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Brief Communication: Newly developing rift in Larsen C Ice Shelf presents significant risk to stability

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brightness and contrast. Nevertheless, measurements of rift tip position and width are potentially subject to error of up to a few tens of meters.

To investigate a range of possible outcomes from the proposed calving event, we present two scenarios for the rift trajectory based on its current orientation and direction of propagation, and on visual inspection of MODIS data (Fig. 1). Surface features in these data indicate the scale and orientation of existing weaknesses (e.g. basal crevasses) along which the rift might be expected to preferentially propagate (Luckman et al., 2012). In Scenario I the rift approaches the calving front by the shortest route via existing weaknesses, and so would result in a reasonable minimum estimate for the calved area. In Scenario II the rift continues along its current trajectory for a further 80 km before approaching the ice front. The hypothetical turning point in this scenario is chosen to smoothly continue the orientation of the ice front where the rift will meet it (Fig. 1). We present this as a reasonable possibility for which to test the impact of a calving event, rather than a maximum for the projected calved area. The eventual calving may be within the range we test, or may be more extreme still.

2.2 Numerical modelling

To determine the influence of the potential calving event on the future stability of the Larsen C Ice Shelf we use a numerical ice shelf model, previously applied to the Larsen B (Sandhäger et al., 2005) and the Larsen C ice shelves (Jansen et al., 2010, 2013; Kulesa et al., 2014). This finite difference model is based on the continuum mechanical equations of ice shelf flow. Friction at the ice shelf base as well as vertical shear strain due to bending are neglected. Thus horizontal flow velocities are vertically invariant and the flow field is two-dimensional. In the vertical dimension the model domain is divided into 13 levels, scaled by ice thickness, to allow for a realistic vertical temperature profile, influencing the vertically integrated flow parameter.

Simulations are carried out on a 2.5 km grid varying only the position of the ice shelf calving margin between the present ice front position and rift Scenarios I and II. The model we apply is a steady-state mode which assumes that the ice shelf is not in

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stress (the *stress-flow angle*; Fig. 3). This diagnostic has previously been used to investigate ice shelf stability on the basis that existing weaknesses (rifts and crevasses) are typically oriented across-flow (Kulessa et al., 2014). Regions of the shelf exhibiting low stress-flow angles are likely to be more affected by small-scale calving because stresses act to open existing weaknesses; conversely, regions with a stress-flow angle approaching 90° are likely to be stable.

The stress-flow angles at the present (early 2015) ice front are generally high (Fig. 3a) and, as a result, calving events are rare and the ice front is stable (Kulessa et al., 2014). If the ice shelf calves under Scenario I, the new ice front will, in the immediate term, still mostly be fringed by ice with a high stress-flow angle (Fig. 3a). However, this safety margin is narrowed by the calving, and the centre of the new ice front will exhibit very low stress-flow angles. Under this modest calving scenario, if the ice shelf is able to adapt to the new geometry (Fig. 3b), a new region of high stress-flow angles develops, but this region remains significantly narrower than at present. Under calving Scenario II, much more of the ice front is immediately left without a buffer of high stress-flow angle ice (Fig. 3a). Even if it were possible to adapt to this new geometry (Fig. 3c), a significant section of the new ice front would retain very low values of stress-flow angle.

4 Discussion

The rift highlighted here has been present since the earliest satellite imagery (Glasser et al., 2009) but has recently propagated beyond its neighbouring structures to the point at which a large calving event is anticipated. Over the past 4 years the rate of development of the rift width has been steady, but the length has grown intermittently with a particular acceleration during 2014 (Fig. 2). We hypothesize that the strain which opens the rift may be relatively constant, but that the fracture response varies with tip position. This may be a result of variations in fracture toughness of the ice which are

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likely to be related the presence of marine ice in suture zones (Holland et al., 2009; Jansen et al., 2013) and the locations of pre-existing weaknesses.

The reduction in area of Larsen C Ice Shelf under Scenarios I and II of 9 and 12 %, respectively will be significant, but will of course not contribute to immediate sea level rise since the floating ice already displaces its own weight of sea water. The predicted ice loss is also not unprecedented: in the late 1980s a calving event removed 14 % of Larsen C Ice Shelf (Cook and Vaughan, 2010). The real significance of this new rift to this ice shelf is two-fold. First, the predicted calving will reduce its area to a new minimum both in terms of direct observations, and probably since the last interglacial period (Hodgson et al., 2006). Second, unlike during the 1980s, but highly comparable to the development of Larsen B Ice Shelf between 1995 and 2002, the resulting geometry may be unstable. According to the stress-flow angle criterion, our calving scenarios lead to a range of unstable outcomes from partial to significant. Under our modest rift propagation Scenario I, immediately following the predicted calving event, the central part of the ice front will be unstable and prone to persistent calving of small ice blocks as the principal strain works to open existing fractures. It is not clear how quickly the velocity of a real ice shelf will be able to adapt to the new boundary conditions, but even if this is rapid, the margin of stabilizing ice becomes very narrow. Under Scenario II, the unstable part of the new ice front is considerably larger and, even if the flow field adapts quickly to the new geometry, parts of the calving margin remain unstable and prone to run-away calving of a similar nature to Larsen B Ice Shelf between 1995 and 2002. Our model demonstrates that the newly developing rift presents a considerable risk to the stability of the Larsen C Ice Shelf.

5 Conclusions

We have investigated a newly developing rift in the south of Larsen C Ice Shelf which has propagated beyond its neighbours in 2013, and grew very rapidly in 2014. It seems inevitable that this rift will lead to a major calving event which will remove between 9 and

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12% of the ice shelf area and leave the ice front at its most retreated observed position. More significantly, our model shows that the remaining ice may be unstable. The Larsen C Ice Shelf may be following the example of its previous neighbour, Larsen B, which collapsed in 2002 following similar events.

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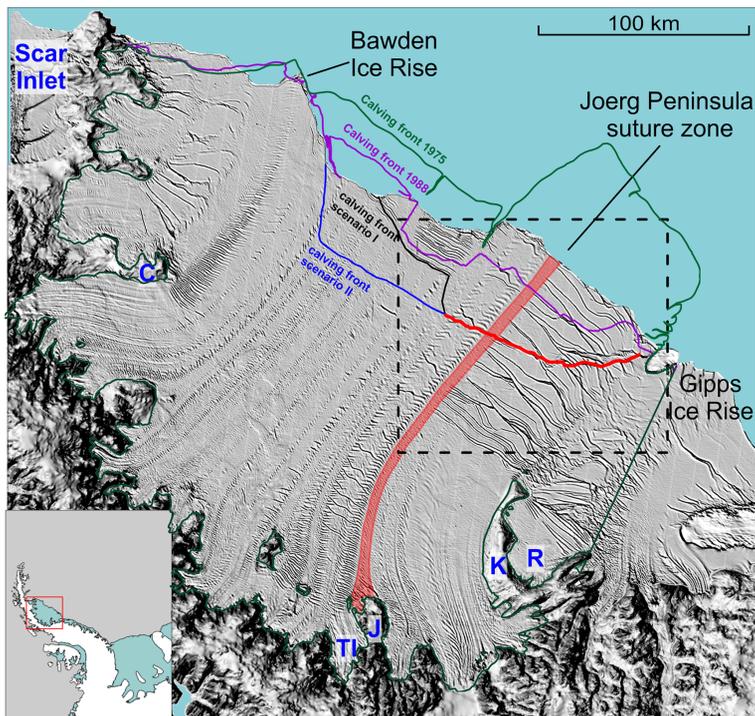


Figure 1. Overview of the Larsen C Ice Shelf in late 2014 showing the contemporary location of the developing rift (red line), and a selection of previous and predicted future calving fronts. Background image is MODIS Aqua, 3 December 2014. Geographic features of interest are marked (R = Revelle Inlet, FI = Francis Island, TO = Tonkin Island, TI = Trail Inlet, SI = Solberg Inlet, K = Kenyon Peninsula) and the dashed box shows the extent of Fig. 2. The highlighted flow line indicates the location of the Joerg Peninsula suture zone.

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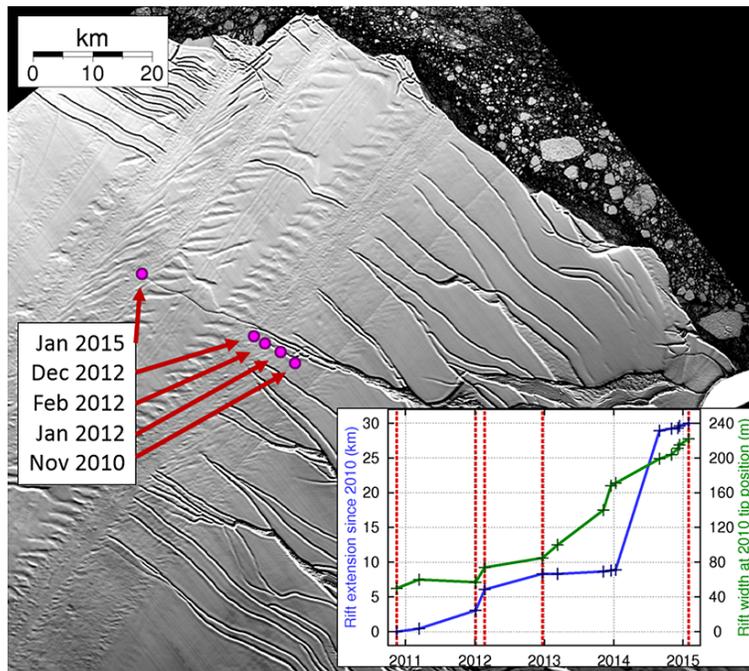


Figure 2. Analysis of rift propagation using Landsat data. Background image, in which the rift is visible, is from 4 December 2014. Inset graph shows the development of rift length with respect to the 2010 tip position, and rift width at the 2010 tip position, measured from 15 Landsat images (crosses). Circles and labels on the map, and dotted red lines on the graph, show the positions of notable stages of rift development.

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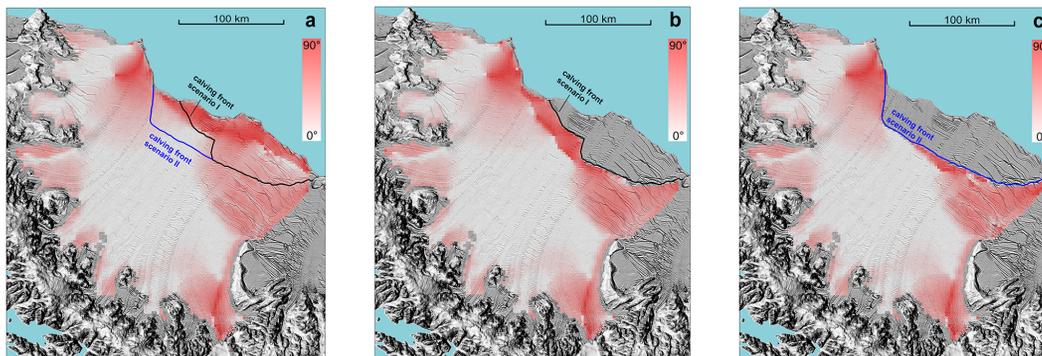


Figure 3. Results from ice shelf flow model: Stress-flow angle fields for the present day ice front geometry (a) and for the new geometries under Scenarios I (b) and II (c).

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