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caverns

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A data-constrained model for compatibility check of remotely sensed basal melting with the hydrography in front of Antarctic ice shelves

D. Olbers¹, H. H. Hellmer¹, and F. F. J. H. Buck²

¹Alfred Wegener Institute Helmholtz Centre for Polar and Marine Research, Bussestr. 24, 27570 Bremerhaven, Germany

²Leibniz-Institute for Baltic Sea Research, 18119 Rostock-Warnemünde, Germany

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Correspondence to: D. Olbers (dirk.olbers@awi.de)

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Abstract

The ice shelf caverns around Antarctica are sources of cold and fresh water which contributes to the formation of Antarctic bottom water and thus to the ventilation of the deep basins of the World Ocean. While a realistic simulation of the cavern circulation requires high resolution, because of the complicated bottom topography and ice shelf morphology, the physics of melting and freezing at the ice shelf base is relatively simple. We have developed an analytically solvable box model of the cavern thermohaline state, using the formulation of melting and freezing as in Olbers and Hellmer (2010). There is high resolution along the cavern's path of the overturning circulation whereas the cross-path resolution is fairly coarse. The circulation in the cavern is prescribed and used as a tuning parameter to constrain the solution by attempting to match observed ranges for outflow temperature and salinity at the ice shelf front as well as of the mean basal melt rate. The method, tested for six Antarctic ice shelves, can be used for a quick estimate of melt/freeze rates and the overturning rate in particular caverns, given the temperature and salinity of the inflow and the above mentioned constrains for outflow and melting. In turn, the model can also be used for testing the compatibility of remotely sensed basal mass loss with observed cavern inflow characteristics.

1 Introduction

The physical processes inside ice shelf caverns are still mostly unobservable. As satellite and airborne observations became available, better estimates of the mass budget of the ice lid were possible (Rignot, 1998; Corr et al., 2001; Shepherd et al., 2004; Rignot et al., 2013). Autonomous vehicles have been developed for entering a cavern and measure bathymetric, hydrographic, chemical and turbulence parameters, but the range of such vehicles is very limited and only few expeditions took place so far (Nicholls et al., 2006; Jenkins et al., 2010). Numerical models of various complexity have been developed (Hellmer and Olbers, 1989; Jenkins, 1991; Holland and Jenkins,

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that case all solutions fail to pass through the constrained region in the data space and the data, coming from diverse sources such as hydrography and remote sensing, must be judged as incompatible.

In Sect. 2 the governing equations are derived and solved. In Sect. 3 the model setup is described and the method of data constraints is explained simulating the Amery Ice Shelf (AMY) cavern, followed by the application of the model to five more caverns, namely Pine Island Ice Shelf (PIIS), Ross (ROS), Fimbulisen (FIM), Ronne (RON), and Larsen C (LAR) ice shelves (Sect. 4). The paper ends with concluding remarks and an Appendix configuring the procedure for setting up the box model geometry.

2 Governing equations and solution

The model represents in a crude manner the circulation in oceanic caverns beneath ice shelves and aims at to provide an efficient calculation of melting and/or freezing rates from inflow conditions. The governing equations are formulated similar to the approach of Olbers and Hellmer (2010), but simplified with respect to the dynamics of the overturning rate and pattern (which are now specified parameters) and extended to a multitude of boxes under the ice draft (see Fig. 1). In contrast to Olbers and Hellmer (2010), the attempt to model the water characteristics in front of the ice cavern is abandoned. The model is thus restricted to the immediate cavern domain and includes an arbitrarily large number of boxes beneath the ice draft and a single bottom box (labeled with index d) between the bottom and the layer of sub-ice boxes. The equations for temperature and salinity are formulated as balance between (horizontal and vertical) advection, (vertical) diffusion and heat and freshwater exchange with the ice shelf by melting/freezing.

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We regard a particular sub-ice box with volume V and contact area A to the ice. The heat and salt balances are written as:

$$V \frac{dT}{dt} = (u - w)T_0 + wT_d - uT - Ak(T - T_d) + A(\gamma_T + m)(T_f - T)$$

$$V \frac{dS}{dt} = (u - w)S_0 + wS_d - uS - Ak(S - S_d) + A(\gamma_S + m)(S_f - S) \quad (1)$$

Here m is the local melt rate (negative for freezing), and $\gamma_{T,S}$ are the turbulent exchange coefficients for the layer next to the ice shelf base. Furthermore, u is the horizontal advective volume flux [$\text{m}^3 \text{s}^{-1}$], positive out of the box and towards the ice shelf front, and $\kappa = K_v/h$ derives from vertical diffusion with a diffusivity K_v and a vertical scale h . The temperature T_0 and salinity S_0 are prescribed as inflow values from the preceding box in the system while T_d and S_d are the values in the bottom box. The model considers upwelling into the sub-ice box by incorporating a flux w [$\text{m}^3 \text{s}^{-1}$], directed from the deep box into the respective sub-ice box. Conservation of mass has been considered, i.e., $u - w$ enters from the upstream sub-ice box, w from the deep box, and u leaves to the downstream sub-ice box. Note that Eqs. (1) are valid only for $u > 0$ and $w > 0$.

The effect of the mixing terms is only marginal: deviations from the zero-mixing approach only occur for low transport values $q \sim Ak$, which are typically $10^3 \text{ m}^3 \text{ s}^{-1}$. In view of other model deficiencies and the uncertainty in the prescribed values at the ice front we thus abandon the diffusive term in the present study. Without diffusion T_d and S_d are fixed and equal to the respective inflow values at the ice shelf front. The linearized freezing temperature:

$$T_f = aS_f + b - cp \quad (2)$$

determines the freezing point of seawater for the box with pressure p , representative for the ice draft, and the constants $a = -0.057^\circ\text{C pss}^{-1}$, $b = 0.0832^\circ\text{C}$, and $c = 7.64 \times 10^{-4}^\circ\text{C dbar}^{-1}$. The placement of the pressure point to calculate the freezing temperature Eq. (2) is a critical issue if the resolution is low. It is obvious that the

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deeper the location in the respective box the higher the resulting local melt rate. In all applications of this study we have chosen the deepest point of the ice draft in the respective box for providing the pressure p (for the resolution with 50 boxes, used in this study, the location of p is irrelevant). The salinity S_f is calculated from the “three-equations model” (Hellmer and Olbers, 1989; Olbers and Hellmer, 2010), resulting in a quadratic equation for S_f , the salinity of the melting/freezing layer at the ice shelf base:

$$(T_f - T)S_f - \delta(S_f - S) = 0 \quad (3)$$

with $\delta = \lambda\gamma_S/\gamma_T$, $\lambda = L/c_p = 84$ K (here L is the latent heat of fusion and c_p the specific heat of seawater). The pressure p is set as being representative for each box (see below). The solution is given by:

$$S_f = F(T, S) = \frac{1}{2a}(T - b + cp + d) + \sqrt{\frac{1}{4a^2}(T - b + cp + d)^2 - \frac{d}{a}S} \quad (4)$$

with $d = \lambda\gamma_S/\gamma_T$. The local melt rate is determined as:

$$m = \gamma_T(T - T_f)/(\nu\lambda) \quad (5)$$

where $\nu = \rho_{\text{ice}}/\rho_{\text{water}} = 0.89$. In the following applications the values for $\gamma_T = 3 \times 10^{-5} \text{ ms}^{-1}$ and $\gamma_S = 1.2 \times 10^{-6} \text{ ms}^{-1}$ are fixed.

The m term in Eqs. (1) accounts for the change of volume when melting or freezing occurs (Jenkins et al., 2001). It appears a bit anachronistic if this term is retained while other mass fluxes related to the ice dynamics are absent, which are important for the volume budget. We will abandon the m term in the present study not only for this reason but also because generally $\gamma_T \gg \gamma_S \gg m$ applies. With respect to the ensemble of caverns investigated here, this assumption is questionable only for PIIS where melt rates of the order of 40 myr^{-1} (Jacobs et al., 2011) are expected and m thus has a similar size as γ_S .

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We now search for an analytical solution for the steady state of the system Eqs. (1)–(5) for any of the sub-ice boxes, neglecting the m correction and considering the equations with $\kappa = 0$. With the abbreviations $u_T = \gamma_T A$, $u_S = \gamma_S A$, we obtain the two equations:

$$\begin{aligned} (u + u_T) T &= (u - w) T_0 + w T_d + u_T (a F(T, S) + b - cp) \\ (u + u_S) S &= (u - w) S_0 + w S_d + u_S F(T, S) \end{aligned} \quad (6)$$

for temperature T and salinity S in the box. Mathematically, we find a quadratic equation for either T or S , which is readily solved. However, only one solution conforms with the positive root in S_i , as given by Eq. (4).

Knowing the solution for the outflow as function of the inflow for a single sub-ice box we may iterate it for an ensemble of subsequent boxes. The inflow values of temperature and salinity are then the outflow values of the upstream box. Counting the sub-ice boxes by $j = 1, \dots, n$, starting at the grounding line, the outward flux u_j of box j is given by $u_j = \sum_{i=1}^j w_i$. The upwelling w_i pattern, which will be prescribed and used as a tuning parameter, might change from box to box. The total overturning strength is $q = u_n = \sum_{i=1}^n w_i$. The complete model is thus a stack of modules with the above described thermodynamics, with the inflow values of temperature and salinity into the bottom box at the grounding line and outflow T_n, S_n at the front. The latter are then determined as function of the upwelling pattern w_i , the inflow characteristics, and the other fixed parameters.

An important issue of modeling ocean-ice shelf interaction is the resolution of the cavern geometry. A two-box configuration along the ice shelf base, as used in Olbers and Hellmer (2010), is certainly too coarse to resolve the melting close to the grounding line. The resolution of the present model can be increased at no expense as only additional modules of the above described dynamics have to be placed in the stack. Figure 2 compares the results for different resolutions of the AMY cavern by means of

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the mean basal melt rate:

$$\bar{m} = \frac{\sum_{i=1}^n m_i A_i}{\sum_{i=1}^n A_i} \quad (7)$$

shown as function of the total overturning rate q for a specific upwelling pattern (the “fast decrease” scenario, see Sect. 3). The conversion at about 50 sub-ice boxes becomes obvious. We emphasize that the distribution of melting and its rate in boxes close to the grounding line strongly depend on the number of boxes resolving the sub-ice cavern. This difference is mainly due to the above mentioned pressure effect. In all applications of the present study we keep the number of sub-ice boxes fixed to 50, corresponding to the blue line in Fig. 2.

3 Model setup and evaluation – Amery Ice Shelf

We first evaluate the impact of three scenarios of upwelling into the sub-ice boxes underneath AMY on melt rate and sub-ice temperature and salinity, representing different views on the interaction of the inflowing water with the ice shelf base. The upwelling w is either distributed uniformly along the ice shelf’s center line or concentrated near the grounding line with either slow or fast decrease towards the cavern interior (Fig. 3 – left column). Such distribution directly controls the sub-ice overturning circulation reaching its maximum at the ice shelf front either linearly or exponentially (Fig. 3 – right column).

The averaged melt rate at the base of AMY as a function of the maximum overturning (red lines in Fig. 3 – right column) changes with the prescribed upwelling distribution. While the difference is small for the “uniform” and “slow-decrease” cases, mean melting is strongest when most of the upwelling occurs near the grounding line (Fig. 4). The latter demonstrates the importance of pressure, i.e. depth of the ice shelf base, on the in-situ freezing point and thus on the amount of potential heat for melting. The average melt rate is largest when most of the heat is delivered to – and used at – a deep ice shelf base.

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The corresponding T/S diagrams (Fig. 5) show two significant differences for the properties of the sub-ice boxes, namely (1) a warmer temperature minimum for upwelling concentrated near the grounding line and small overturning rates together with (2) a smaller spread of the T/S lines. The latter becomes smaller as the bulk of upwelling moves towards the grounding zone. All lines start at the inflow values (upper right corner) following the “Gade line” (Gade, 1979), which represents the dilution relation for ice melting/forming in sea water, towards the salinity minimum and related in-situ freezing temperature. The latter increases as the water reaches the freezing point at lower pressure, i.e. shallower ice shelf base. Beyond this point freezing occurs, adding salt and heat to the sub-ice boxes. Deviations from the straight line are due to the upwelling, which extends to the ice shelf front in the “uniform” case and prevents the formation of ice in the sub-ice boxes (Fig. 6 – upper left panel). With no upwelling along most of the ice shelf base and strong overturning the T/S characteristics follow the “Gade-line” (Fig. 5 – right panel).

The impact of different upwelling distributions on the melt/freeze pattern and related temperature and salinity in the sub-AMY boxes as well as at the ocean/AMY interface is shown in Fig. 6. As mentioned above, uniform upwelling along the ice shelf cuts off ice formation for low overturning rates, preventing the T/S characteristics from following the “Gade line”. In contrast, intense upwelling in the grounding zone slightly reduces the fast decrease of melting but causes an earlier and a more pronounced shift into the freezing zone. Especially for low overturning rates part of the basal mass loss is compensated by the basal accretion of ice. Temperatures and salinities in the sub-ice boxes almost follow the same pattern with a fast reduction over the grounding zone followed by a moderate increase towards the ice shelf front. The reduction becomes less as the overturning rate increases, extending all the way to the ice shelf front for the “fast decrease” upwelling scenario (Fig. 6 – lower row). Non-uniform upwelling causes a crossing of the T/S lines near the ice shelf front, indicating either intense freshening of the sub-ice boxes due to longer lasting melting for high overturning or intense salt rejection due to longer lasting freezing for low overturning.

In summary, the pattern of upwelling into the sub-ice boxes has a significant impact on the basal mass flux and thus on the ice thickness distribution with consequences for the ice shelf dynamics, e.g. Determann (1991).

4 Data-constrained application

In the following, we use the 50-box version for five other caverns located around Antarctica: Pine Island Ice Shelf (PIIS), Ross (ROS), Fimbulisen (FIM), Ronne (RON), and Larsen C (LAR) ice shelves. As for AMY, the inflow temperature and salinity, T_d and S_d , are chosen from hydrographic observations at the respective cavern front. To compare the model output with observations we concentrate on the measured hydrographic outflow characteristics, T_n and S_n , and the mean basal melt rate \bar{m} . The most likely values of T_n , S_n and \bar{m} , including reasonable uncertainties (as minima and maxima), are listed in Table 1, obtained from observations as referenced. Though the minima-maxima constraints are certainly a bit arbitrary (Table 2), the entirety of constraints should represent the feasibility space reasonably well.

The model is evaluated for a certain range of transport values q in a specified upwelling scenario and fixed values for the other parameters (Table 1). From a mathematical point of view, we are looking at the trajectory $T_n(q), S_n(q)$, and $\bar{m}(q)$ in the three-dimensional space with coordinates T_n, S_n and \bar{m} . A rough measure of consistency of the model and the data with their uncertainties is found when the trajectory enters the constraining box defined by $T_n \pm \Delta T_n, S_n \pm \Delta S_n, \bar{m} \pm \Delta \bar{m}$ derived from the constraints of minimum and maximum values. The values q_{\min} of entrance of the trajectory into and q_{\max} of exit of the trajectory out of the constraining box defines the feasibility range $q_{\min} < q < q_{\max}$ where the model has solutions consistent with all constraints. If non-empty, the feasibility range is plotted as black line segment in the following figures.

We continue with AMY to illustrate the data constraint method, though AMY turns out to be an extreme case. Within the given thresholds only the “fast decrease” scenario (blue line) is able to meet all constraints (Fig. 7) for the interval $q_{\min} = 0.08 \text{ Sv} <$

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$q < q_{\max} = 0.09 \text{ Sv}$ ($1 \text{ Sv} = 1 \times 10^{-6} \text{ m}^3 \text{ s}^{-1}$; Table 2). Note that only a few hundredth of a degree warmer outflow temperature (right panel) would eliminate all consistent solutions. The constraint on salinity is not effective for the “fast decrease” case.

The effectiveness of the different constraints on the solution and feasibility domain for the remaining suite of caverns is demonstrated in Figs. 8 to 12. Certainly due to its width and probably two quasi independent sub-ice circulation regimes (Hellmer and Jacobs, 1995; Assmann et al., 2003), the hydrographic constraints for ROS are very wide leaving the remote sensed melt rate as the only sensible constraint (Fig. 8). On the other hand, our study shows that the melt rate is compatible with the hydrographic conditions along the ROS front for all upwelling scenarios and for the interval $q_{\min} = 0.28 \text{ Sv} < q < q_{\max} = 1.24 \text{ Sv}$ (Table 2). FIM, also an ice shelf with characteristics of inflow and outflow difficult to define, is bounded at both ends by the melt rate and, in addition, at the upper end by salinity (Fig. 9). If we assume the FIM melt rate to be the most trustable constraint, the temperature and salinity range of the outflow might be narrower than inferred from existing observations. In turn, the uncertainty of melting might be larger than the remotely sensed data is adding up to. The range of solutions for RON (Fig. 10), the other large ice shelf of our study, shows similarities with both ROS (temperature vs. salinity) and AMY (melt rate vs. temperature). Since connected to the Filchner Ice Shelf cavern at its southeastern corner (Nicholls et al., 2001), the used outflow temperature (Table 1) might cover only part of the water masses modified at the base of RON. A slightly colder outflow would allow all upwelling scenarios to contribute to the solution (Table 2); the constraint on salinity is not effective for all cases. Nevertheless, based on our results and the constraints used, upwelling underneath RON seems to be more uniform along the base (melt rate vs. temperature) while more concentrated near the grounding line for AMY (temperature vs. salinity). An interesting feature of the dependence of T_n , S_n , and \bar{m} on q is that some caverns show a distinct minimum for a non-zero q (not shown). This leads to two separated feasibility intervals as evident in the solution for LAR (Fig. 11). The latter is the only ice shelf which has a minimum overturning, and thus minimum melt rate, equal zero (Table 2).

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The results for PIIS are an excellent example for illustrating the scope of application of this study. While the hydrographic conditions in front of the ice shelf are quite well known, e.g. Jacobs et al. (2011), the mean basal melting changes significantly depending on the method/analysis applied (Jacobs et al., 1996; Hellmer et al., 1998; Shepherd et al., 2004; Payne et al., 2007; Nakayama et al., 2013). The melt rate vs. salinity diagram (Fig. 12 – left) indicates that some fresher outflow (at the southern coast) might have been missed by the observations, but the melt rate vs. temperature diagram (Fig. 12 – right) convincingly shows that the mean melt rate (plus some uncertainty) used from Rignot et al. (2013) is not compatible with the observations, independent of the upwelling scenario prescribed. Since we actually consider a 3-dimensional space for the solution, the missing pass through the melt rate/temperature plane is sufficient to result in no solutions for PIIS (Table 2). In turn, a slightly higher melting, still within the published range, would allow for all scenarios to contribute to the solution. It is interesting to note, that similar to AMY and RON the “uniform” case provides solutions which are closest to the range constrained by the observations.

We are aware that other uncertain model parameters exist than those taken into account so far. Of most interest are the inflow characteristics T_d and S_d , which are not well constrained and may vary considerably. If more data for more variables becomes available, on melting near the grounding line and/or the ice front, the box constraints must be applied in a space of higher dimension than three. However, this route is beyond the scope of the present study.

5 Conclusions

We developed a simple numerical tool which allows for estimating the overturning rate (strength of advection within the cavern), the pattern of local basal melting, and the temperature and salinity in Antarctic ice shelf caverns. The tool combines an analytical solution of the advective/diffusive balances of heat and salt with hydrographic data of the outflow and the total melt rate. The solution is constrained by finding feasible

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ranges for the strength of advection. The method is similar to the conventional linear programming, except that the model used here is non-linear because of the non-linear melting/freezing physics at the ice shelf base. The spatial resolution along the assumed path of water through the cavern can be arbitrarily high, however, across the cavern a simple box-type pattern is used, adjusted to the local width. Given the temperature and salinity of the deep flow into the cavern and reasonable limits for the outflow temperature and salinity and on the total melting/freezing rate, a range of feasible values for the overturning rate is determined. The along-cavern dependence of temperature, salinity, and basal melt/freeze rate follows from the analytical solution.

The box model has been applied to six Antarctic sub-ice caverns. The constraining data comes from diverse observations and high-resolution numerical models. The results reveal that some caverns have reasonably constrained solutions while others are only insufficiently constrained or have almost conflicting constraints. For the first ensemble of our suite of caverns, namely Amery (AMY), Ross (ROS), and Pine Island (PIIS) ice shelves, we thus find a narrow range of consistency between the established characteristics of inflow, outflow, and total basal melt rate. The observational data for the second ensemble, namely Fimbulisen (FIM) and Larsen (LAR), yields a quite broad range of feasible solutions, i.e., further observations are necessary to reduce the range of the prescribed characteristics. Ronne (RON), on the other hand, is at the brink of having no feasible solution. This might be due to the complex interaction of the RON cavern with the neighboring Filchner cavern around the southern tip of Berkner Island (Nicholls et al., 2001) which does not allow for a clear characterization of the inflow and, in particular, outflow conditions. The limitations of the model might be responsible for some of the insufficiencies, first to mention the coarse resolution across the cavern and the absence of any horizontal circulation. However, our method, applied to six Antarctic ice shelves, seems suitable for testing the compatibility of remotely sensed mass loss at the base of an ice shelf with the observed hydrography in front of it.

Appendix A

Generating the box geometry

We briefly describe how the geometry of the caverns is simplified to yield the structure of the box model. We use realistic data of the ice shelf draft and bathymetry to provide reliable areal estimates of the interface between ocean and ice. The geometry of all caverns is taken from a consistent data set (Timmermann et al., 2010) and extracted with a script provided by R. Timmermann. Figure 13 shows the conditions for the AMY cavern. To define a characteristic two-dimensional data set, a starting point and an end point is defined. Only data taken from a small area around the connecting line (CL) between the two points is used. To obtain data without artifacts near the grounding line, all points with difference between the draft and the bathymetry below a certain tolerance threshold are discarded. For instance, the limiting points of CL taken for AMY are 73.267° E, 67.017° S and 68.633° E, 72.55° S, the width of the area was 0.02° in latitude for each point of longitude along CL, and the tolerance threshold was 280 m. If there are obstacles found along a particular CL, the line is divided into multiples between additional coordinate points, which are defined to circumvent those obstacles. The length of the ice shelf is determined by computing the distance between the first coordinate of the available data and following coordinates until the last coordinate at the ice shelf front.

The bathymetry and draft data, obtained this way, are represented by a multi-degree polynomial fit. The pressure along CL of each cavern is computed from these polynomial functions (lower panel of Fig. 13). The length of each box is chosen in an equidistant way according to the specified total number of boxes beneath the ice shelf. The width of each box is calculated from a cross section perpendicular to the connecting line.

Each box has two limiting pressure points p_{left} and p_{right} along CL, and the pressure p , entering the freezing point equation Eq. (2) for the respective box, is calculated

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from $p = p_{\text{left}}$. The heights of the respective upper boxes are set by $(h_{\text{bathy}} - h_{\text{draft}})/3$. Other choices are straightforward. The box configuration shown in Fig. 1 represents the conditions for AMY with a total of 50 sub-ice boxes.

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Table 1. Temperature T_d [°C] and salinity S_d of the cavern inflows and the constraints (appropriate minima and maxima) on the mean basal melt rate [m a^{-1}] and temperature [°C] and salinity in the front box, according to observations from sections along the ice shelf front and other data taken from the literature. Melt rate data from Rignot et al. (2013). Hydrography: AMY (Wong et al., 1998), PIIS (Hellmer et al., 1998), ROS (Jacobs and Giulivi, 1998), FIM (Nicholls et al., 2006), RON (Nicholls et al., 2003), LAR (Nicholls et al., 2004).

Cavern	T_d	S_d	\bar{m}_{\min}	\bar{m}_{\max}	min T_n	max T_n	min S_n	max S_n
AMY	-1.85	34.53	0.2	1.0	-2.1	-2	34.45	34.5
ROS	-1.7	34.65	0.1	0.5	-2.1	-1.95	34.4	34.65
FIM	-1.87	34.35	0.4	0.8	-2.1	-1.9	34.23	34.32
RON	-1.95	34.7	0.2	0.4	-2.1	-2	34.6	34.75
LAR	-1.7	34.61	0.0	1.4	-2.04	-1.9	34.45	34.59
PIIS	1.05	34.67	15.2	17.2	-0.4	0	34.1	34.4

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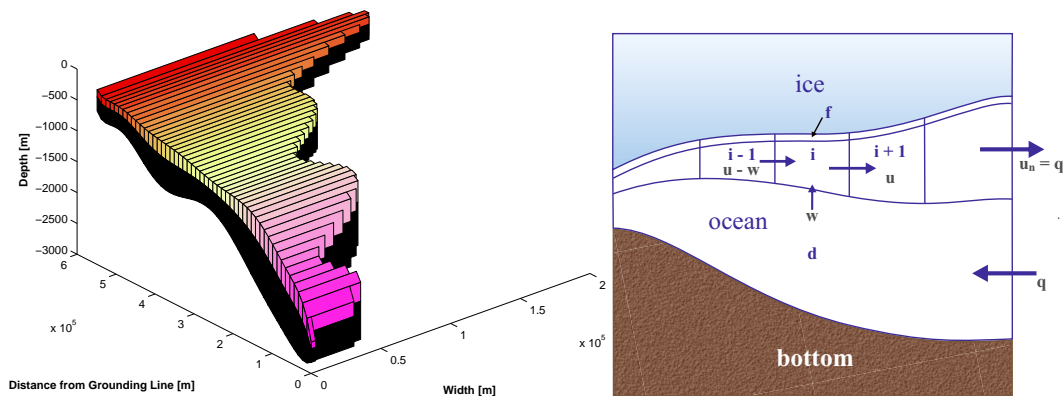


Fig. 1. (a) Model geometry of the Amery Ice Shelf (AMY) cavern with 50 boxes following the ice draft. The height of the upper boxes is set by $(h_{\text{bathy}} - h_{\text{draft}})/3$. One deep box (black) connects the ice shelf front (red) with the grounding line zone (purple). The cavern is viewed from the side with the boxes arranged to yield a plane side. Data for bottom topography and ice shelf draft is obtained from RTOPO-1 (Timmermann et al., 2010). **(b)** Sketch of the side view of the cavern showing ice, ocean, and bottom areas, bounded to the left by the grounding line and to the right by the ice-shelf front. Beneath the ice the freezing layer f acts as transition between the ice and the sub-ice boxes, with the boxes $i-1$, i , and $i+1$ shown with inflow transports $(u-w)$, w and outflow transport u for box i . Below the sub-ice boxes there is the deep ocean box d . The inflow transport into box d at the front has the magnitude q , and the same amount leaves the last sub-ice box at the ice-shelf front.

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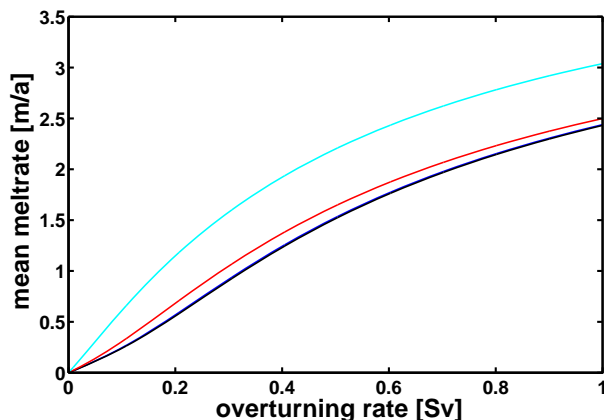


Fig. 2. Mean melt rate for the AMY geometry with 3 (cyan), 10 (red), 50 (blue), and 100 (black) sub-ice boxes as function of the overturning q ($1 \text{ Sv} = 1 \times 10^{-6} \text{ m}^3 \text{ s}^{-1}$); the difference between 50 and 100 sub-ice boxes is minimal causing an overlap of the curves. Upwelling w is predominantly close to the grounding line (the “fast decrease” scenario; further details are given in Sect. 3).

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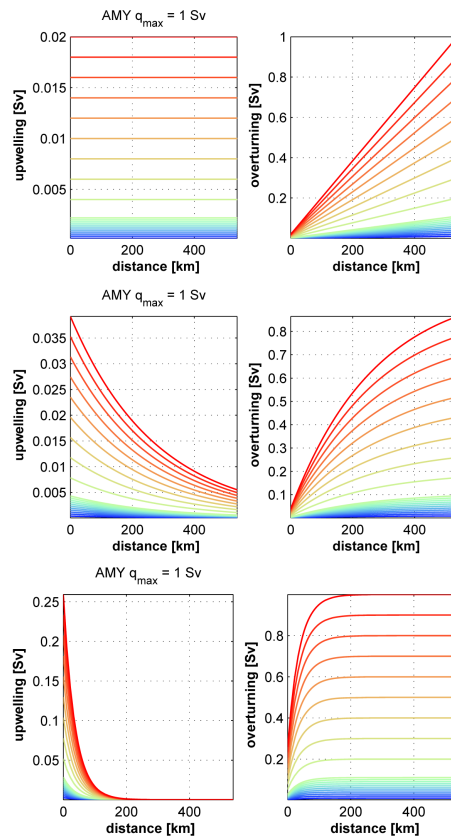


Fig. 3. For three upwelling scenarios: uniform upwelling (upper), slow decrease from grounding line (middle), fast decrease from grounding line (lower). The upwelling transport w (left) and the horizontal transport u (right) is shown as function of distance from the grounding line. 20 values of q are considered: the blue curves are for the range $0 < q < 0.1$ Sv ($1 \text{ Sv} = 1 \times 10^{-6} \text{ m}^3 \text{ s}^{-1}$) in steps of 0.01 Sv, proceeding then in steps of 0.1 Sv to 1.0 Sv (green to red).

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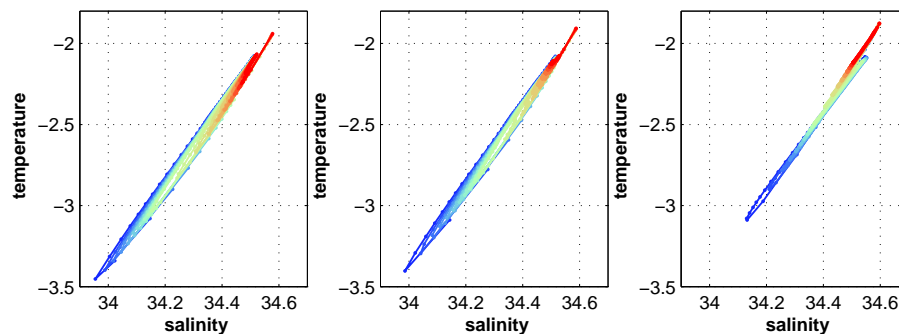


Fig. 5. T/S -diagram for all (50) sub-ice boxes and the suite of overturning rates (color coded as in Fig. 6): uniform upwelling scenario (left), slow decrease from grounding line (middle), fast decrease from grounding line (right).

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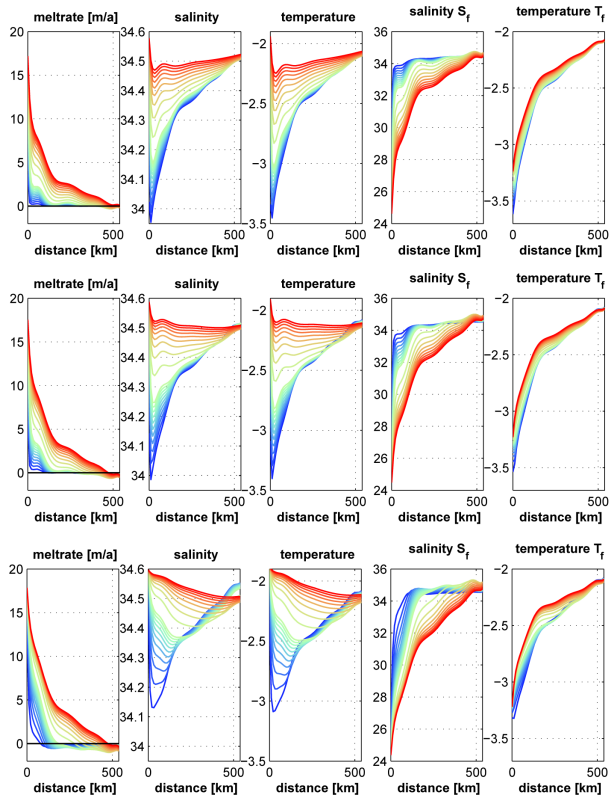


Fig. 6. Melt rates, salinity, and temperature in the boxes beneath AMY as function of distance from the grounding line for different q values. The two right panels display the thermohaline state of the freezing layer (subscript f). The blue curves are for the range $0 < q < 0.1$ Sv ($1 \text{ Sv} = 1 \times 10^{-6} \text{ m}^3 \text{ s}^{-1}$) in steps of 0.01 Sv, proceeding then in steps of 0.1 Sv to 1.0 Sv (green to red). Uniform upwelling (upper row), slow decrease from grounding line (middle row), fast decrease from grounding line (lower row).

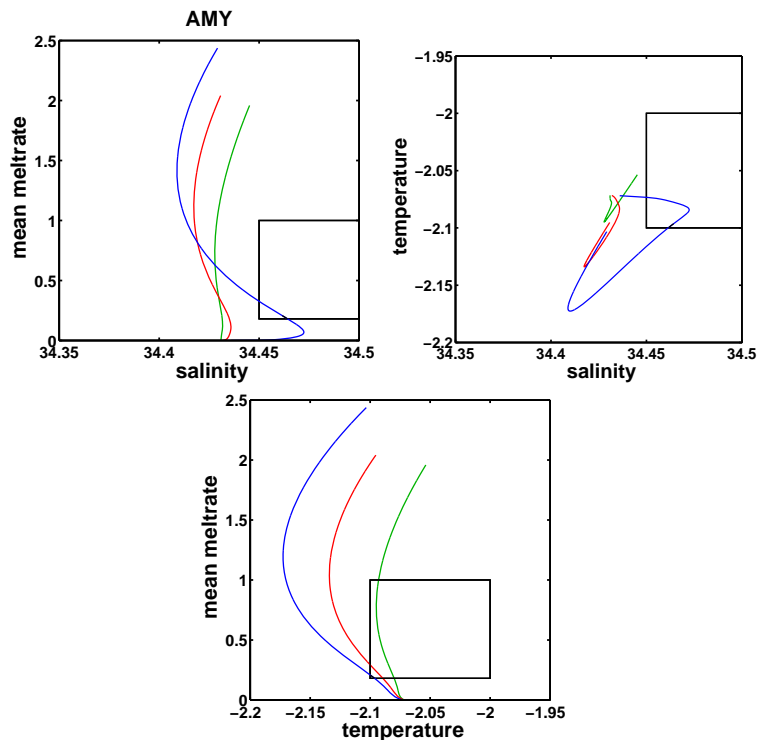


Fig. 7. Salinity and temperature in the front box of Amery Ice Shelf (AMY), and the mean melt rate [ma^{-1}] as trajectories $T_c(q)$, $S_c(q)$, and $\bar{m}(q)$ in the phase space. The three upwelling scenarios are plotted as green (“uniform”), red (“slow decrease”) and blue (“fast decrease”) curves, representing the two-dimensional views of the respective trajectories. The black portion of the curves, almost invisible for AMY due to a short pass through the melt rate/temperature plane (lower panel), indicates q values, which are compatible with all constraints given by the black boxes.

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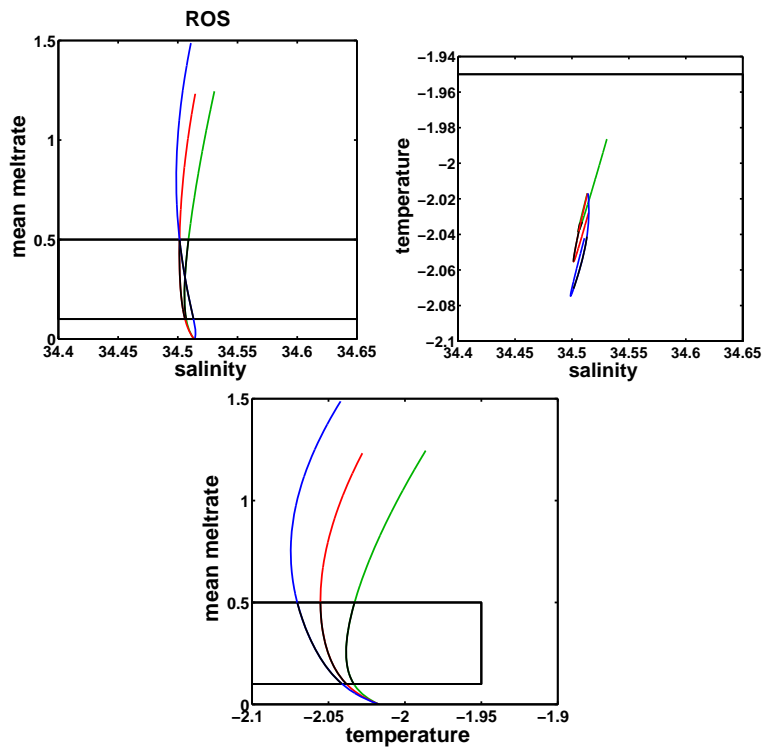


Fig. 8. Same as Fig. 7 but for the Ross Ice Shelf (ROS).

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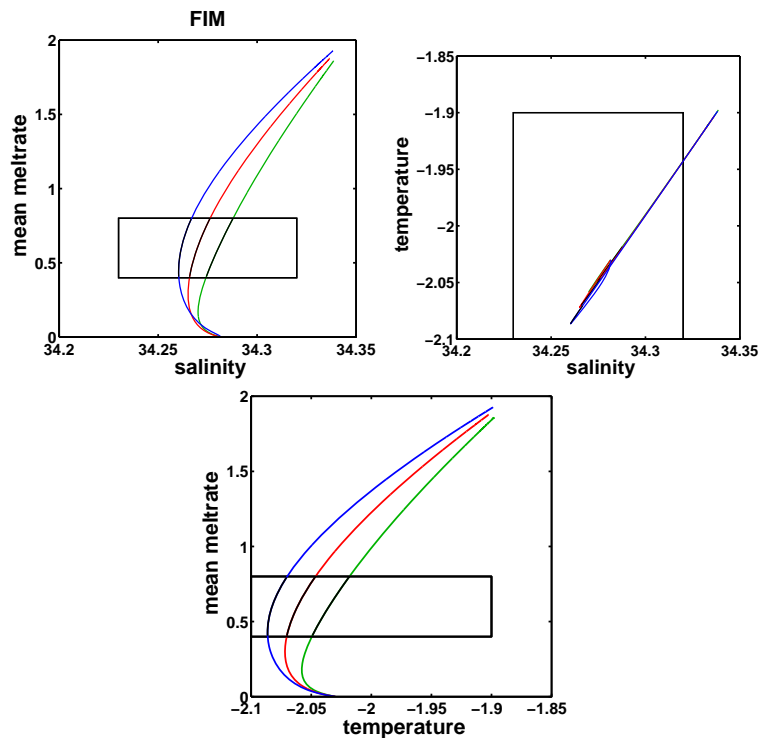


Fig. 9. Same as Fig. 7 but for Fimbulisen (FIM).

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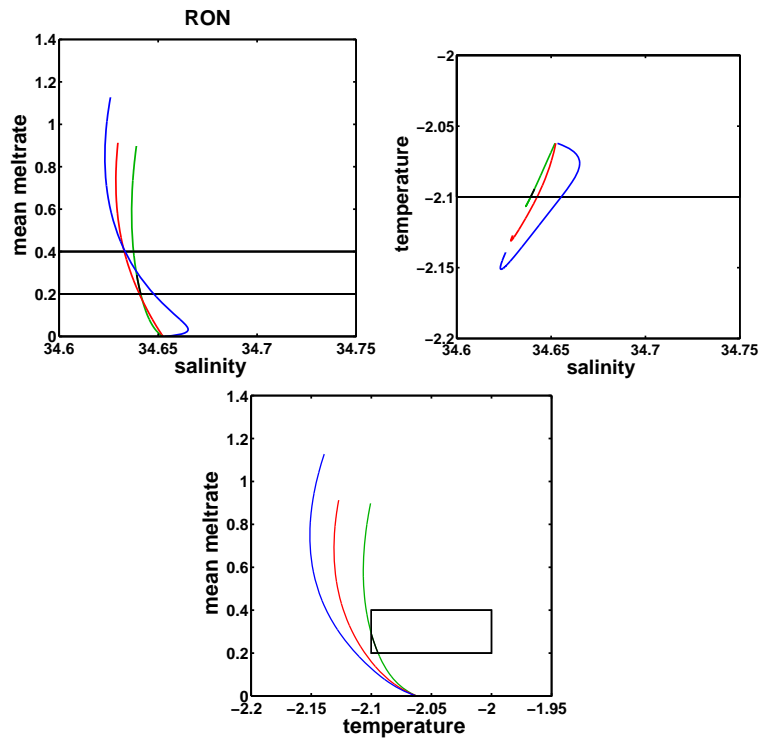


Fig. 10. Same as Fig. 7 but for Ronne Ice Shelf (RON).

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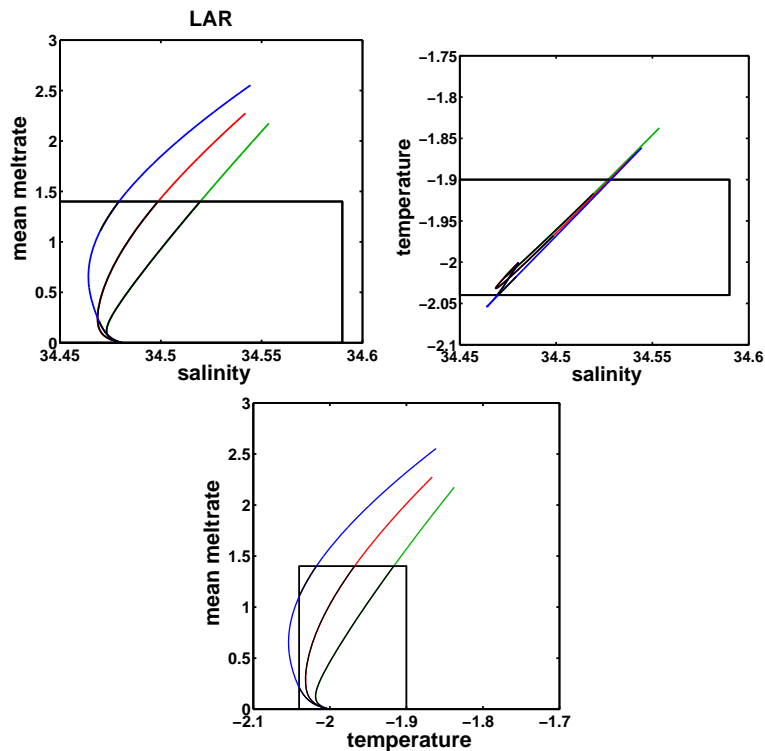


Fig. 11. Same as Fig. 7 but for Larsen C Ice Shelf (LAR).

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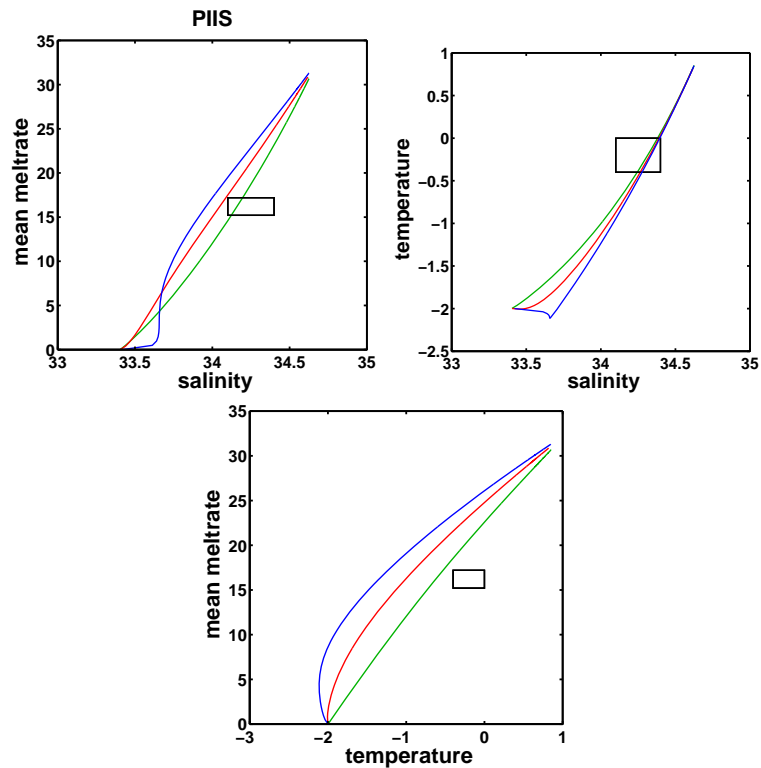


Fig. 12. Same as Fig. 7 but for Pine Island Ice Shelf (PIIS).

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Fig. 13. Bathymetry (upper) and draft (middle) of the AMY cavern. The black straight line is the Center Line (CL). Bathymetry and draft along CL and the fit was derived with a 9th-degree polynomial (lower). The data is retrieved from RTOPO-1 (Timmermann et al., 2010).

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