. We refer to these as summer data points or summer
 brightness temperatures in the following text.

9 V. A red line connecting FYI and MYI tie points denotes the ice line.

10

11

4.1.1 NASA-Team algorithm

For NASA-Team algorithm (Figure 6 a) summer data points from July 2009 are located well 12 within the cloud of winter data points (see I.). The NASA-Team tie-point triangle (Cavalieri 13 et al., 1990) is approximated by the dashed white lines and the red (ice) line (see V.). A 14 considerable number of Many summer data points are located to the left of the ice line. For 15 these data points, NASA-Team sea-ice concentrations exceed 100% and MODIS ice-surface 16 fractions are between 80 and 100% (see the color scale). To the right of the ice line, summer 17 data points coincide with MODIS ice-surface fractions of ~70% and are supposed to provide 18 NASA-Team sea-ice concentrations between 80 and 100% (compare Figure 5 c). 19

20 21

4.1.2 ASI or Near90_lin algorithm

For the ASI or Near90_lin algorithm (Figure 6 b) summer data points from July 2009 are also 22 located well within the cloud of winter data points. A considerable number of the summer 23 data points are located above the ice line (see V.). For these data points, ASI or Near90_lin 24 25 sea-ice concentrations exceed 100%. Most of the summer data points located below the ice line are corresponding toresult in ASI or Near90 lin sea-ice concentrations between 80 and 26 100%. The associated MODIS ice-surface fractions decrease from ~100% close to the MYI 27 tie point to $\sim 70\%$ when following the summer data points towards the FYI tie point and 28 beyond (secompare Figure 5 d). 29

30

1 4.1.3 Bootstrap_f algorithm

For the Bootstrap f algorithm (Figure 6 c), a substantial number of summer data points from 2 July 2009 fall outside the winter data-point cloud-(see I.). The majority of the summer data 3 points are located above the winter ice line (red: our tie points, black: Comiso et al. (1997)). 4 The locations of these data points relative to the open-water tie point, the winter ice lines and 5 the tie points for MYI and FYI suggests, that Bootstrap f sea-ice concentrations exceed 100% 6 by up to a few ten percent (compare Figure 5 b). The distance between the open-water tie 7 point and the winter ice lines increases from left (MYI tie point) to right (FYI tie point). 8 Similar MODIS ice-surface fractions tend to intersect the winter ice lines. Therefore, the over-9 estimation of Bootstrap f sea-ice concentration decreases with decreasing MODIS ice-surface 10 fraction (see also Figure 5 b). 11

4.1.4 Bootstrap_p algorithm

12

For the Bootstrap p algorithm (Figure 6 d), only few summer data points from July 2009 are 13 located closely above the winter ice lines (see also sub-section 4.1.3). Consequently, 14 Bootstrap p sea-ice concentrations do not exceed 110% (compare Figure 5 e). Similar to As 15 for the Bootstrap f algorithm (Figure 6 c) only very few summer data points are located close 16 to the MYI tie point. The majority of those data points which are associated with MODIS ice-17 surface fractions ~70% are located in a relatively broad band parallel to the winter ice lines 18 19 close to the FYI tie point. The distance between the open-water tie point and the winter ice lines increases upward along these lines. We therefore observe a wide range of Bootstrap p 20 sea-ice concentrations between 70 and ~100% at MODIS ice-surface fractions of ~70% 21 22 (compare Figure 5 e).

23 4.2 Summer sea-ice tie points for the Bootstrap algorithm

We used open-water and sea-ice tie points representative of winter conditions (sub-section 24 2.3). We are not aware of summer sea-ice tie points for the ASI or Near90 lin and the NASA-25 Team algorithms, but they do exist for the Bootstrap algorithm. The solid cyan line in Figure 26 6 c) denotes the summer sea-ice tie point for the Bootstrap f algorithm taken from Comiso et 27 al. (1997). For the Bootstrap p algorithm (Figure 6 d), the solid and dashed cyan lines denote 28 29 the summer sea-ice tie points for the periods July 1-18 and July 19 to August 4, respectively. For the period after August 4, the summer ice line coincides with the winter ice line (black 30 line in Figure 6 d). 31

We use MODIS ice-surface fractions of the period June 20 to July 5 to derive summer tie
points from our summer brightness temperatures. We select only data of MODIS ice-surface
fractions > 97.8% and of vertically polarized 37 GHz brightness temperatures > 250 K. We
doid not discriminate between different ice types. We compute summer sea-ice tie points
(Table 11) at 19, 37 and 89 GHz and from these also derive values of the normalized
brightness-temperature polarization difference (PR). These summer sea-ice tie points are-also
added to Figure 6 c) and d) as cyan crosses.

8 The potential impact of using summer instead of winter sea-ice tie points will be discussed in9 the following sub-section.

10 4.3 Temporal evolution

During the melting season, changes in the snow and sea-ice microphysical properties, the associated variations in AMSR-E brightness temperatures, and the retrieved AMSR-E sea-ice concentrations can occur within a few days. It is likely that Figures 4 to 6 do blur such temporal variations which, we think, need to be discussed to understand the observed differences in the sensitivity of the AMSR-E sea-ice concentration algorithms to the meltpond fraction. Therefore we sub-divide the MODIS and AMSR-E data sets used into pentads (5-day periods) and discuss the temporal evolution for the four algorithms shown in Figure 6.

18

4.3.1 NASA-Team algorithm

For the NASA-Team algorithm, 1st pentad (June 1-5, Figure 7 a), most summer data points 19 are located at PR19 = -0.03 (compare Table 11) and a GR3719 value between -0.05 and -20 0.01. MODIS ice-surface fractions are ~100%. About 20% of the data points belong to the 21 MYI class while only 7 data points belong to the FYI class (see subsection 2.4). NASA-Team 22 sea-ice concentration and MODIS ice-surface fraction agree well with each other by means of 23 slope and correlation coefficient. Later, summer data points cover a larger PR19 range: 0.02 24 to 0.08, and a larger GR3719 range: 0.0 to -0.09 (June 16-20, Figure 7 b) and: 0.0 to -0.12 25 (July 1-5, 6-10, Figure 7 c,d). We explain the larger PR19 range by an increase in snow 26 27 density (Table 2) and snow wetness (Table 1). We explain the expansion of GR3719 towards 28 more negative values with an increase in the surface layer snow grain size (Table 3). Figures 7 c, d) coincide with the onset of widespread melt-pond formation (see Figure 3, days 30 to 40). 29 30 MODIS ice-surface fractions are still mostly > 85% in Figure 7 b), range between $\sim 100\%$ and \sim 70% in Figure 7 c) and decrease to between \sim 90% and 60% in Figure 7 d). With further melt 31

progress, the PR19-GR3719 cloud shrinks to GR3719 values <u>betweenof</u> +0.01 <u>and</u>to -0.06 on
 July 21-25 (Figure 6 f). At this stage MODIS ice-surface fractions are between 60% and 80%.

3 NASA-Team sea-ice concentrations exceed 100% on June 16-20 and especially July 1-5 (Figures 7 b,c) with values up to 120%. We find only few values > 100% for July 21-25, 4 5 shortly after peak melt (Figure 7 f). After the good agreement between NASA-Team sea-ice concentration and MODIS ice-surface fraction for June 1-5 (Figure 7 a) it breaks down. 6 7 During July the correlation between NASA-Team sea-ice concentration and MODIS icesurface fraction increases again, together with the slope, which reaches 1.31 for the-pentad 8 July 21-25 (Figure 7 f, compare Table 9). Correlations are ~0.5 for most of July which 9 corresponds to an explained variance of about 25%. Therefore, after the onset of wide-spread 10 melt-pond formation beginning of July 2009, NASA-Team sea-ice concentrations and 11 12 MODIS ice-surface fractions are linearly related to some degree, i.e. the NASA-Team 13 algorithm is sensitive to melt ponds. The relatively low correlation highlights the importance 14 of other processes such as changes in those snow and sea-ice properties, which influence GR3719. These can be snow grain size and wetness (Tables 1 and 3) and, after snow melt, 15 sea-ice salinity, roughness, and density [Eppler et al., 1992; Hallikainen and Winebrenner, 16 1992]. 17

18

4.3.2 Bootstrap_f algorithm

For the Bootstrap f algorithm, 1st pentad (June 1-5, Figure 8 a), most summer data points are 19 associated with MODIS ice-surface fractions ~100%, are located beyond the upper border of 20 the winter data points and above the winter ice line (see Figure 6 c). Most Bootstrap f sea-ice 21 22 concentrations exceed 100% and over-estimate the MODIS ice-surface fraction-is overestimated. We can attribute these elevated brightness temperatures to elevated snow wetness 23 (and density) which causes a larger increase in the vertically polarized brightness 24 25 temperatures at 37 GHz than at 19 GHz (Table 1). On June 16-20 (Figure 8 b), almost all summer data points are located above the winter ice line and almost all Bootstrap f sea-ice 26 27 concentrations are > 100%; maxima exceed 140%. The <u>A</u> cluster of MODIS ice-surface 28 fractions can be identified atof ~95% which coincides with athe cluster of Bootstrap f sea-ice 29 concentrations centred at 130%. Until July 1-5 (Figure 8 c), the summer data points cloud gradually expands towards lower values. Associated MODIS ice-surface fractions are lowest 30 (~70%) along the bottom of the cloud and highest (~95%) at its left end. We attribute the 31 latter to melt-refreeze cycles causing an increase in snow grain size associated with a smaller 32

brightness-temperature decrease at 19 GHz than at 37 GHz (Table 3). These grid cells at the 1 left end of the cloud are responsible for the Bootstrap f sea ice concentrations of $\sim 140\%$ 2 (compare Figure 8 c) and 6 c). Throughout the remaining three pentads (Figure 8 d) to f). 3 summer data points are shiftingshifted towards lower 19 GHz brightness temperatures and are 4 covering a smaller brightness temperature range at both frequencies. We attribute this to 5 complete snow melt. Snow wetness and grain size variations do not influence the brightness 6 temperatures anymore. MODIS ice-surface fractions are between 60 and 80% now (Figure 8 7 f), compare Figure 7 f). Maximum Bootstrap_f sea-ice concentrations have decreased to 8

9 \sim 120% until July 21-25.

The good agreement between Bootstrap f sea-ice concentration and MODIS ice-surface 10 fraction in the 1st June pentad breaks down during June and re-emerges during July. Between 11 the 3rd pentad of July and the 2^{nd} pentad of August pentad-average correlations are ~0.65 12 explaining > 40% of the variance. The average slope is 1.45 for these six $\frac{1}{2}$ pentads. Therefore, 13 14 with the onset of wide-spread melt-pond formation also-Bootstrap f sea-ice concentrations and MODIS ice-surface fractions are linearly related to each other, i.e., the Bootstrap f 15 algorithm is sensitive to melt ponds. This sensitivity is stronger than for the NASA-Team 16 algorithm (sub-section 4.3.1) which could be explained by a smaller influence of the other 17 surface properties mentioned above in the previous sub-section. 18

It is difficult to quantify how this result would change by using summer sea-ice tie points, 19 which we did not use to compute AMSR-E sea-ice concentrations with the two Bootstrap 20 21 algorithms for the reasons given in sub-section 2.3, but did include in Figure 6 c,d) as cyan 22 lines. The distance between the cyan line and the winter ice lines in proximity to the FYI tie 23 point, measured along the dashed white line (Figure 6 c), suggests that we would reduce 24 Bootstrap f sea-ice concentrations by 10% to 15%. Therefore, at the FYIis side of the parameter space, Bootstrap f sea-ice concentrations would be $\sim 100\%$. However, to the left of 25 the FYI tie point the location of the summer data points (Figure 6c), Figure 8 c,d) suggests, 26 that Bootstrap f sea-ice concentrations would still be > 120%. Therefore, using summer sea-27 ice tie points would reduce the slope between Bootstrap_f sea-ice concentrations and MODIS 28 29 ice-surface fractions but whether the correlations would be similarly high and whether we can exclude unknown non-linear effects cannot be answered in the present paper. 30

31

4.3.3

The other algorithms

The temporal evolution of Bootstrap_p sea-ice concentrations in relation to the MODIS ice-1 surface fraction during June is similar to the Bootstrap f algorithm (Supplementary Figure S1 2 3 a,b). One principal difference is the smaller slope we obtain with Bootstrap p sea-ice 4 concentrations compared to the Bootstrap f algorithm: ~0.9 vs. ~1.1 for June 1-5 and ~1.1 vs. 1.3 for July 1-5; also correlations are smaller. Secondly, we find larger variations of 5 Bootstrap p sea-ice concentrations around MODIS ice-surface fractions, for example do 6 Bootstrap p sea-ice concentrations range from 50% to 110% at 90% MODIS ice-surface 7 fraction. We attribute this to the large and polarization dependent sensitivity of 37 GHz 8 brightness temperatures to variations in snow properties (Tables 1 to 3). In June, any linear 9 relationship to the emerging melt-pond coverage is obscured by this sensitivity. During the 10 first two July pentads, scatter is as high as during most of June. Brightness temperatures 11 associated with MODIS ice-surface fractions of ~90% and ~60% are often located right next 12 to each other in the algorithms' parameter space (Supplementary Figure S1 c,d) which is 13 14 different to the Bootstrap f algorithm (Figure 8 c,d). After mid-July, a linear relationship 15 between Bootstrap p sea-ice concentration and MODIS ice-surface fraction emerges. The average slope is 1.25 and correlations increase from 0.34 (July 16-20) to 0.76 (August 6-10). 16 In summary, also the Bootstrap p algorithm is sensitive to melt-ponds. The sensitivity is 17 smaller than for the Bootstrap f algorithm and snow property variations seem to be of larger 18 19 influence.

How does this results change if we use summer sea-ice tie points (Figure 6 d), cyan lines) and 20 21 sub-section 4.3.2)? The early summer ice line (Figure 6 d), solid cyan line) is steeper than the 22 winter ice lines and intersects these close to the FYI tie point. Therefore, close to the FYI tie 23 point and to the right, all summer data points are below the summer ice line causing Bootstrap p sea-ice concentrations < 100%. However, to the left of the FYI tie point, summer 24 data points are located above the summer ice line causing Bootstrap p sea-ice concentrations 25 of up to ~130% close to the MYI tie point (Figure 6 d). Therefore, for data from 2009, using 26 the early summer sea-ice tie points would not generally provide sea-ice concentrations, which 27 28 improve the relationship between Bootstrap p sea-ice concentrations and MODIS ice-surface fractions. The mid-summer ice line (Figure 6 d), dashed cyan line) is located parallel below 29 the winter ice lines. A large fraction of the summer data points is located above the summer 30 ice line causing Bootstrap p sea-ice concentrations > 100%. For instance, for July 21-25 31 (Supplementary Figure S1 f), about 1/3 of the data points would have a Bootstrap p sea-ice 32 concentration > 100%; currently: 3 data points. Therefore, for data from 2009, using the mid-33

summer sea-ice tie points would increase Bootstrap_p sea-ice concentrations <u>and</u> increaseing
the slope between these and MODIS ice-surface fractions, but would not necessarily improve
the correlation. Compared to the winter sea-ice tie points, using the early-summer (midsummer) sea-ice tie points would result in a decreased (enhanced) sensitivity of the
Bootstrap p algorithm to melt ponds.

6 The temporal development of brightness temperatures, sea-ice concentrations and ice-surface fractions obtained with the Near90 lin algorithm (Supplementary Figure S2, Figure 6 b) is 7 comparable to that obtained with the Bootstrap_p algorithm (Supplementary Figure S1). The 8 scatter in summer data points and the scatter between Near90 lin sea-ice concentrations and 9 MODIS ice-surface fractions is a little less pronounced and peaks earlier. We attribute the 10 scatter again to snow property variations (Table 1-3). For the smaller electromagnetic 11 wavelength at 89 GHz compared to 37 GHz, scattering by coarse-grained snow is more 12 effective than the impact of snow wetness which is evident in the migration of summer data 13 14 points towards lower values (compare Supplementary Figures S1 b) and S2 b). Maximum Near90 lin sea-ice concentrations of $\sim 120\%$ (Supplementary Figure S2 b) are larger than we 15 expect from comparison with Figure 6 b) and can possibly be attributed to an unaccounted 16 weather influence in the open-water tie point (Figure 6b), white line). After mid-July, 17 correlations increase to their maximum in August 6-10 of 0.81. Slopes are considerably larger 18 than for the Bootstrap p sea-ice concentration and vary around 1.33. Both, sSlopes and 19 correlations vary considerably between pentads which we attribute mainly to the larger 20 21 weather influence at 89GHz. Enhanced sensitivity of the smaller electromagnetic wavelength 22 at 89GHz to-of surface property variations, be it remaining or new snow (Grenfell, 1986) or 23 sea-ice surface wetness changes, at the smaller electromagnetic wavelength at 89 GHz might also contribute. We conclude that the Near90 lin algorithm or other algorithms employing 24 near-90 GHz data such as the ASI algorithm, is sensitive to melt ponds only to some degree. 25 Snow and sea-ice property variations but also the weather influence impact sea-ice 26 concentration retrieval with this type of algorithm as much as or even —more than we 27 observetained for the Bootstrap p algorithm. 28

With respect to the 6H algorithm and the Bristol algorithm we state, that both algorithms reveal a temporal development of slopes and correlations between AMSR-E sea-ice concentrations and MODIS ice-surface fractions (Supplementary Figures S3 and S4, Tables 8-10), which are similar to the Bootstrap_f algorithm. Both algorithms, 6H more than Bristol,
 are sensitive to melt ponds.

3

4.3.4 Implications for summer sea-ice concentrations

A MODIS ice-surface fraction value of 60% can in reality be anything between A) 100% sea ice with 40% melt-pond fraction and B) 60% sea ice with 0% melt-pond fraction. Slopes between the AMSR-E sea-ice concentration and the MODIS ice-surface fraction obtained, for example, for the NASA-Team algorithm, of 1.31 (Figure 7 f) would convert 60% MODIS icesurface fraction into 78% NASA-Team sea-ice concentration. In case B) this would be an *over-estimation* by 18%, while in case A) this would be an *under-estimation* by 22%.

10 We compute the average slope and correlation values of all algorithms, except ASI and NT2, for the 6 pentads July 11-15 to August 6-10 together with resulting over- or under-estimation 11 of case A and case B actual sea-ice concentrations for which we chose ice-surface fractions of 12 13 60% and 80%. The Bootstrap_f algorithm is most sensitive to melt ponds (highest slope), followed by the Bristol and 6H algorithms (Table 12). The Bootstrap p algorithm is least 14 sensitive to melt ponds (lowest slope), followed by the NASA-Team algorithm. This 15 sensitivity is most pronounced for the Bristol algorithm (largest correlation), followed by the 16 Bootstrap f algorithm. The sensitivity is least pronounced for the Near90 lin algorithm 17 (smallest correlation), followed by the Bootstrap p algorithm. Most pronounced means that 18 snow and sea-ice property variations as well as the weather influence have a comparably 19 20 small influence. These variations have a larger influence on AMSR-E sea-ice concentrations retrieved with an algorithm with a less pronounced sensitivity to melt ponds. The algorithms 21 22 with the largest sensitivity to melt-ponds interestingly provide the smallest under-estimation of the concentration of melt-pond covered sea ice and the largest over-estimation of the 23 concentration of non-ponded sea ice (e.g. the Bootstrap f and Bristol algorithms, Table 12). 24 25 The algorithms with the smallest sensitivity to melt ponds provide the largest underestimation of the concentration of melt-pond covered sea ice and the smallest over-estimation 26 27 of the concentration of non-ponded sea ice (e.g. Bootstrap p, Table 12).

Using summer sea-ice tie points for the Bootstrap_f algorithm would presumably reduce the mean slope as discussed in sub-section 4.3.2, leading to smaller under- and over-estimation of case A and case B sea-ice concentrations compared to Table 12. Using the mid-summer tie point for the Bootstrap p algorithm would, in the contrary, presumably increase the mean slope as discussed in section 4.3.3, leading to a larger under- and over-estimation of case A
and B sea-ice concentrations, respectively, compared to Table 12.

3 5 Conclusions

We investigate the sensitivity to melt ponds of eight sea-ice concentration retrieval algorithms 4 5 based on satellite microwave brightness temperatures by comparing contemporary daily estimates of sea-ice concentration and melt-pond fraction. We derive gridded daily sea-ice 6 7 concentrations from Advanced Microwave Scanning Radiometer aboard Earth Observation Satellite (AMSR-E) brightness temperatures of June to August 2009. We use a consistent set 8 of tie points to aid inter-comparison of the algorithms. We derive the gridded daily fraction of 9 melt-ponds, open water between ice floes and ice-surface fraction from contemporary 10 Moderate Resolution Spectroradiometer (MODIS) reflectance measurements with a neural 11 12 network based classification approach. We discuss potential uncertainty sources of this data and conclude that MODIS ice-surface fractions are as accurate as 5-10%. We carry out the 13 14 comparison of AMSR-E and MODIS data sets at 100 km grid resolution.

AMSR-E sea-ice concentrations agree fairly well with MODIS sea-ice concentrations, the sum of the ice-surface fraction and the melt-pond fraction, with slopes of a linear regression between 0.90 and 1.16. However, for some algorithms AMSR-E sea-ice concentrations scatter widely for MODIS sea-ice concentrations larger than 80%. We note that the eventual overestimation of the concentration of the sea ice in between the melt ponds, to produce seemingly 'correct' sea-ice concentrations that include the melt ponds, will result in incorrectly overestimating the concentration of sea ice in areas with real open water.

We isolate the influence of melt ponds by comparing AMSR-E sea-ice concentrations with 22 MODIS ice-surface fractions only for grid cells with MODIS sea-ice concentrations above 23 24 90%. By doing so we can use the ice-surface fraction instead of the melt-pond fraction as a measure of the impact of melt ponds and can keep the effect of potential misclassification 25 26 between the two spectrally close surface types, open water and melt ponds, as small as possible. For most of June, we find a non-linear relation between both data sets. We attribute 27 this to the influence of snow-property variations impacting the microwave brightness 28 temperatures and a still small melt-pond fraction. After June, for one group of algorithms, 29 e.g., the Bristol and Comiso Bootstrap frequency mode (Bootstrap f) algorithms, sea-ice 30 31 concentrations are linearly related to MODIS ice-surface fractions. For other algorithms, e.g.,

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Formatiert: Schriftart: (Standard) Arial, 12 Pt., Fett 1 Near90GHz and Comiso Bootstrap polarization mode (Bootstrap_p), the linear relationship is

2 weaker and develops later in summer.

3 We take the degree of correlation between AMSR-E sea-ice concentration and MODIS icesurface fraction as a measure of an algorithms'how sensitivitye a respective algorithm to the 4 melt ponds is and use the obtained linear regression slope to estimate differences between 5 actual and retrieved sea-ice concentration. All algorithms under-estimate the sea-ice 6 concentration of 100% sea ice with an open-water fraction of 40% due to melt ponds (case A) 7 by between 14% (Bootstrap_f) and 26% (Bootstrap_p). The under-estimation reduces to 0% 8 for a melt-pond fraction of ~20%. The concentration of sea ice with a similarly large open-9 water fraction due to leads and openings between the ice floes (case B) is over-estimated by 10 between 2614% (Bootstrap f) and 1426% (Bootstrap p) for 60% sea-ice concentration and 11 by 20% for all algorithms for 80% sea-ice concentration. 12 One next step would be to extend the analysis to more years to confirm the results of our case 13 study with a larger number of data. Currently, at pentad scale, the number of data is too small

study with a larger number of data. Currently, at pentad scale, the number of data is too small
to use – as an important next step – a higher MODIS sea-ice concentration threshold of 98%
instead of 90% to isolate the influence of melt ponds. Using such a higher threshold aAt
monthly scale, e.g. for July, results in an increase of the correlation between AMSR-E sea-ice
concentrations and MODIS ice-surface fraction increases from 0.86 to 0.92 (Bootstrap_f),
from 0.85 to 0.91 (Bristol), and from 0.67 to 0.76 (NASA-Team) while the slopes of the

For reasons outlined in the description of the algorithms, we use a consistent set of sea-ice tie points derived for winter conditions. By applying published summer sea-ice tie points for the Bootstrap algorithms we find that the slopes of the linear regression would be reduced for Bootstrap_f but not for Bootstrap_p. As a result Bootstrap_f would under-estimate sea-ice concentrations for case A less but over-estimate sea-ice concentrations for case B more.

We suggest, that algorithms being more sensitive to melt ponds, could be easier optimized 26 further, because the influence of snow and sea-ice surface property variations, which 27 distribution is unknown, seems to be less pronounced while methods to derive melt-pond 28 fraction, which would be needed for the optimization, have been developed. According to our 29 results, this applies to the Bootstrap f, Bristol, and Near90 lin algorithms, and the CalVal 30 algorithm which is similar to the Bootstrap f mode and is used in the SICCI algorithm. The 31 Bootstrap p and NASA-Team algorithms seem to be less suitable for further optimization. 32 While these seem to have the lowest sensitivity to melt ponds and therefore lowest under-33

estimation for case A, they seem to over-estimate the sea-ice concentration for case B most,
 among the algorithms investigated.

3

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13 NT2 SIC is taken from the AMSR-E/Aqua Daily L3 12.5 km Brightness Temperature, Sea Ice

- 14 Concentration, & Snow Depth Polar Grids product
- 15 (http://nsidc.org/data/docs/daac/ae_si12_12km_tb_sea_ice_and_snow.gd.html, (Cavalieri et
- 16 al., 2014)) available from NSIDC.
- 17

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 doi:10.1016/j.rse.2015.03.012, 2015.

- 1 Table 1: Typical values of changes in brightness temperature due to changes in snow wetness.
- 2 Abbreviations TB, PR, GR, V, and H denote brightness temperature, normalized brightness
- 3 temperature polarization difference ("polarization ratio"), normalized brightness temperature
- 4 frequency difference ("gradient ratio"), vertical, and horizontal (polarization), respectively.
- 5 Abbreviations E92, W14, and G92 refer to Eppler et al. (1992), Willmes et al. (2014), and
- 6 Garrity (1992), respectively.

Snow wetness	E92	W14	W14	G92
Change by	Typical May to June increase	Average May to June	Melt after refreeze	+ 2%
	(~ 2%)	increase		
TB19H	+25 K	+16 K	+5 K	
TB19V	+20 K	+14 K	+7 K	
TB37H	+40 K	+32 K	+25 K	+34K
TB37V	+30 K	+32 K	+10 K	+15K
TB89H		+50 K		
TB89V		+60 K		
PR19			+0.02	
GR3719			+0.05	

- 1 Table 2: Typical values of changes in brightness temperature due to changes in snow density.
- 2 For abbreviations TB, PR, GR, V, and H see Table 1. Abbreviations F98 and B15 refer to
- 3 Fuhrhop et al. (1998) and Beitsch (2014), respectively.

Snow density	F98	B15
Change by	+200 kg/m³	+50 kg/m³
PR19	+0.04	
GR3719	0.00	
TB89V-TB89H		+2.5 K

- 1 Table 3: Typical values of changes in brightness temperature due to changes in snow grain
- 2 size. For abbreviations TB, PR, GR, V, and H see Table 1. Abbreviations F98, W14, and G92
- 3 refer to Fuhrhop et al. (1998), Willmes et al. (2014), and Garrity (1992), respectively.

Snow grain size	F98	F98	W14	G92
	Upper snow	Bottom snow	Upper snow layer	
	layer	layer		
Change by	+0.5mm	+0.5mm	Increase due to	Increase due to surface
			surface refreezing	crust formation
GR3719	-0.025	+0.05	-0.04	
PR19	+0.01	+0.02	0.0	
TB37V			-20K	-10K
ТВ37Н			-35K	-20К
TB19V			-10K	
ТВ19Н			-15K	

Algorithm	Acronym	Reference	Frequencies/Combination
Bootstrap_p	BP	Comiso, 1986	37V, 37H
Bootstrap_f/ CalVal	BF	Comiso, 1986	19V, 37V
Bristol	BR	Smith, 1996	19V, 37V, 37H
NASA Team	NT	Cavalieri et al., 1984	19V, 19H, 37V
ASI	ASI	Kaleschke et al. 2001	85V, 85H
Near 90GHz linear	N90	Ivanova et al., 2014	85V, 85H
One_channel (6H)	6Н	Pedersen, 1994	6Н
NASA Team 2	NT2	Markus and Cavalieri, 2000	19V, 19H, 37V, 85V, 85H
Eumetsat OSI-SAF*	?	Eastwood et al., 2012	Bristol, Bootstrap_f
SICCI*	?	Ivanova et al., 2015	Bristol, Bootstrap_f
Arctic Bootstrap*	?	Comiso et al., 1997; Comiso, 2009	Bootstrap_f, Bootstrap_p

1 Table 4. The sea ice concentration algorithms. *Analysis not shown in this study.

- 1 Table 5. Statistical parameters of the comparison AMSR-E sea-ice concentration versus
- 2 MODIS sea-ice concentration (see Figure 4) for June 2009. Each column gives the value for
- all grid cells with MODIS sea-ice concentration > 20%, the multiyear (MYI) ice grid cells and
- 4 the first-year ice (FYI) grid cells (see sub-section 2,-4). Slopes close<u>std</u> to 1, highest
- 5 correlations and lowest RMSD values are note<u>d byin</u> bold font.

June	Slope	Correlation	RMSD	Ν
Algorithm	All; FYI;MYI	All; FYI; MYI	All; FYI ;MYI	All; FYI ;MYI
6H	1.16; 1.16; 1.19	0.86; 0.89; -0.28	17.1; 16.6; 18.8	6272; 1127; 649
ASI	1.03; 1.05; 1.04	0.81; 0.86; -0.10	7.7; 10.3; 4.4	
Bootstrap_f	1.27; 1.28; 1.28	0.72; 0.86; -0.50	27.9; 27.7; 30.2	
Bootstrap_p	0.92; 0.92; 0.97	0.62; 0.71; -0.01	13.9; 15.3; 9.0	
Bristol	1.14; 1.15; 1.16	0.75; 0.86; -0.42	16.3; 16.6; 18.6	
NASA-Team	1.00; 1.01; 1.01	0.71; 0.73; 0.32	8.9; 11.7; 6.3	
Near90_lin	1.02; 1.03; 1.07	0.68; 0.81; -0.37	12.2; 13.0; 11.1	
NT2	1.02; 1.04; 1.01	0.69; 0.79; 0.07	5.3; 8.5; 2.1	

- 1 Table 6. <u>Statistical parameters of the comparison AMSR-E sea-ice concentration versus</u>
- 2 MODIS sea-ice concentration (see Figure 4) for July 2009. Each column gives the value for
- 3 <u>all grid cells with MODIS sea-ice concentration > 20%, the multiyear (MYI) ice grid cells and</u>
- 4 the first-year ice (FYI) grid cells (see sub-section 2,4). Slopes closest to 1, highest
- 5 <u>correlations and lowest RMSD values are noted in bold font. Like Table 5 but for July 2009.</u>

July	Slope	Correlation	RMSD	N
Algorithm	All; FYI ;MYI	All; FYI; MYI	All; FYI ; MYI	All ; FYI ;MYI
6H	1.05; 1.08; 1.05	0.62; 0.81; -0.03	11.8; 12.4; 11.9	9612; 967; 634
ASI	1.04; 1.09; 1.04	0.72; 0.83; -0.05	8.4; 11.8; 6.6	
Bootstrap_f	1.12; 1.16; 1.13	0.55; 0.78; 0.14	18.1; 17.7; 20.1	
Bootstrap_p	0.90; 0.94; 0.90	0.62; 0.85 ; -0.22	13.9; 9.9; 14.4	
Bristol	1.04; 1.08; 1.05	0.62; 0.85 ; 0.05	11.7; 10.8; 12.0	
NASA-Team	0.97; 1.00 ; 0.97	0.13; 0.80; -0.16	10.3 ; 8.9 ; 10.4	
Near90_lin	0.98 ; 1.03; 1.00	0.63 ; 0.82; 0.04	10.7; 10.9; 7.3	
NT2	1.04; 1.10; 1.02	0.66; 0.74;-0.03	7.4; 12.1; 5.7	

- 1 Table 7. <u>Statistical parameters of the comparison AMSR-E sea-ice concentration versus</u>
- 2 MODIS sea-ice concentration (see Figure 4) for August 2009. Each column gives the value
- 3 for all grid cells with MODIS sea-ice concentration > 20%, the multiyear (MYI) ice grid cells
- 4 and the first-year ice (FYI) grid cells (see sub-section 2,4). Slopes closest to 1, highest
- 5 correlations and lowest RMSD values are noted in bold font. Like Table 5 but for August
- 6 2009.

August	Slope	Correlation	RMSD	N
Algorithm	All; FYI;MYI	All; FYI;MYI	All; FYI;MYI	All ; FYI ;MYI
6H	1.08; 1.03 ; 1.11	0.48; 0.62 ; 0.22	10.0; 8.1; 11.0	5158; 162; 505
ASI	1.13; 1.15; 1.14	0.55; 0.37; 0.25	12.5; 14.2; 13.0	
Bootstrap_f	1.16; 1.15; 1.19	0.30; 0.49; 0.18	17.7; 15.4; 19.1	
Bootstrap_p	1.00; 0.95; 1.03	0.27; 0.54; 0.44	17.0; 8.8; 6.2	
Bristol	1.10; 1.07; 1.13	0.46; 0.57; 0.35	12.0; 9.5; 12.8	
NASA-Team	1.03; 0.95; 1.06	0.48; 0.53; 0.31	7.9 ; 8.5 ; 8.1	
Near90_lin	1.10; 1.07; 1.11	0.54 ; 0.35; 0.37	11.2; 11.2; 11.4	
NT2	1.10; 1.14; 1.11	0.19; 0.15; 0.08	10.6; 13.8; 10.5	

1 Table 8. Statistical parameters of the comparison AMSR-E sea-ice concentration versus

2 MODIS ice-surface fraction for MODIS sea-ice concentration > 90% (see Figure 5) for June

3 2009. Each column gives the value for all grid cells with MODIS sea-ice concentration >

4 90%, and the respective multiyear (MYI) and first-year ice (FYI) grid cells.

June	Slope	Correlation	RMSD	N
Algorithm	All; FYI ; MYI	All; FYI ; MYI	All; FYI; MYI	All; FYI;MYI
6H	1.23; 1.28; 1.22	0.40; 0.33;-0.14	22.6; 25.9; 21.9	5821; 916; 649
ASI	1.09; 1.16; 1.07	0.09;-0.02;-0.01	10.8; 16.2; 7.6	
Bootstrap_f	1.34; 1.43; 1.32	0.10; 0.36;-0.38	33.8; 38.3; 33.4	
Bootstrap_p	0.97; 1.02; 1.00	0.09;-0.10; 0.02	11.8; 13.9; 8.8	
Bristol	1.20; 1.28; 1.20	0.12; 0.22;-0.31	21.5; 25.8; 21.7	
NASA-Team	1.06; 1.11; 1.04	0.15;-0.15; 0.31	10.8; 16.0; 7.3	
Near90_lin	1.08; 1.15; 1.10	0.09; 0.05;-0.28	13.8; 17.1; 13.8	
NT2	1.07; 1.14; 1.04	0.07;-0.08; 0.06	8.9; 14.2; 5.1	

- 1 Table 9. <u>Statistical parameters of the comparison AMSR-E sea-ice concentration versus</u>
- 2 MODIS ice-surface fraction for MODIS sea-ice concentration > 90% (see Figure 5) for July
- 3 <u>2009. Each column gives the value for all grid cells with MODIS sea-ice concentration ></u>
- 4 <u>90%, and the respective multiyear (MYI) and first-year ice (FYI) grid cells. Like Table 8 but</u>
- 5 for July 2009.

l				
July	Slope	Correlation	RMSD	Ν
Algorithm	All; FYI ; MYI	All; FYI ; MYI	All; FYI; MYI	All; FYI; MYI
6H	1.34; 1.33; 1.33	0.82; 0.56; 0.84	26.8; 26.9; 26.5	7572; 491; 539
ASI	1.30; 1.30; 1.29	0.43; 0.24; 0.36	25.8; 25.1; 26.5	
Bootstrap_f	1.44; 1.42; 1.45	0.86; 0.65; 0.91	34.1; 33.7; 35.1	
Bootstrap_p	1.14; 1.15; 1.11	0.43; 0.15; 0.02	15.9; 15.9; 17.8	
Bristol	1.33; 1.32; 1.32	0.85; 0.65; 0.85	25.9; 25.8; 26.1	
NASA-Team	1.23; 1.21; 1.21	0.67; 0.26; 0.57	19.9; 19.4; 19.8	
Near90_lin	1.24; 1.26; 1.24	0.54; 0.33; 0.41	21.4; 22.6; 22.3	
NT2	1.29; 1.28; 1.26	0.38; 0.36; 0.38	25.3; 23.7; 24.3	

1 Table 10. <u>Statistical parameters of the comparison AMSR-E sea-ice concentration versus</u>

2 MODIS ice-surface fraction for MODIS sea-ice concentration > 90% (see Figure 5) for

3 August 2009. Each column gives the value for all grid cells with MODIS sea-ice

- 4 concentration > 90%, and the respective multiyear (MYI) and first-year ice (FYI) grid
- 5 <u>cells.Like Table 8 but for August 2009.</u>

August	Slope	Correlation	RMSD	Ν
Algorithm	All; FYI ; MYI	All; FYI ; MYI	All; FYI; MYI	All; FYI; MYI
6H	1.28; ; 1.30	0.39; ; 0.28	23.1; ; 24.2	2091; 44; 207
ASI	1.33; ; 1.33	0.50; ; 0.65	26.8; ; 26.5	
Bootstrap_f	1.36; ; 1.39	0.19; ; 0.19	30.3; ; 31.8	
Bootstrap_p	1.21; ; 1.25	0.14; ; 0.79	29.8; ; 19.4	
Bristol	1.31; ; 1.34	0.41; ; 0.51	25.3; ; 26.9	
NASA-Team	1.23; ; 1.26	0.49; ; 0.70	19.0; ; 21.0	
Near90_lin	1.32; ; 1.33	0.54; ; 0.68	25.4; ; 25.8	
NT2	1.29; ; 1.29	0.18; ;-0.14	23.7; ; 23.6	

Table 11. Top row: winter tie points for first-year ice (FYI) and multiyear ice (MYI)
 expressed as normalized brightness temperature polarization difference PR; other rows:
 summer tie points derived as outlined in the text expressed as PR and brightness temperature
 (TB) at vertical (TBV) and horizontal (TBH) polarization. Brightness temperatures are given
 together with one standard deviation.

	Frequency	19 GHz	37 GHz	89 GHz
	PR (winter, FYI;MYI)	0.030; 0.043	0.025; 0.031	0.021; 0.024
	PR (summer)	0.034	0.033	0.021
	TBH (summer) [K]	247.6 ± 6.5	239.0 ± 4.9	226.3 ± 10.0
	TBV (summer) [K]	265.2 ± 2.5	255.5 ± 4.5	235.0 ± 11.8
6				
7				
8				
9				
9				
LO				
11				
12				
12				
13				
L4				
L5				
16				
.0				
L7				
18				
9				
.9				
20				
1				

Table 12. Slope of the linear relationship and correlation between AMSR-E sea-ice 1 2 concentrations and MODIS ice-surface fractions for the six algorithms, which do not cut-off sea-ice concentrations, averaged over the six pentads July 11-15 to August 6-10. For each 3 algorithm, the average value ± 1 standard deviation (stddev), the range in the slope values and 4 5 the range in the correlations are given. (EV) denotes the explained variance. Case A60 and A80 denote 100 % sea-ice concentration with 40% and 20% (apparent) open-water fraction 6 7 due to melt ponds, i.e. 60% and 80% ice-surface fraction, respectively. Case B60 and B80 8 denote 60% and 80% sea-ice concentration in case of 40% and 20% real open-water fraction, i.e. ice-surface fraction = sea-ice concentration. A "*" indicates saturation, i.e. the retrieved 9 AMSR-E sea-ice concentration exceeds 100%. Bold numbers denote the maximum values for 10 mean slope and mean correlation. 11

Algorithm	6H	Bootstrap_f	Bootstrap_p	Bristol	NASA-Team	Near90_lin
Mean slope ±	1.36 ± 0.04	1.44 ± 0.02	1.24 ± 0.03	1.36 ± 0.02	1.29 ± 0.03	1.33 ± 0.03
1 stddev						
Mean	0.55 ± 0.16	0.62 ± 0.10	0.49 ± 0.14	0.68 ± 0.09	0.51 ± 0.10	0.46 ± 0.20
correlation ±	(30%)	(38%)	(24%)	(46%)	(26%)	(21%)
1 stddev (EV)						
Slope range	1.29 to 1.41	1.41 to 1.47	1.21 to 1.29	1.34 to 1.39	1.26 to 1.32	1.29 to 1.38
Correlation	0.33 to 0.78	0.48 to 0.79	0.34 to 0.76	0.58 to 0.82	0.38 to 0.69	0.21 to 0.81
	Under-est	imation of Case	A / over-estimat	ion of Case B sea	-ice concentrati	ons by the
			respective	algorithm		
Case A60	-18.4%	-13.6%	-25.6%	-18.4%	-22.6%	-20.2%
Case A80	0.0% *	0.0% *	-0.8%	0.0% *	0.0% *	0.0% *
Case B60	+21.6%	+26.4%	+14.4%	+21.6%	+17.4%	+19.8%
Case B80	+20.0% *	+20.0% *	+19.2%	+20.0% *	+20.0% *	+20.0% *

12

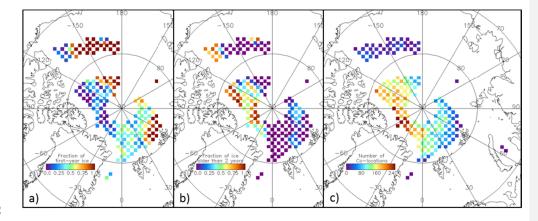
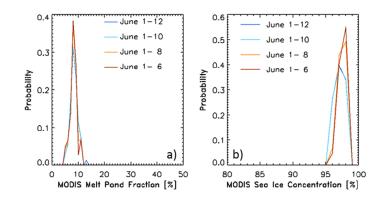




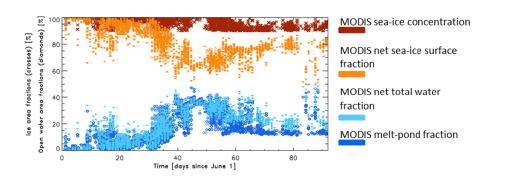
Figure 1. Spatial distribution of the MODIS sea-ice parameter data set super-posed with the
fraction of first-year ice (a), multiyear ice (b), and the number of co-located daily MODIS
sea-ice parameter data for the entire period June to August (c).



5 Figure 2. Histograms of MODIS melt-pond fraction (a) and MODIS sea-ice concentration (b)

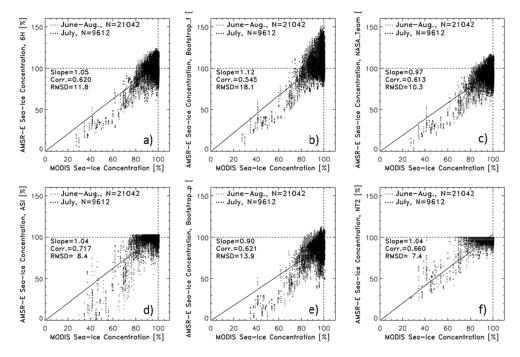
- 5 derived when sea-ice cover was near 100% and melt ponds were not yet present (see text for
- details) for the first 7, 9, 11, and 13 days of June 2009.



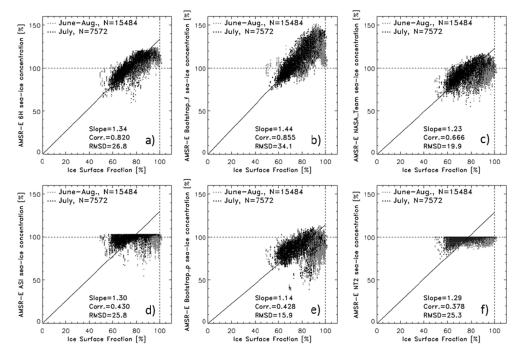


- A Figure 3. Time series of open water and sea-ice fractions for all MODIS grid cells used in the
- 5 present study for June 1, 2009 to August 31, 2009.





D Figure 4. AMSR-E sea-ice concentration computed with 6 of the 8 algorithms listed in Table 2 versus MODIS sea-ice concentration for all grid cells with MODIS sea-ice concentration > 1 20%, and cloud fraction < 5%. Grey and black symbols denote data of the entire period and 2 9 July only, respectively. The black line denotes a linear regression of the sea-ice concentrations of July forced through (0,0) with the slope as given in the each image. The linear correlation 4 5 coefficient and root mean squared difference for sea-ice concentrations of July are denoted by "Corr." and "RMSD". Slope, Corr, and RMSD for June, July (this figure), and August are б summarized in Tables 5 to 7. 9



D Figure 5. AMSR-E sea-ice concentration computed with 6 of the 8 algorithms listed in Table 2 versus MODIS ice-surface fraction for all grid cells with MODIS sea-ice concentration > 1 90%, and cloud fraction < 5%. Grey and black symbols denote data of the entire period and 2 9 July only, respectively. The black line denotes a linear regression of the sea-ice concentrations of July forced through (0,0) with the slope as given in the each image. The linear correlation 4 5 coefficient and root mean squared difference for sea-ice concentrations of July are denoted by "Corr." and "RMSD". Slope, Corr, and RMSD for June, July (this figure), and August are б summarized in Tables 8 to 10. 9

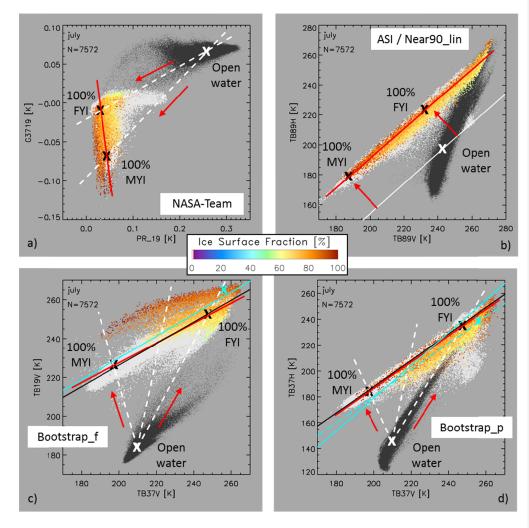
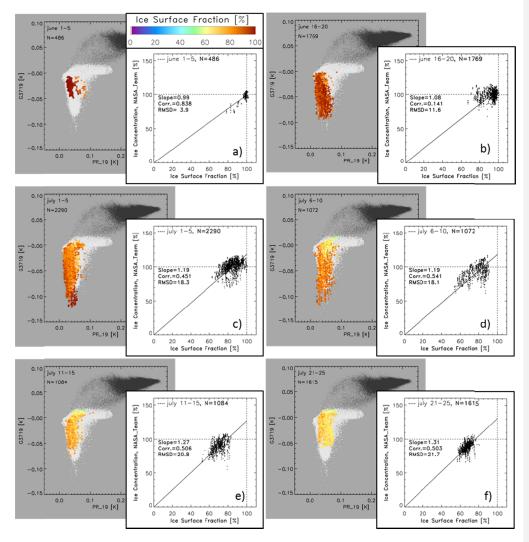




Figure 6. Parameter spaces for NASA-Team (a), ASI / Near90 lin (b), Bootstrap f (c), and 2 Bootstrap p (d) algorithms. Each image contains AMSR-E brightness-temperature data for 3 the respective space for July 2009, color coded with the contemporary MODIS ice-surface 4 5 fraction for cloud cover < 5% and MODIS sea-ice concentration > 90%. Black and white dots denote winter (February 10, 2007) Arctic brightness temperatures for 0% and > 90 % NT2 6 7 sea-ice concentration, respectively. White and black crosses denote open water and sea-ice tie points for winter, respectively (Ivanova et al., 2015). Red arrows direct into sea-ice 8 9 concentration increase. Red lines connect first-year ice (FYI) and multiyear ice (MYI) tie points and are referred to as ice lines in the text. For white, black, and cyan lines and crosses 10 see text in sub-section 4.2. 11



2

Figure 7. Background: AMSR-E brightness temperature frequency difference (gradient ratio, 1 GR) at 37 GHz and 19GHz, vertical polarization, versus AMSR-E brightness temperature 2 polarization difference (polarization ratio, PR) at 19 GHz, color-coded with the co-located 3 MODIS ice-surface fraction for 6 selected pentads denoted in the upper left corner of each 4 image together with the number N of data pairs. For white and black dots see Figure 6. 6 Foreground: NASA-Team sea-ice concentration versus MODIS ice-surface fraction for the Б 7 same pentads together with the linear regression line forced through (0,0). The slope of this line is given together with the correlation between and the root mean squared difference 8 (RMSD) of the two data sets in each image. 10

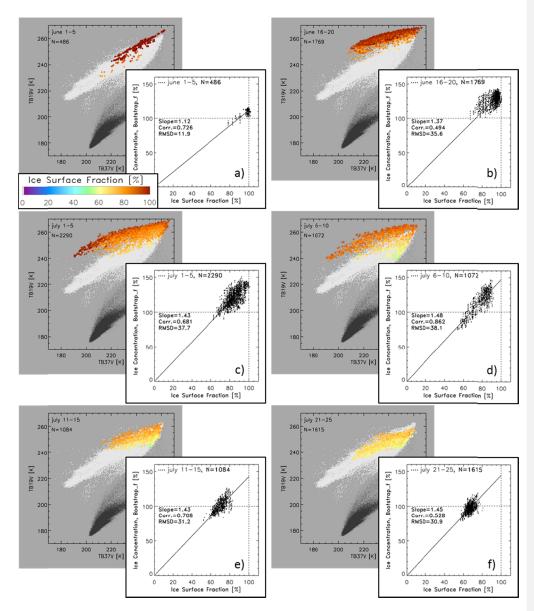


Figure 8. Background: Vertically polarized AMSR-E brightness temperature at 19 GHz and
versus at 37 GHz, color-coded with the co-located MODIS ice-surface fraction for the same 6
selected pentads as in Figure 7 denoted in the upper left corner of each image together with
the number N of data pairs. For white and black dots see Figure 6. Foreground: Same as in
Figure 7 but for the Bootstrap_f algorithm.

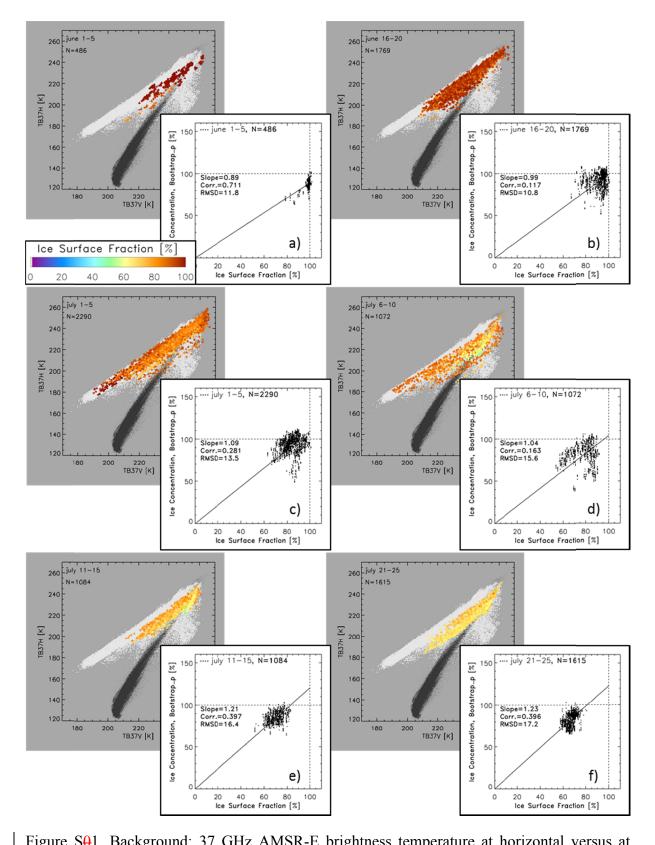


Figure S θ 1. Background: 37 GHz AMSR-E brightness temperature at horizontal versus at vertical polarization, color-coded with the co-located MODIS ice-surface fraction for the same 6 selected pentads as in Figure 7 denoted in the upper left corner of each image together with the number N of data pairs. For white and black dots see Figure 6. Foreground: Same as in Figure 7 but for the Bootstrap_p algorithm.

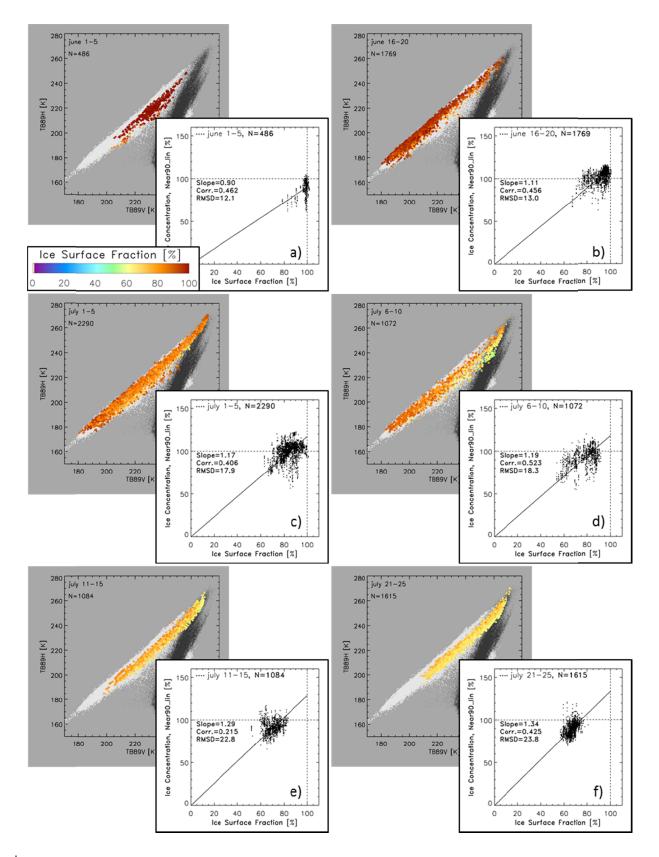


Figure S02. Background: 89 GHz AMSR-E brightness temperature at horizontal versus at vertical polarization, color-coded with the co-located MODIS ice-surface fraction for the same 6 selected pentads as in Figure 7 denoted in the upper left corner of each image together with the number N of data pairs. For white and black dots see Figure 6. Foreground: Same as in Figure 7 but for the Near90_lin algorithm.

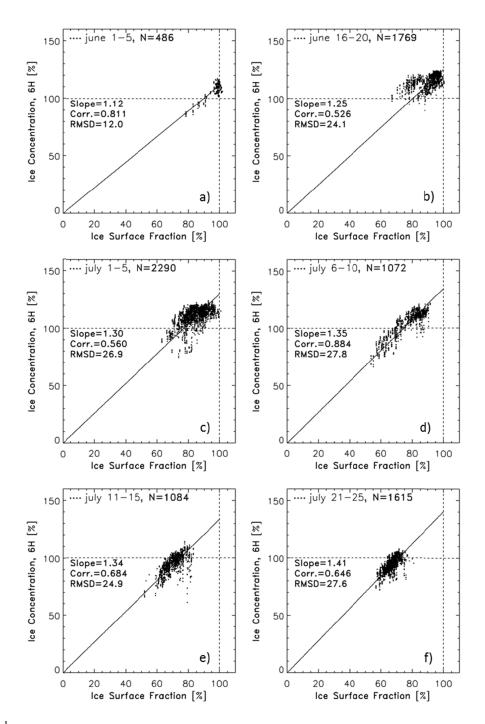


Figure S θ 3. 6H algorithm sea-ice concentration versus MODIS ice-surface fraction for the same pentads together with the linear regression line forced through (0,0). The slope of this line is given together with the correlation between and the root mean squared difference (RMSD) of the two data sets in each image.

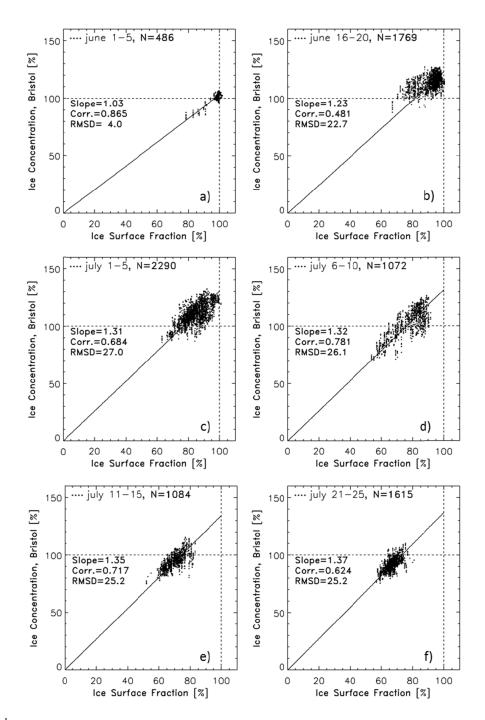


Figure S 04 . Bristol algorithm sea-ice concentration versus MODIS ice-surface fraction for the same pentads together with the linear regression line forced through (0,0). The slope of this line is given together with the correlation between and the root mean squared difference (RMSD) of the two data sets in each image.