

1 **Geodetic mass balance record with rigorous uncertainty**
2 **estimates deduced from aerial photographs and LiDAR data.**
3 **Case study from Drangajökull ice cap, NW-Iceland**

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9
10 **Abstract**

11
12 In this paper we describe how recent high resolution Digital Elevation Models (DEMs) can be
13 used to extract glacier surface DEMs from old aerial photographs and to evaluate the
14 uncertainty of the mass balance record derived from the DEMs. We present a case study for
15 Drangajökull ice cap, NW-Iceland. This ice cap covered an area of 144 km² when it was
16 surveyed with airborne LiDAR in 2011. Aerial photographs spanning all or most of the ice cap
17 are available from survey flights in 1946, 1960, 1975, 1985, 1994 and 2005. All ground control
18 points used to constrain the orientation of the aerial photographs were obtained from the high
19 resolution LiDAR DEM. The LiDAR DEM was also used to estimate errors of the extracted
20 photogrammetric DEMs in ice and snow free areas, at nunataks and outside the glacier margin.
21 The derived errors of each DEM were used to constrain a spherical semivariogram model,
22 which along with the derived errors in ice and snow free areas were used as inputs into 1000
23 Sequential Gaussian Simulations (SGSim). The simulations were used to estimate the possible
24 bias in the entire glaciated part of the DEM and the 95% confidence level of this bias. This
25 results in bias correction varying in magnitude between 0.03 m (in 1975) and 1.66 m (in 1946)
26 and uncertainty values between ± 0.21 m (in 2005) and ± 1.58 m (in 1946). Error estimation
27 methods based on more simple proxies would typically yield 2-4 times larger error estimates.
28 The aerial photographs used were acquired between late June and early October. An additional
29 bias correction was therefore estimated using a degree day model to obtain the volume change
30 between the start of two hydrological years (1 October). This correction corresponds to an

1 average elevation change of -3.5 m in the worst case for 1960, or $\sim 3/4$ of volume change
2 between the 1960 and the 1975 DEMs. The total uncertainty of the derived mass balance record
3 is mostly due to uncertainty of the SGSim bias correction, the uncertainty of the seasonal bias
4 correction and the uncertainty of the interpolated glacier surface where data is lacking. The
5 record shows a glacier-wide mass balance rate of $\dot{B} = -0.26 \pm 0.04$ m w.e. a^{-1} for the entire
6 study period (1946-2011). We observe significant decadal variability including periods of mass
7 gain, peaking in 1985-1994 with $\dot{B} = 0.27 \pm 0.11$ m w.e. a^{-1} . There is a striking difference if
8 \dot{B} is calculated separately for the western and eastern halves of Drangajökull, with a reduction
9 of eastern part on average ~ 3 times faster than the western part. Our study emphasises the need
10 of applying rigorous geostatistical methods for obtaining uncertainty estimates of geodetic mass
11 balance, the importance of seasonal corrections of DEMs from glaciers with high mass turnover
12 and the risk of extrapolating mass balance record from one glacier to another even over short
13 distances.

14

15 **1 Introduction**

16 Mountain glaciers and ice caps accounted for more than half of the land ice runoff contribution
17 to global mean sea level rise during the 20th century (Vaughan et al., 2013). Understanding
18 how these glaciers respond to a changing climate is essential to close the budget of the sea-level
19 rise over the last decades and project the sea-level rise in the near future. In recent years an
20 increased part of our knowledge on how these glaciers are changing has been based on remote
21 sensing. The majority of these studies describe current or recent glacier changes in different
22 parts of the globe applying geodetic methods (Gardelle et al., 2012; Berthier et al., 2010). Others
23 have presented results on the geodetic mass balance extending further back (e.g. Fischer et al.,
24 2015; Nuth et al., 2007; Soruco et al., 2009); these studies are particularly important since they
25 indicate how the glaciers responded to 20th century climate variability. Such observations can
26 be used to constrain or correct glacier mass balance models that are used to estimate how the
27 glaciers will respond to future climate changes (e.g. Clarke et al., 2015).

28 Studies on long term geodetic mass balance are generally based on digitised contour maps, with
29 some exceptions where mass balance records have been derived from Digital Elevation Models
30 (DEMs) extracted from old archives of aerial photographs applying digital photogrammetry
31 (e.g. James et al., 2006; 2012). The applicability of geodetic mass balance records as a key to
32 predicting future glacier changes depends on the accuracy of such records and their resolution.

1 To maximize both the accuracy and the resolution we should rather focus, if possible, on
2 archives of aerial photographs, because:

3 i) These archives often span more epochs than the published topographic maps.

4 ii) With new and rapidly improving tools in digital photogrammetry the potential to produce
5 much more accurate and detailed DEMs than those deduced by interpolating elevation contours
6 from old maps has increased significantly.

7 iii) The availability of high resolution DEMs has opened a new source of ground control points
8 (GCPs) for constraining the orientation of photogrammetric DEMs (James et al., 2006; Barrand
9 et al., 2009). Like ii), this will lead to more accurate DEMs from aerial photograph archives in
10 future studies. New spaceborne sensors such as Worldview and Pléiades may allow such studies
11 in remote areas without conducting expensive field campaigns to survey GCPs (Papasodoro et
12 al., 2015).

13 In order to maximize the value of geodetic mass balance records, realistic uncertainty
14 assessments are required. If the uncertainty is overestimated, the value of the information that
15 we can extract from the geodetic data will be diminished, the results will be neglected by the
16 scientific community or not even be published. If, however, the uncertainty is underestimated,
17 geodetic mass balance records with significant errors will be interpreted as solid observations.
18 When extracting volume change from two different DEMs a common approach is to use the
19 standard deviation of the DEM difference in the unglaciated part of the DEMs as a proxy for
20 the uncertainty of the average elevation change (e.g. Cox and March, 2004). This method
21 corresponds to an extreme case, assuming that the errors of the surface elevation change are
22 totally correlated between all grid cells within the glacier. The opposed extreme case assuming
23 that the errors of surface elevation change are totally uncorrelated between all grid cells has
24 also been applied in the literature (e.g. Thibert et al., 2008). This approach results in an
25 estimated uncertainty reduced by a factor \sqrt{n} compared to the totally correlated uncertainty
26 where n is the number cells for which the difference is calculated. The third alternative, where
27 the spatial dependence of the DEM errors is estimated and inherent in the uncertainty estimate,
28 was described by Rolstad et al. in 2009. This method results in uncertainty somewhere between
29 the two extremes and has been adopted in several studies (e.g. Trüssel et al., 2013; Zemp et al.,
30 2013; Fischer et al., 2015). This method includes some simplifications, which so far have not
31 been validated with other geostatistical methods.

1 Here, we present a case study of Drangajökull ice cap in NW-Iceland (Fig. 1) based on seven
2 sets of aerial photographs in 1946-2005 and a LiDAR DEM obtained from an airplane in 2011
3 (Jóhannesson et al., 2013). The glacier covered an area of 144 km² in 2011 and is the 5th largest
4 glacier in Iceland. This study describes an alternative method to estimate uncertainties of the
5 average elevation change derived by differencing DEMs, applying geostatistical methods. The
6 approach, which uses the DEM difference from ice and snow free areas as input, allows for a
7 simultaneous estimate of a bias correction for the glaciated part of the DEMs. Both the
8 estimated uncertainty and the bias correction are compared with results from conventional
9 methods. We also interpolate volume changes in areas where data is lacking and inspect how
10 much of the derived volume change may be caused by seasonal variation. The study results in
11 a seasonally corrected mass balance record of Drangajökull ice cap with estimates of possible
12 errors contributing to the record as well as the derived net uncertainty.

13

14 **2 Data and methods**

15 In this study, seven sets of aerial photographs covering Drangajökull ice cap in 1946, 1960,
16 1975, 1985, 1986 and 1994 from the archives of the National Land Survey of Iceland,
17 Landmælingar Íslands, and in 2005 from Loftmyndir ehf were used. Negative films were
18 scanned with a photogrammetric scanner in a resolution of 15 µm and 20µm. The aerial
19 photographs have an average scale between ~1:30000 and ~1:40000, which result in a Ground
20 Sampling Distance (GSD) of ~0.4 m to ~1 m. Complete camera calibration information is
21 available for the surveys of 1975, 1985, 1986, 1994 and 2005, but calibration information is
22 lacking for the oldest flights (1946 and 1960). Only the focal length is available for the
23 photographs of 1946, and focal length and radial distortion are available for the photographs of
24 1960. Table 1 summarizes the main characteristics of each series.

25 During the International Polar Year (IPY) 2007–09, a major effort was initiated to produce
26 accurate DEMs of all the major Icelandic glaciers and ice caps (Jóhannesson et al., 2013). In
27 July 2011 Drangajökull ice cap was surveyed with airborne LiDAR model Optech ALTM 3100.
28 The LiDAR DEM covers the entire ice cap as well as the close vicinity of the glacier, which
29 provides a useful reference to constrain and validate the other DEMs produced in this study.
30 Specifications of the survey are described in Jóhannesson et al., 2013. The average density of
31 the point cloud measured with the LiDAR corresponded 0.33 hits m⁻². The high density
32 facilitates a well constrained bi-linear interpolation of the point cloud into a grid with 2mx2m
33 cell size. Cells where the distance to nearest LiDAR hit exceeds 4 m were masked out. A

1 comparison of differential GPS profiles and 5mx5m grid derived from identical Lidar survey
2 in the Snæfelljökull ice cap in western Iceland indicated vertical accuracy well within 0.5 m
3 (Jóhannesson et al., 2011).

4 **2.1 Creation of DEMs and orthorectified photographs**

5 The DEMs were created from the aerial photographs using the software bundle IMAGINE
6 Photogrammetry (© Intergraph). The photogrammetric processing is carried out in four steps:
7 Orientation of the images, automatic stereo matching, manual editing of the DEMs and
8 orthorectification of aerial photographs.

9 Each series of aerial photographs was oriented individually by means of a rigorous bundle
10 adjustment (Wolf and Dewitt, 2010). The glacier is covered by a single series of images for all
11 years except in 1960 when the glacier was covered by three tiles, one per date (Table 1). Tie
12 points were automatically measured in the images and semi-automatically revised, ensuring a
13 good connection between all the adjacent photographs and between strips. The exterior
14 orientation was constrained by using series of Ground Control Points (GCPs) extracted from
15 the LiDAR DEM (2mx2m cell size) applying a similar approach to the one carried out by James
16 et al. (2006). The LiDAR DEM was viewed as a hillshade with approximately the same sun
17 position as during the acquisition of the photographs. This allowed recognition of and extraction
18 of GCPs from stable features such as boulders and sharp edges in the ice-free areas. To ensure
19 stability in the orientation a fairly regular distribution of GCPs over the photographed area as
20 well as over the elevation span of the terrain is required (Kraus, 2007; Nuth and Kääb, 2011).
21 Artificial dip or rise in the DEM due to insufficient coverage of GCPs would skew the geodetic
22 mass balance record and make its uncertainty estimate explained below less valid (further
23 explained in Sect. 2.2). In our case the nunataks of Drangajökull ice cap allows fairly even
24 spatial and vertical distribution of GCPs for all epochs (GCP locations shown for each DEM in
25 Fig. 2). The photogrammetric orientations performed in this study never span more than 2
26 photographs without having constraints from a GCP. This is considered as sufficient coverage
27 of GCPs for a reliable orientation (Kraus, 2007). The assigned uncertainty of the GCPs used in
28 the DEM processing was 2 m standard deviation in XY and 0.5 m for Z corresponding
29 respectively to the Lidar DEM resolution and expected vertical accuracy. A significant part the
30 large scale errors in the derived photogrammetric DEM may be related to errors in the GCPs
31 3D locations, particularly for DEMs from 1975 and later when other data constraining the
32 geometric model are relatively accurate. For the 1946 and 1960 DEMs a lack of camera
33 calibration information is likely to be a more important source of errors.

1 The orientation of the 1960 images was carried out using the focal length and lens distortion
2 information obtained from the calibration report of the DMA Cameras (Spriggs, 1966). The
3 1946 images included information of the focal length written at the margin of the first image of
4 each strip. Both cases needed auxiliary pre-calibration, therefore pseudo-fiducial marks were
5 created allowing the location of a pseudo-principal point (see e.g. Kunz et al., 2012, for details).
6 The orientation of both sets of images included additional parameters in the bundle adjustment
7 for refinement of the camera geometry. Bauer's model (Bauer and Müller, 1972) was used for
8 the images of 1946 and Jacobsen's model (Jacobsen, 1982) was used for the images of 1960.

9 Once oriented, we produced the elevation point clouds from stereo-matching of the images. The
10 routine eATE (enhanced Automatic Terrain Extraction) of the software allows for a pixel-wise
11 evaluation in the matching process, thus obtaining a high density of points. The low-contrast in
12 firn and snow covered areas caused failures in the matching process. The point clouds for low-
13 contrast areas were therefore created from reduced resolution of the stereo images and a larger
14 windows size and lower correlation coefficient of the stereo matching. This resulted in an
15 improved coverage of points automatically measured in the snow-covered areas. A first edition
16 of the point clouds was carried out with the software CloudCompare (GPL Software); automatic
17 outlier removal was performed using the routine "Statistical Outlier Removal" (Rusu et al.,
18 2011). The dense point clouds were then subsampled in regular density of points corresponding
19 to ~10mx10m spacing for all epochs except 1946 and 1985 for which density equivalent to
20 ~20mx20m spacing was applied. This was done to reduce the size of the point clouds and
21 remove double points that could introduce noise when interpolating the point clouds as a grid
22 with fixed cell size (Sect. 2.2 and 2.3). The lower subsampled point density was due to large
23 GSD in the case of 1946 and high level of noise in the images in 1985, resulting in large amount
24 of outliers. Finally a thorough manual revision of the results in stereoscopic vision was carried
25 out, editing the DEMs in the glacier areas where the automatic matching failed and surface
26 details were still perceptible.

27 To delineate the glacier margin and mask out snow covered areas (Sect. 2.2 and 2.4)
28 orthorectified photographs were required. The orthorectification was carried out using
29 preliminary DEMs linearly interpolated from the point clouds as grids with 10mx10m (DEMs
30 of 1960, 1975, 1994 and 2005) and 20x20m cell size (DEMs of 1946 and 1985). The series of
31 1975 included 2 strips finishing on the glacier (Fig. 2) without covering completely the glacier
32 in stereo. These images were orthorectified using the LiDAR DEM, revealing the location of
33 the glacier margin at its intersection with the bare ground, free of ice and snow in both 1975

1 and 2011 (resulting in insignificant elevation change at the 1975 margin location in this area).
2 The orthorectification of all the series of photographs was performed in resolution
3 corresponding to a 2mx2m pixel size.

4 **2.2 DEM error assessment and bias correction**

5 We use the high resolution LiDAR DEM obtained in 2011 to assess the quality of the
6 photogrammetric DEMs. The photogrammetric DEMs are expected to be of significantly worse
7 quality in terms of accuracy than the LiDAR data and we therefore assume for simplicity that
8 statistical parameters derived from the difference between the photogrammetric DEM and the
9 LiDAR DEM (in areas assumed stable) describe errors in the photographic DEM. This is likely
10 to produce a minor underestimate of the actual quality of the photographic DEMs. As described
11 below, all photogrammetric DEMs were bias corrected relative to the LiDAR DEM. A possible
12 bias in the absolute location of the LiDAR DEM does not affect our result since this the bias is
13 cancelled out when calculating the difference between the DEMs.

14 The first step in estimating the quality of a DEM derived from the aerial photographs was
15 calculating the difference between the photogrammetrically derived point clouds (Fig. S1 in
16 Supplement) and the LiDAR DEM with 2mx2m cell size. This was calculated using the residual
17 operation in Surfer 12 (©Golden Software, Inc). From this a digital model of the difference
18 between the DEMs was linearly interpolated for a grid with 20mx20m cell size. All cells with
19 snow or glacier cover at either or both dates (photograph and LiDAR acquisitions) were masked
20 out as well as cells where distance to the next element of the point cloud exceeds 40 m. The
21 glacier outlines were delineated manually (see Sect. 2.4) and the snow covered areas were
22 derived with semiautomatic classification of the orthorectified aerial photographs and the
23 intensity images derived from the LiDAR scanning. The mean and the standard deviation (σ)
24 of the derived difference (photogrammetric DEM - LiDAR DEM) of the remaining data after
25 snow and glacier masking is shown in Table 2.

26 Extraction of geodetic mass balance requires co-registered DEMs prior to calculation of glacier
27 volume changes. This usually includes estimates of relative vertical and horizontal shift
28 between the DEMs using areas where the elevation change is expected to be insignificant
29 (Kääb, 2005; Nuth and Kääb, 2011; Guðmundsson et al., 2011). In this study the GCPs used
30 during the orientation of the photographs were extracted from the LiDAR DEM in maximum
31 resolution (2mx2m cell size). We were able to extract several GCPs at nunataks near the glacier
32 centre. The distribution of GCPs is therefore fairly regular over the survey area in all cases both

1 spatially (Fig. 2) and with elevation. The orientation of aerial photographs resulted in horizontal
2 RMSE of the GCPs <3m in all cases, and typically 1-2 m (Table 2). These values are obtained
3 from least square adjustment resulting in residual mean equal to zero. The horizontal shift
4 relative to the LiDAR DEM is likely to exceed the derived horizontal RMSE locally for a given
5 photogrammetric DEM. It is however unlikely that the average horizontal shift relative to the
6 LiDAR DEM exceeds the derived horizontal RMSE of the GCPs. We therefore concluded that
7 horizontal shift corrections are not required for the photographic DEMs.

8 The elevation difference between DEMs covering stable areas is commonly used to estimate
9 zero order (bias correction, see e.g. Nuth and Kääb, 2011; Guðmundsson et al., 2011) or higher
10 order correction (e.g. Rolstad, 2009; Nuth and Kääb, 2011) to compensate for slowly varying
11 errors in DEM difference over glaciated areas. The result from such approach is, however,
12 sensitive to the area chosen as the reference area. One can choose to use the entire area covered
13 by both DEMs outside the glacier or an area limited by a certain distance from the glacier. In
14 this study we apply geo-statistical methods for deriving bias correction of each
15 photogrammetric DEM within the glacier and an estimate of the uncertainty in the derived bias
16 correction. These calculations consisted of five main steps:

17 1) Preparation of DEM error input data (derived from the comparison with the LIDAR),
18 explained below. Resulting error data from ice and snow-free areas is shown in Fig. 3.

19 2) Transformation of the derived DEM errors into a new variable with the nscore function
20 (Deutsch and Journel, 1998) in WinGSLib V.1.5.8 (© Statios LLC). The histogram of the new
21 variable fits a normal distribution, with zeros mean and $\sigma=1$. This step is a recommended
22 preparation of a dataset for valid Sequential Gaussian Simulation (SGSim) carried out in step 5
23 particularly if the histogram of the DEM error does not closely resemble a normal distribution.

24 3) Calculation of semivariogram for the nscored input data, in which the semivariogram
25 describes the variance, γ , of a given coordinate-based variable as a function of distance, d ,
26 between sampled locations.

27 4) Calculation of a spherical semivariogram model, fitting the derived semivariogram.

28 5) Use of the derived spherical model and the nscored data that constrain the semivariogram to
29 run 1000 Sequential Gaussian Simulation (SGSim) of the nscored errors in the glaciated areas
30 using the sgsim function (Deutsch and Journel, 1998) in WinGSLib. The sgsim function includes
31 reversed transformation from the nscored variable to the derived DEM error. SGSim are
32 commonly applied in errors assessments of geo-statistical studies (e.g. Lee et al., 2007;

1 Cardellini et al., 2003). The results from the sgsim runs were used to estimate both the most
2 likely bias of each photogrammetric DEM within the glacier and 95% confidence level of this
3 bias, as explained further below.

4 The approach adopted here requires that the statistics of the DEM errors outside the glacier are
5 descriptive for the errors in the photogrammetric DEM within the glacier margin. This should
6 be kept in mind, both during the photogrammetric processing and in the preparation of input
7 data (step 1) used in the geo-statistical calculation. The photogrammetric processing requires
8 fairly even spatial distribution of GCPs, otherwise artificial dip or rise in the photogrammetric
9 DEM are likely to be produced in areas far from a GCP (Kraus, 2007). Such errors would not
10 be represented in a semivariogram based on DEM error in areas where distribution of GCPs is
11 adequate.

12 The low contrast of snow covered glacier surface may also result in a difference in error
13 statistics between the glacier and the ice and snow free areas (Rolstad et al., 2009). The low
14 contrast should mostly produce high frequency errors, whereas low frequency errors are mostly
15 caused by an inaccurate orientation. The eATE configuration used resulted in fewer but better
16 matching points in the low-contrast areas (Sect. 2.1) and the thorough manual 3D revision likely
17 removes most of the high frequency noise in the resulting DEM. A semivariogram of the
18 difference between the point cloud in 1946 at low contrast glacier areas and the LiDAR DEM
19 (blue crosses in Fig. 4c) reveals the variance with distance for the elevation error plus the
20 elevation changes in 1946 to 2011. The variance of elevation changes over short distance should
21 be small for smooth glacier surface. At short distances the semivariogram should therefore
22 mainly represent the DEM errors. For $d < 200$ m the low contrast areas show variance at similar
23 level as for the DEM error data outside the glacier (Fig. 4c) indicating similar level of high
24 frequency error for the two area types. This supports that the errors in low contrast area are
25 unlikely to skew significantly our geo-statistical analyses.

26 A difference in terrain slope between areas can produce a significant difference in the calculated
27 semivariogram (Rolstad et al., 2009). Local horizontal shift between DEMs can produce
28 significant artificial elevation difference in steep areas. The average slope on the glacier in 2011
29 was 6.2° whereas the unglaciated area in the 2011 LiDAR DEM had an average slope of 9.8° .
30 The preparation of our data (step 1) therefore includes exclusion of all data where slope exceeds
31 20° ; unglaciated area in the 2011 LiDAR DEM below this slope limit has an average slope of
32 7.2° .

1 The glaciated parts of the photogrammetric DEMs were all manually revised using 3D vision,
 2 securing removal of significant outliers within the glacier. A thorough revision was not carried
 3 out for the unglaciated areas. Instead we apply automatic removal of outliers. This was carried
 4 out by calculating standard deviation of the DEM error (photogrammetric DEM- LiDAR
 5 DEM), $\sigma_{\epsilon h}$ (after masking out snow-covered, glacier-covered and steep areas) and filtering the
 6 DEM difference with a 500mx500m median filter. Values where the difference between the
 7 unfiltered and the median filtered value DEM difference exceeded $\sigma_{\epsilon h}$ were then masked out.
 8 The mean DEM error and $\sigma_{\epsilon h}$ after the slope and outlier masking is shown in Table 2.

9 The semivariograms obtained with (step 3) and without the nscore transformation of the 1946
 10 DEM error in ice and snow free areas are shown in Fig. 4a-b. The spherical semivariogram
 11 model calculated in step 4 is given as function of d (distance between sampled locations):

$$\begin{aligned}
 \gamma(d) &= 0 & d &= 0 \\
 &= c_0 + c_1 \left[\frac{3d}{2r} - \frac{1}{2} \left(\frac{d}{r} \right)^3 \right] & 0 < d \leq r \\
 &= c & d > r
 \end{aligned} \tag{1}$$

15 $c = c_0 + c_1$ and $\gamma(0)$ describes the correlation of a point with itself. The main parameters in
 16 the model, nugget (c_0), range (r) and sill (c) are shown in the Fig. 4b. We expect c to equal
 17 approximately the global variance of the data set, hence $c \sim 1$ for the nscored data. The shape
 18 of the semivariograms that we obtain (Fig. 4a-b and Fig. S2 in supplementary data) indicate a
 19 reasonable fitting with a single spherical model unlike in the study by Rolstad et al., (2009)
 20 where two spherical models describing the variance at different ranges of distances were
 21 required.

22 The size of the DEM error grid (in full resolution (20mx20m cell size) was too large for the
 23 sgsim function to operate (step 5). The data size was reduced by picking out every 5th column
 24 and line in the DEM error grid. In areas where data was sparse, at nunataks and where few data
 25 points remained due to the snow mask near the glacier margin, the 20mx20m data was used.
 26 Tests with smaller study areas indicated that this reduction of the input data only have minor
 27 effects on the results derived from the simulation.

28 Each SGSsim, constrained by the input data and the spherical semivariogram model and
 29 calculated in resolution corresponding to 100mx100m cell size, reveals possible errors in the
 30 measured glaciated area of the examined photogrammetric DEM. From each simulation the
 31 mean error of the glaciated area was calculated. From the 1000 simulations a histogram was

1 derived and used to approximate a probability function of the likely bias in glaciated part of the
2 DEM. Figure 4f shows the derived histogram for the 1946 DEM. It also shows the mean (Fig.
3 4d) and γ (Fig. 4e) of the derived error from 1000 simulation at each cell of the simulated area
4 within the glacier. The latter reveals how the uncertainty in the derived error increases with
5 distance from the input data. This should reach a maximum at a distance corresponding
6 approximately to the range (r) in the spherical semivariogram model, but all points on glacier
7 in the 1946 DEM are at distance $<r$ from input data. The spatially varying mean error (Fig. 4d)
8 could be used directly for correction of the photographic DEM, but instead we subtract the
9 mean of the derived probability function to bias correct the area of interest in the
10 photogrammetric DEM. Both approaches would lead to same result when deducing volume
11 changes from the DEM differencing. The derived bias, z_bias , used to correct each DEM, and
12 the corresponding 95% upper (z_bias_u) and lower confidence limits (z_bias_l), is tabulated in
13 Table 2. For comparison purposes the table also shows error bars derived by calculating
14 analytically the expected variance ($\sigma_{z_bias}^2$) in the DEM error averaged over circular region
15 corresponding to the size of Drangajökull, using a spherical semivariogram model (Rolstad et
16 al., 2009), which fits the semivariogram without nscoring the error input data (Fig. 4a).

17 **2.3 Finalizing the glacier DEMs**

18 The photogrammetrically derived point clouds are typically much less dense for the snow
19 covered glacier surface than for bare ice or ground (see Supplement). The typical distance
20 between points on the snow covered glacier surface in the 1946 point cloud (the worst dataset
21 in terms of noise and point density) is ~ 100 m, corresponding approximately to the resolution
22 of the SGSim carried out. The point density is poorer for limited areas and in some regions gaps
23 in the point clouds are caused by lack of contrast. Interpolating the elevation point clouds
24 directly over long distances can be risky due to the spatial variability of the elevation. The
25 spatial variability of the elevation changes derived from the difference between the point cloud
26 and the LiDAR DEM is expected to be much lower (Cox and March, 2004). Therefore the bias
27 corrected difference was interpolated (Sect. 2.2) and added to the LiDAR DEM. The kriging
28 function in Surfer 12 (©Golden Software, Inc.) was used to interpolate the data applying default
29 linear variogram model and data search radius of 500 m. Even though the elevation changes
30 compared to LiDAR are expected to be spatially smooth, interpolation over longer distance
31 would reduce the reliability of the uncertainty assessment carried out for the photogrammetric
32 DEMs. The different interpolation methods used within (kriging) and outside (linear) the glacier
33 produces minor difference in the error statistics. For the 1946 bedrock data (after slope and

1 outlier masking) σ is 4.80 m and 4.79 m for the linear and kriging methods respectively but
2 4.77 m derived directly from the point cloud difference compared to the full resolution LiDAR
3 DEM.

4 The resulting grids of elevation changes relative to LiDAR contained some larger gaps due to
5 lack of contrast, cloud cover or incomplete coverage of aerial photographs for all datasets
6 except the one of 2005 (Table 2). To complete the difference maps two main interpolation
7 methods were used: For relatively small gaps, spanning short elevation range, kriging
8 interpolation with data search radius >500 m was applied using the derived elevation difference
9 at the boundary of the data gap as input. For larger areas spanning significant elevation range
10 we estimated a piecewise linear function for the elevation change as function of the 2011
11 elevation (at 100 m elevation intervals) using the elevation difference between the point cloud
12 and the LiDAR DEM as input (see supplementary data). For data gaps covering an area at both
13 the east and west side off the glacier the two different interpolations were carried out, one for
14 the area west of the ice divides and another for the area east of it. In four cases neither of the
15 above interpolation methods were considered applicable. The approaches adopted for each of
16 these cases is described in the supplementary data. The location of data gaps are shown in Fig.
17 S1 and the interpolation method applied in each case is shown supplementary data.

18 The uncertainties associated with interpolation of data gaps in the DEMs was approximated
19 independently from the uncertainties of measured photogrammetric DEMs (Sect. 2.2). It is
20 difficult to quantify these errors, but since these areas are generally small relative to the
21 measured areas we adopted a generous approximation of the uncertainty roughly based on the
22 scatter of the elevation change with altitude (point clouds compared to LiDAR DEMs). We
23 assign three values of elevation uncertainty (95% confidence level) to the interpolated areas,
24 ± 7.5 m, ± 10 m and ± 15 m, depending on the quality of the input data used for the interpolation
25 and the applicability of the interpolation method (for further details see supplementary data).
26 The interpolated areas with the highest uncertainties were adopted for the lowermost part of
27 Leirufjarðarjökull that was not covered in the 1975 survey flight (see supplementary data). Also
28 a relatively large area in southernmost part of Drangajökull in 1946 where the interpolated area
29 is poorly constrained by data. Cluster of nearby data gaps are considered as single area with
30 assigned elevation uncertainty. We however assume that the error in one area is independent
31 from the elevation error in other areas due to the distance between them.

1 **2.4 Delineating glacier margins and nunataks**

2 The glacier margin and nunataks at each time were delineated manually using the orthorectified
3 aerial photographs at given time as well as the derived elevation difference compared to the
4 LiDAR DEM. For 2011 the glacier outlines were drawn based on a shaded relief image of the
5 2011 DEM in maximum resolution and the intensity image of the LiDAR measurements. All
6 glacier margins were delineated by the same person. The glacier margin was therefore
7 interpreted in similar manner for all years, in areas where the outlines are uncertain. This
8 working procedure minimizes variations in relative area changes of the ice cap. Due to
9 numerous firn patches in the vicinity of Drangajökull, some of which are connected to the ice
10 cap, it is actually a matter of definition if these connected patches should be included as part of
11 Drangajökull or not. We follow the approach of Jóhannesson et al. (2013) and exclude these
12 patches. In a few areas the aerial photographs do not always reveal the glacier margin. This
13 includes the southernmost part of Drangajökull in 1946. In this area the location of the glacier
14 margin has been very stable since 1960. We therefore adopted at each location, the outermost
15 glacier margin in the 1960-2011 datasets, as the 1946 margin in this area. Data used to
16 approximate the location of the glacier margin in other areas where data is absent is described
17 in the supplementary data. The evolution of the glacier area is shown in Fig. 5. Also shown in
18 Fig. 5 is the area of the eastern and western sections of the glacier, when Drangajökull is divided
19 in two along the ice divides from north to south (see Fig. 6).

20 **2.5 Calculating volume changes**

21 To derive the volume change, $\delta V(t_s, t_f)$, of the ice cap during a period t_s-t_f , the elevation
22 difference DEM_f-DEM_s (Fig. 6), was integrated over the area covered by glacier at either or
23 both DEM dates. A continuous DEMs and glacier outlines had been completed for all years
24 except for the year 1994, but this data set covered only $\sim 2/3$ of Drangajökull with the
25 southernmost third of the ice cap missing. In order to estimate volume changes for this part of
26 the glacier in the periods 1985-1994 and 1994-2005 the volume changes for the southernmost
27 third of the glacier were plotted as function of deduced volume changes in the other $\sim 2/3$ of the
28 glacier for the periods 1960-1975, 1975-1985, 1985-2005 and 2005-2011 (Fig. 7). Linear fit
29 describing relation between the volume changes in the two areas estimated with least-squares
30 was used to estimate volume changes for the southern part of the glacier in the period 1985-
31 1994 and 1994-2005. Errors in these volume change estimates were approximated using the
32 95% confidence level of the linear fit (estimated in Grapher 10 ©Golden Software, Inc.). Instead
33 of approximating the position of the 1994 glacier margin, we only approximated the area

1 covered by this part of the glacier. The volume change for the southernmost part of
 2 Drangajökull in the periods 1975-1985 was approximately the same as the estimated volume
 3 change in 1985-1994. We therefore extrapolate the 0.7 km² area increase of this glacier part of
 4 in 1975-1985 to the period 1985-1994 to estimate the area of this glacier part in 1994.

5 **2.6 Seasonal correction of volume change between DEMs**

6 The DEMs of Drangajökull were extracted from data acquired at different dates during the
 7 summer or the autumn (Table 1). Deriving mass balance records from DEM difference without
 8 taking this into the account will skew the results, particularly if the acquisition time of the
 9 DEMs differs much from one DEM to another. Seasonal correction (sometimes referred to as
 10 date correction) have been applied and discussed in numerous studies (e.g. Krimmel, 1999; Cox
 11 and March, 2004; Cogley, 2009). In this study the derived volume change in between DEMs
 12 ($\delta V(t_s, t_f)$, in Sect. 2.5) was seasonally corrected by compensating for the expected volume
 13 change of the ice cap from the acquisition date of each DEM until the end of the glaciological
 14 year (1 October). The end of the glaciological year was chosen because it makes comparison
 15 with both mass balance records and meteorological data easier and more eligible. This choice
 16 results in larger magnitude of seasonal correction (and consequently larger uncertainty
 17 estimates), when compared to the average acquisition date of the DEMs. The seasonally
 18 corrected volume changes is given by

19

$$20 \quad \delta V^*(t_s, t_f) = \delta V(t_s, t_f) + \delta V_{S_cor}(t_s) - \delta V_{S_cor}(t_f) \quad (2)$$

21

22 The expected volume changes, δV_{S_cor} from the time of data acquisitions t_a until the end of the
 23 glaciological year t_{end} was estimated using positive degree day (T_+) model (e. g. Jóhannesson
 24 et al., 1995) with a constant degree day factor (ddf) for the whole ice cap:

25

$$26 \quad \delta V_{S_cor} = \frac{1}{c_{\delta V_{S_cor}}} \cdot ddf \sum_{t_a}^{t_{end} \text{ glacier}} \int T_+(t, x, y) dA \quad (3)$$

27

28 Where $c_{\delta V_{S_cor}}$ is the conversion factor from the glacier volume change during the period t_a -
 29 t_{end} to the melt water draining from the ice cap in the same period. For seasonal volume
 30 correction of the DEMs in 1960 to 2011 we use daily grids of temperature at 2 m height above
 31 ground available back to 1949 (Crochet and Jóhannesson, 2011; unpublished data of the

1 Icelandic Meteorological Office, for the year 2011). The grids were derived in two steps: i)
2 Applying tension spline interpolation of measured temperature at meteorological stations
3 corrected with fixed lapse rate to represent temperature at sea level. ii) Lapse rate adjustment
4 ($6.5^{\circ}\text{C km}^{-1}$) of interpolated temperature to compensate for the effects of topography. The
5 temperature grids were in 1 km x 1 km cell size, but we linearly interpolated the grid in same
6 resolution as the DEMs we are working with (20mx20m cell size). Published values of ddf for
7 Langjökull, Hofsjökull and Vatnajökull ice caps in Iceland (Jóhannesson et al., 2007;
8 Guðmundsson et al., 2009) using comparable temperature data spans the range from 4.45 mm
9 w.e. $^{\circ}\text{C}^{-1}$ (minimum value for snow using lapse rate of $0.56^{\circ}\text{C km}^{-1}$; Jóhannesson et al., 2007)
10 to 7.5 mm w.e. $^{\circ}\text{C}^{-1}$ (maximum value of firn/ice using lapse rate of $0.6^{\circ}\text{C km}^{-1}$; Guðmundsson
11 et al., 2009). If these values had been obtained with lapse rate equal to the one applied when
12 creating the temperature grids used here ($6.5^{\circ}\text{C km}^{-1}$) the resulting ddf would have been slightly
13 higher. We therefore use $ddf=6.5\pm 1.5$ mm w.e. $^{\circ}\text{C}^{-1}$ instead of $ddf=6.0\pm 1.5$ mm w.e. $^{\circ}\text{C}^{-1}$ (the
14 span of published values). Assuming that our conversion factor $c_{\delta V_{S_cor}}=0.75\pm 0.1$ (where
15 $c_{\delta V_{S_cor}}=0.65$ corresponds to volume change mostly due to melting of snow and $c_{\delta V_{S_cor}}=0.85$
16 corresponds to volume change mostly due melting of ice) is independent of ddf , results in
17 seasonal corrections from Eq. 3 with 28% uncertainty (95% confidence level). The value of ddf
18 is actually lower for snow than firn/ice, hence this assumption should lead to overestimate of
19 the ratio $ddf/c_{\delta V_{S_cor}}$ and consequently the uncertainty of δV_{S_cor} derived from Eq. 3. The
20 seasonal volume correction of each DEM is given in Table 3. The aerial photographs used to
21 produce the 1946 DEM were taken at the beginning of October before the start of winter snow
22 fall. No seasonal correction was therefore required.

23 **2.7 Deriving the geodetic mass balance and its uncertainty**

24 The glacier-wide mass balance rate, \dot{B} (the UNESCO, IACS mass balance terminology (Cogley
25 et al., 2011) is adopted) is estimated during the period $t_s - t_f$, using the equation:

26

$$27 \quad \dot{B}(t_s, t_f) = \frac{\delta V^*(t_s, t_f)}{\bar{A}(t_s, t_f) \cdot \delta t} c_{\delta V} \quad (4)$$

28

29 where $\delta t = t_f - t_s$ and $\bar{A}(t_s, t_f) = (A(t_s) + A(t_f))/2$ approximates the average area of the
30 glacier during the period. It is reasonable to assume that the variables in Eq. 4 are independent
31 of one another, hence the uncertainty in \dot{B} can be approximated as

$$\begin{aligned}
\Delta\dot{B} &\approx \sqrt{\left(\Delta\delta V^* \frac{\partial\dot{B}}{\partial\delta V^*}\right)^2 + \left(\Delta\bar{A} \frac{\partial\dot{B}}{\partial\bar{A}}\right)^2 + \left(\Delta c_{\delta V} \frac{\partial\dot{B}}{\partial c_{\delta V}}\right)^2} \\
&= \frac{1}{\delta t} \sqrt{\left(\Delta\delta V^* \frac{c_{\delta V}}{\bar{A}}\right)^2 + \left(\Delta\bar{A} \frac{\delta V^* c_{\delta V}}{\bar{A}^2}\right)^2 + \left(\Delta c_{\delta V} \frac{\delta V^*}{\bar{A}}\right)^2} \quad (5)
\end{aligned}$$

$\Delta\bar{A} = 4 \text{ km}^2$ is applied in all cases corresponding to $\sim 2.5\%$ of the glacier area, which is considered a generous estimate of the uncertainty in the glacier area for the given definition (Sect. 2.4). We used $c_{\delta V} = 0.85 \pm 0.06$ (Huss, 2013).

When estimating $\Delta\delta V^*$ the error budget of δV^* was examined. The error, ε , of the seasonally corrected volume change, $\delta V^*(t_s, t_f)$, is the sum:

$$\begin{aligned}
\varepsilon\{\delta V^*(t_s, t_f)\} &= \varepsilon\{V_m(t_s)\} + \varepsilon\{V_i(t_s)\} + \varepsilon\{\delta V_{S_cor}(t_s)\} + \\
&\quad \varepsilon\{V_m(t_f)\} + \varepsilon\{V_i(t_f)\} + \varepsilon\{\delta V_{S_cor}(t_f)\} \quad (6)
\end{aligned}$$

where the error in the measured volume at time t is

$$\varepsilon\{V_m(t)\} = A_m(t) \cdot \bar{\varepsilon}\{h(t)\} \quad (7)$$

where A_m is the area of measured DEM within the glacier and $\bar{\varepsilon}\{h\}$ the mean error of the glaciated area. The error in volume for the interpolated glacier sections lacking measurement (Sect. 2.3) is

$$\varepsilon\{V_i(t)\} = \sum_{j=1}^N A_j(t) \cdot \bar{\varepsilon}\{h_j(t)\} \quad (8)$$

where A_j is the area of the interpolated section, j , and $\bar{\varepsilon}\{h_j\}$ is the corresponding mean elevation error. Assuming that the individual errors contributing to Eq. 6 and 8 are independent of one another the probability function of the error in $\delta V^*(t_s, t_f)$ is given by the multiple convolutions:

$$f_{\varepsilon\{\delta V^*(t_s, t_f)\}} = f_{\varepsilon\{V_m(t_s)\}} * f_{\varepsilon\{V_i(t_s)\}} * f_{\varepsilon\{\partial V_{s,cor}(t_s)\}} * f_{\varepsilon\{V_m(t_f)\}} * f_{\varepsilon\{V_i(t_f)\}} * f_{\varepsilon\{\delta V_{s,cor}(t_f)\}} \quad (9)$$

2

3 The probability function $f_{\varepsilon\{V_m(t)\}}$ was derived directly from Eq. 10 and by approximating
 4 $f_{\bar{\varepsilon}\{h(t)\}}$ using the histogram of the corresponding elevation bias correction (Sect. 2.2) minus its
 5 mean. All other errors are assumed to be normally distributed with zero mean, hence

6

$$f(\varepsilon) = \frac{1}{\sigma_\varepsilon \sqrt{2\pi}} e^{-\frac{\varepsilon^2}{2\sigma_\varepsilon^2}} \quad (10)$$

8

9 The probability distribution $f_{\varepsilon\{V_i\}}$ is hence also a normal distribution with

10

$$\sigma_{\varepsilon\{V_i\}} = \sqrt{\sum_{j=1}^N (A_j \cdot \sigma_{\bar{\varepsilon}\{h_j\}})^2} \quad (11)$$

12

13 The uncertainty in the volume change $\Delta\delta V$ (95% confidence level) was now derived from the
 14 probability distribution given by Eq. 9. Table 3 shows the 95% confidence level of $f_{\varepsilon\{V_m\}}$,
 15 $f_{\varepsilon\{V_i\}}$ and $f_{\varepsilon\{\delta V_{s,cor}\}}$ for each year of acquisition, revealing the main source of error in the
 16 derived volume changes.

17

18 3 Results

19 3.1 Bias corrections and uncertainty estimates deduced from the DEM errors

20 Table 2 gives values of several error estimation parameters for the photogrammetric DEMs
 21 deduced by comparison with the 2011 LiDAR DEM in ice and snow free areas. Some of these
 22 parameters can be used both to correct the DEMs and to estimate the uncertainty of geodetic
 23 mass balance results. In some cases significant difference is observed between the mean DEM
 24 error, commonly used to correct for bias (0 order correction) of the DEM (e.g. Guðmundsson
 25 et al. 2011), and the bias derived from the SGSim. The greatest difference is for the 1946 DEM,
 26 which after removal of outliers and steep slopes the ice and snow free part of it has a mean error
 27 of -0.86 m whereas the SGSim results in bias of 1.66 m. The difference would presumably be
 28 lower if we would only calculate the mean error using areas within certain distance from the

1 glacier margin but it is not straight forward to select this distance without using geostatistical
2 approaches.

3 The parameters in Table 2 that can be used to estimate the uncertainty of geodetic mass balance
4 show even more diversity. The crudest parameter would be the standard deviation of the DEM
5 error derived from ice and snow free areas. Standard deviation is commonly interpreted as 68%
6 confidence level assuming normal error distribution and should therefore be multiplied by 1.96
7 to obtain 95% confidence level as derived for the other two approaches shown in Table 2. This
8 interpretation of the standard deviation as uncertainty proxy of the volume change implies the
9 assumption that the DEM errors at different locations within the glacier are totally correlated
10 (Rolstad et al., 2009). Since the confidence level of geodetic mass balance results is typically
11 not mentioned in studies using the standard deviation as their uncertainty proxy, the conversion
12 of the standard deviation to 95% confidence level is omitted in Table 2. The values of standard
13 deviation for the ice free DEMs are 5-45% lower after removal of outlier and steep slopes. The
14 lower standard deviation values are however still by far higher than the uncertainty (95% conf.
15 level) of the bias correction derived with SGSim. The SGSim results in uncertainty between
16 0.21 m (in 2005) and 1.58 m (in 1946). The SGSim uncertainties correspond to 24-46% of the
17 standard deviation (after slope and outlier removal). If we exclude the three DEMs from 1960,
18 covering only ~1/3 of Drangajökull each, the range is 24-33%. The SGSim uncertainties
19 correspond to 27-80% of the uncertainties derived with method described by Rolstad et al.
20 (2009) and the percentage seems to depend strongly on the range of the spherical semivariogram
21 model used in both calculations (Fig. 8).

22 **3.2 DEM seasonal corrections and contribution of different error sources to** 23 **the geodetic mass balance**

24 The effects of seasonal correction and the estimated contribution of each type of error to the
25 total volume change is summarised in Table 3. The importance of seasonal correction for
26 Drangajökull is clearly revealed, particularly for the first two periods, 1946-1960 and 1960-
27 1975, due to the early acquisition of the 1960 aerial photographs. The sum of the two seasonal
28 corrections for these periods corresponds to larger value than the derived total uncertainty of
29 δV^* . The correction effectively increases the difference in \dot{B} between the periods by 0.42 m
30 w.e. a^{-1} (~0.21 m w.e. a^{-1} absolute change for each period). With the inferred correction the
31 period 1946-1960 is the period of highest mass loss rate, along with 1994-2005, whereas the
32 period 1960-1975, differs insignificantly from equilibrium (Fig. 9). For other periods the net
33 seasonal correction changed the derived \dot{B} by 0.06-0.12 m w.e. a^{-1} .

1 The main source of uncertainties is different from one period to another, but in no case is the
2 highest contribution is from the estimated uncertainty of the DEM elevation ($\Delta\delta h_m$ in Table 3).
3 For periods, where volume change is based on the 1946 or 1994 DEM, we have relative high
4 uncertainties due to interpolations of large gaps in the derived DEMs (Fig. 3 and Table 2). The
5 derived value of δV^* for the period 2005-2011, obtained from the best two DEMs in terms of
6 accuracy and coverage, has significant uncertainty due large seasonal correction for both
7 DEMs. The 2005 and 2011 data were acquired in late July, and the summer remainder for both
8 years was relatively warm. The sum of seasonal corrections (which have opposite signs) is
9 actually smaller than the uncertainty related to the seasonal corrections for the period 2005-
10 2011.

11 The uncertainty percentage of δV^* is typically significantly higher than the uncertainty
12 percentage of A (2.5%) and $c_{\delta V}$ (~7%). Uncertainty of the derived \dot{B} (Fig. 9) produced by the
13 uncertainty of the latter two variables is therefore generally minor compared to the uncertainty
14 contribution of δV^* .

15 **3.3 The geodetic mass balance of Drangajökull**

16 Figure 9 shows the derived \dot{B} for Drangajökull during six intervals since 1946. During the
17 period 1946-1960 relatively high mass loss rates of $\dot{B} = -0.66 \pm 0.17$ m w.e. a⁻¹ are estimated.
18 The glacier was near equilibrium in 1960-1985 with $\dot{B} = -0.07 \pm 0.07$ m w.e. a⁻¹ and $\dot{B} =$
19 0.07 ± 0.08 m w.e. a⁻¹ in 1960-1975 and 1975-1985, respectively. The mass balance was
20 significantly positive in 1985-1994 with $\dot{B} = 0.26 \pm 0.11$ m w.e. a⁻¹. In the period 1994-2005
21 again, as in the mid-century, there is high rate of mass loss with $\dot{B} = -0.64 \pm 0.10$ m w.e. a⁻¹
22 and then slightly less negative mass balance rate in 2005-2011, with $\dot{B} = -0.46 \pm 0.15$ m w.e.
23 a⁻¹. The glacier wide mass balance rate for the entire period 1946-2011 is $\dot{B} = -0.26 \pm 0.040$
24 m w.e. a⁻¹. In the same period Drangajökull was reduced in area by ~11% from 161 km² to 144
25 km² (Fig. 8).

26 The two lower panels of Fig. 9 show \dot{B} for the western and eastern half of Drangajökull ice cap,
27 as defined by the ice divides from north to south shown in Fig. 6. The results are derived in the
28 same manner as the result for the entire glacier, where the steps taken to correct for bias of the
29 DEM, derive seasonal correction and derive uncertainties were carried out focusing specifically
30 on either the western or the eastern part. The bias correction of each half may vary up to few
31 decimetres from the correction of the entire ice cap and the uncertainty limits of the bias
32 correction is generally slightly higher.

1 Figure 9 shows different evolution of the west and east glacier. Both parts suffered significantly
2 negative mass balance rate in 1946-1960 and 1994-2011. The period in between was
3 significantly negative on the east side, apart from the period 1985-1994, when the upper 95%
4 confidence level is slightly above 0, whereas the western part had \dot{B} near 0 in 1960-1975 and
5 significantly positive mass balance rate with $\dot{B} = 0.23 \pm 0.10$ m w.e. a⁻¹ and $\dot{B} = 0.52 \pm 0.15$
6 m w.e. a⁻¹ in 1975-1985 and 1985-1994, respectively. Mean mass balance rate of $\dot{B} = -0.16 \pm$
7 0.05 m w.e. a⁻¹ is estimated for the period 1946-2011 on the western part. The mass loss rate is
8 on average ~3-fold higher for the eastern part with $\dot{B} = -0.41 \pm 0.04$ m w.e. a⁻¹. This is also
9 reflected in the area change but in 1946-2011 the eastern part decreased in area 21%, while the
10 western part shrank only by 3% (Fig. 8).

11

12 **4 Discussion**

13 The high precision of the geodetic mass balance results presented can be primarily explained
14 by: i) The use of the high resolution and accuracy LiDAR DEM to extract evenly distributed
15 GCPs for constraining the orientation of photogrammetric DEMs; obtaining equivalent
16 distribution of GCPs in the field was not possible within the financial frame of this study. ii)
17 The thorough uncertainty assessment of the results where the LiDAR data from ice and snow
18 free areas is also a key data since it enables assessment of geo-statistical parameters of the
19 photogrammetric DEMs. Both i and ii, highlight the need of high resolution and accuracy DEMs
20 from the present in areas of interest to conduct studies of geodetic mass balance using aerial
21 photographs from the past. The third important use of the LiDAR data in this study, is the
22 creation of DEMs from the photogrammetric point clouds within the glacier. Rather than
23 interpolating the elevation point clouds directly we interpolate the difference between the point
24 cloud and LiDAR DEM (much less high frequency variability, the difference is a smoother
25 surface (Cox and March, 2004)) and add the interpolated product to the LiDAR DEM. This
26 results in more accurate DEMs in areas where the density of the photogrammetric point clouds
27 is low.

28 Other state of the art high resolution elevation data sets obtained with airborne or spaceborne
29 sensors are also suitable to replace the LiDAR data in the work procedure described here. This
30 probably includes Worldview and Pléiades high resolution stereo images, allowing extraction
31 of DEM with <5m cell dimensions and orthorectified photographs with <1mx1m cell size (e.g.
32 Berthier et al., 2014; Howat et al., 2015). Part of the work procedure described has already been
33 carried out using such satellite data as replacement for the airborne LIDAR. In a recent study

1 by Papasodoro et al. (2015), Pléiades data was used to collect GCPs for constraining DEMs
2 from aerial photographs. Even though the absolute accuracy of data from spaceborne sensors
3 does not match data from airborne LiDAR, it does not make the satellite data inadequate. Each
4 photogrammetric DEM from the past can be fixed into the reference frame of the high resolution
5 DEM through the extraction and usage of GCPs and implementation of proposed bias
6 correction. The relative elevation change between DEMs should therefore be fairly accurate
7 despite lower absolute accuracy of the DEMs, and shifts and tilts of the reference frame cancels
8 out in DEM differencing.

9 In this study, the derived bias correction of the glaciated DEM section and the uncertainty of
10 volume changes related to DEM errors are obtained from the probability distribution calculated
11 by using SGSim. The bias correction corresponds to the probabilistic mean of the average error
12 within the glacier. As shown in Table 2 the difference between the mean error in snow and ice
13 free areas and the bias derived from the SGSim (the estimated probabilistic mean of the glacier
14 DEM error) was up to 2.5 m (in 1946). This difference would presumably be lower if we would
15 only calculate the mean error using areas within certain distance from the glacier margin but it
16 is not straight forward to select this distance without using some geo-statistical approaches. The
17 relation is also not obvious between the probabilistic mean of an average DEM error within the
18 glacier and higher order corrections of a glacier DEM obtained with least square fit (or similar)
19 using deduced DEM errors in ice and snow free areas. If the average correction does not
20 correspond to the probabilistic mean, the results of geodetic mass balance will be incorrectly
21 centered even if the width of the error bars is realistic.

22 When comparing different proxies used for estimating the uncertainty of DEM difference
23 derived volume change, it is no surprise that using the standard deviation of the DEM error in
24 snow and ice free areas leads to great overestimate of the uncertainty (Table 2). This has been
25 shown before by Rolstad et al. (2009). Other estimators that ignore information of the spatial
26 dependency of the DEM errors, such as the NMAD value (Höhle and Höhle, 2009), should also
27 be considered as incomplete for this purpose.

28 The difference in uncertainty estimates between the method described here and the method of
29 Rolstad et al. (2009) is especially noteworthy (Table 2 and Fig. 8). Rolstad et al. (2009)
30 provided a simple and logical method to estimate the uncertainty of derived volume change.
31 The DEM errors (or difference) in ice and snow free areas are used to calculate a semivariogram
32 that constrains a spherical semivariogram model. From the spherical semivariogram model
33 alone the expected variance of the DEM error ($\sigma_{z_{bias}}^2$) averaged over circular region

1 corresponding to the size of the glacier is calculated analytically. The method compensate for
2 the spatial dependency of the DEM error at different location within the glacier. The method
3 does however not take into the account how the DEM error within the glacier depends on the
4 DEM errors outside the glacier, unlike the method proposed here utilizing SGSim. This is most
5 likely the explanation why the ratio between the two uncertainty estimates
6 ($\Delta z_{biasSGSim}/\Delta z_{biasRols.}$) appears to be strongly dependent on the range, r , in the spherical
7 semivariogram model, which is common for both approaches (Fig. 8). If r is small compared
8 the size of the glacier, meaning that large proportion of the glacier has DEM error independent
9 of DEM error outside the glacier, the uncertainty derived SGSim is only slightly smaller than
10 the uncertainty derived analytically from the spherical semivariogram model alone. If r is
11 however large, meaning that large proportion or even the entire glacier has DEM error
12 dependent on the DEM errors outside the glacier, the SGSim results in much lower uncertainty.
13 This interpretation implies that the method of Rolstad et al. (2009) gives a good approximation
14 of the uncertainty if most of the glaciated area is at distance $>r$ from ice and snow free areas
15 providing measurements of the DEM errors, but can otherwise result in great overestimate of
16 the uncertainty in the derived volume change. The main disadvantage of SGSim approach
17 compared to the approach of Rolstad et al. (2009) is that is more time consuming. The tool
18 applied here (WinGSlib) also has problems with dataset larger than worked with in this study.
19 New tools enabling the SGSim approach for large data sets should however be developed in
20 order to facilitate the usage of this methodology.

21 Our study emphasises the importance of including seasonal correction of DEMs for glacier with
22 high mass turnover to avoid wrong interpretation of derived volume change. The most extreme
23 case is the negative volume change derived from the difference between the 1960 and 1975
24 DEMs. The seasonal correction results in $\sim 3/4$ of the of this negative volume change being
25 effectively transferred in to the period 1946-1960 due to large seasonal correction of the 1960
26 DEM resulting from relatively early acquisition of the aerial photographs (Table 1). The
27 seasonally corrected volume change revealing the volume change between the start of different
28 glaciological year obviously has higher uncertainty than the uncorrected volume change. We
29 however consider this trade-off important for easy comparison with other data records,
30 including meteorological data and in situ mass balance measurements. The uncertainty due to
31 the seasonal correction as well as the uncertainty related to the interpolation of the data gaps
32 should be considered as cautious estimates of the 95% confidence level of the error associated
33 with these two error sources. Effort should be made to constrain these uncertainties further,

1 which could narrow the uncertainty estimates of this study and other similar even further, but
2 it is beyond the scope of this paper.

3 The presented geodetic mass balance record indicate slower volume decrease for Drangajökull
4 ice cap since the 1940's than for most other glacier in Iceland with geodetic mass balance record
5 extending back to that period. While we observe $\dot{B} = -0.26 \pm 0.04$ m w.e. a⁻¹ for Drangajökull
6 in the period 1946-2011 the corresponding values for Langjökull ice cap in 1945-2011 is $\dot{B} \approx$
7 -0.5 m w.e. a⁻¹ (Pálsson et al., 2012, with extension from traditional mass measurements in
8 2004-2011 from Björnsson et al. (2013) until 2010, and unpublished Institute of Earth Sciences
9 (IES) data for 2011). Two outlets of S-Vatnajökull, Kvíárjökull and Skaftárjökull have similar
10 rate of mass decrease in 1945-2010 or $\dot{B} \approx -0.25$ m w.e. a⁻¹ (Hannesdóttir et al., 2015). Other
11 outlets of S-Vatnajökull ice cap show \bar{B}_n between -0.3 and -0.8 m w.e. a⁻¹ in 1945-2010
12 (Hannesdóttir et al., 2015; Aðalgeirsdóttir et al., 2011). For the relatively warm period in 1994-
13 2011 we obtain $\dot{B} = -0.58 \pm 0.08$ m w.e. a⁻¹, which is in good agreement with the study of
14 Jóhannesson et al. (2013), which indicated $\dot{B} \approx -0.5$ m w.e. a⁻¹ for Drangajökull ice cap in the
15 period 1996-2011. Comparison of Drangajökull mass balance in 1994-2011, with results from
16 traditional in situ mass balance measurements from Langjökull (in 1996-2011) and Vatnajökull
17 ice caps show that the reduction rate has been ~140% faster on Langjökull ($\dot{B} \approx -1.4$ m w.e.
18 a⁻¹, from Björnsson et al. (2013) until 2010, and unpublished IES data for 2011) and ~20%
19 faster on Vatnajökull ($\dot{B} \approx -0.7$ m w.e. a⁻¹, from Björnsson et al. (2013) until 2010, and
20 unpublished IES data for 2011).

21 The difference in the geodetic mass balance results between the east and west part of
22 Drangajökull highlights how difficult it is to extrapolate mass balance records from one glacier
23 to another, even over short distances. The results, showing ~3 times more negative mass balance
24 rate for the eastern part of Drangajökull than the western part for the entire period 1946-2011,
25 is not reflected in changing spatial trends of summer temperature during the period. The
26 summer temperature measured east of Drangajökull is typically ~1°C lower than revealed by
27 measurements west of Drangajökull (Fig. 9c) and this is rather consistent throughout the survey
28 period. Daily precipitation maps (1 km x 1 km cell size) in 1958-2006 deduced from ERA-40
29 (Uppala, 2005) by dynamic downscaling with linear model of orographic precipitation (an
30 update of Crochet et al. (2007) described in Jóhannesson et al. (2007)) do not indicate strong
31 trend in winter precipitation from east to west. The modelled winter precipitation may however
32 not be representative for winter accumulation due to excess of lee-drying in the modelled
33 precipitation or transport of snow from east to west by snow drift; the most common wind

1 direction on Drangajökull is from NE. Most of the precipitation also falls on the glacier when
2 the wind blows from NE. Ongoing geodetic mass balance studies of Drangajökull on seasonal
3 time scale may reveal further answers.

4 The geodetic mass balance record on Drangajökull ice cap is the first such record revealing
5 glacier volume change in Iceland on decadal time scale the past ~70 years. Other records
6 spanning this period have coarser resolution particularly over the period 1945-1985, which is
7 typically assigned a single mass balance value (e.g. Pálsson et al., 2012; Hannesdóttir et al.,
8 2015). However, accurate and detailed studies pertaining to this period are of particular interest
9 as they may reveal how the Icelandic glaciers responded to the change from a relatively warm
10 climate in 1925-1965 to a significantly colder climate in 1965-1990, and subsequently to a
11 warming with a short setback around 1995 (cf. Figs 2.6 and 3.1 in Björnsson et al., 2008). We
12 consider this study the first step in filling this gap in our knowledge. The key data to continue
13 this work is the archive of aerial photographs at the National Land Survey of Iceland, covering
14 the Icelandic glaciers in the 1940's-1990's. Similar archives covering other glaciated parts of
15 the world should be fully utilized using the new processing techniques and recent and future
16 availability of high resolution DEMs of the present state of the glaciated areas and its vicinity.

17

18 **5 Conclusions**

19 This paper highlights the opportunities that new high resolution DEMs are opening to improve
20 the procedure carried out to obtain geodetic mass balance records. Such DEMs are key data in
21 three aspects of this study: a) Extracting GCPs from recent airborne LiDAR DEM to constrain
22 photogrammetric DEMs at 6 different epochs. b) Interpolate over glacier surface the elevation
23 difference of derived photogrammetric point cloud relative to the LiDAR DEM. c) Apply new
24 geostatistical approach based on comparison with the LiDAR data, to estimate simultaneously
25 a bias correction for the glacier DEMs along with its 95% confidence level. The latter reveals
26 the uncertainty associated with DEM errors in geodetic mass balance record.

27 The new geostatistical method applies SGSims using the DEM errors in ice and snow free areas
28 and a spherical semivariogram model constrained by the DEM errors as input data. The
29 resulting bias correction may differ considerably (in our case up to 2.5m in 1946) from the
30 simple approach of applying bias correction using the mean DEM error outside the glacier. The
31 resulting uncertainty of the DEM (95% conf. level) was typically estimated 20-35% of the
32 standard deviation derived from the DEM errors in ice and snow free areas after outliers and
33 high slopes were masked out. The uncertainty contribution from DEM errors obtained with

1 SGSim was 25-80% of the uncertainty estimate obtained with the geostatistical method of
2 Rolstad et al. (2009). We argue that methods typically carried out in uncertainty assessments of
3 geodetic mass balance generally overestimate the uncertainty related to DEM errors, while the
4 geostatistical approach described here results in more realistic uncertainty estimates.

5 This study also reveals the importance of seasonal corrections of geodetic mass balance for
6 glaciers with high annual turnover; Drangajökull is a good example. The highest correction in
7 our study was -3.5 m (in 1960), which corresponds to $\sim 3/4$ of the average elevation change
8 between the 1960 and the 1975 DEMs.

9 During the whole period 1946-2011 we obtain $\dot{B} = -0.26 \pm 0.04$ m w.e. a^{-1} for entire
10 Drangajökull. This is among the lowest retreat rate reported for glaciers in Iceland spanning
11 approximately this period. Only two outlet glaciers in S-Vatnajökull have been reported with
12 similar retreat rate. When calculating this for the western and eastern half of Drangajökull
13 specifically we obtain $\dot{B} = -0.16 \pm 0.05$ m w.e. a^{-1} and $\dot{B} = -0.41 \pm 0.04$ m w.e. a^{-1} ,
14 respectively. This difference between east and west part of the glacier varies significantly
15 during the survey period and does not seem to be related to relative changes in summer
16 temperature. This great difference between east and west shows how difficult it is to extrapolate
17 mass balance record from one glacier to another even over short distances. No glacier unit in
18 Iceland has been reported as close to equilibrium on average since the 1940's as the western
19 part of Drangajökull ice cap.

20

21 **Authors contributions**

22 The writing of this paper and the research it describes was mostly carried out by the first two
23 authors of this paper, with inputs from the other three co-authors. All photogrammetric
24 processing and revision of the resulting point clouds was carried out by J.M.C.B. The
25 interpolation of the point cloud differences compared to the LiDAR DEM and construction of
26 glacier DEM based on that, interpolation of data gaps, delineation of glacier margin, seasonal
27 correction of the volume change, the construction of the presented mass balance records and
28 associated error analysis was carried out by E.M. based on fruitful discussions with J.M.C.B.
29 and F.P. All figures in this paper were made by E.M. and J.M.C.B. as well as tables. P. C. and
30 H. Á. contributed to the handling and interpretation of the meteorological data.

31

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15

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11

1 Table 1. Dates, main parameters and notes describing the data sets used in the study. *GSD:
 2 Ground Sampling Distance.
 3

Date	N. Images	Average GSD* (m)	Notes
12.10.1946	15	0.94	Missing southernmost part of Drangajökull. Over-exposed areas
Summer 1960	40	0.42	Divided in 3 flights: 14.06.1960, 08.07.1960 and 12.7.1960.
05.09.1975	18	0.77	Missing Leirufjarðarjökull outlet.
27.07.1985	32	0.70	Missing Reykjarfjarðarjökull outlet.
04.08.1986	5	0.70	Used for filling the gaps of 1985 on Reykjarfjarðarjökull outlet
29.08.1994	21	0.53	Missing southern part
27.07.2005	57	0.53	Complete coverage
20.07.2011	-	-	Complete coverage (LiDAR)

4

1 Table 2. The horizontal RMSE of the GCPs (nr. of GCPs within brackets), glacier coverage and
 2 error assessment of the photogrammetric DEMs, using four different approaches: i) Direct
 3 comparisons of ice-free areas (mean and standard deviation). ii) Comparisons in ice-free areas
 4 after masking out outliers and areas with slope > 20° (see Sect. 2.2). iii) SGSim. z_bias
 5 corresponds the mean elevation bias from 1000 simulation, z_bias_u and z_bias_l the upper and
 6 lower 95% confidence level and $\Delta z_bias = (z_bias_u - z_bias_l)/2$. iv) Method described by Rolstad
 7 et al., (2009). To derive uncertainties with 95% conf. level we assume normal probability
 8 function and therefore $\Delta z_bias_{Rols.} = 1.96 * \sigma_{z_bias_Rols.}$

9

Year	RMSE XY GCPs (m)	Glacier cover- age (%)	Error mean ice- free (m)	Std. dev. ice-free (m)	Error mean ice-free masked (m)	Std. dev. ice-free masked (m)	z_bias (m)	z_bias_l (m)	z_bias_u (m)	Δz_bias (m)	Δz_bias Rols. (m)
1946	2.99 [43]	75.3	-0.95	5.09	-0.86	4.80	1.66	0.12	3.27	1.58	3.41
1960 W	2.87 [25]	31.0	0.37	2.23	0.49	1.84	0.48	-0.34	1.34	0.84	1.05
1960 C	2.54 [31]	30.5	-0.31	2.08	-0.26	1.52	0.34	-0.29	1.02	0.66	1.04
1960 E	2.21 [47]	35.6	0.03	2.26	0.09	1.51	0.20	-0.45	0.93	0.69	0.96
1975	1.22 [44]	96.5	0.48	2.05	0.39	1.52	0.03	-0.47	0.48	0.48	0.62
1985	1.37 [33]	87.2	-0.67	1.97	-0.60	1.15	-0.48	-0.80	-0.17	0.32	0.47
1994	0.84 [40]	66.3	-0.09	1.04	-0.09	0.80	0.22	-0.03	0.47	0.25	0.72
2005	1.14 [55]	100.0	-0.24	1.30	-0.26	0.87	0.22	0.01	0.42	0.21	0.78

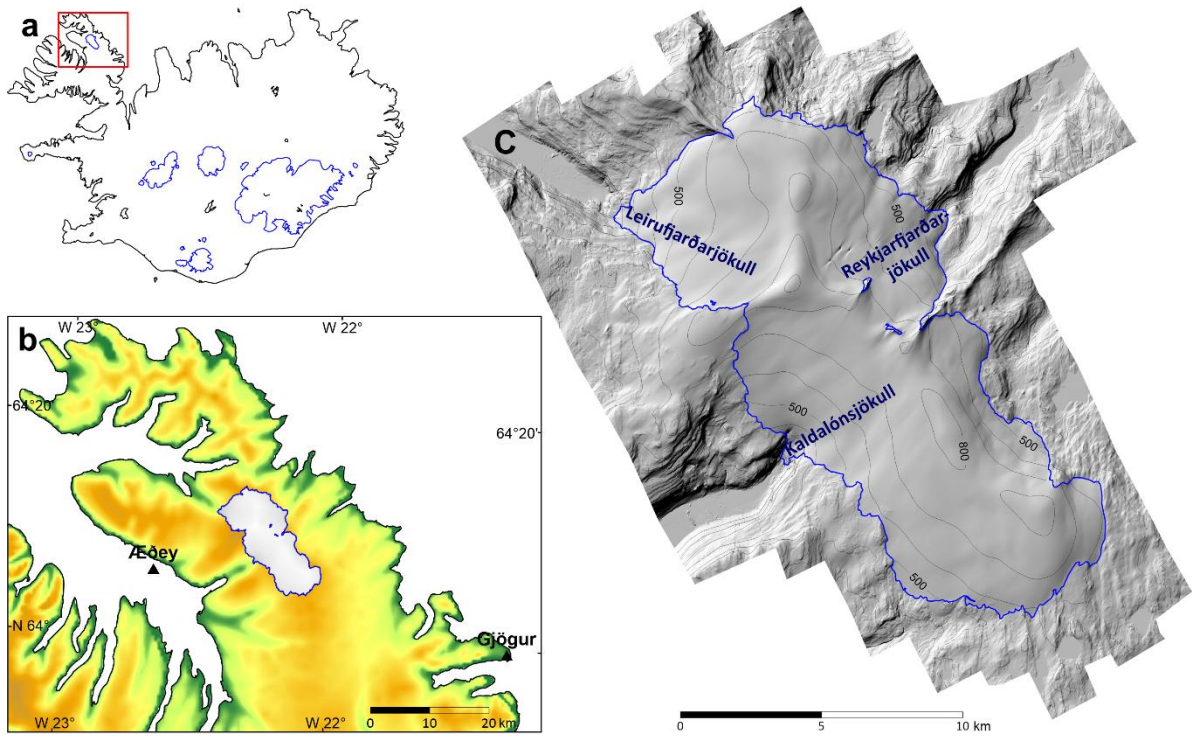
10

1 Table 3. The average elevation change during periods defined by the DEMs before (δh) and
 2 after (δh^*) the seasonal correction, the seasonal correction (δh_{S_cor}) corresponding to DEM at
 3 time t_s and t_f (the correction at t_f is shown with minus sign since this correction term has minus
 4 in front of it in Eq. 2), the uncertainties (95% conf. level) of seasonally corrected elevation
 5 change ($\Delta\delta h^*$) and the uncertainty contribution from the seasonal corrections ($\Delta\delta h_{S_cor}$), DEM
 6 errors ($\Delta\delta h_m$) and interpolation of data gaps ($\Delta\delta h_i$), respectively. All values were originally
 7 calculated in terms of volumes but are here averaged over the area $\bar{A}=(A(t_f)+ A(t_s))/2$.

8

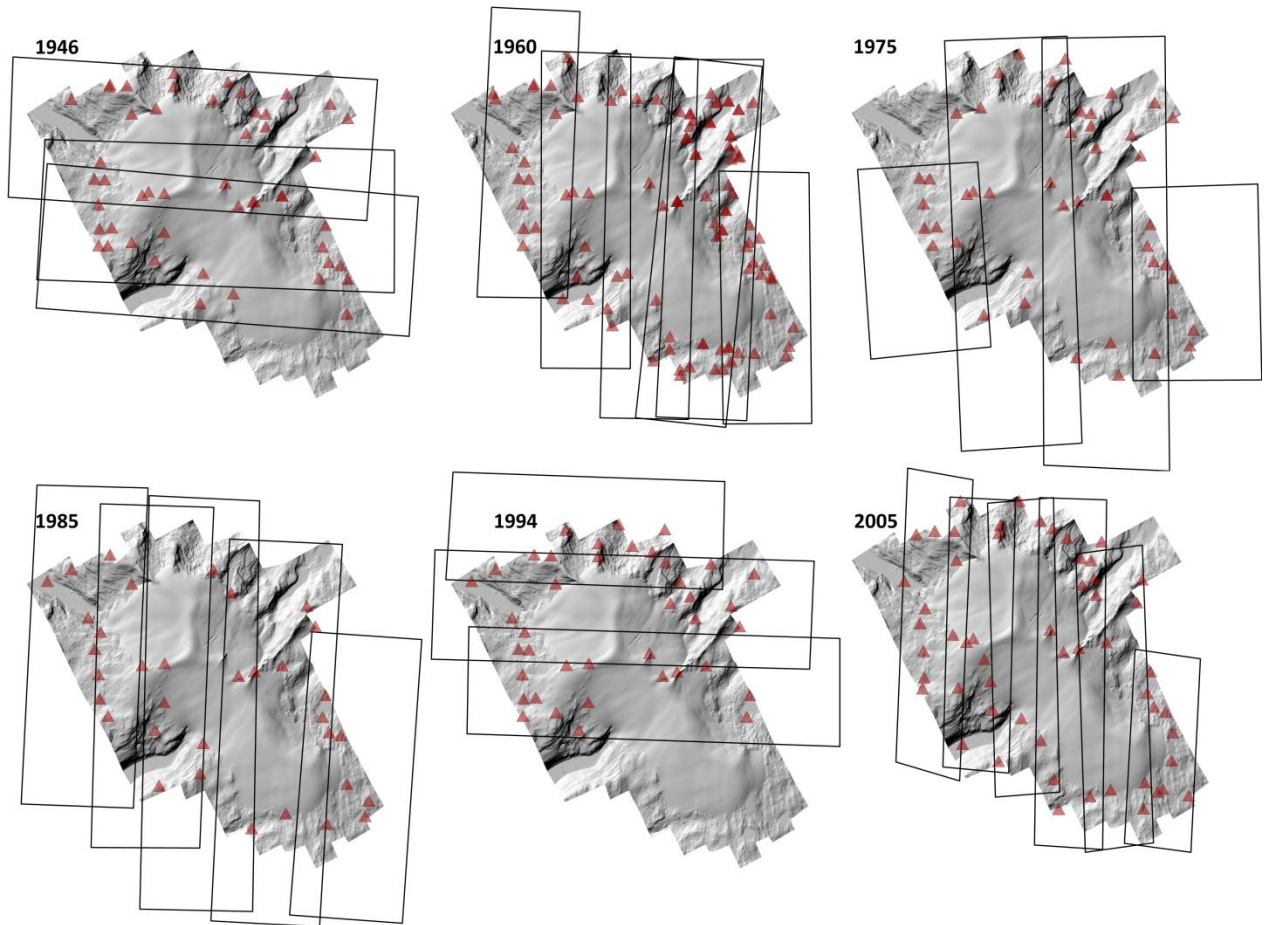
t_s	t_f	Average δh (m)	Average δh^* (m)	Average $\delta h_{S_cor}(t_s)$ (m)	Average $-\delta h_{S_cor}(t_f)$ (m)	Average $\Delta\delta h^*$ (m)	Average $\Delta\delta h_{S_cor}$ (m)	Average $\Delta\delta h_m$ (m)	Average $\Delta\delta h_i$ (m)
1946	1960	-7.36	-10.89	0	-3.53	2.73	0.99	1.28	2.19
1960	1975	-4.73	-1.27	3.69	-0.22	1.29	1.03	0.62	0.39
1975	1985	2.06	0.86	0.22	-1.42	0.95	0.40	0.54	0.62
1985	1994	2.15	2.84	1.42	-0.74	1.14	0.44	0.32	1.08
1994	2005	-7.11	-8.29	0.74	-1.92	1.17	0.58	0.26	0.96
2005	2011	-2.38	-3.23	1.94	-2.79	1.00	0.95	0.21	0

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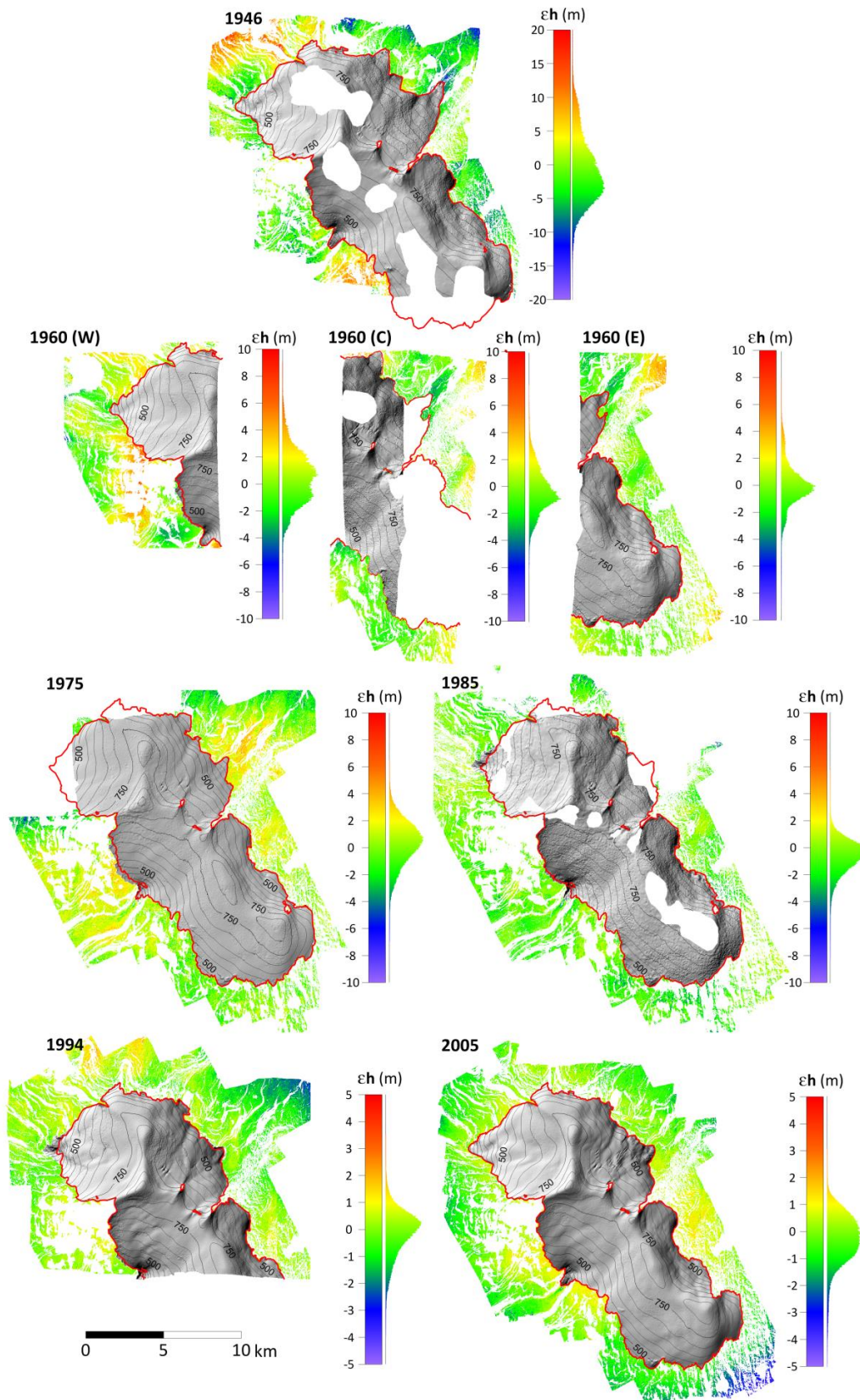
3 Figure 1. Location of study area. Blue lines in **a** are the outline of the larger glaciated areas in
 4 Iceland. The triangles in **b** indicates the locations of the meteorological stations at Aðey and
 5 Gjögur. Image **c** shows a Lidar DEM of Drangajökull (glacier margin shown with blue line)
 6 and vicinity obtained in 2011 (Jóhannesson et al., 2013) represented as shaded relief image and
 7 contour map (100 m contour interval). The names and locations of the 3 main outlet glaciers
 8 are shown.



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3 Figure 2. The coverage of aerial photographs at different epochs with the LiDAR DEM as
4 background. The GCPs used for orientation of each series of aerial photographs are marked
5 with triangles.

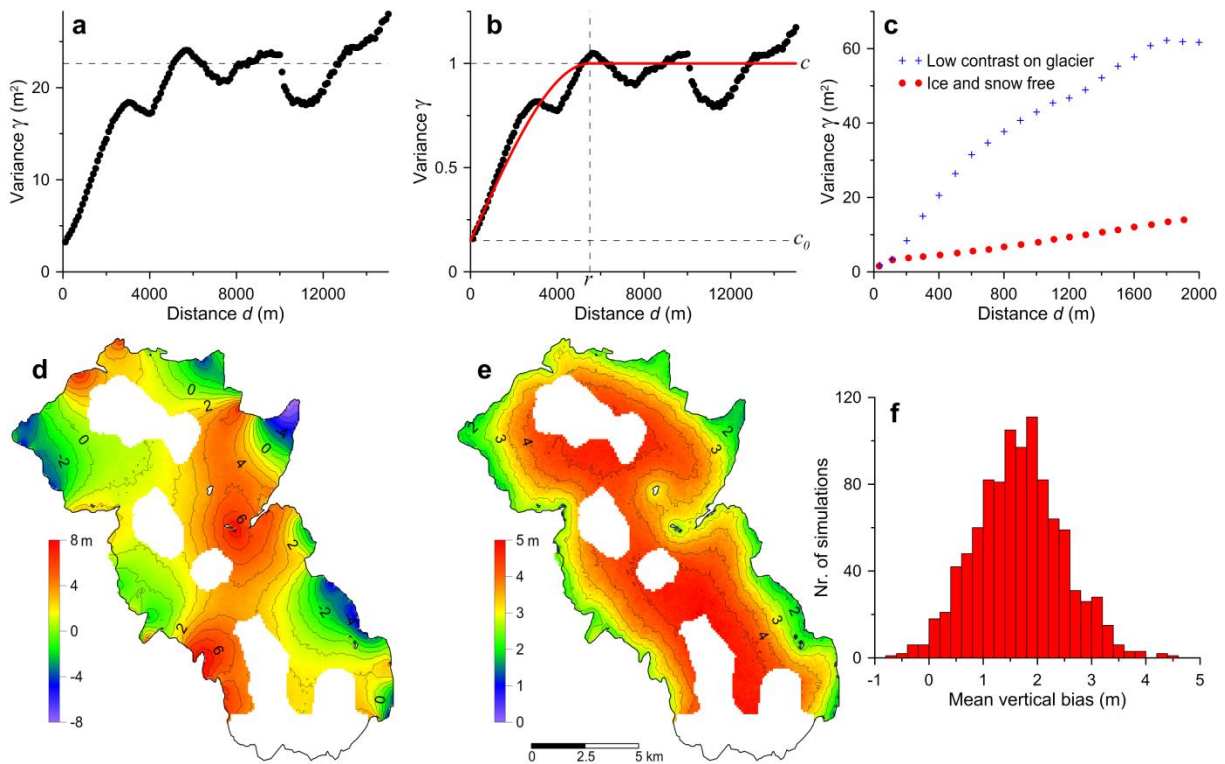


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1 Figure 3. The series of DEMs of Drangajökull ice cap created from the aerial photographs. The
 2 shaded relief images and contour maps indicate the glaciated part of each DEM. The elevation
 3 difference off ice (after masking out outliers and areas with slope $>20^\circ$) are shown as color
 4 images. The color scale is extended for the DEM in 1946 and reduced for the 1994 and 2005
 5 DEMs. A vertical histogram next to the scale bar shows the error distribution.

6

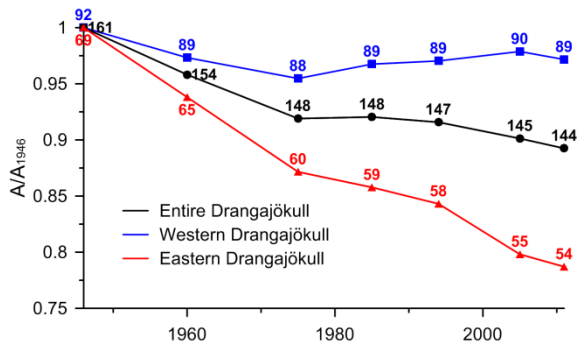


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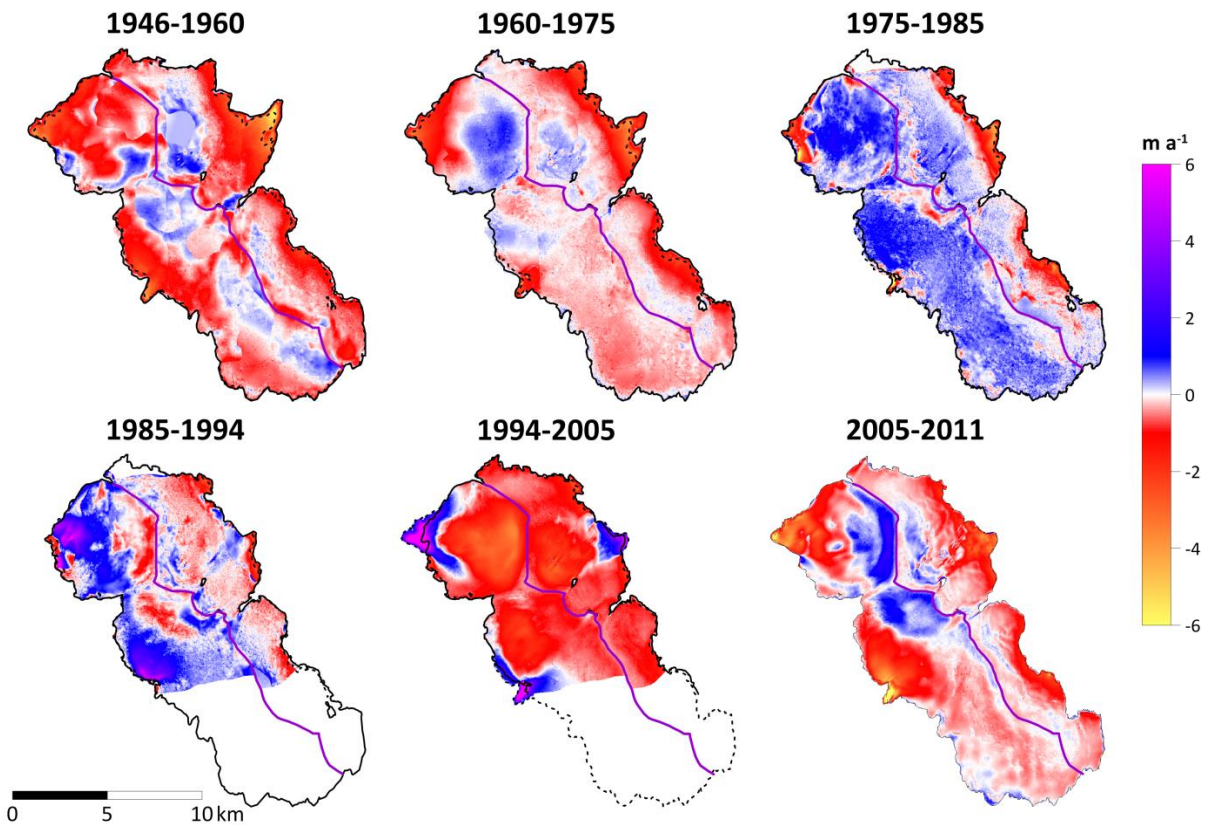
9 Figure 4. The semivariograms of the 1946 DEM error before (a) and after (b) nscoring the data.
 10 The DEM error data is derived from the elevation difference compared to the LiDAR DEM in
 11 ice and snow free areas. Outliers in the elevation difference and areas with slope $>20^\circ$ were also
 12 masked out. The spherical semivariogram model (red line) used in the SGSim and the
 13 parameters defining it (c , c_0 and r) are shown in b. Graph c shows comparison between
 14 semivariograms for the deduced error (same as in a) and the difference compared to the LiDAR
 15 DEM in low contrast areas within the glacier. d-f shows the results of the SGSim for the 1946
 16 glacier DEM. Images d and e, respectively show the mean and standard deviation of 1000
 17 simulations at each 100mx100m pixel. Graph f shows histogram (0.2 m bins) of the mean
 18 vertical bias values of the glacier DEM deduced from each simulation.

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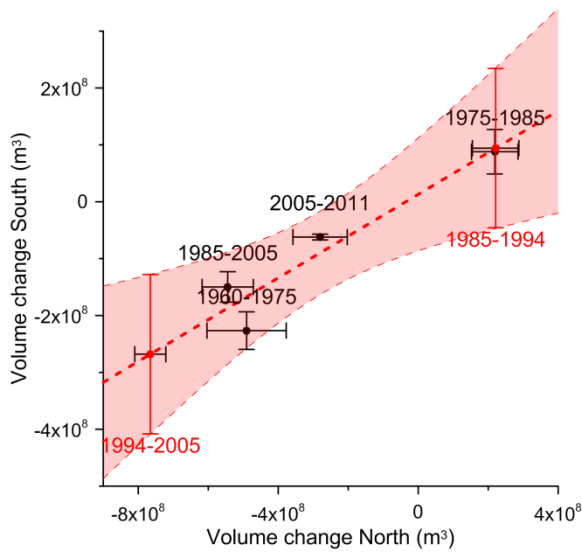
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3 Figure 5. The relative area change of all, the western and the eastern sections of Drangajökull
 4 ice cap (relative to the initial area in 1946). The purple lines in Fig. 6 show the ice divides; they
 5 are used to define the east and west sections of the glacier. Labels give the glacier area in km²
 6 at each epoch.



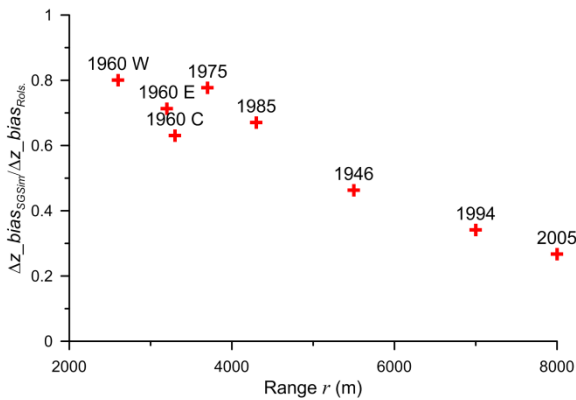
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9 Figure 6. The average annual elevation change of Drangajökull during 6 intervals since 1946.
 10 Red colors indicate thinning and blue colors thickening.



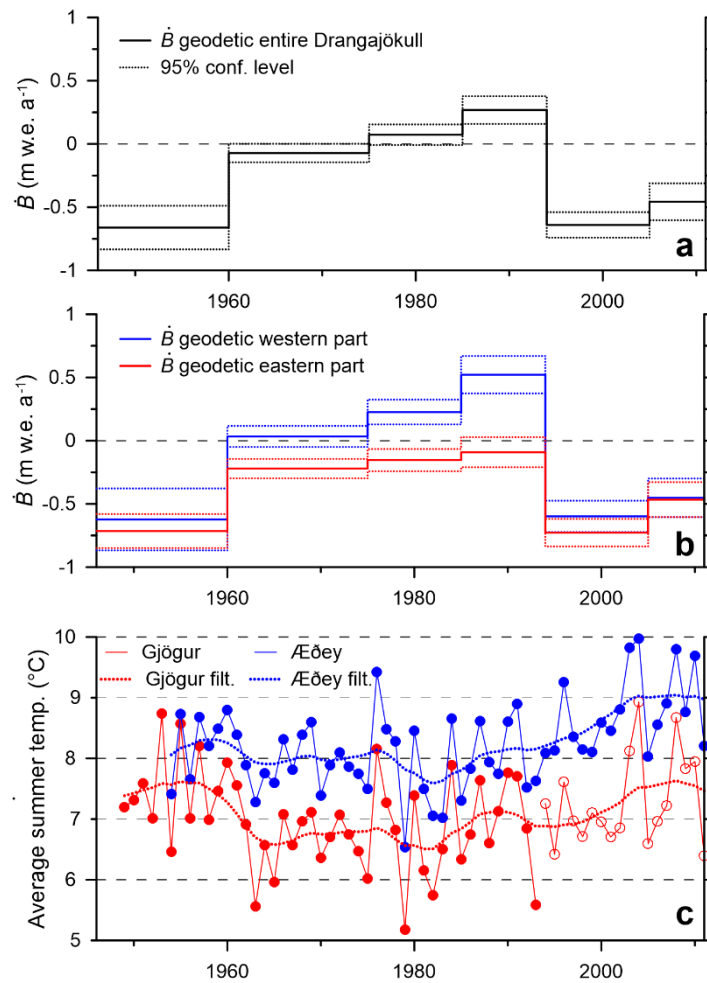
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Figure 7. The volume change of the southernmost of Drangajökull, which is missing in the 1994 DEM (Fig. 3), plotted as function of the volume change in the area north of it covered by the 1994 DEM, for the periods available (shown with black labels). The thick dashed line shows linear fit for the data points with the 95% confidence area shown as light red. The red dots are the corresponding volume change estimates for the southern part in 1985-1994 and 1994-2005.



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Figure 8. The ratio between uncertainties (95% conf. level) from the methods demonstrated in this work and the method demonstrated by Rolstad et al. (2009) as function of the range, r , in the deduced spherical semivariogram model. The DEM epoch corresponding to each point is shown with a label.



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3 Figure 9. The glacier-wide mass balance rate (\dot{B}) during 6 different periods since 1946,
 4 calculated for the entire ice cap (a), and split into the western and the eastern sections of
 5 Drangajökull (b) using the ice divides shown as purple lines in Fig. 6. The dotted line in a-b
 6 represent 95% confidence level. Graph c shows the average summer temperature at the
 7 meteorological stations Gjögur, since 1949, and Aedey since 1954 (see Fig. 1b, for locations).
 8 Close circles indicate data from manned station, open circles from automatic station. The dotted
 9 lines show the average summer temperature at each location filtered with 11 year triangular
 10 weighted running average.