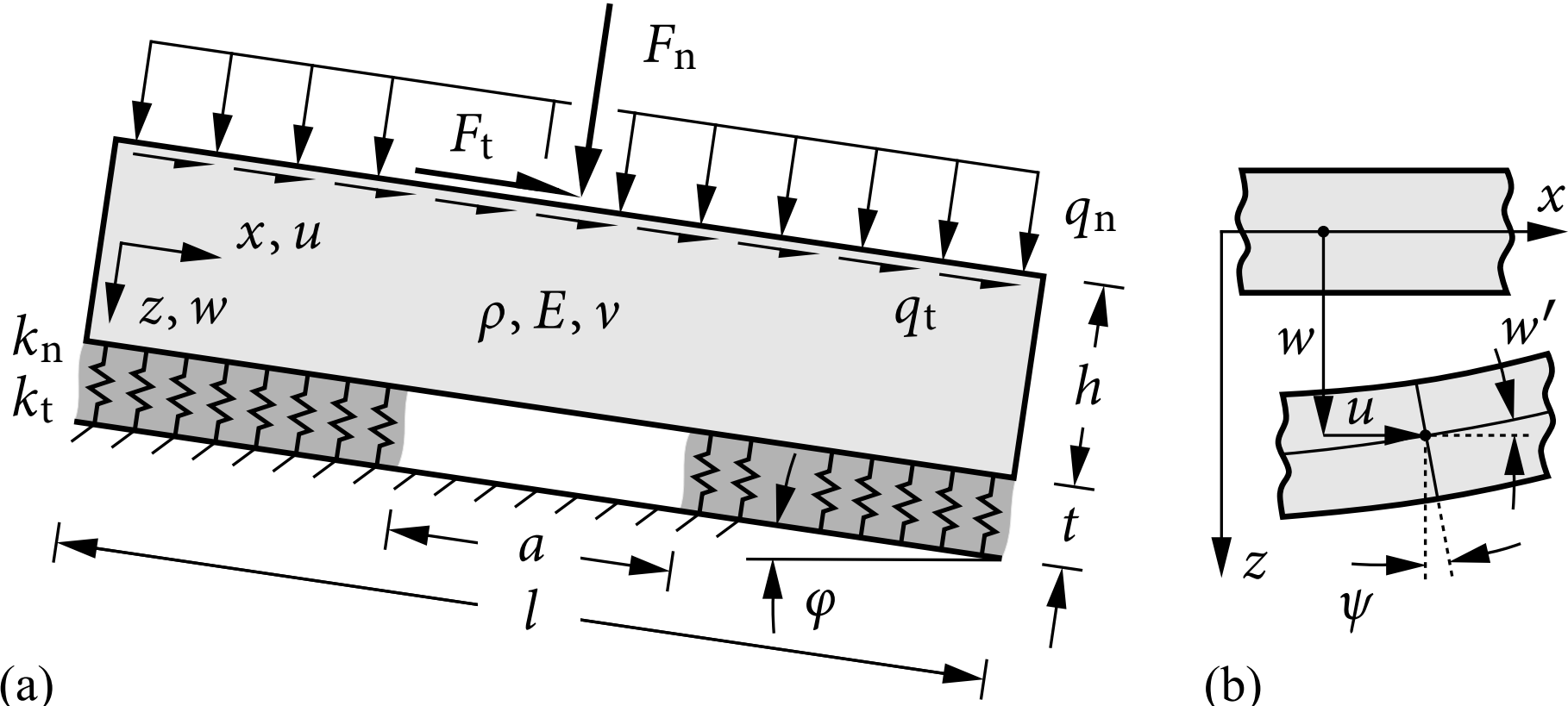
F_n
F_t
q_n
x, u
z, w
ρ, E, ν
q_t
k_n
k_t
h
t
a
l
φ
(a)
x
w
w'
u
z
ψ
(b)