



*Supplement of*

**Brief communication: Monitoring snow depth using small, cheap, and easy-to-deploy snow–ground interface temperature sensors**

**Claire L. Bachand et al.**

*Correspondence to:* Claire L. Bachand (clbachand@alaska.edu)

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## Section S1: Data Collection

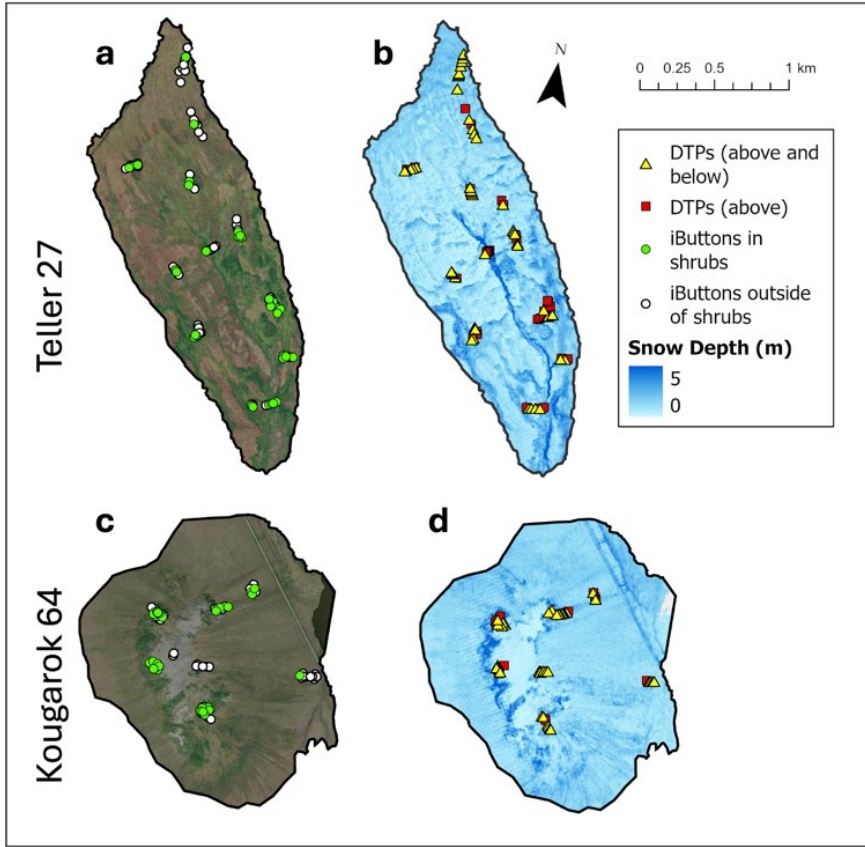
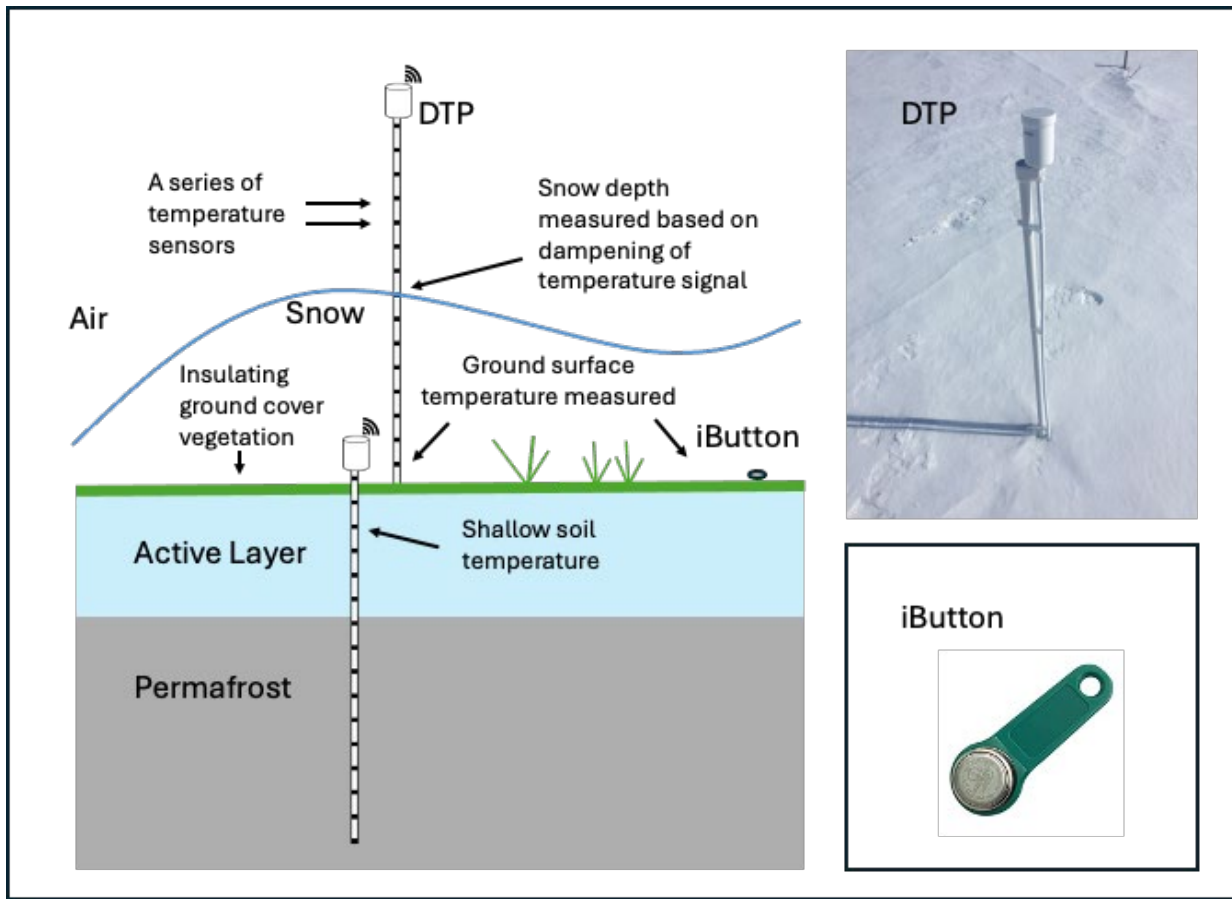


Figure S1. Locations of iButton Link Thermochron (DS1921G-F5#) temperature sensors deployed in (green circles) and outside (white circles) of tall shrubs over the 2022 – 2023 snow season at a) Teller27 and c) Kougarak64 (Bennett et al., 2024). Background  
5 imagery from Esri, Garmin, USGS, Maxar, 2024, ArcGIS RGB Basemap. Locations of DTP temperature systems that recorded both above and below ground temperature (yellow triangles) or only above ground temperature (red squares) over the 2021 – 2022 snow season at b) Teller27 and d) Kougarak64 (Wang et al., 2024). Blue background imagery shows snow depth in April 2022 estimated using Light Detection and Ranging (LiDAR) data (Singhania et al., 2023a, b).



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**Figure S2. Set up of DTP systems and iButton temperature sensors. Only shallow soil temperature data was used in this study, but the soil DTP systems can measure temperature down to 100 to 160 cm of depth. Figure source: Bachand et al., 2024; <https://doi.org/10.15485/2371854>.**

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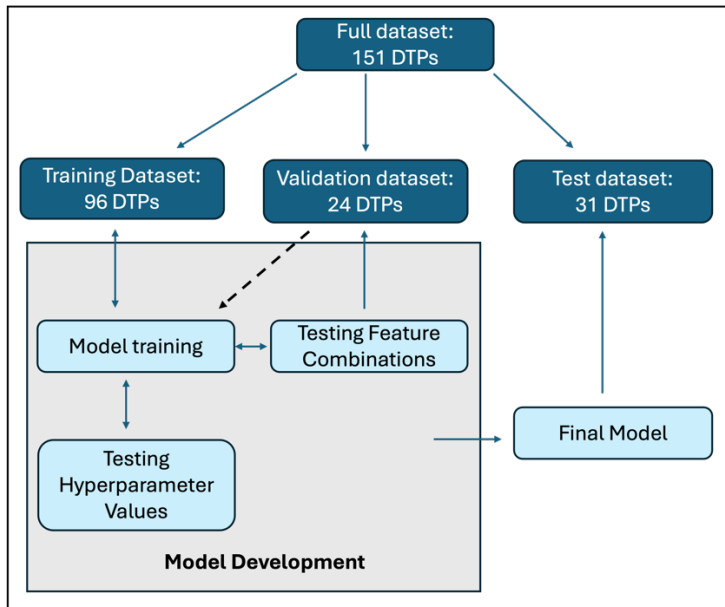


Figure S3. Use of training, validation, and test datasets in model development. We split the training data into groups of DTP systems rather than groups of daily data points to maintain the independence of entire snow depth/ temperature time series during model testing. Different combinations of input features were tested using the validation dataset. After the best-performing set of input features was determined, the final model was trained using both the training dataset and validation dataset. The test dataset was excluded completely from the model development process.

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Parameter	Value
Number of decision trees	70
Maximum depth of decision tree	10 layers
Minimum number of samples required to form a yes/no split	15
Maximum amount of samples used to build a decision tree	80 %
Maximum number of features used in each decision tree	2

Table S1. Random forest parameters. To tune hyperparameters, we first visualized how different hyperparameter values affected model performance using the validation dataset. After selecting three candidate values for each hyperparameter, we used a 5-fold cross validation grid search algorithm to determine the best hyperparameter combination.

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<b>Model</b>	<b>Number of training data points</b>	<b>Related figure</b>
RF-Seward (applied to the test dataset)	<b>20,963</b>	<b>1a</b>
RF-Seward (trained at Teller27 and tested at Kougarok64)	<b>17,171</b>	<b>1b</b>
RF-Seward (trained at Kougarok64 and tested at Teller27)	<b>9,272</b>	<b>1c</b>
RF-Seward (retrained on all DTP data; applied to evaluation sites)	<b>25,418</b>	<b>2a-g, i, j</b>
RF-Below (applied to the test dataset)	<b>15,197</b>	<b>1d</b>
RF-Below (trained at Teller27 and tested at Kougarok64)	<b>11,396</b>	<b>1e</b>
RF-Below (trained at Kougarok64 and tested at Teller27)	<b>7,980</b>	<b>1f</b>
RF-Below (retrained on all DTP data; applied to evaluation sites)	<b>18,968</b>	<b>2c-h</b>
RF-Deep (applied to first Senator Beck Basin Site)	<b>1,305</b>	<b>2i</b>
RF-Deep (applied to second Senator Beck Basin Site)	<b>3,294</b>	<b>2j</b>

**Table S2. Number of training data points (days) used to train the random forest models.**

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### Section S3: Model Evaluation Sites

Site	Years	Sensor Details ( <i>vegetation description provided for belowground sensors</i> )	End-of-Winter Snowpack Bulk Density	Source
Bayelva Station, Svalbard, Norway	2003 - 2017	5 cm above the ground surface	350 kg m <sup>-3</sup>	Boike et al., 2017, 2018
Senator Beck Basin, CO, USA (2 sites)	2003 - 2022	At the snow-ground interface	450 kg m <sup>-3</sup> to 500 kg m <sup>-3</sup>	Center for Snow and Avalanche Studies, 2024; Landry et al., 2014
Imnaviat Creek, North Slope, AK, USA	1990 - 1992	At the snow-ground interface	250 kg m <sup>-3</sup>	Stuefer et al., 2020; Sturm and Holmgren, 1994
Los Alamos, NM, USA (18 iButtons deployed in pairs)	2023 - 2024	9 at the snow-ground interface; 9 1-5 cm below the ground surface; <i>bare ground with sparse grasses</i>	400 kg m <sup>-3</sup> during the 2024 water year, according to the nearby Quemazon SNOTEL Station	Thomas et al., 2024; Snow depth data at site B is from <a href="https://weathermachine.lanl.gov/">https://weathermachine.lanl.gov/</a>
SnowEx Grand Mesa Study Plot, CO, USA	2017 - 2022	5 cm below the ground surface; <i>forest clearing with sparse grasses</i>	400 kg m <sup>-3</sup> , according to the nearby Mesa Lakes SNOTEL Station	Houser et al., 2022
Samoylov Island, Siberia, Russia	2002 - 2020	1 cm below the ground surface in low centered polygon; <i>wet tundra</i>	175 kg m <sup>-3</sup> to 225 kg m <sup>-3</sup>	Boike et al., 2019a, b
Council, Seward Peninsula, AK, USA (two sites)	2000 - 2004	0 to 1 cm below the soil surface; <i>tussock and mossy tundra</i>	Unknown	Hinzman et al., 2016
Ivotuk, North Slope, AK, USA	1998 - 2006	0 to 1 cm below the soil surface; <i>tussock sedge and dwarf-shrub tundra</i>	Unknown	Hinzman et al., 2016

Table S3. Description of model evaluation sites

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