1 Two well marked cases of aerodynamic adjustment of sastrugi

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11 form drag

12 Abstract

In polar regions, sastrugi are a direct manifestation of drifting snow and form the main surface 13 roughness elements. In turn, sastrugi influence the local wind field and associated aeolian snow 14 mass fluxes. Little attention has been paid to these feedback processes, mainly because of 15 experimental difficulties, and, as a result most polar atmospheric models currently ignore 16 sastrugi. More accurate quantification of the influence of sastrugi remains a major challenge. 17 In the present study, wind profiles and aeolian snow mass fluxes were analyzed jointly on a 18 sastrugi covered snowfield in Antarctica. Neutral stability 10-m air-snow drag coefficients 19 C_{DN10} were computed from six level wind speed profiles collected in Adélie Land during austral 20 winter 2013. The aeolian snow mass flux in the first meter above the surface of the snow was 21 also measured using a windborne snow acoustic sensor. This paper focuses on two cases during 22 23 which sastrugi responses to shifts in wind direction were evidenced by variations in drag coefficients and aeolian snow mass fluxes. Using this dataset, it was shown that (i) C_{DN10} values 24 were in the range of $1.3-1.5 \times 10^{-3}$ when the wind was well aligned with the sastrugi and 25 increased to 3 x 10^{-3} or higher when the wind only shifted 20-30°, (ii) as C_{DN10} increases, the 26 aeolian snow mass flux can decrease (to 80%) in response to a shift in wind direction. (iii) the 27 timescale of sastrugi aerodynamic adjustment can be as short as 3 h for friction velocities of 1 28 m $s^{\text{-1}}$ or above and during strong windborne snow conditions, and (iv) knowing C_{DN10} is not 29 sufficient to estimate the erosion flux that results from drag partitioning at the surface because 30 C_{DN10} includes the contribution of the sastrugi form drag. These results not only support the 31 existence of feedback mechanisms linking sastrugi, aeolian particle transport and surface drag 32

properties over snow surfaces but also provide orders of magnitude in terms of changes in drag coefficients and aeolian snow mass fluxes as well as sastrugi streamlining timescales, although further measurements including continuous accurate descriptions of the sastrugi field are certainly still needed. Such measurements are essential to improve parameterization schemes for aeolian snow transport models and general drag parameterizations for weather, climate and earth system models.

7 1. Introduction

In polar regions, sastrugi are a direct manifestation of drifting snow. Sastrugi are elongated 8 9 ridges of wind-packed snow 1 to 2 meters in length whose longitudinal axis is parallel to the prevailing wind at the time of their formation. These erosional surface roughness features are 10 11 very widespread over the Antarctic ice sheet (Kotlyakov 1961) where they can be major 12 determinants of surface roughness (Jackson and Carroll 1978; Inoue 1989; Andreas 1995; Andreas and Claffey 1995). Sastrugi orientations have been recognized as useful indicators of 13 the Antarctic near-surface wind direction (Mather 1962, 1969; Mather and Miller 1966; Rémy 14 15 et al. 1992; Long and Drinkwater 2000) in agreement with continent-scale modeling studies (Parish and Bromwich 1987, 2007; Van Lipzig et al., 2004). 16

The development of sastrugi depends on the ability of snow to be eroded and thus on the 17 threshold velocity needed to lift snow particles from the surface. In the literature, aeolian 18 19 erosion thresholds have been reported to vary over a wide range of values depending on diverse parameters such as temperature, time of sintering, snow cohesion or snow density, all of which 20 21 are interrelated. From observations in Antarctica, Mellor (1965) reported that 10-m wind speeds of 3 to 8 m s⁻¹ are strong enough to cause aerodynamic entrainment of loose, unbounded snow, 22 whereas winds exceeding 30 m s⁻¹ are needed to erode snow consolidated by the freeze-thaw 23 process. Budd et al. (1966) suggested a high threshold wind speed (14 m s⁻¹) was needed to 24 trigger snow transport in the cold environment of Byrd station. Schmidt (1980) reported that 25 26 the threshold wind speed increases with the time since snow deposition, and that this increase slows with time and is slower at lower temperatures. Schmidt (1982) also showed that the 27 28 cohesion of the snow surface determines the threshold speed required for snow erosion to occur. In Antarctica, Bromwich (1988) highlighted a seasonal contrast between winter threshold wind 29 speeds of 7 m s⁻¹ and higher thresholds of more than 13 m s⁻¹ in summer because of greater 30 31 surface adhesion. Pomeroy et al. (1993) identified significantly lower thresholds for fresh, loose, dry snow than for older, wind hardened, dense or wet snow. Yong and Metaxas (1985) 32

referred to age hardening to describe a measured increase in the density of natural fresh snow 1 from 100 kg m⁻³ to 300 and 400 kg m⁻³ after respectively 30 and 50 days at a relatively constant 2 temperature of -13 °C. Gray and Morland (1995) reported that snow compaction (related to 3 snow density) increases rapidly after deposition due to the thermal processes of metamorphism 4 5 (i.e. changes in snow structure over time). Li and Pomeroy (1997) discussed the major role of 6 temperature in surface erodibility (i.e. the potential of a surface to be eroded; Shao 2008) and 7 showed an empirical but generally positive correlation between threshold wind speed and air temperature on the prairies of western Canada. From the work of Guyomarc'h and Mérindol 8 (1998), Gallée et al. (2001) developed an aeolian snow transport model that takes 9 metamorphism into account by allowing the threshold condition for erosion to vary with the 10 11 properties of the snow such as density, dendricity, sphericity and particle size. All studies suggest that the physical properties of the snow play a major role in the formation of sastrugi. 12

13 Sastrugi contribute to the drag exerted on the atmosphere over the snow surface and enhance interactions at the air-snow interface compared to over a smooth snow surface. Rougher snow 14 15 surfaces favor the generation of turbulence in the near surface air stream that is likely to further increase the wind driven snow mass flux (Das et al. 2013). On the other hand, sastrugi are 16 17 responsible for a loss of wind momentum through pressure fluctuation gradients in their 18 immediate vicinity (sastrugi form drag) that directly reduces the energy budget available for 19 erosion of snow. This attenuating effect on snow erosion is taken into account in the coupled 20 atmosphere-snowpack-aeolian snow transport model MAR (Galleé et al. 2013) and was 21 parametrized as in Marticorena and Bergametti (1995). By comparing observed and simulated 22 aeolian snow mass fluxes over Adélie Land using MAR, Amory et al. (2015) showed that in 23 the model, erosion efficiency is highly sensitive to the parameterization of surface roughness, 24 and underlined the need for observational characterization of interactions between wind-25 induced roughness features and aeolian transport of snow. Some authors have shown that the 26 sastrugi form drag actually depends on how the wind is oriented with respect to the main 27 sastrugi axis. Based on measurements of wind speed and temperature profile in the atmospheric surface layer at the South Pole, Jackson and Carroll (1978) reported that sastrugi form drag was 28 29 essentially absent when the wind was perfectly aligned with the sastrugi up to a height of 50 cm. As the wind rotated, sastrugi form drag increased, to reach maximum when the wind 30 direction was perpendicular to the prior sastrugi pattern. These authors developed an idealized 31 single sastruga model from Lettau's (1969) findings to reproduce their observations. Using 32 33 another analytical sastruga model adapted from Raupach (1992), Andreas (1995) also found a minimum and a maximum drag for wind directions respectively parallel and perpendicular to 34

1 the sastruga longitudinal axis.

2 However, these modeling efforts were undertaken without accounting for the erodible character of sastrugi or for their possible reorganization when realigning with persistent (erosive) winds 3 4 blowing transversally to their elongated sidewalls. If the crosswise flow continues from a 5 relatively constant direction thereby allowing sufficient shear stress to dislodge snow surface 6 particles, sastrugi can adjust aerodynamically; transversal sastrugi are eroded, and new 7 streamlined sastrugi form parallel to the mean wind (Andreas and Claffey 1995). This results in a gradual decrease in the contribution of the sastrugi to the total surface drag, and hence in 8 9 an increase in erosion efficiency. Andreas and Claffey (1995) reported that the timescale for this streamlining process on Weddell Sea ice in winter was about half a day with 6-8 m s⁻¹ 10 winds, but might be shorter if the winds are stronger. To date, no observational study has 11 provided quantitative insight into the potential effect of erodible roughness elements of the 12 13 snow surface on snow erosion.

Quantifying the variable influence of sastrugi on the local wind field and associated surface drag could improve parameterization of surface roughness and erosion in polar atmospheric models that currently ignore sastrugi. The present paper focuses on two erosion events during which sastrugi responses to shifts in wind direction were interpreted from temporal variations in both measured drag and aeolian snow mass flux in coastal Adélie Land during austral winter 2013.

20 **2. Data and Method**

21 **2.1. Field area**

22 Site D17 (66.7°S, 139.9°E; ~450 m asl.) is located about 10 km inland in a coastal accumulation zone of Adélie Land (Agosta et al. 2012), roughly 15 km southwest of the permanent French 23 station Dumont d'Urville (Fig. 1). An annual temperature of -10.8 °C and a mean wind of 24 around 10 m s⁻¹ have been reported at Dumont d'Urville station (König-Langlo et al. 1998). 25 26 The measurement area consists in a gently sloping snowfield with a long unobstructed upstream 27 fetch several hundred kilometers over a uniform snow surface. Local topographic channeling 28 acts together with the Coriolis force to produce southeasterly flows all year round that result 29 either from pure katabatic or combined katabatic-synoptic forcings (Parish et al. 1993, Naithani 30 et al. 2001).

Site D17 is visited only during summer (December to February), when the presence of sastrugi
is often reported. Frequent strong winds combined with the permanent snow surface lead to

frequent aeolian snow transport events (Trouvilliez et al. 2014), thereby favoring aerodynamic
 adjustment of the snow surface. This results in a net south-southeast orientation of the sastrugi
 (Fig. 2).

4 2.2. Instrumentation

5 The measurement structure deployed at site D17 is a 7-m high meteorological mast. Wind 6 speed, relative humidity and air temperature are recorded along the mast at 6 logarithmically 7 spaced intervals between 0.8 and 7 m above the snow surface using Vector A100LK cup 8 anemometers and HMP45A thermo-hygrometers installed in naturally ventilated MET21 9 radiation shields (Fig 3). The anemometers are mounted on roughly 1-m long booms pointing southeastward. Wind direction was only sampled at the upper level by a Vector W200P wind 10 vane. Surface level variations were measured by a Campbell SR50A acoustic depth gauge. 11 Information on drifting snow was obtained from a second-generation acoustic FlowCapt[™] 12 13 device that was set up vertically close to the ground to allow detection of the beginning of 14 aeolian snow transport events. The sensor is a 1-m long tube that converts the acoustic pressure 15 caused by snow particles impacting the tube into an aeolian snow mass flux integrated over the length of the tube. The second-generation FlowCaptTM was evaluated in the French Alps by 16 Trouvilliez et al. (2015). The authors reported that the instrument underestimates the aeolian 17 snow mass flux compared to a reference optical sensor (Snow Particle Counter S7; Sato et al. 18 1993), especially during snowfalls. Nevertheless, the equivocal behavior of the second-19 20 generation FlowCapt[™] does not affect its ability to accurately detect the occurrence of aeolian 21 snow transport. Data were sampled at 15 s intervals, averaged to half-hourly means and stored 22 in a Campbell CR3000 datalogger.

23 2.3. The 10-m drag coefficient in near-neutral conditions

Computing the drag coefficient (C_D) is a convenient way to estimate the local drag exerted by the surface on the overlying air. C_D can be computed by measuring the vertical wind speed gradient (profile method) under near-neutral conditions following the Monin-Obukhov similarity theory. Assuming stationarity and horizontal homogeneity when the atmospheric surface layer is statically neutral, the wind speed profile is logarithmic and can be written as

$$U(z) = \frac{u_*}{\kappa} \ln\left(\frac{z}{z_0}\right),\tag{1}$$

where U(z) is the average wind speed as a function of height z, κ is the von Kármán constant
 (taken as 0.4), z₀ is the aerodynamic roughness length, and u_{*} the friction velocity describing
 the wind shear at the surface and is related to the vertical momentum flux at the surface (τ; also
 known as Reynolds shear stress)

$$\tau = \rho u_*^2 = -\rho \overline{u} \overline{w} = \rho C_{DNz} U_z^2, \tag{2}$$

5 where ρ is the air density, u and w are fluctuations in the longitudinal and vertical turbulent 6 velocity, respectively, and C_{DNz} and U_z are the neutral-stability drag coefficient and the average 7 wind speed at height z, respectively. The overbar stands for a time average. C_{DN} is usually 8 discussed at a standard reference height of 10 m (C_{DN10}). From (2) and (3), it follows that

$$C_{DN10} = \left[\kappa / \ln\left(\frac{10}{z_0}\right)\right]^2,\tag{3}$$

9 with z₀ expressed in meters. Here C_{DN10} and z₀ are two equivalent quantities for evaluating the
10 momentum exchange at the air-snow interface that results from the integrated (in space and
11 time) turbulent drag caused by the roughness elements.

The wind profiles used to compute C_{DN10} were selected following a strict procedure. After 12 13 discarding icing or malfunctioning cases and half-hourly runs for which a rare (northwesterly) flow was likely to be disturbed by the measurement structure, stationary conditions were 14 15 selected by requiring that temperature changes between two consecutive half-hourly runs not exceed 0.3 K, as suggested by Joffre (1982). Near-neutral conditions were then selected 16 requiring $U > 5 \text{ m s}^{-1}$ and an absolute value of the bulk Richardson number below 10^{-2} . The last 17 selection criterion was applied following a suggestion by Andreas and Claffey (1995) that 18 19 demands

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$$\frac{\sum_{i=1}^{6} \left[U(z_i) - (u_*/\kappa) \ln(z_i/z_0) \right]^2}{u_*^2} \le \varepsilon,$$
(4)

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where ε is an empirical constant determined from visual inspection of the observed wind speed profiles. Here it was set to 0.15. Wind profiles that survived this filtering process were fitted (1) using a least-square log-linear regression technique, and u_* and z_0 deduced from the regression coefficients. All of them yielded a correlation coefficient (r²) larger than 0.99. The 80% confidence limits of each calculated C_{DN10} value were determined following the statistical method proposed by Wilkinson (1984). The highest uncertainty bounds deduced from these
 confidence limits reached ±14%.

3 **3. Results**

The two erosion events depicted in Figure 4 occurred respectively in March (left panels) and 4 October (right panels), 2013, during particularly constant wind direction conditions, which 5 persisted after a wind shift of a few tens of degrees. Such a constancy in wind direction, 6 7 necessary for the following demonstration, is very rare. Combined to the strict selection procedure, only two cases were exploitable in this context. The 2-m wind speed, wind direction, 8 9 profiled-derived C_{DN10} values and aeolian snow mass flux recovered by the second-generation FlowCaptTM sensor are shown in Figure 4. As the friction velocity is the actual dynamic quantity 10 involved in aerodynamic entrainment of surface snow particles (Gallée et al. 2001), it is also 11 12 plotted on the graph. The two events are split into three parts, before (A_i), during (B_i) and after (C_i) the shift in wind direction. The occurrence of precipitation may affect the detection of 13 erosion events because the FlowCapt[™] sensor does not distinguish between eroded (saltating 14 particles and/or suspended particles of snow) and precipitating snow particles. No visual 15 16 observation of precipitation from the nearby Dumont d'Urville station were available for the period concerned. Moreover, as Adélie Land is very prone to aeolian transport of snow 17 Trouvilliez et al. (2014), these observations, if performed, are limited by the inability to 18 19 discriminate between actual precipitation and pure drifting snow. Here we used the operational 20 analyses of the European Center for Medium-Range Weather Forecasts (horizontal resolution of ~16 km) to evaluate the occurrence of precipitation at our measurement site. We assumed 21 22 that both events were pure erosion events after finding negligible precipitation rates for the fully 23 continental grid point including D17.

24 At the beginning of Julian day (JD) 87 (part A₁), the wind direction was around 140°, the friction velocity was above the erosion threshold with a related aeolian snow mass flux of 100 25 g m⁻² s⁻¹, and C_{DN10} was near 1.5 x 10⁻³. At the end of JD 87 (part B₁), the wind rotated toward 26 160° while C_{DN10} increased to nearly 3.3 x 10⁻³, i.e. by 120%, in response to a wind shift of 27 only 20°. As assumed in Jackson and Carroll (1978) and Andreas and Claffey (1995), it is likely 28 that as the wind turned, it was deflected from the mean sastrugi axis, thereby encountering a 29 rougher surface. As a result, C_{DN10} soared, reflecting the growing contribution of the sastrugi 30 31 form drag to the vertical momentum flux at the surface, and hence to the total surface drag. Within the same time frame, the measured aeolian snow mass flux fell by ~30% from 365 to 32

- $260 \text{ g m}^{-2} \text{ s}^{-1}$, despite increasing friction velocity (wind speed) from 0.7 to 1.6 (18 to 24) m s⁻¹. 1 2 Then, until the end of the event (part C_1), the wind direction remained centered about 160°. From 0330 UT to 0630 UT on JD 88, C_{DN10} fell back to 1.5 x 10⁻³ as high winds presumably 3 streamlined the surface. In other words, C_{DN10} was reduced by ~50% in only 3 hours. As C_{DN10} 4 decreased, the aeolian snow mass flux again rose above 400 g m⁻² s⁻¹. The erosion event lasted 5 through JD 90 when u_* (wind speed) dropped to 0.7 (15) m s⁻¹, causing a significant decrease 6 in the aeolian snow mass flux. After nearly 48 hours of persistent erosive winds, C_{DN10} was as 7 8 low as 1.3×10^{-2} .
- During the two days that preceded the second erosion event (part A₂), the wind direction was 9 within $\pm 10^{\circ}$ of 150°, the friction velocity was generally not strong enough to erode the snow 10 surface, and C_{DN10} was between 1.3 – 1.6 x 10⁻³. C_{DN10} and wind direction were strongly 11 correlated during this period, with the lowest drag coefficients occurring for a wind direction 12 13 of around 140°, suggesting that this was the sastrugi alignment before erosion started and the wind changed direction. Then, the same situation depicted in the left panels of Figure 4 occurred 14 15 again. At mid-JD 286 (part B₂), u_{*}increased beyond the erosion threshold as the wind rotated from 150° to 180°. Consequently, C_{DN10} increased to 1.9 x 10⁻³. The aeolian snow mass flux 16 dropped simultaneously from 320 to 55 g m⁻² s⁻¹ under increasing friction velocity. That is, for 17 $a \sim 30\%$ increase in C_{DN10} as the result of a wind deflection of 30°, the aeolian snow mass flux 18 decreased by ~80%. Together with the first case of erosion, this illustrates how the form drag 19 20 exerted by sastrugi can significantly affect snow erosion when the wind and sastrugi are not 21 aligned (this effect is discussed later in the paper; see Section 4). Then (part C₂), the wind 22 direction remained roughly unchanged until erosion ceased. Again, the rise in aeolian snow mass flux coincided with a decrease in C_{DN10} . After nearly 3 hours of winds above 20 m s⁻¹ (u_{*} 23 $> 0.9 \text{ m s}^{-1}$) from 180°, C_{DN10} fell from 1.9 x 10⁻³ to 1.4 x 10⁻³, i.e. decreased by ~30%. 24
- In summary, for friction velocities (wind speeds) around 1 (20) m s⁻¹ and above, the sastrugi streamlining timescale can be as fast as 3 hours. For a windflow initially aligned with the sastrugi, a deviation of 20-30° from the streamlining direction has the potential to both increase C_{DN10} by 30-120% and to significantly reduce (up to 80%) the aeolian snow mass flux, even under increasing friction velocity.

30 **4. Discussion**

At Ice Station Weddell, Andreas and Claffey (1995) measured a decrease in C_{DN10} of 20-30% in 12 hours with considerably weaker winds (< 12 m s⁻¹) than those reported here. The

1 observations reported in this paper show that this timescale can be 4 times faster for winds exceeding 20 m s⁻¹ ($u_* > 1$ m s⁻¹), and the associated decrease in C_{DN10} can reach 50%. And reas 2 and Claffey (1995) also proposed generic C_{DN10} values in the range 1.5-1.7 x 10⁻³ when the 3 wind is well aligned with the sastrugi, and around 2.5×10^{-3} when the wind is at an angle of 20° 4 to the dominant orientation of the sastrugi. In both cases, the present results differ slightly from 5 these values: C_{DN10} was more in the range 1.3-1.5 x 10⁻³ for sastrugi-parallel winds, and 6 increased to more than 3×10^{-3} with wind shifts of similar amplitude. For a given erosion 7 8 threshold, the quantity of windborne snow increased with wind strength according to a power 9 law (Radok 1977; Mann 2000). As sastrugi mainly form through snow erosion/deposition 10 processes (Filhol and Sturm 2015), it is likely that under the strong wind (shear) conditions in 11 Adélie Land, rougher snow surfaces develop, whose aerodynamic adjustment ability is greater than at the less windy Ice Station Weddell. 12

13 It can be argued that friction velocity also influences the value of C_{DN10} . It is true that changes 14 in the wind during saltation are perceived by the flow as an increase in surface roughness due 15 to the straight line extrapolations of the wind velocity on a log-linear plot from above the 16 saltation layer down to U=0 (Anderson and Haff 1991; Bintanja 2001). Therefore, the saltation 17 layer behaves as solid roughness. Owen (1964) suggested that the aerodynamic roughness 18 length should scale as u_*^2/g , roughly the height to which saltating particles are ejected. He wrote

$$z_0 = \alpha \frac{u_*^2}{g},\tag{5}$$

with α a constant and g the gravitational acceleration. However, aeolian snow mass flux peaks 19 did not match C_{DN10} peaks. However, significant variations in C_{DN10} strongly correlated to the 20 wind direction were observed during roughly constant friction velocity conditions and in the 21 absence of drifting snow (Part A2, Fig. 4). Moreover, aeolian snow mass flux peaks did not 22 match C_{DN10} peaks for both erosion events. A simple order-of-magnitude calculation allows the 23 assessment of Owen's relation during a period of drifting snow at our measurement site. From 24 06:00 UT on JD 88 to 06:00 UT on JD 89 during part C_1 , the wind speed is around 27 m s⁻¹, 25 drifting snow is active with an aeolian snow mass flux around 350 g m⁻² s⁻¹, and u* and C_{DN10} 26 are about 1.1 m s⁻¹ and 1.5 x 10⁻³. According to Eq. (5), the corresponding value for α is 2.7 x 27 10⁻³. Using Eq. (5) with this value of α to predict the increase in z₀ during period B₁ when u* 28 reaches 1.7 m s⁻¹ yields $z_0 = 7.8 \times 10^{-4}$ m, that is, $C_{DN10} = 1.79 \times 10^{-3}$. This last value is well 29 below the observed one of 3.3×10^{-3} . Here the height of the saltation layer was probably not a 30

1 major determinant of the roughness length, and the variability in C_{DN10} (or z_0) due to Owen's

effect was presumably swamped by those due to sastrugi alignment. A single-parameter
formulation for z₀ as (5) is therefore innately incomplete, a conclusion already reached by

4 Raupach (1991) and Andreas and Claffey (1995).

During both erosion events, the FlowCapt[™] sensor measured significant aeolian snow mass 5 fluxes for 2-m wind speeds (u_{\star}) of 10 (0.6) m s⁻¹ or above. As the wind (friction) velocity likely 6 frequently exceeds this threshold on the coastal slopes of Adélie Land, the sastrugi alignment 7 8 process might be also frequently active, depending on persistence of the wind. As explained in Section 1, this mechanism is probably also strongly controlled by the properties of the snow 9 surface that determine the threshold shear stress required for erosion to begin rather than only 10 11 the characteristics of the wind. Since the erosion flux is the integrated result of both the capacity 12 of the wind to erode and carry snow, and snow surface erodibility, the sastrugi streamlining 13 timescale presumably mostly depends on this specific quantity. The implication is that the drag 14 coefficient must be strongly related to other factors including the current wind orientation and the history of the wind's interactions with the snow surface as well as past timescales and past 15 16 temperatures of the snowpack.

On the other hand, the sastrugi streamlining timescale also appears to control snow erosion in 17 18 the form of feedback by fixing the time during which the sastrugi form drag mainly contributes 19 to total surface drag. With friction velocities above the snow erosion threshold, increasing u_* 20 could be expected to result in an increase in erosion efficiency. However, in both cases, the 21 observations showed a significant decrease in the aeolian snow mass flux in phase with an 22 increase in the drag coefficient (Figure 4, parts B). By analogy with measurements made in a water flume (Wiberg and Nelson 1992; Le Bouteiller and Venditti 2015), it can be considered 23 24 that the flow and turbulence in the sastrugi region are the result of interaction between flow 25 separation and wake formation, which can lead to a local Reynolds shear stress peak 26 corresponding to flow separation. Above the region of influence of the wake, named outer 27 region, the flow has adjusted to increased roughness and exhibited a logarithmic profile, as shown by the relative continuous time series of C_{DN10} and u_* despite the strict selection 28 29 procedure (Fig. 4). Even if the shear stress of the outer flow (τ) is relatively easy to measure, it 30 cannot be extrapolated to the snow bed. The averaged snow bed shear stress (also referred to as skin friction in the literature), which is the ultimate parameter for aeolian erosion (Li and Shao 31 2003), varies depending on its position along the sastrugi field. In absence of direct 32 measurements, it is necessary to link outer shear stress, sastrugi geometry, and skin friction to 33 be able to estimate aeolian snow mass fluxes. This is guite important since the reduction of 34

shear stress near the surface is crucial in limiting the growth of the mass flux (Groot Zwaaftink 1 2 et al., 2014). For erodible forms in riverbeds such as ripples, Smith and McLean (1977) and later Wiberg and Nelson (1992) developed a method for partitioning the outer shear stress. 3 These authors considered that the averaged bed shear stress is equal to the difference between 4 5 the outer shear stress and the drag-related stress produced as the flow is forced around the 6 bedform -i.e., in the present case, the form drag induced by the sastrugi. As mentioned above, 7 an increasing form drag can be expected, and hence a decrease in skin friction and in aeolian snow mass flux, when the wind direction gradually shifts away from the longitudinal axis of 8 9 the sastrugi. Because C_{DN10} reflects the contribution of the sastrugi form drag, knowing the drag coefficient is not sufficient to estimate skin friction. A better knowledge of skin friction 10 11 over a sastrugi field is also needed to improve aeolian snow mass flux parameterizations in 12 aeolian erosion models. The measurements made in the present study showed that a 13 considerable decrease (even 80%) of the aeolian snow mass flux can occur during the transitional regime during which the wind and sastrugi are not aligned (Figure 4, parts B). But 14 15 it should be also noted that the rapid aerodynamic adjustment of sastrugi (3 hours) will limit errors if the aeolian snow transport event considered is strong and sufficiently long. 16

17 **5.** Conclusion

18 An experimental meteorological dataset collected in coastal Adélie Land during austral winter 19 2013 was exploited to document surface turbulent fluxes of momentum and snow over an 20 Antarctic sastrugi field. The main results of the analysis of two erosion events can be 21 summarized as follows:

- 22 C_{DN10} values were in the range of $1.3-1.5 \times 10^{-3}$ when the wind was well aligned with 23 sastrugi and increased to 3×10^{-3} or higher with wind shifts of only 20-30°,
- As C_{DN10} increases, the aeolian snow mass flux may decrease (to 80%) in response to
 the wind shift in direction,
- the timescale for the aerodynamic adjustment of sastrugi can be as low as three hours
 for friction velocities of 1 m s⁻¹ or above and during strong windborne snow conditions,
- because C_{DN10} includes the contribution of the sastrugi form drag, knowing C_{DN10} is
 not sufficient to estimate the erosion flux that results from drag partitioning at the
 surface.

These results support the existence of mechanisms linking aeolian particle transport and surface 1 2 drag properties over (Antarctic) snow, as already demonstrated for other erodible natural 3 surfaces (Marticorena and Bergametti 1995). In contrast with non-erodible roughness elements 4 such as rocks or vegetation, these mechanisms involve the time needed for sastrugi to adjust to 5 the main wind (3 hours in both erosion events), during which both the drag coefficient and the 6 aeolian snow mass flux can be greatly modified. In comparison, Andreas and Claffey (1995) 7 reported a longer timescale (12 hours) for the sastrugi to realign with weaker winds. Because 8 lighter winds are supposed to be associated with lower erosion fluxes, it is suggested that the 9 sastrugi streamlining timescale most likely depends on the snow erosion flux. Real-time observations of the distribution (size, abundance, orientation) of the sastrugi would 10

further advance understanding of the physical processes involved in the development of sastrugi 11 and enable better characterization of sastrugi aerodynamic adjustment timescales. In addition, 12 having a more accurate representation of the distribution of sastrugi would make small-scale 13 14 modeling in a wind tunnel possible, in which case, it would be possible to realistically estimate 15 shear stress partitioning. One possible way to monitor sastrugi would be to set up an automatic mini laser-scan. Such a device was developed in the framework of the MONISNOW research 16 17 project (Picard and Arnaud, LGGE, personal communication) and has been operating daily at Dome C in Antarctica since the beginning of 2015. These complementary approaches are vital 18 19 to improve parameterization schemes for aeolian snow transport models and general drag

20 parameterizations for weather, climate and earth system models.

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2 Fig. 1. Map of Adélie Land showing the location of Dumont d'Urville station and measurement

3 site D17. Contour lines are in meters.

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2 Fig. 2. Photograph of the snow surface at D17 in January 2014. The arrow indicates the mean

3 direction of the wind episode that led to the formation of the sastrugi.





Fig. 3. The measurement structure deployed at D17.



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Fig. 4. Two erosion events showing sastrugi responses to shifts in wind direction. Note the different vertical scales between right and left panels concerning measured 2-m wind speed and profile-derived C_{DN10} and u_* values. The aeolian snow mass fluxes come from the secondgeneration FlowCaptTM sensor set up from 0 to 1 m above the snow surface. In both cases, the event is split into three parts, respectively before (A_i), during (B_i) and after (C_i) the wind shift.