



# Supplement of

## Brief communication: On the potential of seismic polarity reversal to identify a thin low-velocity layer above a high-velocity layer in ice-rich rock glaciers

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*Fig.* S1 a) experimental recordings of 1 shot at Schafberg site with 20kg sledgehammer, time and frequency domain; b) Ricker wavelet adopted for synthetic modelling centred at 50 Hz.

### S1. Technical info for SRT / ERT processing



#### > SRT acquisition

Geode seismographs, 48 channels, 100 Hz geophones, 2 m geophones spacing, 4 meters shots spacing, 2 shots in each position, 20 kg hammer as seismic source.

#### SRT inversion modelling Pygimli

Inversion modelling:

- Picking error: 2 ms
- smoothing factor: normal isotropic regularisation (= 1);
- Regularization factor λ: 150;
- Starting model: gradient model 300-3000 m/s;
- Iteration: 4;
- Abort criteria reached: dPhi = 1.26 (< 2.0%);</li>
- rms/rrms(data, Response) = = 0.00489155/14.2038%;
- chi<sup>2</sup>(data, Response, error, log) = 5.48181;

Picking error: we evaluated the data uncertainty by performing a repeated picking of P-wave first arrivals for several shot gathered, calculating this way a representative standard deviation of 2 ms.

Regularization factor: we chose  $\lambda$  values using the L-curve analysis.

We applied an isotropic smoothing since we were interested in highlighting both lateral and vertical variations of Vp.

#### Schafberg site

ERT Acquisition

Syscal Pro- device, 48 channels, 3 m spacing, Dipole-Dipole skip 0-3, stacking range 3-6 (5% standard deviation threshold), and direct and reciprocal measurements.

> ERT inversion modelling ResIPy

Filtering

- $\rho_a < 0$
- stacking error < 5%
- reciprocal error < 20% (saved 1029/1901)

Inversion modelling

- Inversion type: regularized inversion with linear filtering;
- Regularization mode: normal regularization;
- Data type: logarithmic;
- Expected data error: 20% (a\_wgt = 0.01, b\_wgt = 0.20);
- Flux type: 3D;
- Weights update: routine based on Morelli and LaBrecque (1996);
- smoothing factor: normal isotropic regularisation (= 1);
- Iteration: 2;
- Final RMS misfit: 1.17

Expected data error evaluated with the reciprocal check. We defined a boundary threshold for the reciprocal error that allowed for a reliable quality of the measured apparent resistivities but at the same time a homogeneous distribution of measured points in the pseudo-section.

We applied an isotropic smoothing since we were interested in highlighting both lateral and vertical variations of resistivity.

#### SRT acquisition

Geode seismographs, 48 channels, 100 Hz geophones, 3 m geophones spacing, 4 meters shots spacing, 2 shots in each position, 20 kg hammer as seismic source.

SRT inversion modelling Pygimli

Inversion modelling:

- Picking error: 2 ms
  - smoothing factor: normal isotropic regularisation (= 1);
- Regularization factor λ: 200;
- Starting model: gradient model 500-5000 m/s;
- Iteration: 4;
- Abort criteria reached: dPhi = 0.42 (< 2.0%)</li>
- rms/rrms(data, Response) = 0.00309603/17.893%
- chi<sup>2</sup>(data, Response, error, log) = 2.39635;

Picking error: we evaluated the data uncertainty by performing a repeated picking of P-wave first arrivals for several shot gathered, calculating this way a representative standard deviation of 2 ms. Regularization factor: we chose  $\lambda$  values using the L-curve analysis.

We applied an isotropic smoothing since we were interested in highlighting both lateral and vertical variations of Vp.