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Abstract

We use the BISICLES adaptive mesh ice sheet model to carry out one, two, and three century simulations of the fast-flowing ice streams of the West Antarctic Ice Sheet. Each of the simulations begins with a geometry and velocity close to present day observations, and evolves according to variation in meteoric ice accumulation, ice shelf melting, and mesh resolution. Future changes in accumulation and melt rates range from no change, through anomalies computed by atmosphere and ocean models driven by the E1 and A1B emissions scenarios, to spatially uniform melt rates anomalies that remove most of the ice shelves over a few centuries. We find that variation in the resulting ice dynamics is dominated by the choice of initial conditions, ice shelf melt rate and mesh resolution, although ice accumulation affects the net change in volume above flotation to a similar degree. Given sufficient melt rates, we compute grounding line retreat over hundreds of kilometers in every major ice stream, but the ocean models do not predict such melt rates outside of the Amundsen Sea Embayment until after 2100. Sensitivity to mesh resolution is spurious, and we find that sub-kilometer resolution is needed along most regions of the grounding line to avoid systematic under-estimates of the retreat rate, although resolution requirements are more stringent in some regions – for example the Amundsen Sea Embayment – than others – such as the Möller and Institute ice streams.

1 Introduction

The present day West Antarctic Ice Sheet (WAIS) is experiencing an imbalance between the mass it receives as snowfall and that which it loses through discharge to the oceans (Rignot, 2008; Pritchard et al., 2009; Shepherd et al., 2012; Mouginot et al., 2014; Rignot et al., 2014). In several areas this has led to the persistent loss of ice amounting to a significant contribution to sea-level rise. Continued acceleration of these losses would imply a significant additional global sea-level rise in coming decades and

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widespread melt-rate increases, as well as projections further into the future, in order to investigate the additional response to more extreme scenarios. The century-scale evolution of the ice sheet model is also sensitive to its present day state, especially in the Amundsen Sea Embayment, and we evaluate at least a part of this sensitivity – which will prove to be substantial – by varying the initial accumulation rate and hence the initial thinning rate.

In summary, the aim of this paper is to consider the response of the West Antarctic ice streams to process-based and simplified projections of future ocean and atmosphere warming over the 21st and 22nd centuries. We focus on West Antarctica primarily because of constraints on available computational resources; however these areas are also thought to be most vulnerable to future grounding line retreat because of their deep bedrock and changes in oceanic forcing (Hellmer et al., 2012; Pritchard et al., 2012; Ross et al., 2012; Joughin et al., 2014).

2 Methods

2.1 Model equations

BISICLES employs a vertically integrated ice flow model based on Schoof and Hindmarsh (2010) which includes longitudinal and lateral stresses and a simplified treatment of vertical shear stress which is best suited to ice shelves and fast flowing ice streams. Ice is assumed to be in hydrostatic equilibrium so that given bedrock elevation b and ice thickness h the upper surface elevation s is

$$s = \max \left[h + b, \left(1 - \frac{\rho_i}{\rho_w} \right) h \right], \quad (1)$$

in which ρ_i and ρ_w are the densities of ice and ocean water.

The ice thickness h and horizontal velocity \mathbf{u} satisfy a two-dimensional mass transport equation

$$\frac{\partial h}{\partial t} + \nabla \cdot [\mathbf{u}h] = M_s - M_b, \quad (2)$$

and two dimensional stress-balance equation

$$\nabla \cdot [\phi h \bar{\mu} (2\dot{\epsilon} + 2\text{tr}(\dot{\epsilon})I)] + \boldsymbol{\tau}^b = \rho_i g h \nabla s, \quad (3)$$

together with lateral boundary conditions. The terms on the right hand side of Eq. (2), M_s and M_b , are accumulation and melt rates. As for Eq. (3), $\dot{\epsilon}$ is the horizontal strain-rate tensor,

$$\dot{\epsilon} = \frac{1}{2} [\nabla \mathbf{u} + (\nabla \mathbf{u})^T] \quad (4)$$

and I is the identity tensor. The vertically integrated effective viscosity $\phi h \bar{\mu}$ is computed from the vertically varying effective viscosity μ through

$$\phi h \bar{\mu}(x, y) = \phi \int_{s-h}^s \mu(x, y, z) dz, \quad (5)$$

where μ includes a contribution from vertical shear and satisfies

$$2\mu A(T) (4\mu^2 \dot{\epsilon}^2 + |\rho_i g (s - z) \nabla s|^2)^{(n-1)/2} = 1, \quad (6)$$

where the flow rate exponent $n = 3$, ϕ is a stiffening factor (or, equivalently, ϕ^{-n} is an enhancement factor), and $A(T)$ depends on the ice temperature T through the Arrhenius law described by Hooke (1981),

$$A(T) = A_0 \exp \left(\frac{3f}{[T_r - T]^k} - \frac{Q}{RT} \right) \quad (7)$$

BISICLES ice sheet model was designed primarily with this in mind, and discretizes the stress and mass balance Eqs. (2) and (3) on block-structured meshes built from rectangular subsets of uniform grids with resolution Δx^ℓ , with $0 \leq \ell \leq L$ and $2\Delta x^{\ell+1} = \Delta x^\ell$. While restrictive in some senses – all model domains must be rectangular, for example – these meshes have a signal advantage: it is straightforward to generate new meshes as the ice sheet evolves, and to transfer the previous time-step’s ice thickness data to the new mesh in a conservative fashion. It is also relatively easy to study convergence with mesh resolution by running the same experiment for successive values of L and check that the differences between, say, the volume above flotation calculated in each case converge at the expected rate. We include the results of such a study in Sect. 3.1.1.

2.4 Model data requirements

Time-dependent simulations require initial ice thickness data $h_0(x, y)$ as well as accumulation rates $a(x, y, t)$ and melt rates $M(x, y, t)$ for Eq. (2), together with a bedrock elevation map $b(x, y)$, a basal friction coefficient field $C(x, y)$, a temperature field $T(x, y, z)$ and a stiffening factor $\phi(x, y)$ to solve Eq. (3). Bedrock elevation and initial ice thickness data for the RISFRIS and MBL domains were taken from the ALBMAP 5 km DEM (Le Brocq et al., 2010). A custom map of bedrock elevation and ice thickness set on a 1 km grid was used for the ASE domain: it is close to the more recent Bedmap2 (Fretwell et al., 2013) data, and was used before for studies of Pine Island Glacier (Favier et al., 2014). It was prepared in a similar manner to ALBMAP, but includes extra data from high resolution airborne radar (Vaughan et al., 2006) and submarine surveys (Jenkins et al., 2010). It also includes a pinning point at the tip of Thwaites Glacier’s slower flowing eastern ice shelf, a feature that is clearly visible in the velocity data (Joughin et al., 2009; Rignot et al., 2011), that corresponds to peak one of the two described in Tinto and Bell (2011), but is absent in the bathymetry data. We raised the bathymetry by 120 m to ground the ice in that region. Ice temperature data is provided

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by a three-dimensional thermo-mechanical model (Pattyn, 2010) and is held fixed in time.

The remaining data are rather more complicated. The basal friction and stiffening coefficients inside the drainage basin are estimated by solving an inverse problem, described in Sect. 2.4.1, while the accumulation and melt rates are composed of initial accumulation and melt rates a_0 and M_0 , described in Sect. 2.4.2, and future climate anomalies, described in Sect. 2.5.

2.4.1 Basal friction and stiffening coefficients

We estimate basal friction and stiffening coefficient by solving an inverse problem similar to those of MacAyeal (1993), Joughin et al. (2009) and Morlighem et al. (2010). Broadly speaking, we choose smooth fields $C(x, y)$ and $\phi(x, y)$ that minimise the mismatch between modeled and observed speeds. A nonlinear conjugate gradient method was employed to seek a minimum of the objective function

$$J = J_m + J_p \quad (12)$$

composed from a misfit function

$$J_m = \frac{1}{2} \int_{\Omega_v} \alpha_u^2(x, y) (|\mathbf{u}| - |\mathbf{u}_{\text{obs}}|)^2 d\Omega \quad (13)$$

and a Tikhonov penalty function

$$J_p = \frac{\alpha_C^2}{2} \int_{\Omega_v} |\nabla C|^2 d\Omega + \frac{\alpha_\phi^2}{2} \int_{\Omega_v} |\nabla \phi|^2 d\Omega. \quad (14)$$

The coefficient $\alpha_u^2(x, y)$ is related to error estimates for the observed velocity and we set it to 1 where velocity data is available and 0 elsewhere.

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Ideally, the penalty function J_p would not be required (so that $\alpha_C^2, \alpha_\phi^2 = 0$) because it is equivalent to a claim to some prior knowledge of ϕ and C – specifically, their probability distributions are $p(C) \propto \exp(-\alpha_C^{-2} |\nabla C|^2)$ and $p(\phi) \propto \exp(-\alpha_\phi^{-2} |\nabla \phi|^2)$ – and we clearly do not have such knowledge. In practice, though, we require $\alpha_C^2, \alpha_\phi^2 > 0$ for two reasons. First, J does not have a unique minimum with respect to both ϕ and C : in other words, the inverse problem would be under-determined, because we have one field of data and two fields of unknowns. Second, even if we were only seeking (say) C , the inverse problem would be ill-conditioned, that is, sensitive to small changes in u_{obs} . We follow Hansen (1994) and choose $\alpha_C^2, \alpha_\phi^2$ such that lower values lead to faster growth in J_p than reduction in J_m and larger values lead to the converse.

To ensure that C and ϕ are positive definite, we express them as

$$C = C_0 e^q \quad \text{and} \quad \phi = \phi_0 e^p \quad (15)$$

and minimise Eq. (12) with respect to p and q . C_0 and ϕ_0 are initial guesses for the basal traction and stiffening factor, and here we set

$$C_0 = \begin{cases} \frac{\rho_i g h |\nabla s|}{|u_0|^{+1}} & \text{if } \alpha_u^2 > 0 \\ 10^5 & \text{otherwise} \end{cases} \quad (16)$$

and $\phi_0 = 1$.

The nonlinear conjugate gradient method requires expressions for the Gâteaux derivatives $d_q J(q, p; q')$ and $d_p J(q, p; p')$. Here we have used similar notation to Arthern and Gudmundsson (2010), for example:

$$d_q J'(q, p; q') = \lim_{\epsilon \rightarrow 0} \frac{J'(q + \epsilon q', p) - J'(q, p)}{\epsilon}. \quad (17)$$

We neglect the non-linearity of $\bar{\mu}$ in the adjoint of the viscous tensor operator in Eq. (3) – an omission discussed by e.g. Goldberg and Sergienko (2010) and Morlighem et al.

(2013) – and approximate the Gâteaux derivatives $d_q J_m(q, p; q')$ and $d_p J_m(q, p; p')$ by

$$d_q J_m(q, p; q') \approx - \int_{\Omega_V} q' \boldsymbol{\lambda} \cdot \mathbf{u} C d\Omega \quad (18)$$

and

$$d_p J_m(q, p; p') \approx \int_{\Omega_V} p' \phi \bar{\mu} h \nabla \boldsymbol{\lambda} \cdot (\nabla \mathbf{u} + (\nabla \mathbf{u})^T + 2 \nabla \cdot \mathbf{u} I) d\Omega \quad (19)$$

5 where the vector field $\boldsymbol{\lambda}$ is the solution to a linear boundary value problem, with

$$\nabla \cdot \left\{ \phi h \bar{\mu} \left(\nabla \boldsymbol{\lambda} + (\nabla \boldsymbol{\lambda})^T + 2(\nabla \cdot \boldsymbol{\lambda}) I \right) \right\} - C \boldsymbol{\lambda} = \left[\frac{|\mathbf{u}_0|}{|\mathbf{u}|} - 1 \right] \mathbf{u} \quad (20)$$

and on the domain boundary

$$\boldsymbol{\lambda} \cdot \mathbf{n} = 0, \quad \mathbf{t} \cdot \nabla \boldsymbol{\lambda} \cdot \mathbf{n} = 0. \quad (21)$$

The penalty function (Eq. 14) is easily differentiated to give

$$10 \quad d_p J_p(q, p; p') = -\alpha_C^2 \int_{\Omega_V} p' C \nabla^2 C d\Omega \quad (22)$$

and

$$d_q J_p(q, p; q') = -\alpha_\phi^2 \int_{\Omega_V} q' \phi \nabla^2 \phi d\Omega. \quad (23)$$

The inverse problem requires accurate speed data consistent with the thickness and bedrock data and having near-complete spatial coverage. For the RISFRIS and MBL

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the SMB to the 1990–1999 mean from a high resolution atmosphere model (RACMO2, with HadCM3 boundary conditions and the E1 emissions), and the sub-shelf melt rate is chosen to keep the ice shelf in steady state. After 50 years, we compute an accumulation rate a^0 required to keep the grounded ice close to steady state, and a melt rate M_0 that will keep the ice shelf close to steady state. We then run the model for 50 years starting again from the original state. The resulting ice sheet is closer to, but not at, equilibrium, and we carry out all projections starting from this state, with SMB and melt rates computed by adding the perturbations described in Sect. 2.5.1 to a_0 and M_0 .

Although the melt-rate M_0 at the end of the relaxation could be estimated directly from the flux divergence, we will need to adjust it as the grounding line moves. Flowline calculations indicate that elevated melt rates close to the grounding line can result in a dynamic response quite different from the response to elevated melt some distance downstream (Walker et al., 2008; Gagliardini et al., 2010). Observations and ocean model tend to show that melt-rates do decay downstream of the grounding line (Jenkins et al., 2006; Payne et al., 2007; Rignot et al., 2013; Dutrieux et al., 2013, 2014), and we expect peak melt-rates to move with the grounding line, partly because pressure melting point is higher there, and partly because the steeper underside of the ice shelf leads to more entrainment of heat and salt.

We construct a scheme that allows higher melt rates to follow the grounding by decomposing M_0 into grounding line localized and ambient components, as in Gong et al. (2014) and Wright et al. (2014). We set

$$M_0(x, y, t) = M_{\text{GL}}(x, y)\xi(t) + M_{\text{A}}(x, y)(1 - \xi(t)) \quad (24)$$

where $\xi = 1$ at the grounding line, $\xi = 0$ in the ocean, and

$$\xi - \chi^2 \nabla^2 \xi = 0 \quad (25)$$

across the ice shelf, with the scale-length $\chi = 10$ km, so that ξ decays exponentially with distance from the grounding line. The components M_{GL} and M_{A} are determined by considering the ice mass flux in regions close to and far from the initial grounding line

respectively, and then extrapolating over the entire domain. To compute the ambient component, we construct a parabolic equation

$$\frac{\partial M_A}{\partial t'} - \chi^2 \nabla^2 M_A = R_A \quad (26)$$

where

$$R_A(x, y) = \begin{cases} \nabla \cdot (\mathbf{u}h) & \text{if } 0 < \xi < \frac{1}{10} \\ 0 & \text{otherwise.} \end{cases} \quad (27)$$

Integrating Eq. (26) from $t' = 0$ to $t' = t''$ leads to a value $M_A(x, y, t'')$, and given a large enough t'' the effect is to extrapolate values of $\nabla \cdot (\mathbf{u}h)$ from those regions of the ice shelf further than about 25 km from the grounding line across the domain, and at the same time smooth it. M_{GL} is computed in a similar fashion, but with a different right-hand-side

$$R_{GL} = \begin{cases} \frac{1}{\xi} [\nabla \cdot (\mathbf{u}h) + (\xi - 1)M_A] & \text{if } 0 < \xi < 1 \\ 0 & \text{otherwise.} \end{cases} \quad (28)$$

Figure 5 shows how $M_0(x, y, t)$ varies in Pine Island Glacier's ice shelf as the grounding line retreats.

2.4.3 Further adjustments

An adjustment in the region of Pine Island Glacier's grounding line was required, prior to the relaxation, to prevent sustained thickening of the order of 100 m a^{-1} . A similar tendency is seen in other models of Pine Island Glacier, and is dealt with elsewhere by imposing a large synthetic mass balance (Joughin et al., 2010), by constraining the ice viscosity and accepting a worse match to the observed velocity (Favier et al., 2014), or by modifying the bed to give acceptable thickening rates while matching the observed velocity (Rignot et al., 2014; Nias et al., 2015). Here, we soften the ice around

fourteen experiments forced by combinations of time-dependent climate model data, and six melt-rate anomaly experiments, which are subject to constant accumulation. The experiments are summarized in Table 1 and described in detail below.

2.5.1 Combined anomaly experiments

Future climate forcings were derived from the atmosphere and ocean models by computing space- and time-dependent anomalies with respect to the 1980–1989 mean, and adding them to $a_0(x, y)$ and $M_0(x, y, t)$. By combining the seven atmosphere projections with the eight ocean projections, we have fourteen experiments, as shown in Table 1. These are named after the anomalies: for example, the experiment named H/A/R/F combines the HadCM3/A1B/RACMO2 accumulation anomalies with the HadCM3/A1B/FESOM melt-rate anomalies. Given the fourteen forcing combinations, the ice sheet model was evolved, starting from its initial state in 1980 to at least 2100 and on to 2150 or 2200 if the forcing data were available. The HadCM3/A1B/FESOM ocean data, both sets of HadCM3/A1B/BRIOS ocean data and all of the HadCM3/A1B atmosphere projections were sufficient to run the ice sheet model until 2200, the HadCM3/E1/FESOM data run to 2150, and the ECHAM5 data to 2100.

Neither ocean model produced substantial melt rate increases in the ASE or MBL domains, presumably because they are not able to resolve the small ice shelves along those coasts. We computed melt rates in those regions from projections of nearby ocean temperatures. The melt rates and consequent thinning experienced by small ice shelves, such as Pine Island Glacier is thought to be forced by changes in the temperature of near-coast water masses (Jacobs et al., 2011; Pritchard et al., 2012). We compute a local ocean temperature anomaly $\Delta T(t)$ by averaging the projected ocean temperature over volume bounded laterally between the contemporary ice front, the sector boundaries, and the 1000 m bathymetric contour and vertically between depths of 200 and 800 m, on the grounds that water contributing to melting must be deep enough to interact with the base of an ice shelf but shallow enough to cross the conti-

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mental shelf break. Finally, a melt-rate anomaly $\Delta M(t) = 16\Delta T(t) \text{ ma}^{-1} \text{ K}^{-1}$ was chosen to be at the upper end of the range of observational and modelling studies (Holland et al., 2008; Rignot, 2002).

The accumulation and melt-rate anomalies, plotted in Figs. 7 and 8, have a notable feature. The A1B atmosphere models project increased accumulation during the 21st century, and a further increase during the 22nd century, over and above the E1 models. Although the two atmosphere models distribute snowfall differently, with RACMO2 concentrating its increased accumulation over the Amundsen Sea Embayment and Filchner–Ronne Ice Shelf drainage basins and LMDZ4 heaping mass over Marie-Byrd Land and the Ross Ice Shelf drainage basin, both models project a threefold increase for A1B over E1. At the same time, the A1B and E1 ocean models both provide enhanced melt rates from 2100, with the most obvious difference between trends being the choice of FESOM or BRIOS. Even before carrying out any simulations, we can expect to see similar dynamic thinning in the two emissions scenarios, which, coupled with the extra accumulation in A1B, means that we expect to simulate more sea level rise for E1 (mitigation) emissions than A1B (business as usual) emissions.

2.5.2 Melt-rate anomaly experiments

The climate-forced experiments outlined above present a rather limited view of future change. Since both the ocean and atmosphere models project similar futures, they cannot provide much information about the response to earlier or more widely distributed ice shelf thinning. At the same time, the assumption that the ice sheet was in steady state at the end of the 20th century does not allow us to examine changes that may already be underway. A number of experiments with melt-rate anomalies but no accumulation anomalies were carried out to address these limitations.

Parts of the ice sheet model might be on the brink of dramatic change in 2200, so we ran a longer set of calculations, starting in 1980 and running until 2300, based on the HadCM3/A1B/FESOM melt rates. This experiment has only the synthetic accumu-

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lation field, so we label it H/A/0/F. The HadCM3/A1B/FESOM melt rates were chosen because they run up to 2200, produce enhanced melting in all of the basins, and rise constantly from 2050 onward to give the largest melt rates at the end of the 22nd century. From 1980 to 2200 we applied the melt-rate anomalies as before, and applied the 2200 melt-rate anomaly for the remainder of the simulation.

Imposing a synthetic accumulation field to hold the ice sheets close to steady state given the present day geometry and velocity is a questionable choice in the Amundsen Sea Embayment, where observations over the last decades show extensive thinning. Furthermore, the synthetic mass balance field $a_0(x, y)$, which we constructed to hold Thwaites Glacier in steady state during the control experiment, includes a spot of unrealistic -5 ma^{-1} accumulation close to the Thwaites Glacier grounding line (see Fig. 6). In light of these issues, we carried out three additional simulations. None of these experience accumulation anomalies but the first, H/A/0'/F, has a synthetic accumulation field $a'_0(x, y)$ with the 5 ma^{-1} accumulation spot removed, and the second and third, H/A/0''/F and control'' do not make use of a synthetic accumulation field at all, but employ the HadCM3/E1/RACMO2 1990–1999 temporal mean, which we will call $a''_0(x, y)$, from 1980 onward. H/A/0'/F and H/A/0''/F are subject (like H/A/0/F) to the HadCM3/A1B/FESOM melt-rate anomaly data, while the control'' experiment maintains the same melt-rate parametrization as the control experiment, that is $M_0(x, y, t)$.

As none of the melt-rate anomalies in the ASE exceed 10 ma^{-1} until after 2050, we also examined the model's response to earlier ocean warming. Two simulations, 0/U16 and 0''/U16, were performed, with melt-rate anomalies of 16 ma^{-1} applied across all floating ice from 1980 onward. 0/U16 used the synthetic accumulation field $a_0(x, y)$, while 0''/U16 used the HadCM3/E1/RACMO2 1990–2000 mean accumulation field $a''_0(x, y)$.

Both FESOM and BRIOS ocean models produce similar melt-rate anomalies, with enhanced melt rates concentrated around Berkner Island in the Filchner–Ronne ice shelf, and around Roosevelt Island in the Ross Ice Shelf. Those similar patterns are due to the physics of ocean circulation in the two models, but it makes sense to consider

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ice sheet sensitivity to melt rates that cover a greater extent. At the same time, as in the ASE, melt rates begin to grow around 2100 in all of the drainage basins, so we need to consider our sensitivity to earlier warming. With those aims in mind, we carried out a pair of uniform melt-rate experiments (0/U8,0/U16) in the RISFRIS domain, applying melt-rate anomalies of 8 and 16 ma^{-1} across the entire extent of floating ice starting from 1980.

3 Results and discussion

3.1 Melt-rate anomaly experiments

The melt-rate anomaly experiments (that is, the experiments with no accumulation anomalies) all exhibit grounding line retreat in excess of the control simulation. Figure 9 depicts this retreat for the H/A/0/F experiment, alongside RISFRIS and ASE uniform melt-rate simulations (0/U16) and ASE simulations with no synthetic accumulation (control'', H/A/0''/F and 0''/U16). Provided that melt rates are sufficient, deep bedded glaciers flowing into the Filchner–Ronne and Ross Ice Shelves see their grounding lines retreat by as much 100 km in a century, as do Pine Island and Thwaites Glaciers. However, while the ASE retreats during the 21st, 22nd, and 23rd century in both the FESOM and uniform melt experiments, the RISFRIS glaciers do not show significant retreat until the 22nd century when driven by FESOM melt rates (which do not start to grow until the late 21st century).

3.1.1 Mesh resolution

Before examining the detailed response to melting in each region, we show that our chosen meshes, with $\Delta x_{\min} = 250$ m for the ASE and $\Delta x_{\min} = 625$ m elsewhere, are adequate. To this end, we consider just the H/A/0/F simulations, as the dynamic response is similar for every case.

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Both grounding line migration and overall mass loss in the ASE model are rather sensitive to mesh resolution close to the grounding line. Figure 10 plots the change in volume above flotation (ΔV) over time for meshes with finest resolutions varying from $\Delta x_{\min} = 4000$ m to $\Delta x_{\min} = 250$ m, while Fig. 10 shows grounding line positions around Smith glacier at the start and end of the simulations, together with the final mesh. At the coarsest resolution there is essentially no loss of volume and the grounding line does not retreat at all while at finer resolutions there is progressively greater volume loss and grounding line retreat, just as in previous simulations of Pine Island Glacier (Favier et al., 2014; Cornford et al., 2013).

Provided that the finest resolution $\Delta x_{\min} \leq 1000$ m, the volume change $\Delta V(\Delta x_{\min}, t)$ converges with Δx_{\min} , but we only obtain the theoretical rate of convergence – $O(\Delta x_{\min})$ – when $\Delta x_{\min} \leq 500$ m. If the rate of convergence is $O(\Delta x_{\min})$, we can calculate an estimate of the volume loss for any resolution given the results from two coarser resolutions, through Richardson extrapolation. The error estimate for a given resolution is

$$e(\Delta x_{\min}, t) = -\Delta V(\Delta x_{\min}, t) + \Delta V(2\Delta x_{\min}, t) \quad (30)$$

the estimated volume loss as $\Delta x_{\min} \rightarrow 0$ is

$$\overline{\Delta V}(\Delta x_{\min} \rightarrow 0, t) = \Delta V(\Delta x_{\min}, t) + e(\Delta x_{\min}, t) \quad (31)$$

and the estimated volume loss for a finer resolution is

$$\overline{\Delta V}\left(\frac{1}{2}\Delta x_{\min}, t\right) = \Delta V(\Delta x_{\min}, t) + \frac{1}{2}e(\Delta x_{\min}, t). \quad (32)$$

Figure 10 plots these estimated volume losses alongside the simulated losses: $\overline{\Delta V}(\frac{1}{2}\Delta x_{\min}, t)$ is a good approximation to $\Delta V(\frac{1}{2}\Delta x_{\min}, t)$ once $\Delta x_{\min} = 500$ m. For the chosen resolution, $\Delta x_{\min} = 250$ we estimate that volume losses over 200 years fall short, through under-resolution, by $e(\Delta x_{\min}, t) = 2.5 \times 10^3 \text{ km}^3$ out of $20 \times 10^3 \text{ km}^3$, that is, 7 mm sea level equivalent (SLE) out of 50 mm SLE.

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The RISFRIS model is less sensitive to mesh resolution than the ASE model, and we were able to carry out calculations at a coarser, $\Delta x_{\min} = 625$ m resolution. Figure 11 shows that much of the loss in volume above flotation seen in a simulation with $\Delta x_{\min} = 312.5$ m ($\Delta V = 32$ mm SLE) is also seen in a simulation with $\Delta x_{\min} = 5000$ m ($\Delta V = 21$ mm SLE). At the same time, while the grounding line does retreat more as the resolution is increased, retreat takes place for all resolutions in the Möller, Institute and Foundation ice streams, though only for $\Delta x_{\min} < 2500$ m in Evans Glacier. Nonetheless, the simulation with $\Delta x_{\min} = 1250$ m loses as much additional volume (4 mm SLE) compared to the $\Delta x_{\min} = 2500$ m case as calculations with $\Delta x_{\min} = 2500$ m lose on top of the $\Delta x_{\min} = 5000$ m case. Convergence with Δx_{\min} is apparent once $\Delta x_{\min} < 2500$ m and at the chosen resolution, $\Delta x_{\min} = 625$ m, volume loss is underestimated by $e(\Delta x_{\min}, t) = 0.8 \times 10^3 \text{ km}^3$ out of $12 \times 10^3 \text{ km}^3$ (2 mm SLE out of 30 mm SLE).

In summary, under-resolution results in the loss of volume above flotation being underestimated by around 10% for our chosen meshes, which have $\Delta x_{\min} = 250$ m in the ASE model and $\Delta x_{\min} = 625$ m otherwise. In that context, we now consider the sensitivity of each region to melt-rate anomalies.

3.1.2 Amundsen Sea Embayment

The Amundsen Sea Embayment thins throughout the melt-rate anomaly simulations, losing $5\text{--}14 \times 10^3 \text{ km}^3$ (15–40 mm SLE) volume above flotation between 2000 and 2100 and $20\text{--}70 \times 10^3 \text{ km}^3$ (50–190 mm SLE) by 2200. Pine Island Glacier and the ice streams feeding the Crosson and Dotson Ice Shelves experience $\sim 1 \text{ km a}^{-1}$ grounding line retreat from the present day onward in all of the experiments apart from control and control'', while Thwaites Glacier sees its retreat delayed in some simulations. The major distinction between simulations is the onset of retreat in Thwaites Glacier, and the rates of volume loss plotted in Fig. 12 are more than twice as great when that retreat begins in the present day.

Projections of retreat in Thwaites Glacier are strongly affected by initial conditions, with some simulations showing little retreat and others shedding between 100 and

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210 km³ a⁻¹ volume above flotation over the 21st and 22nd centuries. In calculations with the synthetic mass balance a_0 : H/A/0/F, 0/U16, and the control experiment 0/U0), the grounding line remains close to the present day position until after 2200, despite the near complete removal of its ice shelf by that time in H/A/0/F and 0/U16. It seems that even with the isolated promontory in the slowly flowing eastern section, the ice shelf exerts little back-pressure on the ice stream and so its loss is not felt strongly. The majority of the grounding line retreat only begins after 2200, triggered by the retreat of the small stream which diverts from Thwaites glacier to flow into the south-western corner of Pine Island Glacier and from then on the grounding line retreats at a rate of 1 km a⁻¹ until 2300. In contrast, the glacier begins to retreat around 2100 in the H/A/0'/F experiment, and around 2000 in the H/A/0''/F, 0''/U16 and even the control'' experiments. In these last three simulations, marine ice sheet instability is already acting at the beginning of the simulation, and at no point does the ice shelf provide enough buttressing to prevent it. Provided that retreat is initiated, the higher melt rates applied in H/A/0''/F, 0''/U16 do result in faster retreat (~ 200 km³ a⁻¹) than in the control'' (~ 100 km³ a⁻¹).

Both mass loss and grounding line migration in Thwaites Glacier accelerate during the second century of retreat. For the H/A/0''/F simulation, volume above flotation decreases at a mean rate of 75 km³ a⁻¹ (0.2 mm a⁻¹ SLE) between 2000 and 2100, while the grounding line retreats at a rate ~ 1 km a⁻¹ across a region featuring a broad area less than 800 m below sea level and a narrow trough between 800 and 1200 m below sea level. Over the following century, the grounding line crosses a widening region of deeper bedrock (> 1200 m b.s.l. – below sea level), so that the greater rate of flow associated with thicker ice at the grounding line is integrated over a broadening front. The average rate of grounding line retreat grows to ~ 2 km a⁻¹, and the rate of loss of volume above flotation to 320 km³ a⁻¹ (0.9 mm a⁻¹ SLE). A similar calculation of accelerating mass loss, with losses of less than 0.25 mm a⁻¹ SLE during the 21st century and up to 1 mm a⁻¹ SLE thereafter was reported by Joughin et al. (2014).

Variation between the remaining ASE projections, dominated by Pine Island Glacier, is due to both ocean forcing and initial conditions. Neither the control nor the control''

Ronne Ice Shelf drainage basin remains close to balance. Adding all four trends together, West Antarctica sees a net loss of $0-8 \times 10^3 \text{ km}^3$ by 2100 and $3-23 \times 10^3 \text{ km}^3$ by 2200. Note that Thwaites Glacier does not retreat in these combined calculations, as they all apply the synthetic accumulation, and the ASE could contribute an extra $9 \times 10^3 \text{ km}^3$ loss by 2100 and $40 \times 10^3 \text{ km}^3$ by 2200, based on the difference between the H/A/O/F and H/A/O''/F trends.

Combining melt-rate and accumulation anomalies leads to essentially the same patterns of dynamic thinning and grounding line retreat as melt-rate anomalies alone. For example, the H/A/R/F and H/A/L/F simulations exhibit similar grounding line retreat to the H/A/O/F results shown in Fig. 9. The differences between ocean models are quantitative rather than qualitative, with the higher BRIOS melt rates leading to faster retreat along the same paths. Figure 15 shows the volume above flotation trends for the combined anomaly experiments, where, with everything else held equal, the BRIOS simulations exhibit a $10 \times 10^3 \text{ km}^3$ greater loss ($-\Delta V$) by the end of the 22nd century than the FESOM simulations. Around half of this difference is concentrated in the Amundsen Sea Embayment, with the remainder divided between the Filchner–Ronne Ice Shelf region and Marie-Byrd Land.

The difference between RACMO2 and LMDZ4 simulations with a given ocean model and the A1B scenario is as large as the difference between both ocean models across emission scenarios. Although the H/A/R/F and H/A/L/F grounding line retreat is essentially the same, the decrease in volume above flotation over West Antarctica as a whole differs by $10 \times 10^3 \text{ km}^3$, with the majority of that difference accounted for by the larger LMDZ4 accumulation over the drainage basin of the Ross Ice Shelf. The H/A/R/B and H/A/L/B experiments differ in the same way. Variation between the atmosphere models for the E1 scenario is smaller, with all of the E1 models having similar mass loss trends.

The choice of GCM and emission scenario leads to the largest variation between the combined anomaly experiments. Melt rates grow over time in both A1B and E1 scenarios, but accumulation grows much less in the E1 scenario. The four HadCM3 E1 experiments produce a net volume loss between 6 and $10 \times 10^3 \text{ km}^3$ during the

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21st century, and around $20 \times 10^3 \text{ km}^3$ by the end of the 22nd century (assuming that the E1/FESOM experiments follow the same trend from 2150 onward). Of the A1B simulations, only H/A/R/B results in a similar trend, with H/A/R/B and H/A/L/F giving rise to around $10 \times 10^3 \text{ km}^3$ loss by 2200 and H/A/R/B less than $5 \times 10^3 \text{ km}^3$. The ECHAM5 E1 and A1B simulations are generally closer to balance, but do not run beyond 2100 when the majority of HadCM3 imbalance occurs.

Despite the wide variation in accumulation anomalies, we see little interaction between atmosphere model and ice dynamics. Figure 16b shows the loss of volume above flotation due to ice dynamics, ΔV_d . For a given region Ω , ΔV_d is the difference between the net change in volume above flotation and the cumulative, integrated accumulation anomaly:

$$\Delta V_d(t) = \Delta V(t) - \int_{t'=1980}^{t'=t} \int_{\Omega} \Delta a \, d\Omega \, dt'. \quad (33)$$

In each case the difference between curves is dominated by the difference in ocean anomaly. The H/A/R/F and H/A/L/F curves lie close to one another (and to the H/A/O/F curve), each resulting in $\Delta V_d \approx 10 \times 10^3 \text{ km}^3$ (25 mm SLE) across the whole of West Antarctica by 2100 and around $30 \times 10^3 \text{ km}^3$ (75 mm SLE) by 2200. The H/A/R/B and H/A/L/B trends are also close to one another, but lead to rather more excess discharge – around $40 \times 10^3 \text{ km}^3$ (100 mm SLE) by 2200. Overall, the net $\Delta V(t)$ for a simulation with accumulation anomaly $\Delta a(t)$ and melt-rate anomaly $\Delta M(t)$ can be estimated rather precisely from the result, $\Delta V'(t)$, of a simulation with the same ocean anomaly and a different (or no) accumulation anomaly $\Delta a'(t)$:

$$\Delta V(t) \approx \Delta V'(t) + \int_{t'=1980}^{t'=t} \int_{\Omega} [\Delta a - \Delta a'] \, d\Omega \, dt'. \quad (34)$$

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This result is valid for the Amundsen Sea Embayment and the Filchner–Ronne and Ross ice shelf drainage basins, and only breaks down in Marie-Byrd Land, which contributes little to the projections. We account for it by noting that, in these century scale simulations, increased melt rates lead to large amplitude but localized thinning, whereas increased accumulation causes low amplitude but widely distributed thickening.

4 Conclusions

Our most extreme simulation of widespread dynamic thinning in West Antarctica’s fast flowing ice streams results in 200 mm of eustatic sea level rise by 2100 and 475 mm by 2200. Pine Island and Thwaites Glaciers see their grounding lines retreat by hundreds of kilometres, as do the Möller, Institute, Evans, MacAyeal, Bindshadler, Whillans and Mercer ice streams and to a lesser extent Carlson Inlet and the Rutford Ice Stream. All of these ice streams flow along beds that deepen inland, and so can be subject to marine ice sheet instability. Some of the ice streams appear to be on the edge of critical change; for example Pine Island Glacier and the Möller, Institute and Evans ice streams remain close to their present day configurations unless melt rates are increased. Our model of Thwaites Glacier, on the other hand, depends strongly on its initial state: either it remains steady for up to two hundred years after its ice shelf has all but disappeared, or it retreats rapidly, raising sea level by at least 25 mm each century, even if its ice shelf remains in place.

Wholesale retreat occurs only if enhanced melting is imposed across all the ice shelves, and neither the FESOM nor the BRIOS ocean circulation models project substantial warming beneath the Filchner–Ronne or Ross ice shelves until after 2050. Simulations based upon these more realistic projections also result in significant dynamic losses in the Amundsen Sea Embayment: up to 50 mm SLE by 2100 and 150 mm SLE by 2200 provided that Thwaites Glacier retreats. On the other hand, there is little retreat in the Filchner–Ronne or Siple Coast ice streams until after 2100, and only around

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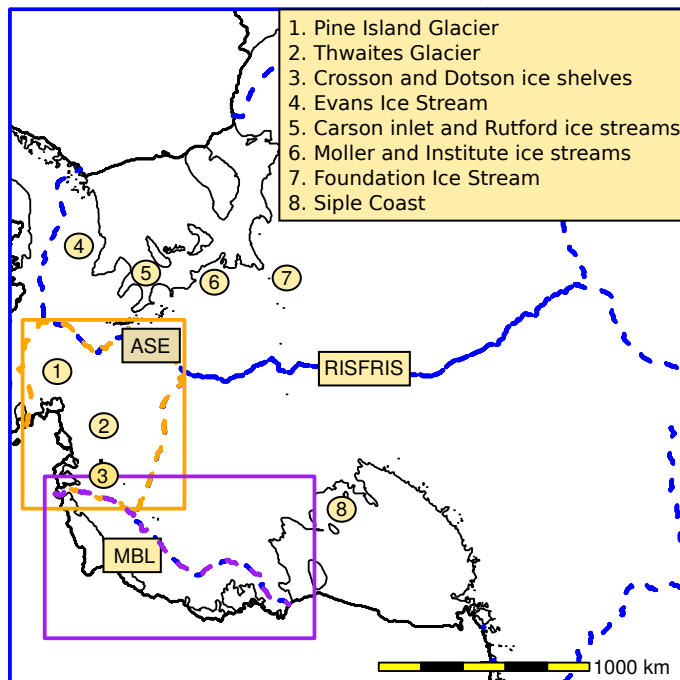


Figure 1. West Antarctica divided into three computational domains. Simulations are carried out in three rectangular model domains: RISFRIS, ASE and MBL. Each of these has an active region Ω_V bounded by the dashed contours and the calving front (black), while the remaining area Ω_Q is made quiescent. Integration of, say, volume above flotation is carried out only over the active regions. Sea level rise results are given separately for the Filchner–Ronne Ice Shelf (FRIS) and Ross Ice Shelf (RIS) regions, but the simulations are carried out on a domain joining both regions together (RISFRIS). The Amundsen Sea Embayment (ASE) and Marie-Byrd Land (MBL) are simulated separately.

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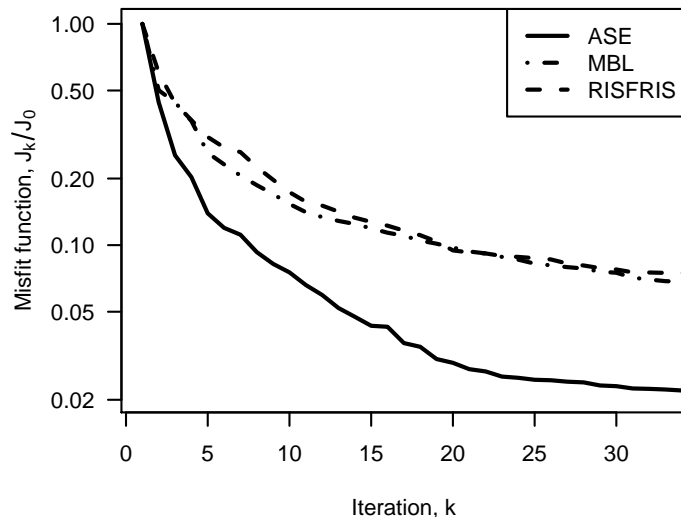


Figure 2. Progress of the nonlinear conjugate gradient method. After around 10 iterations the speed misfit J_m (Eq. 13) is reduced by an order of magnitude in the ASE, MBL and RISFRIS optimization problems.

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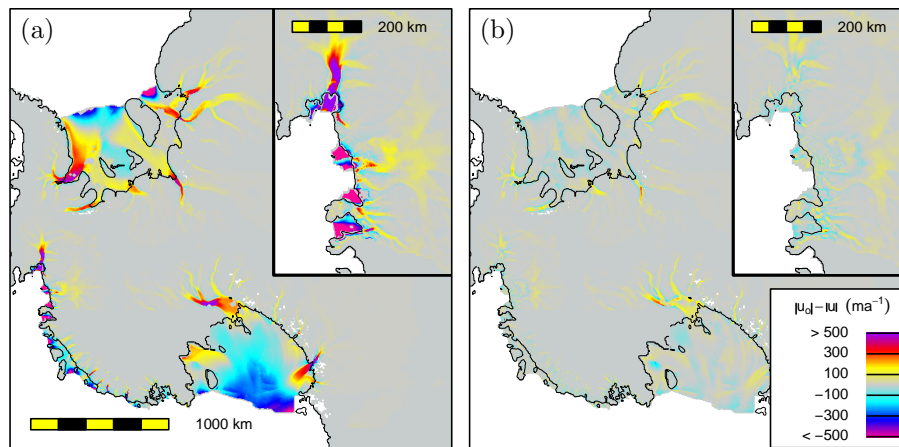


Figure 3. Difference between observed and model speeds. $|u_o| - |u|$ at the start and end of the inverse problem. Data from all three domains is shown, with a magnified inset showing the ASE data in more detail. The initial guess for C and ϕ results in a flow field that is up to 1 km a^{-1} too slow in the fast ice streams. After 24 conjugate gradient iterations, the model and observed speeds rarely differ by more than 100 m a^{-1} .

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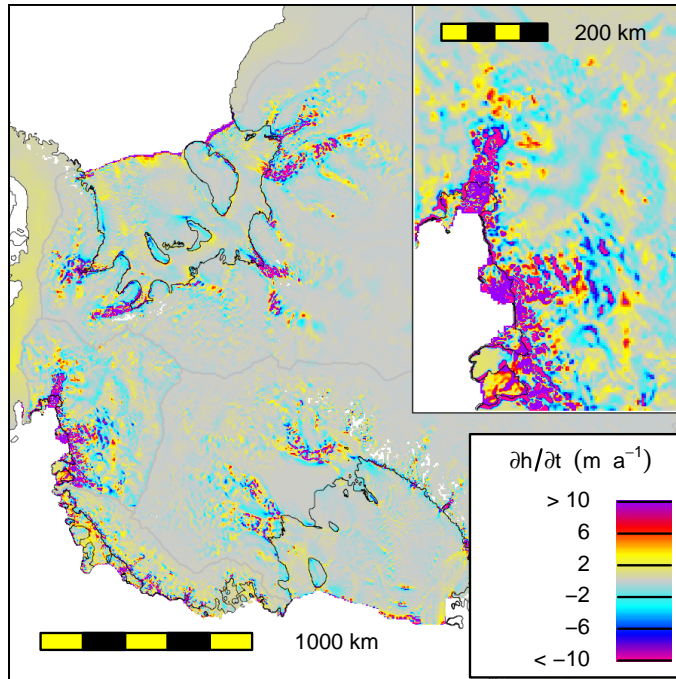


Figure 4. Thickening rates before relaxation. Spatial and temporal mismatch between the observed velocity and thickness data leads to an ice sheet with large amplitude, short wavelength fluctuations in $\nabla \cdot [uh]$ and hence $\frac{\partial h}{\partial t}$. Pine Island Glacier is particularly affected, with thickening rates $\sim 100 \text{ m a}^{-1}$ far in excess of observed values, and having the wrong sign.

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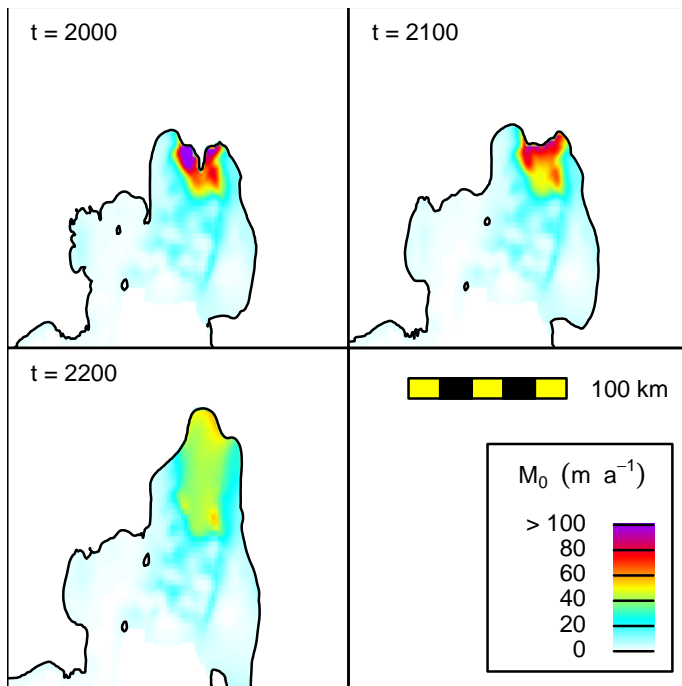


Figure 5. Example evolution of the base melt rate $M_0(x, y, t)$ with Pine Island Glacier's grounding line. Melt rates peak close to the grounding line and decay downstream.

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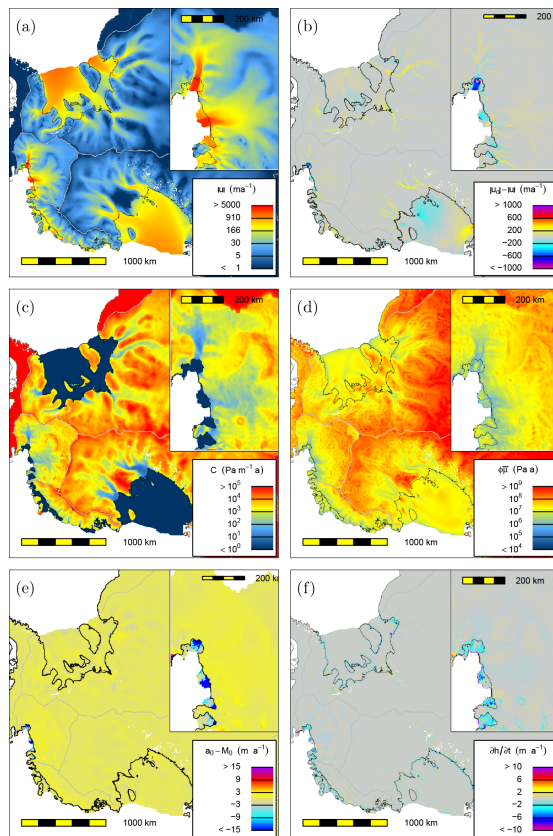


Figure 6. Model initial state. Panels show **(a)** the ice flow speed $|u|$, **(b)** the difference between observed and model speed $|u_0| - |u|$, **(c)** the basal traction coefficient c , **(d)** the vertically averaged effective viscosity $\phi\bar{\mu}$, **(e)** the synthetic mass balance $a_0(x, y) - M_0(x, y, t = 0)$, and **(f)**, the thickening rate $\frac{\partial h}{\partial t}$, all at the start of the prognostic calculations.

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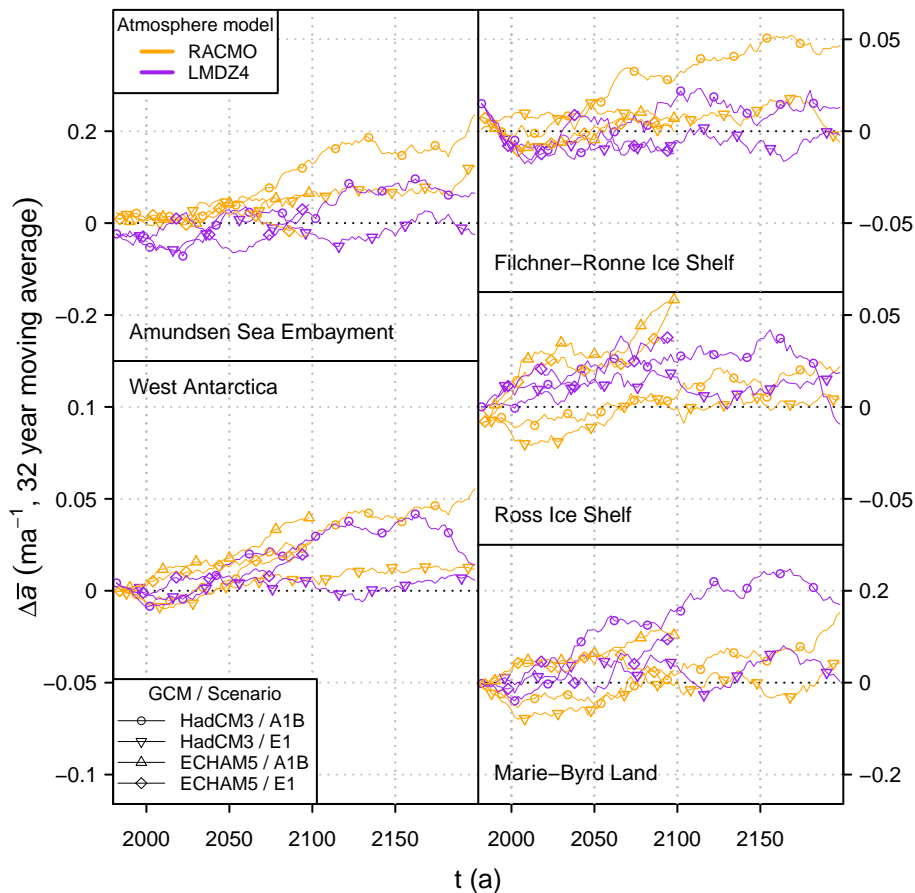


Figure 7. Accumulation anomalies integrated over each region. The atmosphere models provide enhanced accumulation only for the A1B emission scenarios.

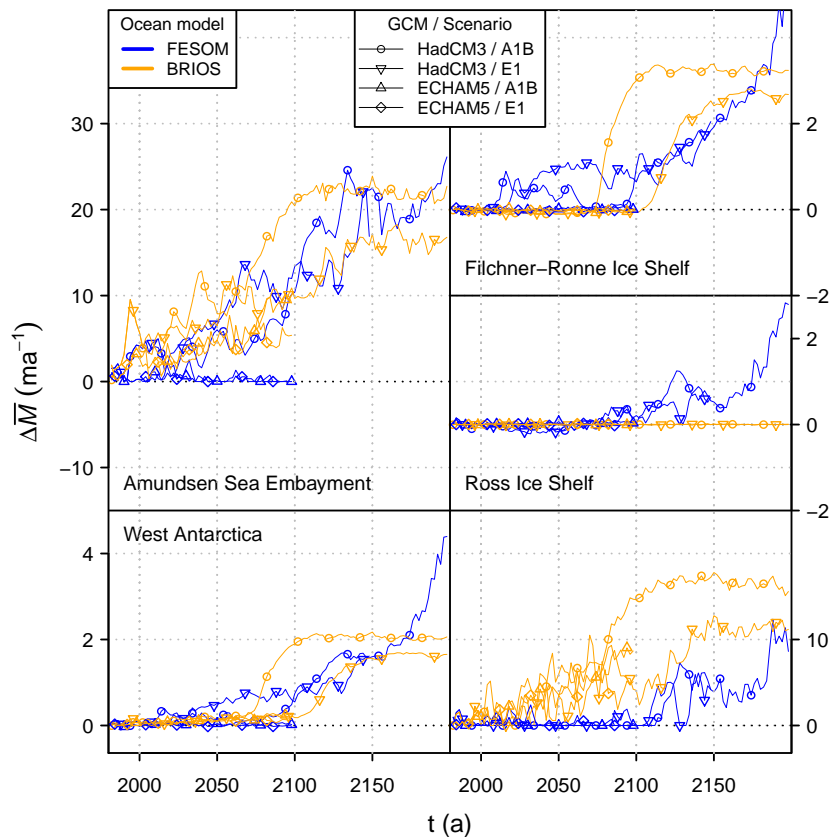


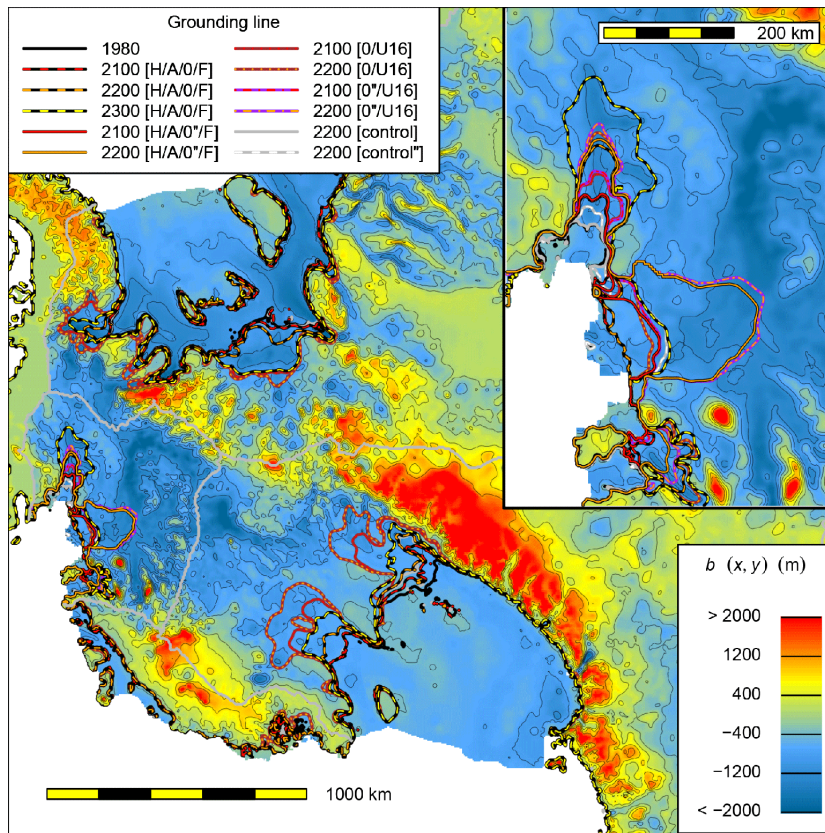
Figure 8. Melt-rate anomalies integrated over each region. In contrast with the atmosphere models, the ocean models provide similarly growing melt rates in both A1B and E1 scenarios. Note that the Amundsen Sea Embayment and Marie-Byrd Land melt-rate anomalies are not given directly by the ocean models, which do not resolve the smaller ice shelves, but are characterised in terms of nearby Circumpolar Deep Water temperatures.

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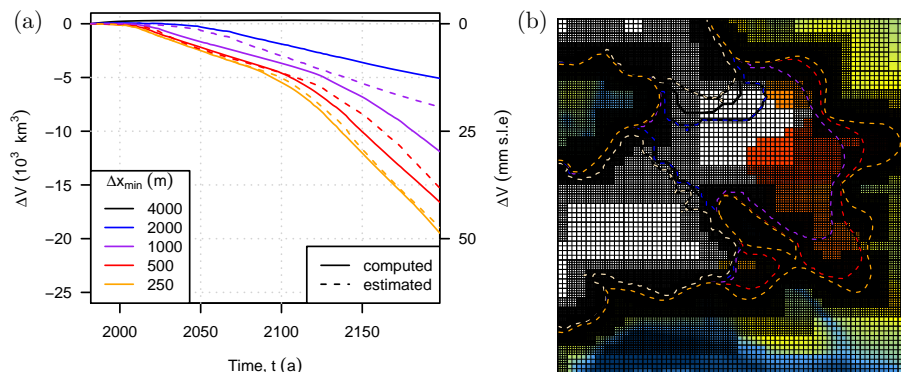


Figure 10. Change in volume above flotation $\Delta V(t)$ vs. mesh resolution **(a)**, and grounding line positions in the Crosson and Dotson ice shelves in 1980 CE and 2200 CE **(b)** for ASE H/A/O/F simulations. The coarsest resolution calculations, with $\Delta x_{\min} = 4000$ m, exhibit little change over the 200 years, while finer resolutions result in progressively greater volume loss. The difference between curves with finest mesh spacing Δx_{\min} and $2\Delta x_{\min}$ decays with Δx_{\min} once $\Delta x_{\min} \leq 2000$ m. The estimated curve $\overline{\Delta V}(\frac{1}{2}\Delta x_{\min}, t) = \frac{3}{2}\Delta V(\Delta x_{\min}, t) - \frac{1}{2}\Delta V(2\Delta x_{\min}, t)$ is close to the computed curve $\Delta V(\Delta x_{\min}, t)$ when $\Delta x_{\min} = 500$ m. Grounding line retreat takes place in the Crosson and Dotson ice shelves (and in Pine Island and Thwaites Glaciers) only when $\Delta x_{\min} \leq 1000$ m.

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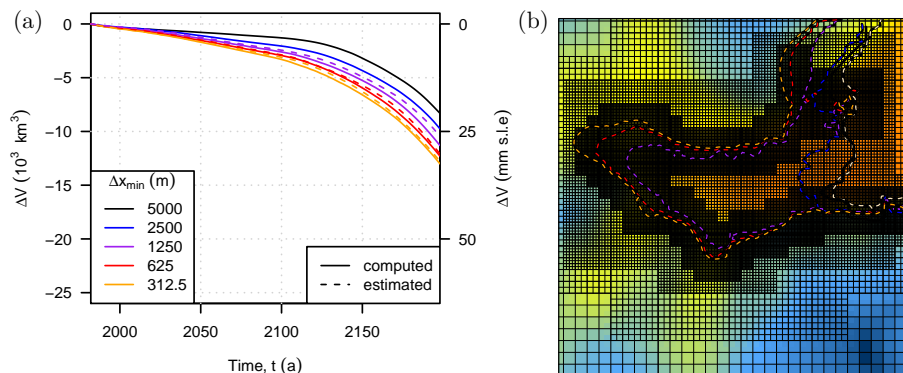


Figure 11. Volume above flotation vs. mesh resolution for RISFRIS H/A/O/F simulations (a) and grounding line positions in 1980 and 2000 CE around Evans Ice Stream. In contrast to the ASE simulations (Fig. 10), even the coarsest resolution calculations show volume loss. Nonetheless, finer resolutions result in greater volume loss, with the difference between curves with finest mesh spacing Δx_{\min} and $2\Delta x_{\min}$ shrinking with Δx_{\min} once $\Delta x_{\min} \leq 2500$ m. Evans Ice Stream, like the ASE glaciers, shows grounding line retreat only for finer resolutions ($\Delta x_{\min} \leq 1250$ m) although other regions (e.g. the Institute and Möller ice streams) show comparable retreat at coarse and fine resolutions.

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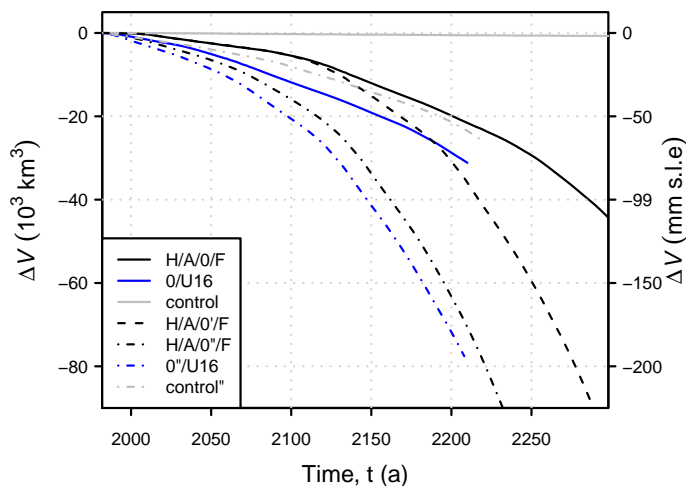


Figure 12. Change in volume above flotation ($\Delta V(t)$) in the Amundsen Sea Embayment during the melt-rate anomaly experiments. The ASE discharges an excess volume between 5×10^3 and $20 \times 10^3 \text{ km}^3$ by 2100, and between 20×10^3 and $60 \times 10^3 \text{ km}^3$ by 2200. The difference is dominated by the onset of retreat in Thwaites Glacier and Pine Island Glacier. Pine Island Glacier begins its retreat around 2000 in all simulations, apart from the control and control'' experiment, as do the glaciers feeding Dotson Ice Shelf and Crosson Ice Shelf. Thwaites Glacier, on the other hand, begins to retreat immediately in the H/A/O''/F, control'' and O''/U16 experiments, in around 2100 in the H/A/O'/F and O'/U16, and after 2200 in the H/A/O'/F and O'/U16 experiments.

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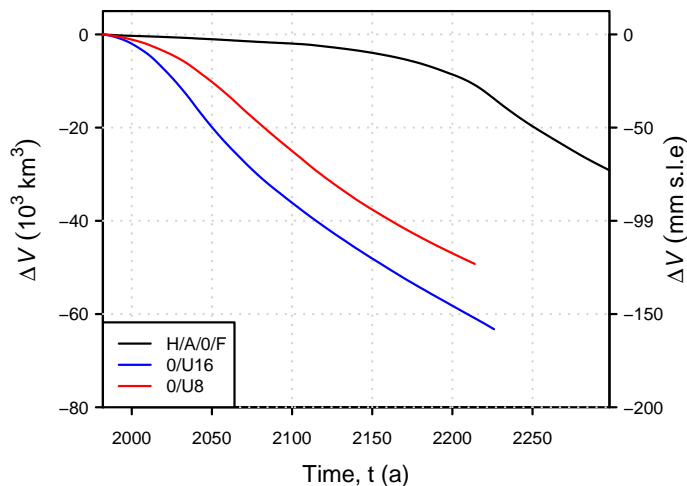


Figure 13. Change in volume above flotation ($\Delta V(t)$) in the Filchner–Ronne Ice Shelf during the melt-rate anomaly experiments. The FESOM-forced simulations (H/A/0/F) lose little volume before 2100, in contrast to the uniform melt rate calculations 0/U8 and 0/U16. All three simulations feature a period where volume is lost at a rate of more than $200 \text{ km}^3 \text{ a}^{-1}$ – starting immediately for the uniform melt rate experiments but delayed till 2200 for H/A/0/F – which corresponds to the retreat of the Möller and Institute Ice Streams across the Robin Sub-glacial Basin and the flotation of Bungenstock ice rise.

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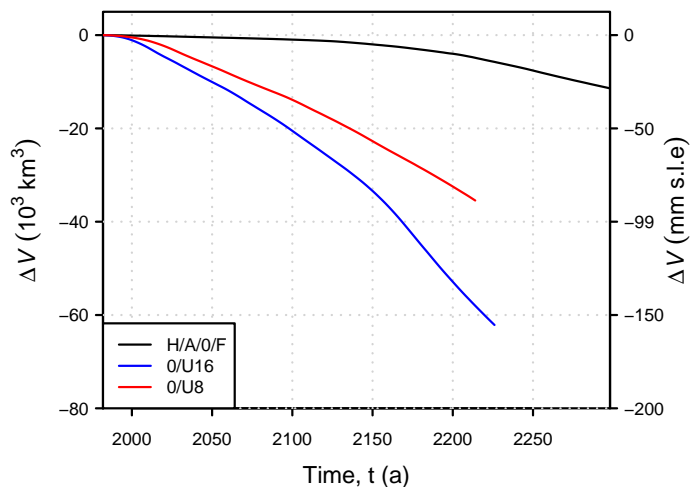


Figure 14. Change in volume above flotation ($\Delta V(t)$) in the Ross Ice Shelf region during the melt-rate anomaly experiments. The FESOM-forced simulations (H/A/0/F) lose little volume before 2100, in contrast to the uniform melt-rate calculations 0/U8 and 0/U16. Once melt rates are elevated, however, the Siple Coast ice streams see their retreat accelerate throughout the simulations.

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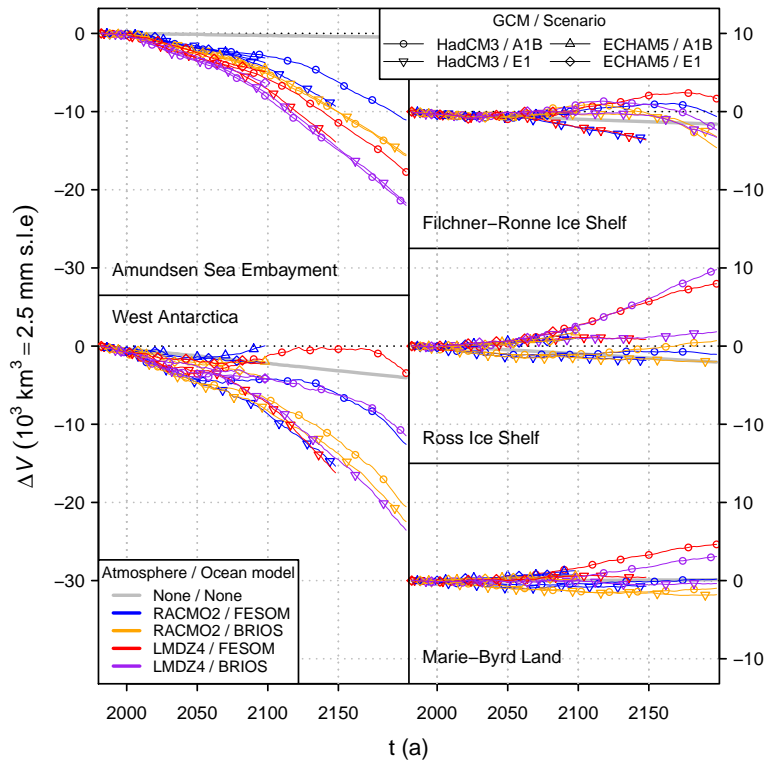


Figure 15. Net change in volume above flotation over the course of the combined anomaly experiments. Only the Amundsen Sea Embayment experiences a net loss (ΔV) in all of the combined experiments. Nonetheless, the result is a net loss over West Antarctica as a whole. Note that Thwaites glacier does not retreat in the combined anomaly experiments (which use the synthetic accumulation), and the ASE could contribute an extra $9 \times 10^3 \text{ km}^3$ loss by 2100 and $40 \times 10^3 \text{ km}^3$ by 2200.

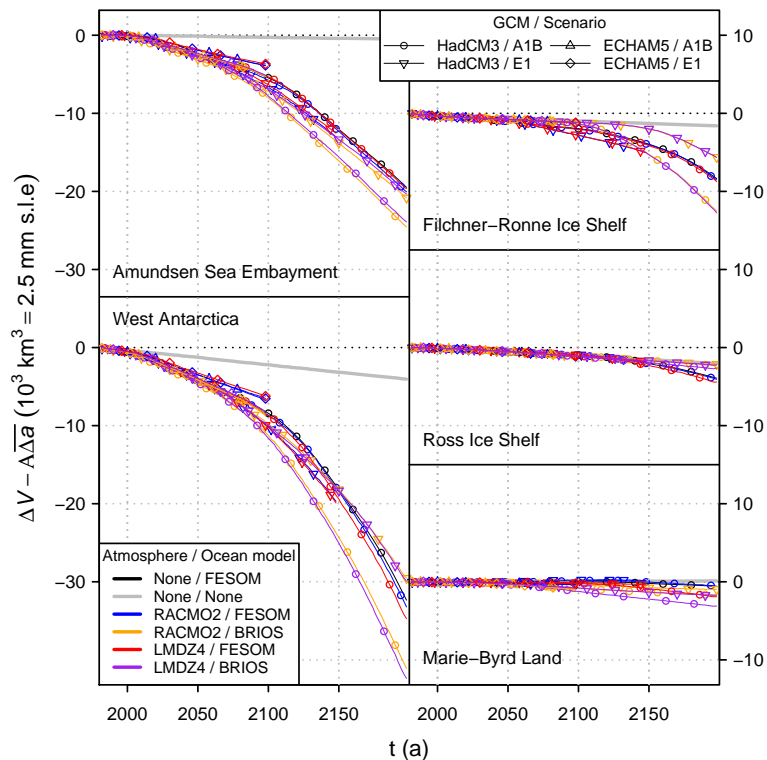


Figure 16. Dynamic change in volume above flotation over the course of the combined anomaly experiments. Dynamic losses (computed by subtracting the accumulation anomaly from the net loss) occur in all regions, and are nearly independent of the accumulation anomalies, so that the net change in (for example) the H/A/R/F simulation is much the same as the sum of the volume change computed for the ocean-forced H/A/O/F simulation and the HadCM3/A1B/RACMO2 accumulation anomaly. Note that Thwaites glacier does not retreat in the combined anomaly experiments (which use the synthetic accumulation), and the ASE could contribute an extra $9 \times 10^3 \text{ km}^3$ loss by 2100 and $40 \times 10^3 \text{ km}^3$ by 2200.

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