

Two cases of
aerodynamic
adjustment of
sastrugi

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Two cases of aerodynamic adjustment of sastrugi

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Abstract

In polar regions, sastrugi are a direct manifestation of wind driven snow and form the main surface roughness elements. In turn, sastrugi influence the local wind field and associated aeolian snow mass fluxes. Little attention has been paid to these feedback processes, mainly because of experimental difficulties, and, as a result most polar atmospheric models currently ignore sastrugi. More accurate quantification of the influence of sastrugi remains a major challenge. In the present study, wind profiles and aeolian snow mass fluxes were analyzed jointly on a sastrugi covered snowfield in Antarctica. Neutral stability 10 m air-snow drag coefficients C_{DN10} were computed from six level wind speed profiles collected in Adélie Land during austral winter 2013. The aeolian snow mass flux in the first meter above the surface of the snow was also measured using a windborne snow acoustic sensor. This paper focuses on two cases during which sastrugi responses to shifts in wind direction were evidenced by variations in snow mass flux and drag coefficients. Using this dataset, it was shown that (i) the timescale of sastrugi aerodynamic adjustment can be as short as 3 h for friction velocities of 1 m s^{-1} or above and during strong windborne snow conditions, (ii) C_{DN10} values were in the range of $1.3\text{--}1.5 \times 10^3$ when the wind was well aligned with the sastrugi and increased to 3×10^3 or higher when the wind only shifted $20\text{--}30^\circ$, (iii) C_{DN10} can increase (to 120 %) and the aeolian snow mass flux can decrease (to 80 %) in response to a shift in wind direction, and (iv) knowing C_{DN10} is not sufficient to estimate the erosion flux that results from drag partitioning at the surface because C_{DN10} includes the contribution of the sastrugi form drag. These results not only support the existence of feedback mechanisms linking sastrugi, aeolian particle transport and surface drag properties over snow surface but also provide orders of magnitude, although further measurements including continuous accurate descriptions of the sastrugi field are certainly still needed. Such measurements are essential to improve parameterization schemes for aeolian snow transport models.

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1 Introduction

In polar regions, sastrugi are a direct manifestation of wind-driven snow. Sastrugi are elongated metric-scale ridges of wind-packed snow whose longitudinal axis is parallel to the prevailing wind at the time of their formation. These erosional surface roughness features are very widespread over the Antarctic ice sheet (Kotlyakov, 1961) where they can be major determinants of surface roughness (Jackson and Carroll, 1978; Inoue, 1989; Andreas, 1995; Andreas and Claffey, 1995). Sastrugi orientations have been recognized as useful indicators of the Antarctic near-surface wind direction (Mather, 1962, 1969; Mather and Miller, 1966; Rémy et al., 1992; Long and Drinkwater, 2000) in agreement with continent-scale modeling studies (Parish and Bromwich, 1987, 2007; Van Lipzig et al., 2004).

The development of sastrugi depends on the ability of snow to be eroded and thus on the threshold velocity needed to lift snow particles from the surface. In the literature, aeolian erosion thresholds have been reported to vary over a wide range of values depending on diverse parameters such as temperature, time of sintering, snow cohesion or snow density, all of which are interrelated. From observations in Antarctica, Mellor (1965) reported that 10 m wind speeds of 3 to 8 ms^{-1} are strong enough to cause aerodynamic entrainment of loose, unbounded snow, whereas winds exceeding 30 ms^{-1} are needed to erode snow consolidated by the freeze–thaw process. Budd et al. (1966) suggested a high threshold wind speed (14 ms^{-1}) was needed to trigger snow transport in the cold environment of Byrd station. Schmidt (1980) reported that the threshold wind speed increases with the time since snow deposition, and that the colder the temperature, the greater but slower the decline in the increase rate over time. Schmidt (1982) also showed that the cohesion of the snow surface determines the threshold speed required for snow erosion to occur. In Antarctica, Bromwich (1988) highlighted a seasonal contrast between winter threshold wind speeds of 7 ms^{-1} and higher thresholds of more than 13 ms^{-1} in summer because of greater surface adhesion. Pomeroy et al. (1993) identified significantly lower thresholds for fresh, loose, dry

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where ρ is the air density, u and w are fluctuations in the longitudinal and vertical turbulent velocity, respectively, and C_{DNz} and U_z are the neutral-stability drag coefficient and the average wind speed at height z , respectively. The overbar stands for a time average. C_{DN} is usually discussed at a standard reference height of 10 m (C_{DN10}).

5 From Eqs. (2) and (3), it follows that

$$C_{DN10} = \left[\kappa / \ln \left(\frac{10}{z_0} \right) \right]^2 \quad (3)$$

with z_0 expressed in meters. Here C_{DN10} and z_0 are two equivalent quantities for evaluating the momentum exchange at the air–snow interface that results from the integrated (in space and time) turbulent drag caused by the roughness elements.

10 The wind profiles used to compute C_{DN10} were selected following a strict procedure. After discarding icing or malfunctioning cases and half-hourly runs for which a rare (northwesterly) flow was likely to be disturbed by the measurement structure, stationary conditions were selected by requiring that temperature changes between two consecutive half-hourly runs not exceed 0.3 K, as suggested by Joffre (1982). Near-
15 neutral conditions were then selected requiring $U > 5 \text{ ms}^{-1}$ and an absolute value of the bulk Richardson number below 10^{-2} . The last selection criterion was applied following a suggestion by Andreas and Claffey (1995) that demands

$$\frac{\sum_{i=1}^6 [U(z_i) - (u_*/\kappa) \ln(z_i/z_0)]^2}{u_*^2} \leq \varepsilon, \quad (4)$$

20 where ε is an empirical constant determined from visual inspection of the observed wind speed profiles. Here it was set to 0.15. Wind profiles that survived this filtering process were fitted Eq. (1) using a least-square log-linear regression technique, where z_0 and $\frac{u_*}{\kappa} \ln(z_0)$ are the regression coefficients. All of them yielded a correlation coefficient (r^2) larger than 0.99.

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3 Results

The two erosion events depicted in Fig. 4 occurred respectively in March (left panels) and October (right panels), 2013, during fairly constant wind direction conditions, which persisted after a wind shift of a few tens of degrees. The 2 m wind speed, wind direction, profiled-derived C_{DN10} values and aeolian snow mass flux recovered by the second-generation FlowCapt™ sensor are shown in Fig. 4. As the friction velocity is the actual dynamic quantity involved in aerodynamic entrainment of surface snow particles (Gallée et al., 2001), it is also plotted on the graph. The two events are split into three parts, before (A_i), during (B_i) and after (C_i) the shift in wind direction. Operational analyses of the European Center for Medium-Range Weather Forecasts related to the fully continental grid point (horizontal resolution of ~ 16 km), which includes D17, indicated that precipitation rates were negligible during both events.

At the beginning of Julian day (JD) 87 (part A_1), the wind direction was around 140° , the friction velocity was above the erosion threshold with a related aeolian snow mass flux of $100 \text{ g m}^{-2} \text{ s}^{-1}$, and C_{DN10} was near 1.5×10^{-3} . At the end of JD 87 (part B_1), the wind rotated toward 160° while C_{DN10} increased to nearly 3.3×10^{-3} , i.e. by 120%, in response to a wind shift of only 20° . As assumed in Jackson and Carroll (1978) and Andreas and Claffey (1995), it is likely that as the wind turned, it was deflected from the mean sastrugi axis, thereby encountering a rougher surface. As a result, C_{DN10} soared, reflecting the growing contribution of the sastrugi form drag to the vertical momentum flux at the surface, and hence to the total surface drag. Within the same time frame, the measured aeolian snow mass flux fell by $\sim 30\%$ from 365 to $260 \text{ g m}^{-2} \text{ s}^{-1}$, despite increasing friction velocity (wind speed) from 0.7 to 1.6 (18 to 24) m s^{-1} . Then, until the end of the event (part C_1), the wind direction remained centered about 160° . From 03:30 to 06:30 UT on JD 88, C_{DN10} fell back to 1.5×10^{-3} as high winds presumably streamlined the surface. In other words, C_{DN10} was reduced by $\sim 50\%$ in only 3 h. As C_{DN10} decreased, the aeolian snow mass flux again rose above $400 \text{ g m}^{-2} \text{ s}^{-1}$. The erosion event lasted through JD 90 when u_* (wind speed) dropped to 0.7 (15) m s^{-1} ,

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causing a significant decrease in the aeolian snow mass flux. After nearly 48 h of persistent erosive winds, C_{DN10} was as low as 1.3×10^{-2} .

During the two days that preceded the second erosion event (part A₂), the wind direction was within $\pm 10^\circ$ of 150° , the friction velocity was generally not strong enough to erode the snow surface, and C_{DN10} was between $1.3\text{--}1.6 \times 10^{-3}$. Then, the same situation depicted in the left panels of Fig. 4 occurred again. At mid-JD 286 (part B₂), u_* increased beyond the erosion threshold as the wind rotated from 150° to 180° . Consequently, C_{DN10} increased to 1.9×10^{-3} . The aeolian snow mass flux dropped simultaneously from 320 to $55 \text{ g m}^{-2} \text{ s}^{-1}$ under increasing friction velocity. That is, for a $\sim 30\%$ increase in C_{DN10} as the result of a wind deflection of 30° , the aeolian snow mass flux decreased by $\sim 80\%$. Together with the first case of erosion, this illustrates how the form drag exerted by sastrugi can significantly affect snow erosion when the wind and sastrugi are not aligned (this effect is discussed later in the paper; see Sect. 4). Then (part C₂), the wind direction remained roughly unchanged until erosion ceased. Again, the rise in aeolian snow mass flux coincided with a decrease in C_{DN10} . After nearly 3 h of winds above 20 m s^{-1} ($u_* > 0.9 \text{ m s}^{-1}$) from 180° , C_{DN10} fell from 1.9×10^{-3} to 1.4×10^{-3} , i.e. decreased by $\sim 30\%$.

In summary, for friction velocities (wind speeds) around 1 (20) m s^{-1} and above, the sastrugi streamlining timescale can be as fast as 3 h. For a windflow initially aligned with the sastrugi, a deviation of $20\text{--}30^\circ$ from the streamlining direction has the potential to both increase C_{DN10} by $30\text{--}120\%$ and to significantly reduce (up to 80%) the aeolian snow mass flux, even under increasing friction velocity.

4 Discussion

At Ice Station Weddell, Andreas and Claffey (1995) measured a decrease in C_{DN10} of $20\text{--}30\%$ in 12 h with considerably weaker winds ($< 12 \text{ m s}^{-1}$) than those reported here. The observations reported in this paper show that this timescale can be 4 times faster

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measure, it cannot be extrapolated to the snow bed. The averaged snow bed shear stress (also referred to as skin friction in the literature), which is the ultimate parameter for aeolian erosion (Li and Shao, 2003), varies depending on its position along the sastrugi field. In absence of direct measurements, it is necessary to link outer shear stress, sastrugi geometry, and skin friction to be able to estimate aeolian snow mass flux. For erodible forms in riverbeds such as ripples, Smith and McLean (1977) and later Wiberg and Nelson (1992) developed a method for partitioning the outer shear stress. These authors considered that the averaged bed shear stress is equal to the difference between the outer shear stress and the drag-related stress produced as the flow is forced around the bedform – i.e., in the present case, the form drag induced by the sastrugi. As mentioned above, an increasing form drag can be expected, and hence a decrease in skin friction and in aeolian snow mass flux, when the wind direction gradually shifts away from the longitudinal axis of the sastrugi. Because C_{DN10} reflects the contribution of the sastrugi form drag, knowing the drag coefficient is not sufficient to estimate skin friction. A better knowledge of skin friction over a sastrugi field is also needed to improve aeolian snow mass flux parameterizations in aeolian erosion models. The measurements made in the present study showed that a considerable decrease (even 80 %) of the aeolian snow mass flux can occur during the transitional regime during which the wind and sastrugi are not aligned (Fig. 4, parts B). But it should be also noted that the rapid aerodynamic adjustment of sastrugi (3 h) will limit errors if the aeolian snow transport event considered is strong and sufficiently long.

5 Conclusions

An experimental meteorological dataset collected in coastal Adélie Land during austral winter 2013 was exploited to document surface turbulent fluxes of momentum and snow over an Antarctic sastrugi field. The main results of the analysis of two erosion events can be summarized as follows:

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- the timescale for the aerodynamic adjustment of sastrugi can be as low as three hours for friction velocities of 1 m s^{-1} or above and during strong windborne snow conditions,
- $C_{\text{DN}10}$ values were in the range of $1.3\text{--}1.5 \times 10^3$ when the wind was well aligned with sastrugi and increased to 3×10^3 or higher with wind shifts of only $20\text{--}30^\circ$,
- $C_{\text{DN}10}$ and the aeolian snow mass may respectively increase (to 120 %) and decrease (to 80 %) in response to the wind shift in direction,
- because $C_{\text{DN}10}$ includes the contribution of the sastrugi form drag, knowing $C_{\text{DN}10}$ is not sufficient to estimate the erosion flux that results from drag partitioning at the surface.

These results support the existence of mechanisms linking aeolian particle transport and surface drag properties over (Antarctic) snow, as already demonstrated for other erodible natural surfaces (Marticorena and Bergametti, 1995). In contrast with non-erodible roughness elements such as rocks or vegetation, these mechanisms involve the time needed for sastrugi to adjust to the main wind (3 h in both erosion events), during which both the drag coefficient and the aeolian snow mass flux can be greatly modified. In comparison, Andreas and Claffey (1995) reported a longer timescale (12 h) for the sastrugi to realign with weaker winds. Because lighter winds are supposed to be associated with lower erosion fluxes, it is suggested that the sastrugi streamlining timescale most likely depends on the snow erosion flux.

Real-time observations would further advance understanding of the physical processes involved in the development of sastrugi and enable better characterization of sastrugi aerodynamic adjustment timescales. In addition, having a more accurate representation of the shape of sastrugi would make small-scale modeling in a wind tunnel possible, in which case, it would be possible to realistically estimate shear stress partitioning. One possible way to monitor sastrugi would be to set up an automatic mini laser-scan. Such a device was developed in the framework of the MONISNOW re-

search project (Picard and Arnaud, LGGE, personal communication) and has been operating daily at Dome C in Antarctica since the beginning of 2015. These complementary approaches are vital to improve parameterization schemes for aeolian snow transport models.

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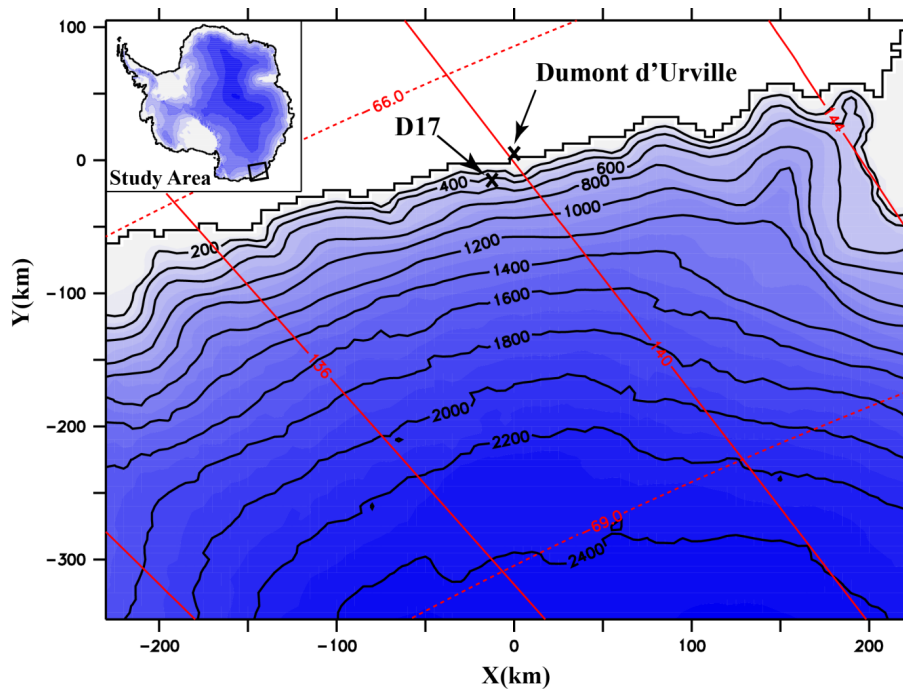


Figure 1. Map of Adélie Land showing the location of Dumont d'Urville station and measurement site D17. Contour lines are in meters.

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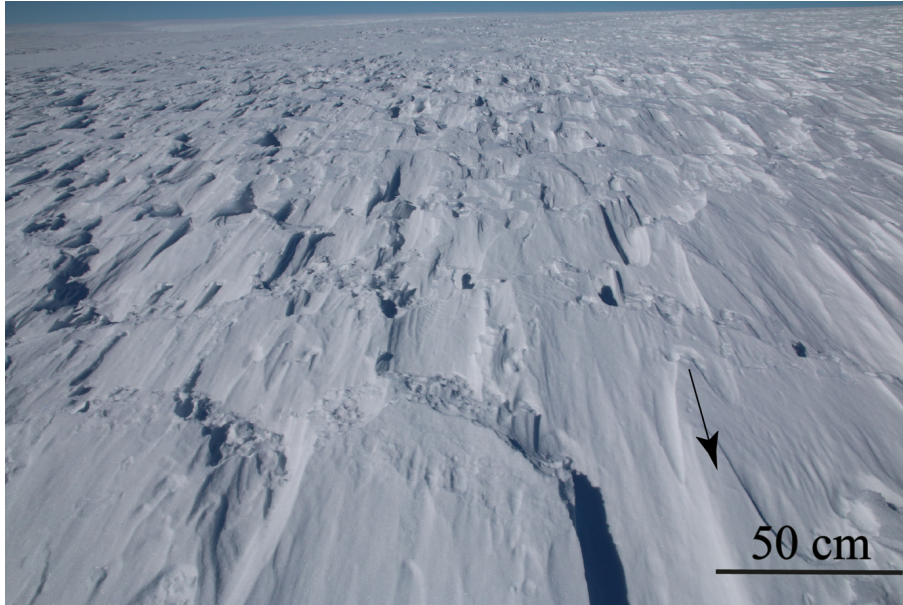


Figure 2. Photograph of the snow surface at D17 in January 2014. The arrow indicates the mean direction of the wind episode that led to the formation of the sastrugi.

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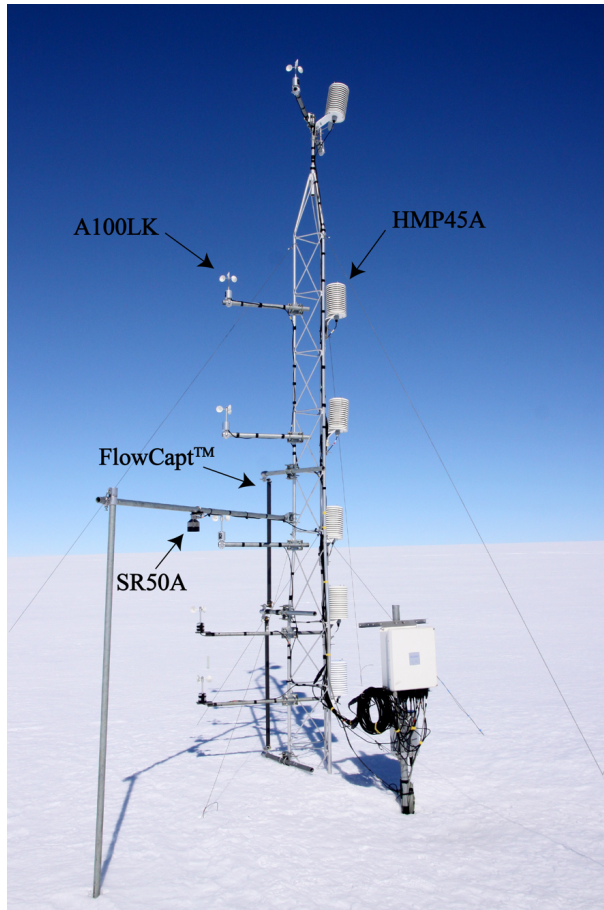


Figure 3. The measurement structure deployed at D17.

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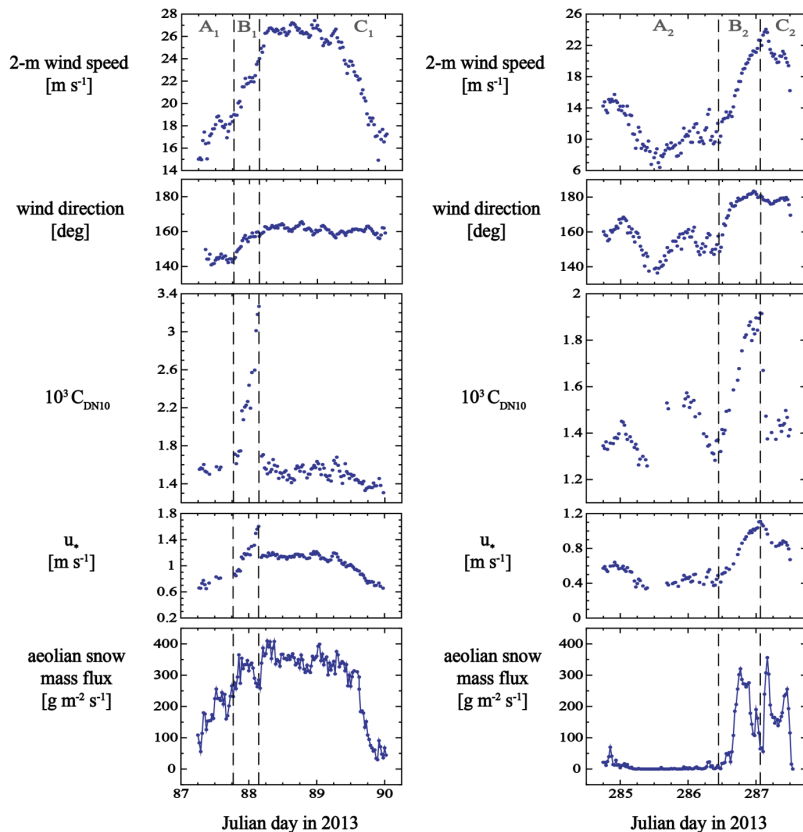


Figure 4. Two erosion events showing sastrugi responses to shifts in wind direction. Note the different vertical scales between right and left panels concerning measured 2 m wind speed and profile-derived C_{DN10} and u_* values. The aeolian snow mass fluxes come from the second-generation FlowCapt™ sensor set up from 0 to 1 m above the snow surface. In both cases, the event is split into three parts, respectively before (A_i), during (B_i) and after (C_i) the wind shift.